

DIRECTORIO DE PROFESORES DEL CURSO INTRODUCCION A LA PROGRAMACION  
Y COMPUTACION ELECTRONICA 1981.

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Introducción a la Programación y Computación Electrónica 1981

Fecha	Tema	Horario	Profesor
Octubre 16	INTRODUCCION A LA COMPUTADORA DIGITAL Las Unidades de Entrada Las Unidades de Salida La Memoria El Control La Unidad Aritmética Lógica	17 a 21 h	Ing. Luis Cordero Borboa
Octubre 17	LENGUAJE FORTRAN Constantes Variables y Expresiones Proposiciones Aritméticas Proporciones de Entrada y Salida Control de Transferencia Variables con Subíndice Proposiciones de Iteración (DO) Formatos Subrutinas y Funciones	9 a 14 h	Ing. Heriberto Olguín Romo Ing. Ricardo Ciria Merce
Octubre 23		17 a 21 h	
Octubre 24		9 a 14 h	
Octubre 30	CASOS DE APLICACIONES MATEMATICOS Práctica , Facultad de Ingeniería, C.U.	17 a 21 h	Ing. Roberto Mandujano
Octubre 31		9 a 14 h	
Nov. 6	CASOS DE APLICACIONES NO-MATEMATICOS Práctica , Facultad de Ingeniería, C.U.	17 a 21 h	M. en C. Marcial Portilla Robertson
Nov. 7		9 a 14 h	
Nov. 13	Programación Lineal, Ruta Crítica, Inventarios Práctica, Facultad de Ingeniería, C.U.	17 a 21 h	Dr. Víctor Gerez Greiser
Nov. 14		9 a 14 h	



# EVALUACION DEL PERSONAL DOCENTE

(1)

**CURSO:** Introducción a la Programación y Computación Electrónica

**FECHA:** del 16 de octubre al 14 de Nov. 81.

	DOMINIO DEL TEMA	EFICIENCIA EN EL USO DE AYUDAS AUDIO VISUALES	MANTENIMIENTO DEL INTERES. (COMUNICACION CON LOS ASISTENTES, AMENIDAD, FACILIDAD DE EXPRESION).	PUNTUALIDAD
<b>CONFERENCISTA</b>				
1. Ing. Luis Cordero Borboa				
2. Heriberto Olguín Romo				
3. Ing. Ricardo Ciria Merce				
4. Ing. Roberto Mandujano Wild				
5. M. en C. Marcial Artilla Robertson				
6. Dr. Víctor Gerez Greiser				

ESCALA DE EVALUACION : 1 a 10

SU EVALUACION SINCERA NOS AYUDARA A MEJORAR LOS PROGRAMAS POSTERIORES QUE DISEÑAREMOS PARA USTED.

TEMA	ORGANIZACION Y DESARROLLO DEL TEMA	GRADO DE PROFUNDIDAD LOGRADO EN EL TEMA	GRADO DE ACTUALIZACION LOGRADO EN EL TEMA	UTILIDAD PRACTICA DEL TEMA	
INTRODUCCION A LA COMPUTACION DIGITAL .					
Las Unidades de Entrada					
Las Unidades de Salida					
La Memoria					
El Control					
La Unidad Aritmética Lógica					
LENGUAJE FORTRAN					
Constantes variables y expresiones					
Proposiciones aritméticas					
Proporciones de entrada y salida					
Control de transferencia					
Variables con subíndice					





# EVALUACION DE LA ENSEÑANZA

(2)  
(b)

SU EVALUACION SINCERA NOS AYUDARA A MEJORAR LOS PROGRAMAS POSTERIORES QUE DISEÑAREMOS PARA USTED.

TEMA	ORGANIZACION Y DESARROLLO DEL TEMA	GRADO DE PROFUNDIDAD LOGRADO EN EL TEMA	GRADO DE ACTUALIZACION LOGRADO EN EL TEMA	UTILIDAD PRACTICA DEL TEMA
CASOS PRACTICOS MATEMATICOS				
CASOS DE APLICACIONES NO-MATEMATICOS				
PROGRAMACION LINEAL				
REJTA CRITICA				
INVENTARIO				
PRACTICAS				

ESCALA DE EVALUACION: 1 a 10

## EVALUACION DEL CURSO

③

	CONCEPTO	EVALUACION
1.	APLICACION INMEDIATA DE LOS CONCEPTOS EXPUESTOS	
2.	CLARIDAD CON QUE SE EXPUSIERON LOS TEMAS	
3.	GRADO DE ACTUALIZACION LOGRADO CON EL CURSO	
4.	CUMPLIMIENTO DE LOS OBJETIVOS DEL CURSO	
5.	CONTINUIDAD EN LOS TEMAS DEL CURSO	
6.	CALIDAD DE LAS NOTAS DEL CURSO	
7.	GRADO DE MOTIVACION LOGRADO CON EL CURSO	


ESCALA DE EVALUACION DE 1 A 10

1. ¿Qué le pareció el ambiente en la División de Educación Continua?

MIY AGRADABLE	AGRADABLE	DESAGRADABLE

2. Medio de comunicación por el que se enteró del curso:

PERIODICO EXCELSIOR ANUNCIO TITULADO DE VISION DE EDUCACION CONTINUA	PERIODICO NOVEDADES ANUNCIO TITULADO DE VISION DE EDUCACION CONTINUA	FOLLETO DEL CURSO

CARTEL MENSUAL	RADIO UNIVERSIDAD	COMUNICACION CARTA, TELEFONO, VERBAL, ETC.
		

REVISTAS TECNICAS	FOLLETO ANUAL	CARTELERA UNAM "LOS UNIVERSITARIOS HOY"	GACETA UNAM

3. Medio de transporte utilizado para venir al Palacio de Minería:

AUTOMOVIL PARTICULAR	METRO	OTRO MEDIO

4. ¿Qué cambios haría usted en el programa para tratar de perfeccionar el curso?

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5. ¿Recomendaría el curso a otras personas?

SI	NO



6. ¿Qué cursos le gustaría que ofreciera la División de Educación Continua?

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7. La coordinación académica fue:

EXCELENTE	BUENA	REGULAR	MALA

8. Si está interesado en tomar algún curso intensivo ¿Cuál es el horario más conveniente para usted?

LUNES A VIERNES DE 9 A 13 H. Y DE 14 A 18 H. (CON COMIDAS)	LUNES A VIERNES DE 17 A 21 H.	LUNES, MIERCOLES Y VIERNES DE 18 A 21 H.	MARTES Y JUEVES DE 18 A 21 H.

VIERNES DE 17 A 21 H. SABADOS DE 9 A 14 H.	VIERNES DE 17 A 21 H. SABADOS DE 9 A 13 Y DE 14 A 18 H.	OTRO

9. ¿Qué servicios adicionales desearía que tuviese la División de Educación Continua, para los asistentes?

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10. Otras sugerencias:

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**DIVISION DE EDUCACION CONTINUA  
FACULTAD DE INGENIERIA U.N.A.M.**

INTRODUCCION A LA PROGRAMACION Y COMPUTACION ELECTRONICA

INTRODUCCION A LA COMPUTADORA DIGITAL

OCTUBRE, 1981

## CONCEPTO DE COMPUTADORA

### OBJETO :

El objeto de esta breve reseña sobre los computadores electrónicos y sus múltiples aplicaciones al servicio del hombre, es transmitir al lector una completa visión de conjunto, mediante un lenguaje sencilla que permita comprender conceptualmente los temas tratados, sin necesidad de conocimientos previos en la materia.

Esperamos que estas páginas, muy simples en apariencia pero con profundo contenido, permitan, a quienes las lean, ingresar al maravilloso mundo de las máquinas automáticas.



Este señor se llama Control. Trabaja en una pequeña habitación. Tiene a su disposición una máquina de calcular que suma, resta, multiplica y divide. Tiene también el señor Control un archivo parecido al casillero que existe en los trenes por clasificación postal. Hay, además, en la habitación, dos ventanillas identificadas con sendas cartelas: "Entrada" y "Salida". El señor Control tiene un manual que le indica cómo debe desenvolverse con estos elementos, si alguien le pide que haga un trabajo.



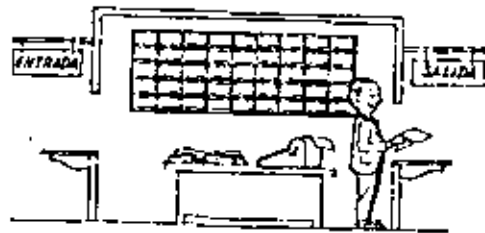
Una persona quiere saber el resultado de un complicado cálculo. Para ello, escribe ordenado, preciso y detalladamente, cada una de las operaciones que, en conjunto, integran ese cálculo, anota cada instrucción elemental en una hoja de papel y coloca todas las hojas en orden en la ventanilla "Entrada". El señor Control, al ver las hojas, lee en su manual que debe tomar esas hojas con instrucciones, una por una, y colocarlas correctamente en su archivo. Y así lo hace.



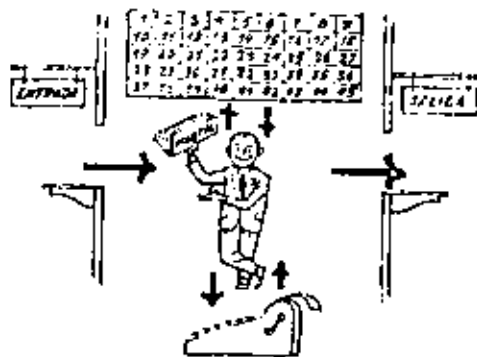
Una vez ubicadas todas las instrucciones en el archivo, el señor Control consulta nuevamente el manual. Allí se le indica que, a continuación, debe tomar la instrucción de la casilla 1 y ejecutarla luego, la de la casilla 2 y ejecutarla, y así sucesivamente hasta ejecutar la última instrucción. Algunas instrucciones indican que hay que sumar una cantidad a otra (instrucciones aritméticas); otras, que el señor Control debe ir a la ventanilla "Entrada" para buscar algún dato que intervenga en el cálculo -- (instrucciones de "entrada/salida"), dato que la persona que le formuló el problema habrá colocado ya en dicha ventanilla, en otra hoja de papel.

Finalmente, otras instrucciones indicarán que debe elegirse una de entre dos alternativas (instrucciones lógicas); por ejemplo, supongamos que una parte del cálculo - desde la instrucción que está en la casilla 5 del archivo hasta la que está en la casilla 9 debe ejecutarse 15 veces porque el cálculo así lo exige. En tal caso, la instrucción que está en la casilla 10 indicará que, si las veces 5 a 9 se han ejecutado menos de 15 veces, se debe volver al paso 5. Cuando se hayan realizado las 15 repeticiones y no antes, el señor Control seguirá con la instrucción de la casilla 11.





Después de ejecutar todas las instrucciones del archivo, haciendo con la máquina de calcular las operaciones en ellos indicadas, el señor Control entrega, a través de la ventanilla "Salida", los resultados obtenidos . . . y se sienta a esperar un nuevo trabajo.



Obsérvese que la actuación del señor Control es puramente mecánica: sólo sigue las indicaciones de su máquina y cumple de acuerdo con ellas las instrucciones que recibe a través de la ventanilla "Entrada". Toma decisiones, pero solamente cuando se le señalan las alternativas que existen y con qué criterio debe elegir una de ellas. El señor Control puede resolver cualquier problema, por complicado que éste sea. Pero para ello debemos indicarle paso a paso, en la forma más elemental y detallada, todo lo que debe hacer para resolverlo, sin olvidarnos absolutamente nada porque, en ese caso, el señor Control no sabría continuar por sí mismo. Haga el lector la prueba de formular un problema cualquiera de modo tal que una persona que no conozca nada acerca de ese problema pueda resolverlo sin necesidad de hacer consultas. Véalo que es una experiencia interesantísima.

El esquema que acabamos de representar mediante el señor Control y sus elementos de trabajo, corresponde exactamente al esquema de funcionamiento de una computadora electrónica.

A continuación presentaremos una breve descripción de los elementos de la computadora que corresponden a los elementos de trabajo del señor Control.

Las unidades de Entrada (representadas por la ventanilla "Entrada"):

Son en la computadora, dispositivos capaces de leer información (Instrucciones o Datos) con el objeto de procesarla. Existen una gran variedad de elementos de entrada, entre los cuales tenemos:

Tarjetas de Cartulina y Cintas de Papel: Que son perforadas de manera que cada perforación representa un número, una letra ó un símbolo especial de acuerdo con un código predeterminado.

Cintas magnéticas: Conocidas como "Memoria externa" tienen la ventaja de permitir almacenar la información en forma más concentrada — (a razón de 80 a 2400 caracteres por pulgada de longitud) y de ser más velaces, ya que pueden enviar o recibir información a la unidad de control y velocidades que van de 10,000 a 680,000 caracteres por segundo. Pueden llegar a tener hasta 730 m. de longitud.

Disco Magnético: También conocidos como "Memoria externa" en general tienen un diámetro aproximado de 30 cms. y pueden grabar hasta 400,000 letras, números, Y caracteres especiales, formando palabras, cifras, ó registros completos se pueden grabar o leer a razón de 77,000 a 312,000 caracteres por segundo y su tiempo de acceso a un registro alcanza un promedio de 60 mili-segundos.

Una diferencia importante entre las cintas y los discos es la siguiente:

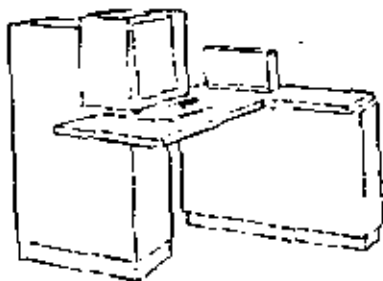
En las cintas los registros se graban o leen secuencialmente.

En los discos se tiene "Libre Acceso" a un registro cualquiera, en forma inmediata, pues cada registro se localiza por su posición física dentro del disco.

Lectora Óptica de Caracteres Impresos: Puede leer un documento impreso por una máquina de escribir, o por una máquina de contabilidad o por la impresora de una computadora a una velocidad de 30,000 caracteres por minuto.

Unidad de Representación Visual: Esta unidad de entrada/salida sirve para hacer consultas a la computadora, por medio de un teclado de máquina de escribir, y obtener la respuesta reflejada en una pequeña pantalla de televisión.

La imagen está formada por hasta 12 renglones de hasta 80 caracteres (letra, números, ó signos especiales) cada uno.



Vemos aquí otra Unidad de Representación Visual, más evolucionada que la anterior, la comunicación hombre-máquina puede establecerse en ella por medio de gráficas, es decir que la entrada y la salida de datos se hacen por medio de imágenes.

Cuenta esta unidad para ello con un dispositivo con forma de lápiz, que tiene en su punta una célula fotoeléctrica. Un delgado haz de luz parte en determinado momento de un punto de la pantalla y lo recorre en forma de zig-zag. Si se apoya el "lápiz" en cualquier posición de la pantalla, su célula fotoeléctrica detectará en algún momento al haz de luz. Por el tiempo transcurrido desde que el haz de luz comenzó su "barrido" hasta que fue detectada, la computadora determina en qué punto de la pantalla se encuentra apoyada el "lápiz".

Como el barrido dura una fracción de segunda y se realizan muchos barridos por segunda, se puede "escribir" con el "lápiz" sobre la pantalla y el dibujo "ingresa" en la memoria de la computadora como una sucesión de puntos codificados.

La pantalla está imaginariamente dividida en 1.040,576 puntos, de manera que los trazos que se obtienen son prácticamente continuos.

Pueden dibujarse así curvas, estructuras, letras, números y cualquier tipo de gráfico, y esa información ingresa automáticamente a la computadora.

Por otra parte, los resultados obtenidos por la computadora son representados en la pantalla también como curvas, letras, etc., bajo control del programa almacenado en la memoria.

Lectora Óptica de Manuscritos: Solvo algunas pequeñas restricciones en cuanto al formato de los caracteres, esta unidad puede "leer" documentos escritos por cualquier persona y con cualquier ejemplo a una velocidad aproximada de 30,000 caracteres por minuto.

El registrador/analizador fotográfico es una Unidad de Entrada/Salida de datos que realiza las siguientes funciones.

- 1) Registra los resultados de la computadora sobre microfotografías, mediante un tubo de rayos catódicos, que inciden sobre una película fotográfica, y cuya haz electrónica está gobernada por el Programa Almacenado. La película se revela automáticamente dentro de la unidad y 48 segundos después está listo para ser proyectado.
- 2) Proyecta sobre una pantalla translúcida las microfotografías registradas.
- 3) Analiza imágenes reproducidas en negativo sobre película transparente, las digitaliza y las transmite a la Unidad Central de Procesamiento.

La película utilizada tiene 30,5 milímetros de ancho y 120 metros de longitud. La Entrada o Salida de imágenes puede consistir en letras, números, símbolos, dibujos, gráficas, mapas, curvas, etc. En una microfotografía de 30,5 mm X 30,5 mm pueden registrarse hasta 30.600 letras y números, o hasta 16.777.216 puntos correspondientes a imágenes. La velocidad de Registración/Análisis es de 40.000 letras, números y símbolos por segundo, o su equivalente si se trata de imágenes.

Máquina de Escribir ( Teletipo ). Las unidades de almacenamiento o memorias ( Representadas por el archivo del señor Control ) permiten registrar las instrucciones y los datos para resolver un problema; entre otros se tienen.

Los Anillos Magnetizantes : Estos pueden magnetizarse en un sentido ó en otro "Recordando" así un 1 a un 0 respectivamente. Con 8 de éstos anillos se forma una posición de memoria, en la cual puede registrarse una letra, un dígito ó un carácter especial, según las distintas combinaciones de anillos "En 1" y "En 0", de acuerdo a un código predeterminado.

Las Memorias de Flip - Flop

Las Cintas Magnéticas

Las Discos Magnéticas

El dispositivo aritmético ( representado por la máquina de calcular ) realiza las cuatro operaciones aritméticas.

Las unidades de salida ( representadas por la ventanilla "Salida" ), que pueden ser :

Impresoras

Máquinas de Escribir ( Teletipos )

Grabadoras de Cintas Magnéticas

Grabadoras de Discos Magnéticos

Unidad de Representación Visual

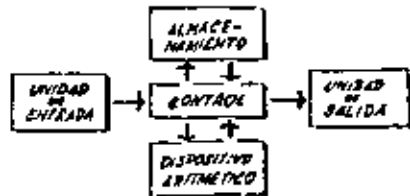
Registrador Analizador Fotográfico

Unidad de Respuesta Oral con la cual la Computadora puede hablar en todo el sentido de la palabra.

Contiene una Cinta magnetofónica en la cual un locutor ha grabado un diccionario de una gran variedad de palabras, en cualquier idioma.

Finalmente, un dispositivo electrónico de control (representado por el señor control) ayudado de un programa especial o sistema operativo (representado por el manual del señor Control), gobierna todas las operaciones de todas las unidades que componen la computadora.

Habiendo descrito las partes que componen la computadora podemos mostrar el siguiente esquema que la representa:



O en forma más resumida:



Siendo:

- UNIDAD : ALMACENAMIENTO
- CENTRAL : CONTROL
- : DISPOSITIVO ARITMETICO

Hemos hablado hasta este momento de la computadora electrónica desde el punto de vista conceptual. Durante las dos últimas décadas se han producido avances tecnológicos tan extraordinarios en materia de electrónica que la computadora ha sufrido enormes transformaciones. Veremos ahora cómo se ha ido modificando la idea original hasta llegar a los más modernos sistemas de procesamiento de datos.

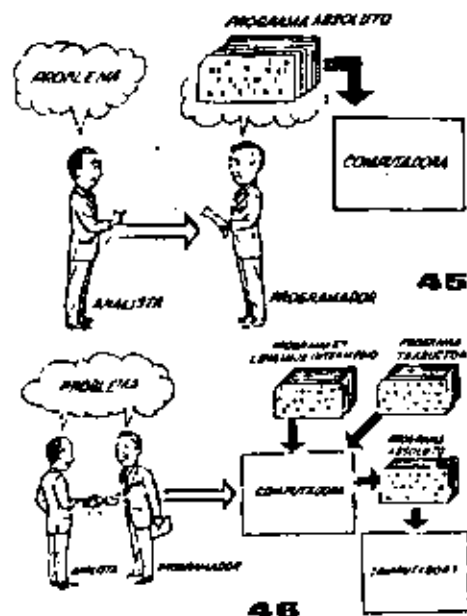
Las primeras computadoras tenían circuitos con válvulas de vacío. Los tiempos de operación se medían en ellas en milisegundos (milésimas de segundo). Cuando aparecieron los transistores, el diseño de los circuitos se mejoró notablemente y la duración de las operaciones en las computadoras que utilizaban esta "tecnología de Estado Sólido" se midió en microsegundos (millonésimas de segundo).

El hecho de que las nuevas máquinas fueran miles de veces más rápidas que las anteriores trajo aparejada la creación de unidades de entrada, salida y memoria externa mucho más veloces.

La invención de un nuevo tipo de transistor ("chip") provocó una verdadera revolución en los circuitos electrónicos y sus procesos de fabricación el nuevo elemento es tan pequeño que en un dedal de costura caben más de 50,000 chips. Puede observarse en la figura, marcada con un círculo, un circuito completo basado en esta nueva "Tecnología de Lógica Sólida". Debido a su tamaño, se los denominan circuitos microminiaturizados o microcircuitos. Los tiempos de operación se miden ahora en nanosegundos (milimillonésimas de segundo). Ha nacido en esta forma la tercera generación de computadoras, y las altas velocidades alcanzadas permitieron un nuevo enfoque en el diseño de los sistemas de procesamiento de datos.

Enunciaré brevemente los adelantos que esta tercera generación ha introducido con respecto a la tecnología anterior :

- La computadora se autogobierna y trabaja sin detenerse, pasando de un trabajo a otro sin demora alguna.
- El Operador interviene sólo cuando algún problema excepcional ocurre. La comunicación entre hombre y máquina se realiza sólo sobre la base de "Informes por Excepción".
- Si ocurre una falla en los circuitos o en la parte electromecánica la máquina realiza un autodiagnóstico e indica cuál es la anomalía.
- La velocidad de Entrada-Programa-Salida se ha incrementado extraordinariamente.
- Todas las operaciones del sistema se realizan en forma simultánea.
- Los lenguajes de programación han evolucionado de manera notable.
- El autocontrol y la autoverificación de operaciones han alcanzado niveles insuspechados.
- Pueden realizarse, con máximo rendimiento, varios trabajos distintos simultáneamente.



Hasta ahora hemos visto muchas unidades que, en distintas combinaciones, configuran computadoras electrónicas para las más variadas aplicaciones. Ahora nos detendremos para analizar el manejo de dichos sistemas.

El Programa de Instrucciones almacenado en la Unidad Control de Procesamiento, consta de una secuencia de órdenes y comandos, expresados según una codificación especial denominada "Lenguaje Absoluta de Máquina". Las primeras computadoras se programaban en este complejo lenguaje. Había entonces una enorme diferencia entre nuestro idioma y aquél según el cual debíamos comunicarnos con la máquina. Esto obligaba a un gran esfuerzo común entre el analista que conocía el problema, y el programador que conocía la computadora, pues ambos hablaban del mismo proceso pero en distintos lenguajes.

Se crearon, para solucionar el problema, los lenguajes intermedios cada vez más parecidos a nuestro idioma. Es decir que cada nuevo lenguaje intermedio se acercaba más al problema y se alejaba más de la máquina. Para cada uno de estos lenguajes se creó un programa traductor llamado "Compaginador" o "Compilador", que tenía la misión de traducir el lenguaje intermedio al absoluto de máquina. Ahora, el analista y el programador "hablan un mismo idioma": ambos conocen el problema y la solución.

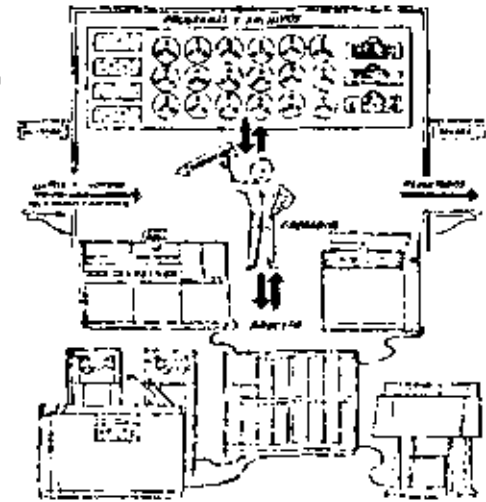
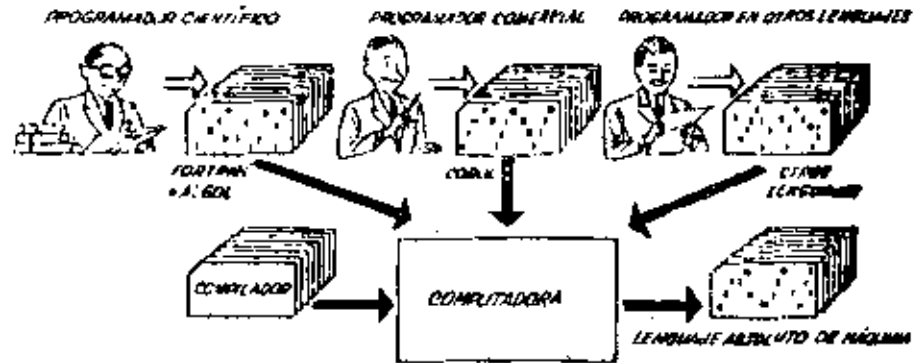
Para la computadora seguía desarrollándose, y pronto los lenguajes intermedios fueron insuficientes para formular intrincados problemas científicos o comerciales. Nacieron, entonces, lenguajes especializados: de alto, el FORTRAN y el ALGOL, permiten programar problemas científicos-matemáticos utilizando una notación casi idéntica a la notación matemática común. El COBOL es un lenguaje comercial cuyas sentencias configuran oraciones y frases en forma tal que una persona que no sabe qué es una computadora, puede leer un programa y entender perfectamente qué es lo que hará la máquina cuando la tenga almacenado.

Cada uno de estos lenguajes tiene un programa Compilador para cada tipo distinto de computadora capaz de procesarlo. Esto significa que un programador que sabe FORTRAN, por ejemplo, puede programar una computadora aún sin conocerla. Es decir que estos tres lenguajes constituyen un "esperanto" de las máquinas.

La tercera generación de computadoras permitió abordar complejos problemas que incluían, entre otras, aspectos comerciales y científicos. No había un lenguaje que abarcara todas las especialidades.

Entonces se reunieron todos los lenguajes conocidos en un superlenguaje llamado PL/I, cuyo compilador es tan poderoso que posibilita la sectorización de la programación en la forma que muestra el dibujo: varios programadores pueden programar distintas partes del proceso, incluso en diferentes lenguajes, y el programa compilado entregará como resultado las instrucciones del proceso completo, en Lenguaje Absoluto de Máquina.

Hemos llegado así a una computadora que "entiende", en lugar de que se limita a recibir órdenes en su idioma.



## 1-1 Algorithms and Flowcharts



FIGURE 1-1  
First flat-tire flowchart.

What is an algorithm? An *algorithm* is a list of instructions for carrying out some process step by step. A recipe in a cookbook is an excellent example of an algorithm. The preparation of a complicated dish is broken down into simple steps that every person experienced in cooking can understand. Another good example of an algorithm is the choreography for a classical ballet. An intricate dance is broken down into a succession of basic steps and positions of ballet. The number of these basic steps and positions is very small but, by putting them together in different ways, an endless variety of dances can be devised.

In the same way, algorithms executed by a computer can combine millions of elementary steps, such as additions and subtractions, into a complicated mathematical calculation. Also by means of algorithms, a computer can control a manufacturing process or coordinate the reservations of an airline as they are received from ticket offices all over the country. Algorithms for such large-scale processes are, of course, very complex, but they are built up from pieces, as in the example we will now consider.

If we can devise an algorithm for a process, we can usually do so in many different ways. Here is one algorithm for the everyday process of changing a flat tire.

1. Jack up the car.
2. Unscrew the lugs.
3. Remove the wheel.
4. Put on the spare.
5. Screw on the lugs.
6. Jack the car down.

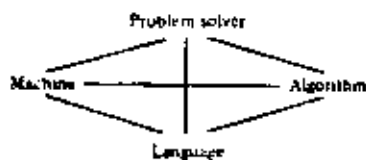
We could add many more details to this algorithm. We could include getting the materials out of the trunk, positioning the jack, removing the hubcaps, and loosening the lugs before jacking up the car, for example. For algorithms describing mechanical processes, it is generally best to decide how much detail to include. Still, the steps we have listed will be adequate to convey the idea of an algorithm. When we get to mathematical algorithms, we will have to be much more precise.

Computers arouse curiosity in most of us. Articles in popular magazines and newspapers, current books, and TV shows heighten this curiosity, but such sources cannot be expected to present information in the carefully ordered sequences that is possible in a book like this. Whether you are drawn by curiosity alone, or economic necessity, or both, conscientious study of this book will help you to break through to a new level of understanding about computers, their uses, and their consequences.

Computer science deals with people who have problems to solve and with algorithms, the solutions to these problems. The solutions are expressed in special languages that represent stored data and communicate to machines the manipulations that are to be carried out on that data.

Each of these four elements (problem solver, algorithm, language, and machine) affects the others in interesting ways. For example, depending on its richness, a language can either limit or extend our ability to express complex plans of action effectively. And, depending on its capabilities (i.e., its architecture), a machine can execute some plans of action on certain data representations more effectively than on others. The loop of interaction closes when the problem solver changes the plan of action, the language, or the machine architecture to suit his purpose.

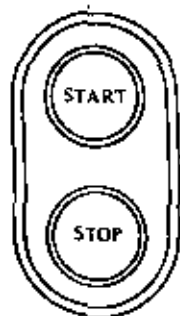
This book introduces all four components of this interaction. Every chapter takes you around this "four-cornered race track" and, with every circumnavigation, you gain a deeper and clearer understanding of the interplay among the four elements. You, of course, play the problem solver using a computer. To get the most out of this experience, laboratory practice is almost indispensable. But, even if you can't have actual computer experience, a careful reading of this book should illuminate the computer science scene far better and far beyond what you have previously perceived.



Elements of computer problem solving.



A *flowchart* is a diagram representing an algorithm. In Figure 1-1 we see a flowchart for the flat-tire algorithm.



The 10  and 

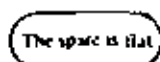
in the flowchart remind us of the buttons used to start and stop a piece of machinery. Each instruction in the flowchart is enclosed in a frame or "box." As we will soon see, the shape of the frame indicates the kind of instruction written inside. A rectangular frame indicates a command to take some action.

To carry out the task described by the flowchart, we begin at the start button and follow the arrows from box to box, executing the instructions as we come to them.

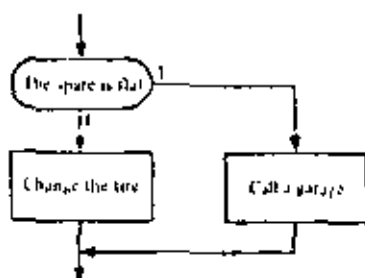
After drawing a flowchart, we always look to see whether we can improve it. For instance, in the flat-tire flowchart we neglected to check whether the spare was flat. If the spare is flat, we will not change the tire; we will call a garage instead. This calls for a decision between two courses of action. For this purpose we introduce a new shape of frame into our flowchart.



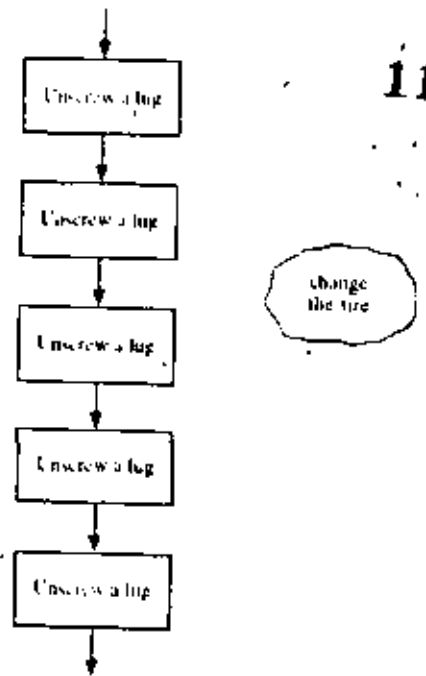
Inside this oval frame we will write an assertion instead of a command.



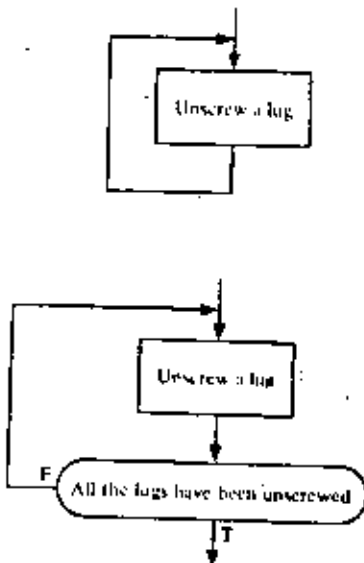
This is called a *decision box* and will have two exits, labeled T (for true) and F (for false). After checking the truth or falsity of the assertion, we choose the appropriate exit and proceed to the indicated activity. Incorporating the flowchart fragment on the left into Figure 1-1, we obtain the flowchart in Figure 1-2.



There is another instructive improvement possible. The instruction in box 2 of our flowchart actually stands for a number of repetitions of the same task. To show the additional detail we could replace box 2 by a step for each lug:



The awkwardness of this repeated instruction can be eliminated by introducing a *loop*.



As we leave the box, we find that the arrow leads us right back to repeat the task again. However, we are caught in an endless loop, since we have provided no way to get out and go on with the next task. To correct this situation, we require another decision box, as shown on the left.

Replacing box 2 of our flowchart with this mechanism and making a similar replacement for box 5, we get the final result shown in Figure 1-3.

Now that you have followed the development of the flat-tire flowchart, try to devise one of your own. In the algorithm of the following exercise, you will probably discover some decisions and loops. There are many different ways of flowcharting this algorithm, so many different-looking flowcharts will be created.

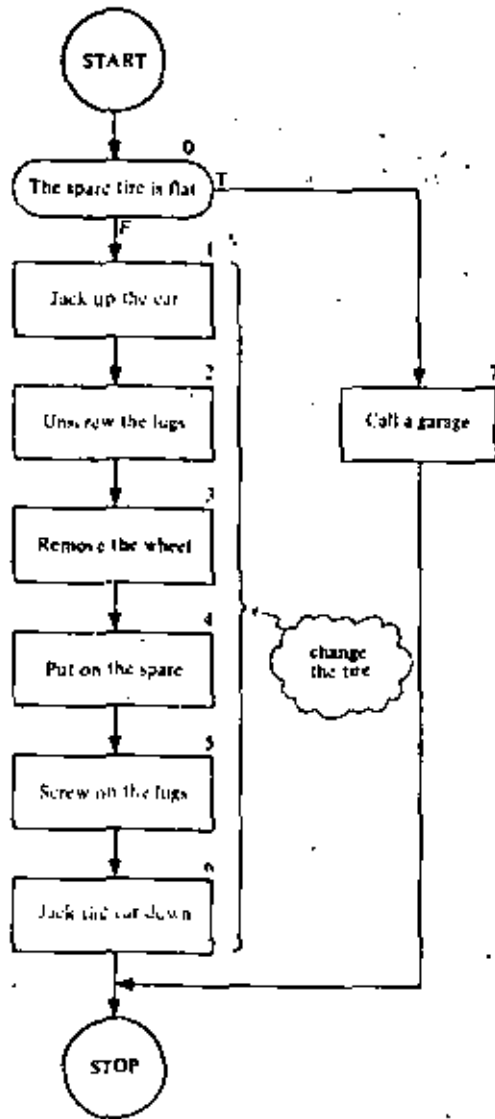


FIGURE 1-2  
Second flat-tire flowchart.

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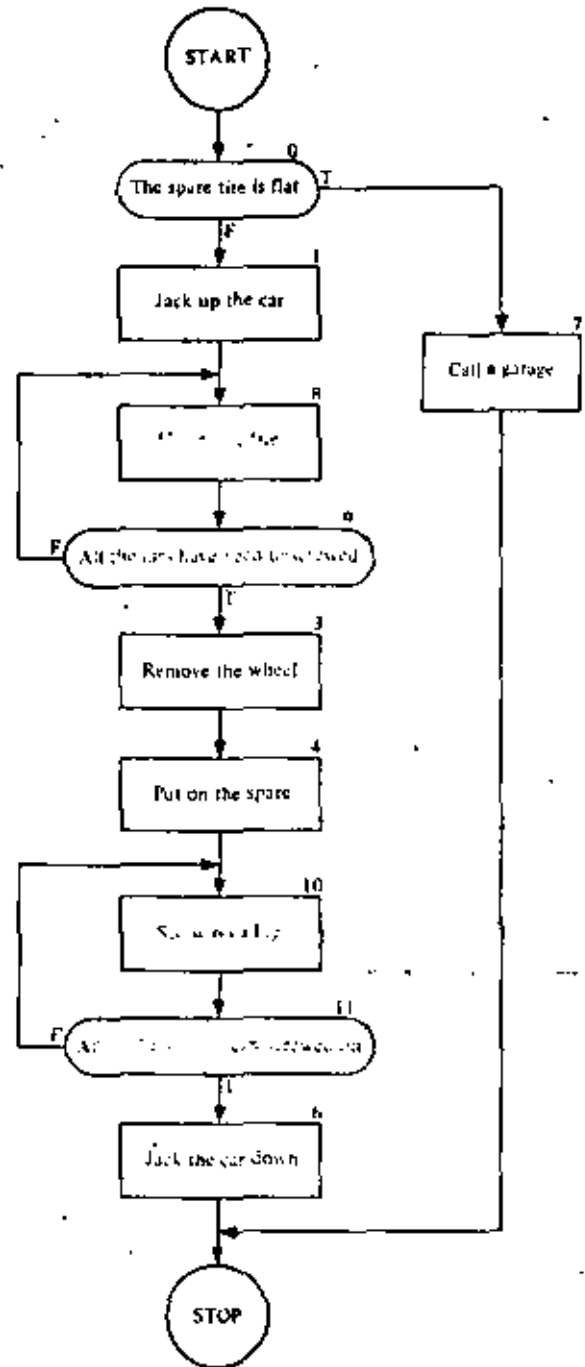


FIGURE 1-3  
Final flat-tire flowchart.

## EXERCISE 1-1

1. Prepare a flowchart representing the following recipe.

*Mrs. Good's Rocky Road*

## Ingredients:

1 cup chopped walnuts	$\frac{1}{2}$ cup evaporated milk
$\frac{1}{2}$ pound block of baker's chocolate	$\frac{1}{2}$ cup corn syrup
$\frac{1}{2}$ pound of marshmallows cut in halves	1 teaspoon of vanilla
3 cups sugar	$\frac{1}{2}$ pound of butter
	$\frac{1}{2}$ teaspoon of salt

Place milk, corn syrup, sugar, chocolate, and salt in a four-quart pan, and cook over a high flame, stirring constantly until the mixture boils. Reduce to medium flame and continue boiling and stirring until a drop of syrup forms a soft ball in a glass of cold water. Remove from the flame and allow to cool for 10 minutes. Beat in butter and vanilla until thoroughly blended. Stir in walnuts. Distribute marshmallow halves over the bottom of a 10-inch square, buttered baking pan. Pour syrup over the marshmallows. Allow to cool for 10 minutes. Cut in squares and serve.

## 1-2 A numerical algorithm

Now we are ready to examine an algorithm for a mathematical calculation. As a first example, we consider the problem of finding terms of the Fibonacci sequence:

0, 1, 1, 2, 3, 5, 8, 13, 21, 34, 55, . . .

In this sequence, or list of numbers, the first two terms given are 0 and 1. After that, the terms are constructed according to the rule that each number in the list is the sum of the two preceding ones. Check that this is the case. Thus, the next term after the last one listed above is

$$34 + 55 = 89$$

Clearly, we can keep on generating the terms of the sequence, one after another, for as long as we like. But, in order to write an algorithm for the process (so that a computer could execute it, for example), we have to be much more explicit in our instructions.

Before subjecting this process to closer scrutiny, let us review a little of the interesting history of this sequence. It was introduced in 1202 A.D. by the Italian mathematician, Fibonacci, to provide a model of population growth in rabbits.

His assumptions were: (1) it takes rabbits one month from birth to reach maturity; (2) one month after reaching maturity, and every month thereafter, each pair of mature rabbits will produce another pair of rabbits; and (3) rabbits never die.

One senses that this model is not completely realistic. But the essence of mathematical modeling is to start with a crude model that emphasizes the important aspects of the situation and suppresses less important information. A more refined model can be developed later, profiting from the experience with the crude model. Thus we might eventually improve the Fibonacci model by obtaining more accurate figures on the birth rate, taking mortality into account, considering the limitations of food supply, the effects of predators, disease, and overcrowding, and the like.

In spite of its frivolous origins, the Fibonacci sequence has many fascinating properties and plays a role in the solution of a number of seemingly unrelated mathematical problems. There is currently a published quarterly journal entirely devoted to the properties and applications of the Fibonacci sequence.

After this long digression, let's see how the rabbit-pair population model gives rise to the Fibonacci sequence. Fibonacci starts with one pair of newborn rabbits at the beginning of month *one*, and he then lets nature take its course. This is shown in Table 1-1, which we now explain.

TABLE 1-1  
Rabbit Population

Beginning of Month	1	2	3	4	5	6	7	8
Infant rabbit pairs	1	0	1	1	2	3	5	8
Mature rabbit pairs	0	1	1	2	3	5	8	13
Total rabbit pairs	1	1	2	3	5	8	13	21

Look at the arrows in the table. The number of pairs of infant rabbits in any month (after the first) is equal to the number of pairs of mature rabbits in the preceding month (condition 2 in the Fibonacci model). This explains the green arrows. In each month after the first, the number of pairs of mature rabbits will equal the total number of rabbit pairs in the preceding month (condition 1 in the Fibonacci model). This

explains the gray arrows. Following the arrows, we see that, from the third month onward, the total in any month is the sum of the totals in the two preceding months. Thus the rabbit population model generates the Fibonacci sequence except for the initial zero, which can be taken as the total number of rabbits in month zero.

Eliminating the reference to rabbits, we can tabulate the calculation of the terms of the Fibonacci sequence in Table 1-2.

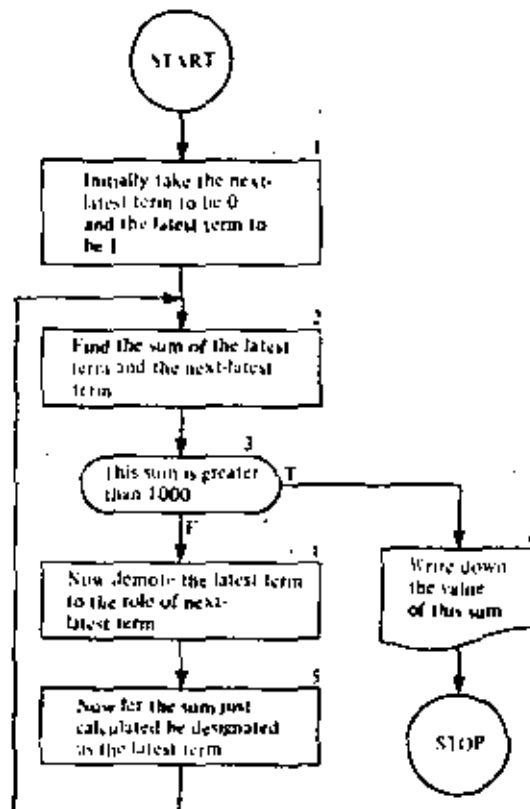


FIGURE 1-4  
Flowchart for Fibonacci  
sequence.

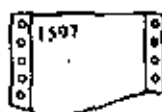
TABLE 1-2

Next Latest Term	Latest Term	Sum
0	1	$0 + 1 = 1$
1	1	$1 + 1 = 2$
1	2	$1 + 2 = 3$
2	3	$2 + 3 = 5$
3	5	$3 + 5 = 8$
5	8	$5 + 8 = 13$
8	13	$8 + 13 = 21$

We can see that in each step the latest term gets "demoted" to the role of next latest term and the sum becomes the new latest term.

Let's construct a flowchart for finding the first term to exceed 1000 in the Fibonacci sequence (Figure 1-4).

After going through the loop of flowchart boxes numbered 2 to 5 enough times (it happens to be 15 times), we eventually emerge from box 3 at the T exit and proceed to box 6. This box is seen to have a different shape because it calls for a different kind of activity—that of writing down our answer. The shape is chosen so as to suggest a page torn off a line printer, once the most common of computer output devices.



## EXERCISES 1-2

- Suppose in the rabbit problem we had started in month one with one pair of infant rabbits and three pairs of mature rabbits. Make a table similar to Table 1-1 to show the state of the population over the first eight months.
  - How would you modify the flowchart of Figure 1-4 so as to generate the first term of this modified sequence greater than 1000?
- Repeat Problem 1 with three pairs of infant rabbits and one pair of mature rabbits.
- For the Fibonacci sequence in Table 1-1, calculate from month two through month twelve the ratio,  $r$ , of the total number of

- 17 rabbits in the current month to that in the preceding month. Express each ratio as a decimal and carry out the calculation to the nearest thousandth.
- Express in your own words what seems to be happening to these ratios.
  - Find the reciprocals of each of the ratios in Problem 3a.
  - What relationship between the ratio  $r$  and its reciprocal  $1/r$  seems to be becoming more and more true? Express this relationship as an equation.
  - If this relationship held exactly, what would be the exact value of  $r$ ? That is, solve the equation for  $r$ .
4. Repeat Problem 3 using:
- The table in Problem 1.
  - The table in Problem 2.

### 1.3 SIMPLOS, a conceptual model of a computer

The algorithm of the preceding section can be expressed in much simpler notation that is, at the same time, more nearly acceptable by a computer as a set of instructions. To do this we must introduce a conceptual model of how a computer works. This conceptual model is so extraordinarily simple that we will call it the SIMPLOS computer. It is amazing, but true, that such a simple view of how a computer works is completely adequate for this entire course. We will present a more realistic picture of a computer in later sections of this chapter.

### Variables

In computing work, a *variable* is a letter or a string of letters used to stand for something. For now, this "something" that a variable stands for will always be a number. (As we progress through this book, we will take an ever broadening view of the sort of thing a variable can stand for.) In the formula

$$A = L \times W$$

the letters  $A$ ,  $L$ , and  $W$  are variables. In the formula

$$\text{DIST} = \text{RATE} \times \text{TIME}$$

$\text{DIST}$ ,  $\text{RATE}$ , and  $\text{TIME}$  are variables.

At any particular time, a variable will stand for one particular number, called the *value* of the variable, which may change from time to time during a computing process. The value of a variable may change millions of times during the execution of a single algorithm.

In our conceptual model of a computer we associate with



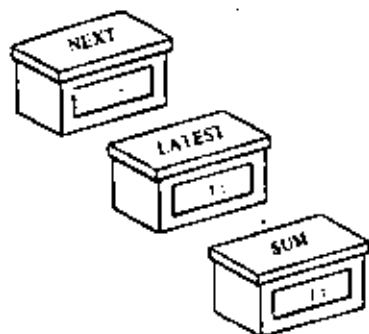


FIGURE 1-5  
Storage.

each variable a *storage box*. On the top of each box there is a removable gummed sticker with the associated variable inscribed on it, and inside the box there is a strip of paper with the *present value* (or current value) of the variable written on it. The variable is a *name for the number* that currently appears inside.

Each box has a lid that may be removed when we wish to assign a new value to the variable. Each box has a window in the side so that we may read the value of a variable with no danger of altering its value. These boxes constitute the *storage* of our computer. In Figure 1-5 we see one stage in the execution of the Fibonacci sequence algorithm of the preceding section. Here NEXT stands for "next latest term" and LATEST stands for "latest term."

To summarize, the *data storage* of a computer is to be thought of as subdividable into a number of information containers or boxes. Each such storage box may be given a meaningful name (sticker), and each may be given (assigned) a value.

Some people view a computer as an electronic and mechanical system having a data storage similar to that just described, along with a number of other interconnected units or modules, each with a special set of functions that, when activated appropriately, carry out algorithms. Figure 1-6 is one way to depict the organization of such a computer system. If we were to pursue the explanation of this system according to the module view, it would be necessary to define the functions of each module and explain the significance of the arrowed lines into and out of each box. But it would also be

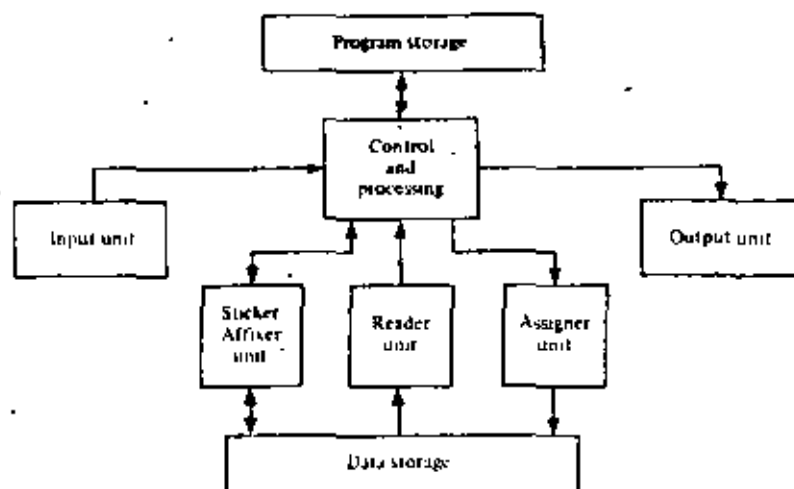


FIGURE 1-6  
View of a SIMPLIOS system  
as a set of interconnected  
modules.

necessary to bring the diagram to life by explaining the action sequences that occur in which each module serves the needs of the others so that the overall effect is to process information (i.e., to compute) in the desired fashion.

A second way to view a computer is to picture the active modules as robots working as a team. The actions of each robot always follow a fixed pattern, according to a set of relatively simple rules. We shall take this view in our conceptual model, SIMPLOS.

### The Model and How It Works

We visualize a computer as a number of storage boxes together with a staff of four robots—the *Master Computer* and three assistants, the *Assigner*, the *Reader*, and the *Sticker Affixer*. All these components are quartered in one room, isolated from those who will use the computer.

The Master Computer corresponds to the control and processing unit in Figure 1-6. He has a flowchart on his desk that sets forth the instructions according to which he delegates certain tasks to his assistants (Figure 1-7). "Note that the flowchart corresponds to the information kept in the *program storage* module of SIMPLOS."

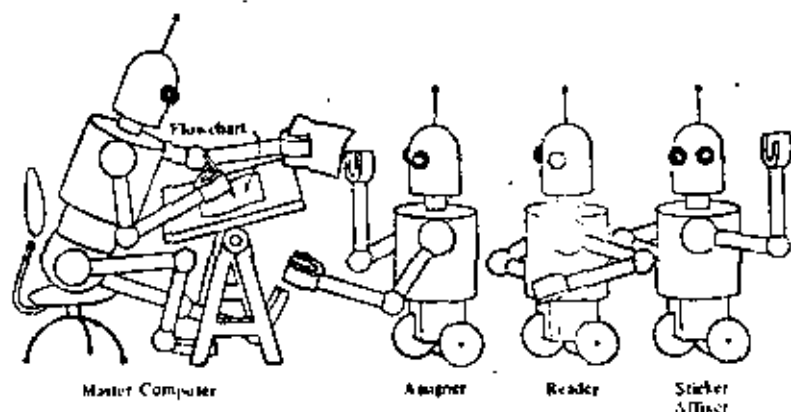
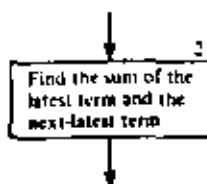
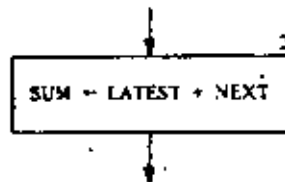


FIGURE 1-7  
The Master Computer and his staff.

To see how this team operates, let us suppose the computer is in the midst of executing the Fibonacci sequence algorithm of Figure 1-4. One of the instructions in this algorithm was:



In a simplified flowchart notation, this instruction will take the form:



Inside this flowchart box we find an *assignment statement*. Reading this statement aloud, we would say, "Assign to SUM the value of LATEST plus NEXT," or more simply, "Assign LATEST + NEXT to SUM." The arrow pointing left is called the *assignment operator* and is to be thought of as an order or a command. Rectangular boxes in our flowchart language will always contain assignment steps and will therefore be called *assignment boxes*.

To see what takes place when the Master Computer comes to the above statement in the flowchart, let us assume that the variables LATEST and NEXT (but not SUM) have the values seen in Figure 1-5. The computation called for in the assignment statement is spelled out on the right-hand side of the arrow, so the Master Computer looks there first.



He realizes that he needs to know the values of the variables LATEST and NEXT, so he sends the Reader out to fetch copies of these values from storage.

The Reader then goes and finds the storage boxes labeled

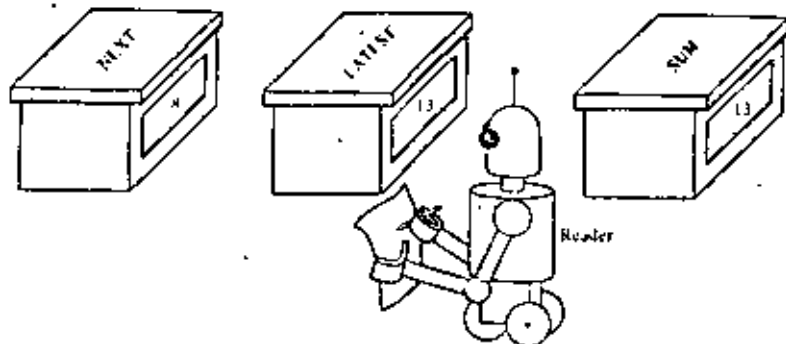


FIGURE 1-8  
The Reader copying a value  
from storage.

LATEST and NEXT. He reads the values of these variables through the windows (Figure 1-8), jots down the values, and carries them back to the Master Computer (Figure 1-9).

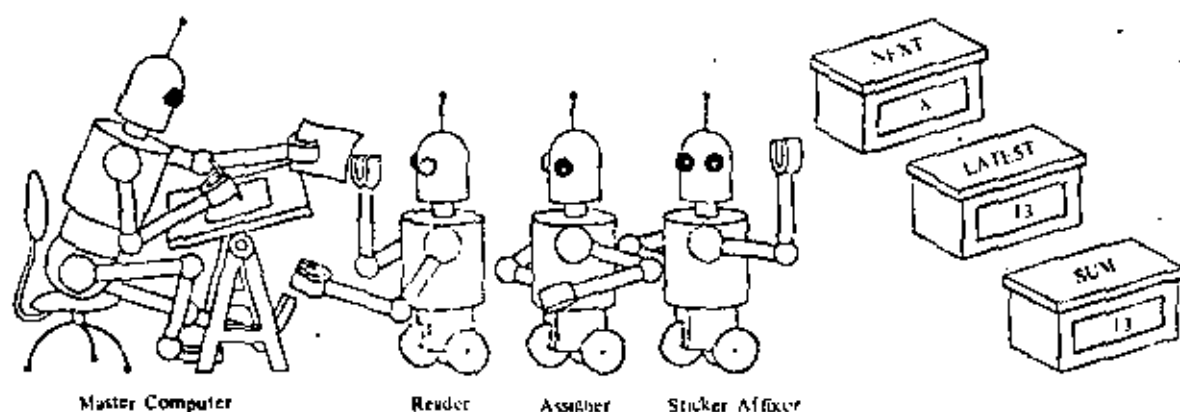


FIGURE 1-9  
The Master Computer receives the copy.

The Master Computer computes the value of  $LATEST + NEXT$  using the values of these variables brought to him by the Reader:

$$8 + 13 = 21$$

What does he do with this value?

The Master Computer now looks to the left of the assignment arrow in his instruction.

$SUM \leftarrow LATEST + NEXT$

He sees that he must assign the computed value of  $LATEST + NEXT$ , namely, 21, to  $SUM$  so he writes "21" on a slip of paper, calls the Assigner, and instructs him to assign this value to the variable  $SUM$ .

The Assigner goes to storage, finds the box labeled  $SUM$ , and dumps out its contents (Figure 1-10). Then he places in the box the slip of paper containing the new value, closes the lid, and returns to the Master Computer for a new task.

In other words, assignment is the process of giving a value to a variable. We say that assignment is *destructive* because it displaces the former value of the variable. Reading is *non-destructive* because the process in no way alters the values of any of the variables in storage.

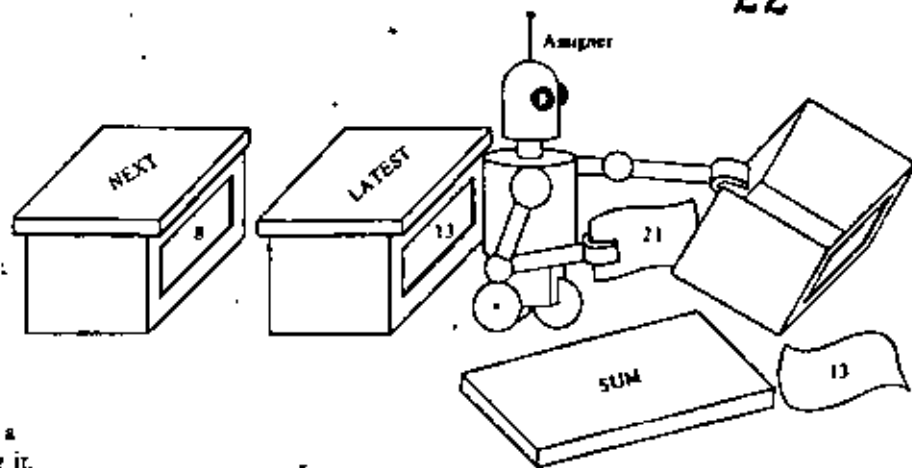


FIGURE 1-10  
The Assigner emptying a  
storage box and refilling it.

In Figure 1-11 we present the entire flowchart of Figure 1-4 in simplified flowchart language. The old and new flowcharts are placed side by side for easy comparison.

The translation requires very little explanation. It should be obvious that the statement in box 1 on the left is equivalent to the two statements in box 1 on the right. The new version of box 2 has been discussed in detail.

We see that the two statements in boxes 4 and 5 of the old flowchart are compressed into one box, box 4 of the new flowchart. This is permissible whenever we have a number of assignment statements with no other steps in between. However, it is very important to understand that these assignment statements must be executed in order from top to bottom, not in the opposite order and not simultaneously. The order in which things are done may be extremely important.

You can see that the statements in box 4 involve no computation but merely change the values in certain storage boxes. This sort of activity occurs frequently in flowcharts.

In box 6 of the flowchart we see only the word SUM. The shape of the box (called an *output box*) tells us that the value of the variable SUM is to be written down or displayed. If, in some other algorithm, we wished to write down the values of several variables, we would list these variables in an output box separated by commas, as illustrated on the left.

A, B, C, DIST

We will now describe the duties of the Sticker Affixer. We consider that the computation is begun by the transmittal of a flowchart to the Master Computer. The first thing the Master Computer does is to scan the flowchart, making a list

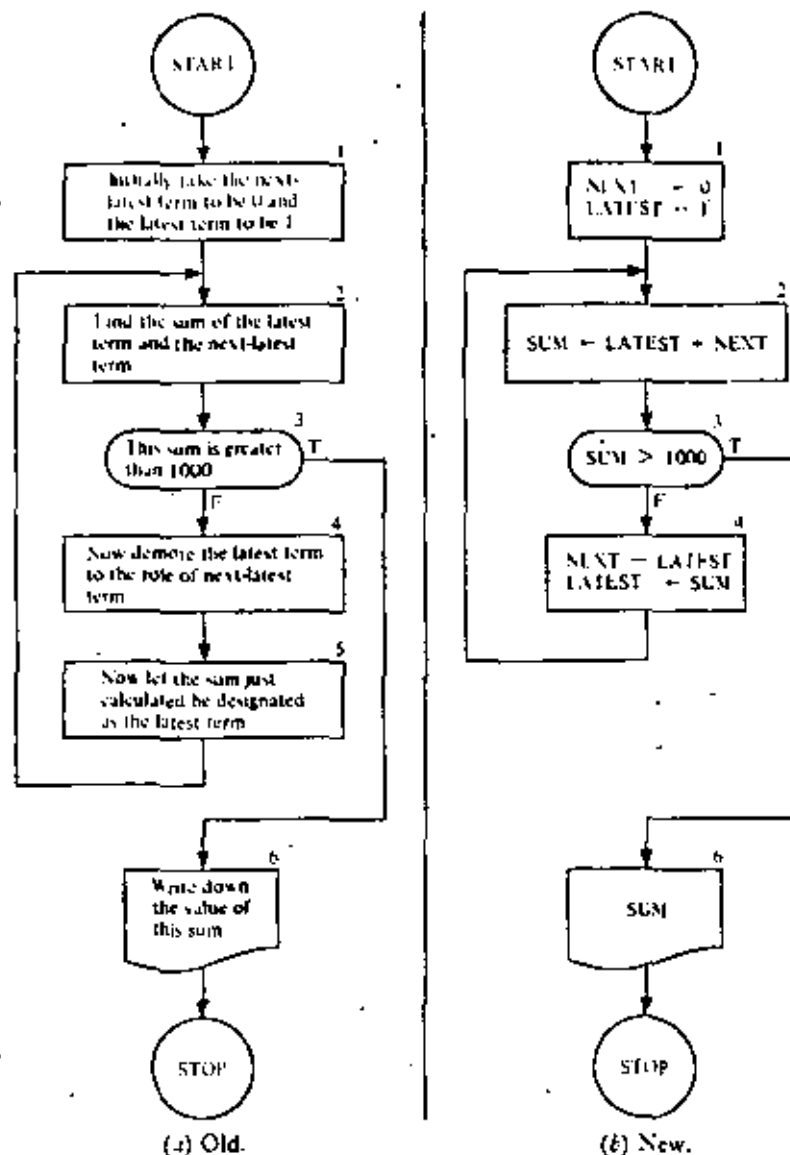


FIGURE 1-11  
Translation of Fibonacci  
sequence flowchart into formal  
flowchart language.

of all the variables used. In the case of the Fibonacci sequence flowchart of Figure 1-11b, this list would have the form

NEXT  
LATEST  
SUM

The Master Computer hands this list to the Sticker Affixer, who now springs into action. He inscribes each of these variables on a sticker, goes to a bin of unlabeled storage boxes, and slaps one of these stickers on each of three boxes (Figure 1-12).

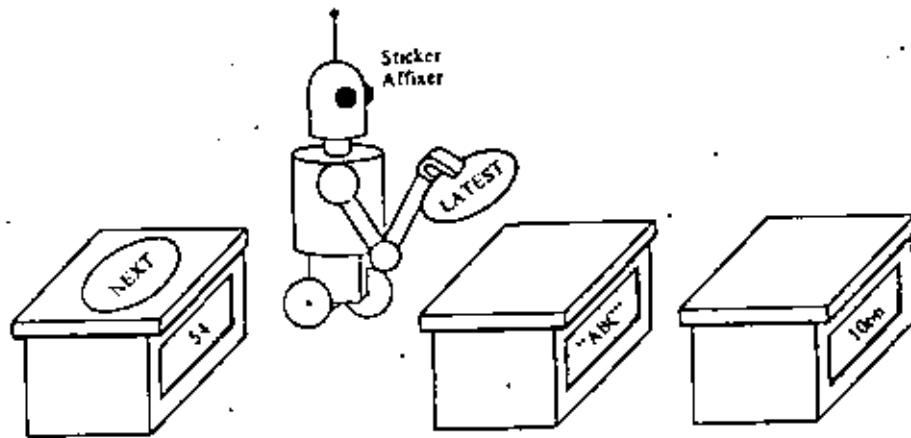


FIGURE 1-12  
Sticker Affixer at work.

Now the instructions in the flowchart are executed until the

**stop**

instruction is reached. At this juncture, the Master Computer directs the Affixer to unpeel all the labels and throw them into a recycle bin.

### Tracing the Flowchart

To understand better what our flowchart in Figure 1-11b does, let us trace through it, executing the steps as the Master Computer and his assistants do them (see Table 1-3).

In this trace, for ease of reading, the values of the variables are reproduced only when assignments are made to them. In between such steps, the values of the variables do not change and therefore have the most recently recorded values. For example, in step 33, where a test is performed, the values of the variables are

$$\text{NEXT} = 55, \quad \text{LATEST} = 89, \quad \text{SUM} = 144$$

In step 34 the values are

$$\text{NEXT} = 89, \quad \text{LATEST} = 144, \quad \text{SUM} = 144$$

You can see that in step 48 in the execution of our algorithm we finally leave box 3 by the *true* exit and pass on to box 6, where we output the answer, 1597, and stop.

The utter simplicity of our conceptual model avoids and removes certain pitfalls. There is an ever-present danger of thinking of assignment as equality or substitution. (We will say

TABLE 1-3  
Tracing of the Flowchart of Figure 1-11b

Step Number	Flowchart Box Number	Values of Variables			Test	True or False
		NEXT	LATEST	SUM		
1	1	0	1	1		
2	2				$1 > 1000$	F
3	3					
4	4	1	1	2		
5	2				$2 > 1000$	F
6	3					
7	4	1	2	3		
8	2				$3 > 1000$	F
9	3					
10	4	2	3	5		
11	2				$5 > 1000$	F
12	3					
13	4	3	5	8		
14	2				$8 > 1000$	F
15	3					
16	4	5	8	13		
17	2				$13 > 1000$	F
18	3					
19	4	8	13	21		
20	2				$21 > 1000$	F
21	3					
22	4	13	21	34		
23	2				$34 > 1000$	F
24	3					
25	4	21	34	55		
26	2				$55 > 1000$	F
27	3					
28	4	34	55	89		
29	2				$89 > 1000$	F
30	3					
31	4	55	89	144		
32	2				$144 > 1000$	F
33	3					
34	4	89	144	233		
35	2				$233 > 1000$	F
36	3					
37	4	144	233	377		
38	2				$377 > 1000$	F
39	3					
40	4	233	377	610		
41	2				$610 > 1000$	F
42	3					
43	4	377	610	987		
44	2				$987 > 1000$	F
45	3					
46	4	610	987	1597		
47	2				$1597 > 1000$	T
48	3					
49	6			1597		

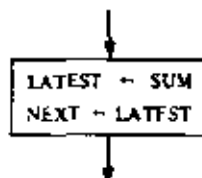


more about this later.) This and other potential sources of confusion, such as the effect of a certain sequence of flowchart statements, can be cleared up by thinking in terms of the SIMPLoS model, which will always give the right answers.

In fact, an excellent way to understand these ideas of reading and assigning values to variables is to make some storage boxes and, with some friends, work through several algorithms as described in this section.

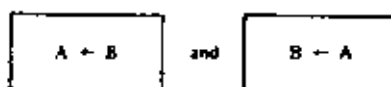
## EXERCISES 1-3

1. What is the effect of changing the order of the two assignment statements in box 4 of Figure 1-11b so as to appear as seen below?



Trace through the flowchart with this modification until you find the answer.

2. (a) To compare the effects of the assignment statements



find the missing numbers in the table below.

Values Before Execution of Assignment		Assignment To Be Executed	Values After Execution of Assignment	
A	B		A	B
7	13	A ← B	?	?
7	13	B ← A	?	?

- (b) In which of the two cases is it true that  $A = B$  after assignment?  
 (c) Are the effects of the two assignment statements the same or different?
3. Modify the flowchart in Figure 1-11b so as to carry out the algorithm of Problem 1, Exercises 1-2.

4. Modify the flowchart of Figure 1-11b so as to output each term of the Fibonacci sequence starting with the third (i.e., omit the initial 0 and 1).
5. Revise the flowchart of Problem 4 to calculate the ratio,  $r$ , of LATEST to NEXT (as calculated in Problem 3a, Exercises 1-2) and output this ratio (as well as LATEST) at each step.
6. Revise the flowchart of Problem 5 to calculate at each step the reciprocal of  $r$ . Add this value to the output list.

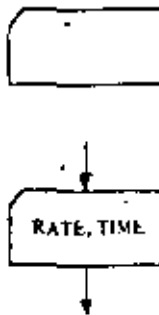
#### 1-4 Input/output

Imagine that you are a bookkeeper in a large factory. You have records of the hourly rate of pay and the number of hours worked for each employee, and you have to calculate the week's wages. Of course, this can be done by hand, but assume there are nearly 1000 workers in the plant, so that the job would be quite tedious. Naturally you prefer to have the computer execute this task for you, but you will have to devise a flowchart to convey the instructions to the computer.

How will the hourly wages and the hours worked come into our computation? Must each new value of RATE and TIME be represented by a separate assignment box? This is certainly a possibility, but it would require thousands of flowchart boxes—a most undesirable state of affairs. This unpleasant necessity can be eliminated by using the concept of *input*.

We now introduce a new shape of frame, the *input box*, into the flowchart language. The input box has this shape to suggest a "punch card" (a frequently used input medium, but not the only one). Inside the box will appear a single variable or a list of variables separated by commas.

What happens in our SIMPLoS model when the Master Computer encounters such an instruction? To answer this question, we must endow the SIMPLoS model with an additional feature not previously needed (Figure 1-13). SIMPLoS has a conveyer belt (called the *input belt*) that carries slips of paper from outside the room into the environment of the computing staff. On the outside end of the belt the "user" or "programmer" (who is not a member of the computer staff) places these slips of paper, with values written on them, on the conveyer belt in the order in which he wants them to be used.



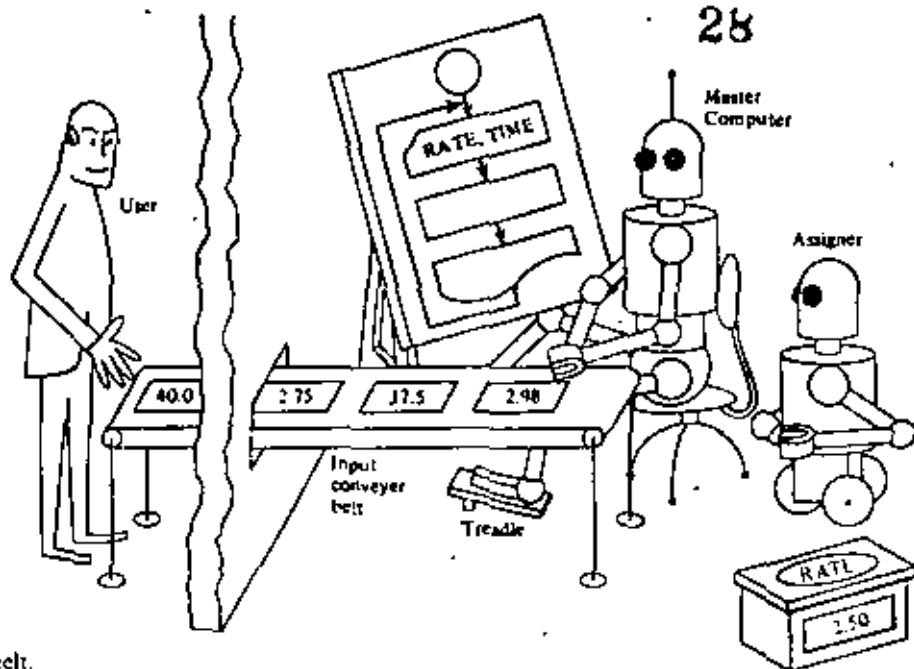
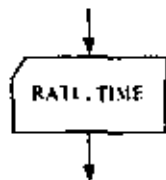


FIGURE 1-13  
SIMPLoS with Input belt.

When the Master Computer comes to the input instruction he does the following.

1. Steps on a treadle running the conveyer belt until the next slip of paper comes within reach.
2. Remove his foot from the treadle, stopping the belt.
3. Takes a slip of paper from the belt and hands it to the Assigner with instructions to assign the value thereon to the variable, RATE.



When the Assigner returns from this task, the Master Computer repeats the above process, but this time tells the Assigner to assign the new value to TIME. When this is done, the Master Computer follows the arrow in his flowchart to the next instruction.

We see that an input box is a command to make assignments, but this command is essentially different from that in an assignment box. In an assignment box the values to be assigned are to be found in computer storage or are computed from values already stored, whereas with an input box the values to be assigned are obtained from outside the computer. No calculation is called for in an input box. Moreover, the

values to be input never appear in the flowchart itself. Only the variables to which these values are to be assigned appear in the input boxes of the flowchart.

In an actual computer (not our conceptual one) the distinction between the two kinds of assignment need not be so sharp. Assignments called for in an input box usually involve some mechanical motion such as transporting a punched card or other unit of recorded information past a reading station where the coded contents may be copied. But to gain speed the data often are transported into a special section of storage called an *input buffer*, well before the data are actually needed by the executing algorithm. In this case, when the input step is executed, what actually happens is that data values are simply copied at electronic speed from storage boxes of the input buffer to storage boxes of the variables that are specified in the input step of the algorithm.

Now let's see how to use the input box in our hourly rate and payroll problem. Should we input the data from all the cards before we start our calculations? If so, we would need a great many storage boxes in which to store all these data. Instead, we will calculate the wages after each data set is read. A description of our method is as follows.

1. Input one value of RATE and one value of TIME by the process described above.
2. Multiply the RATE by the TIME to get the WAGE.
3. Output the values of RATE, TIME, and WAGE.
4. Return to step 1.

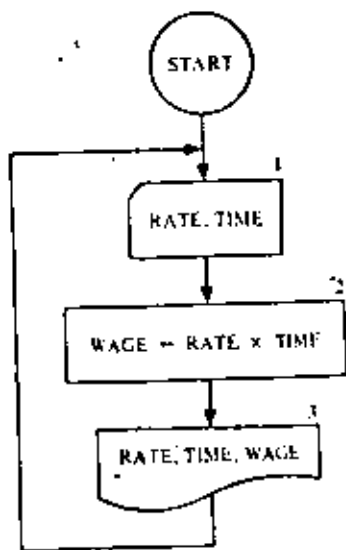


FIGURE 1-14  
Payroll algorithm.

In the flowchart of Figure 1-14 each of the first three steps of the above list appears in a similarly numbered box. Step 4 is represented by the arrow returning from box 3 to box 1.

You may wonder why the flowchart does not have a stop button. SIMPLIS always terminates execution of an algorithm when an input step is being executed, and the input belt contains too few values to match the variables in the input box. Execution of the payroll algorithm will therefore always halt after the last *rate, time* pair of data values has been processed and control once again reaches box 1, where it is discovered that the input belt is empty.

It will also be useful to visualize output in a similar way.

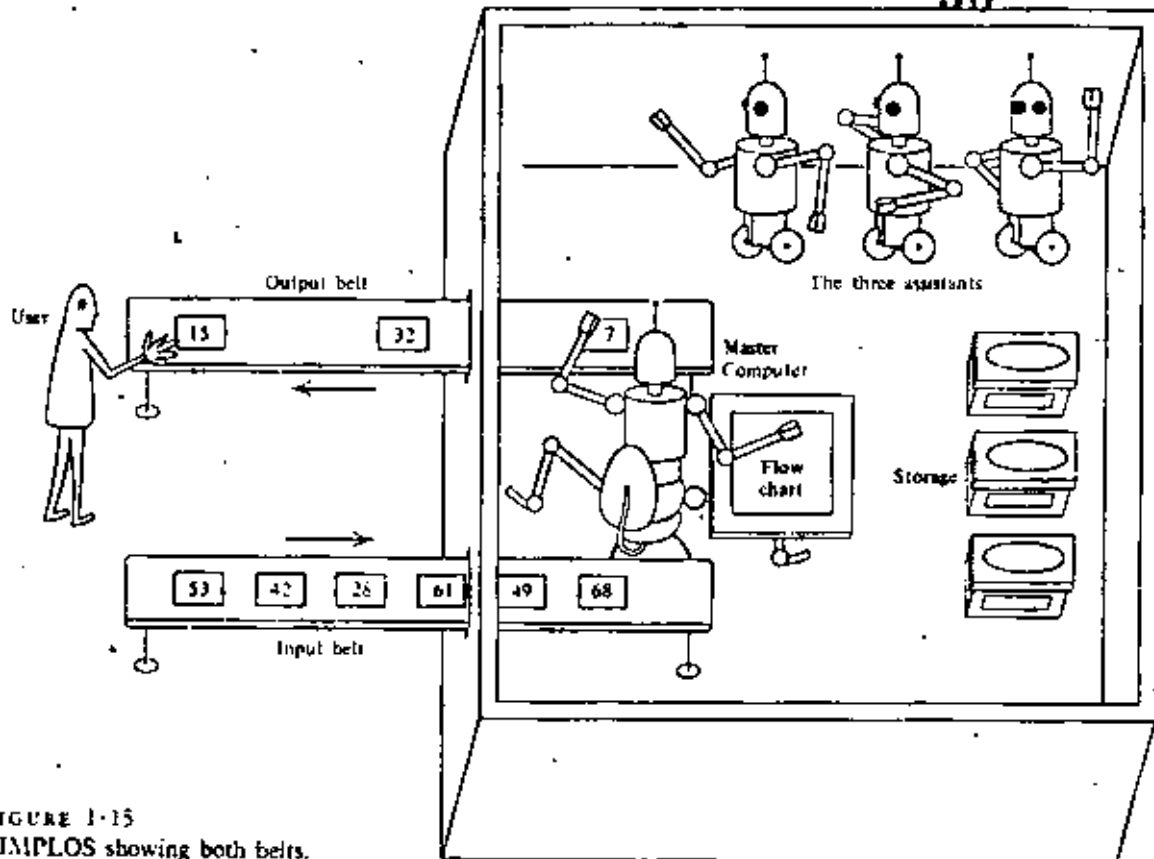


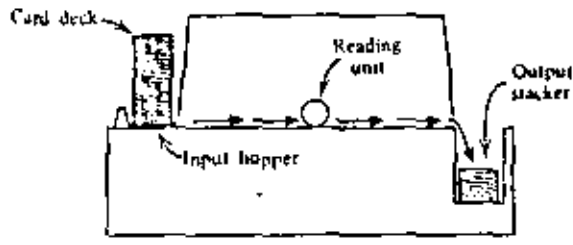
FIGURE 1-15  
SIMPLoS showing both belts.

We endow SIMPLoS with a second conveyer belt, the *output belt*. This belt runs *out* instead of in and runs continuously—it needs no treadle. Each time the flowchart calls for output, the Master Computer writes the proper value on a slip of paper and drops it on the output belt, which carries the slip through the wall to the outside environment of the user. A view of this situation from the top is seen in Figure 1-15.

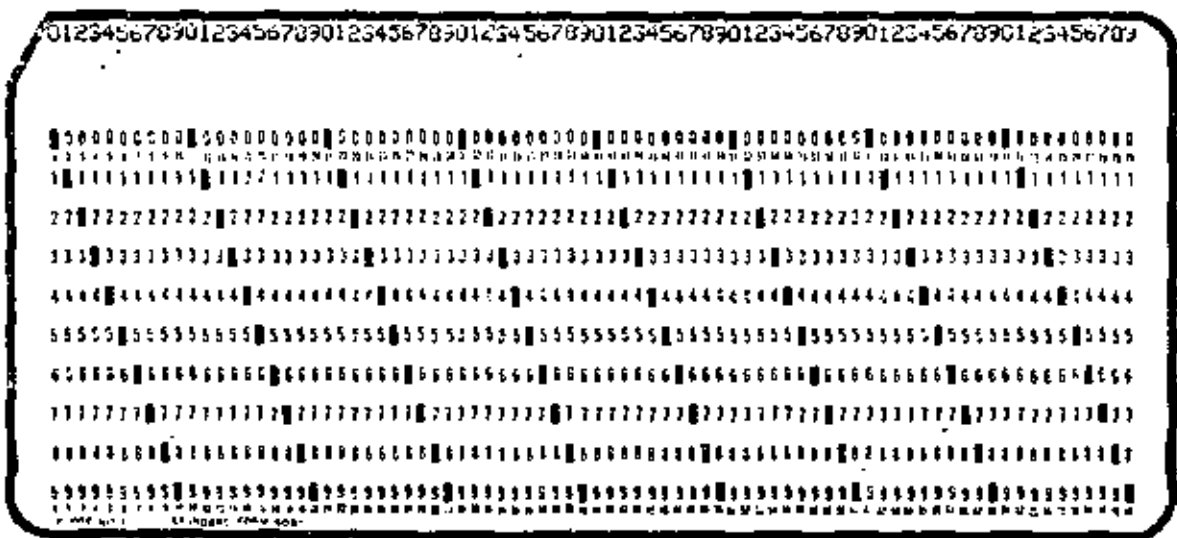
#### Records versus Streams

Our conveyer belt model of input-output suggests that data values move as a stream into and out of a computer system. Although in actual computers this is not always strictly the case, the analogy nevertheless is quite close. To pursue this idea let us consider the punched card reader, one of the most common input devices on actual computers. First, a sequence of data values is punched on cards. The cards are then placed in proper order in the *input hopper* of the card reading device.

Usually the card deck is placed face down so that the bottom (first) card in the deck is the first one to be read. Each time more input data are required, another card is drawn from the bottom of the deck and its contents are read, either electro-mechanically or photo-optically. Once read, the card is dropped into an *output stacker* and thus discarded.

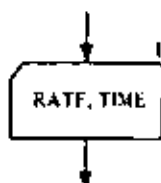


The information contained on a single punched card need not in principle be limited to one value. For example, depending on what a program is designed to expect, an 80-column card may contain up to eight 10-digit integers or up to twenty 4-digit integers.



When preparing data cards one is always faced with the decision of whether to utilize their capacity fully or to punch on each only the values required for the execution of one input step in the algorithm. The latter choice, although somewhat wasteful of card space, makes the data cards easier to check.

Our payroll problem provides us with a case in point. If,



for convenience in locating data preparation errors, we restrict the contents of each card to one *rate*, *time* pair, then each time box 1 is executed, one and only one data card will be drawn off the input deck, read, and discarded. We could be more wasteful and punch only one data value on each card. Then successive cards would contain first a *rate* value, then a *time* value, and so on. In this case, each execution of box 1 must cause *two* data cards to be drawn from the deck and read, and the analogy between the input conveyer belt and the card reading activity is very close indeed. That is, when the Master Computer hits the foot treadle to bring in one data value, the actual computer will signal the card reader to draw off one card and read it.

The analogy is less apparent if we allow the data cards to contain more than one *rate*, *time* pair and if we expect the pairs to be considered in turn during successive executions of box 1. In this case, box 1 can no longer mean "read a card" but, instead, "assign respectively to *rate* and *time* values from the next data pair in the deck. If the next pair cannot both come from the current data card, then draw off another card from the deck and read it. If, on the other hand, there is at least one more data pair yet to be processed from the most recently read card, then process that data pair." This interpretation assumes that an input buffer is filled (and refilled) with data from each newly read data card and that values are assigned to *rate* and *time* by simply copying information from this buffer into the respective program variables, always remembering for future use which items in the buffer have not yet been copied.

We see, therefore, that using an input buffer guarantees that each data pair in the sequence will be processed in turn, no matter how many pairs are punched on each data card. None will be missed or skipped over. It is in this sense that the stream analogy is preserved even though the sequence of data items is grouped into arbitrary-sized *card records*.

The SIMPLoS model is a primitive machine. It has only stream-oriented input and output. After values are placed on the conveyer belt to be output and are carried to the outside environment of the user, how are they displayed? We certainly are aware that in actual computer systems all values are printed or displayed on a screen in some sort of "format" with a



### Importance of the Conceptual Model

particular number of columns, but the only fact we are interested in with respect to SIMPLIS is that the values are output.

When it comes to interpreting output boxes of a flowchart, the situation is somewhat different. The output box on the left is considered to be a command to print the current values of the three variables, RATE, TIME, and WAGE *on one line*. (If the list won't fit on one print line, more lines are used.) Furthermore, if the same output box is executed again, the next set of three values will appear on a new line below the first set. If the three variables appeared in three individual boxes instead of in one single box, then each would be printed on a separate line. Thus each execution of an output box is considered to begin printing a new line.

No doubt you have wondered why, at the very start of our study, so much attention has been given to a conceptual model of a computer and its details. Can any model, especially this one, which seems so simple and at the kindergarten level for some readers, be that important or that valuable to us? You may develop similar doubts about the value of flowcharts as you proceed further.

The model and the flowcharts we develop are *abstractions* of real machines and of real computer programs. Once we see the connection between an abstraction and the *concrete* or real thing, we can often gain more understanding of the real thing by studying and manipulating its abstract counterpart. So, high on our list of priorities should be an attempt to understand and appreciate the connections between the abstract and the concrete. For example, in the next sections of this chapter we examine how an actual computer is organized and how it works. Thereafter, it will be easier to see why the conceptual model, no matter how silly it may have first appeared, is a very useful, simplified view of a real computer. Likewise, just as soon as we try to write and test actual computer programs, we shall see that the flowchart gives us a simpler but more revealing way to think about computer programs for most purposes.

Experience has taught us that problem solving with computers is very effective if we can work first with a simplified model of a machine and a simple descriptive algorithmic lan-



guage in which to express our problem solutions. Then it is comparatively easy to *map* these solutions over to programs written in some convenient programming language such as BASIC, FORTRAN, ALGOL, or COBOL, so that the programs can be executed on some real, convenient computer.

## EXERCISES 1-4

1. Modify the flowchart of Figure 1-14 to provide for an overtime feature. All hours in excess of 40 are to be paid at time and a half. You will have to place a decision box somewhere in the flowchart to determine whether the worker actually put in any overtime. The formula by which his wages are computed will depend on the outcome of this test.

1-5  
Actual computers

Now we are ready to examine how our conceptual model of a computer can be realized in an actual machine. For the first 25 years of modern computer history (1949 to 1974), nearly all actual machines were built following a more or less stereotyped pattern suggested by John Von Neumann (1903-1957). A prototype machine following this pattern is discussed in this and following sections. We will call it SAMOS. SAMOS is a very simple machine; that is, it is stripped down to the bare essentials. Some features of its operation are described in considerable detail, while others are glossed over. The programming of SAMOS is described briefly in Section 1-6 and in more detail in the Appendix, the purpose of which is to help the reader see a closer connection between language for expressing algorithms and machines that execute them.

It would be foolhardy to assume that SAMOS-like machines are the "be all and end all of computers," since the architecture of computers is still undergoing rapid change. For this reason, aspects of two other machines are discussed briefly in this book. One machine, called BITOS, appears later in this chapter; the other, called POSTOS, is considered in Chapter 8. Each of the three machines exhibits certain distinct characteristics for the implementation of our conceptual model, SIMPLIS.



In order to study this book it is useful, although not essential, to gain a good understanding of how an actual computer works. We suggest that you read once through the material of the next two sections without attempting to master it. As you work exercises that relate to SAMOS, or have occasion to study SAMOS in the Appendix, you will no doubt come back to the next two sections for a more careful study.

## 1-6 SAMOS

### Core Storage



FIGURE 1-16  
A magnetic core.

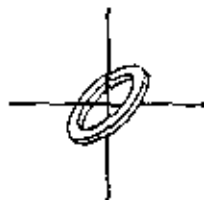


FIGURE 1-17  
Where two wires cross.

How are all those storage boxes of SIMPLIOS realized in actual practice? The storage of actual computers is built of electronic components in a variety of ways and with a variety of materials. Here we describe one way that a SAMOS storage can be built.

SAMOS storage, packaged in a rectangular box, is an arrangement of tiny magnetic doughnuts as small as  $1/40$  of an inch in diameter. These doughnuts are called *cores* (Figure 1-16). The cores are laid out in 61 horizontal layers or trays called *core planes*. On each of these layers, wires are strung evenly in two directions like the lines on a sheet of graph paper. There are 100 wires in each direction. At each point where two wires cross, the wires are threaded through a core, like the thread passing through the eye of a needle (Figure 1-17). (Still other wires are threaded diagonally through each core within each plane. Their function is not important to the discussion that follows, and they are therefore ignored.)

Figure 1-18 is a picture of a core plane from an actual computer built in the mid-1960s. Since there are  $100 \times 100$  crossings in each SAMOS core layer, we see that there are 10,000 cores in each core plane and hence  $61 \times 10,000 = 610,000$  cores in the entire SAMOS store (storage).

These cores are capable of being magnetized in either the clockwise or the counterclockwise sense (Figure 1-19). Because of this a core can store information. We could think of clockwise magnetization as meaning "yes" and counterclockwise as meaning "no." We will instead think of clockwise as standing for "0" and counterclockwise for "1." In any event, the information contained in the magnetization of a core is the smallest

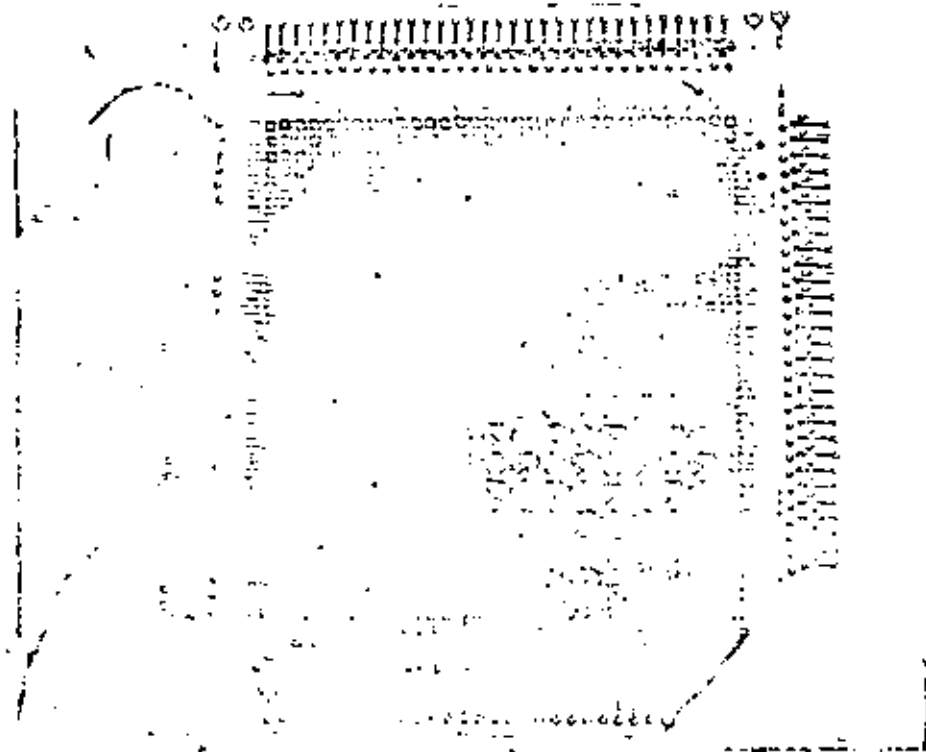


FIGURE 1-18  
An actual core plane.  
(Courtesy of IBM).

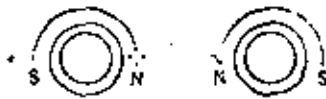


FIGURE 1-19  
Magnetization of cores.

unit of information and is called a *bit* of information. We see that one core can store one binary digit, 0 or 1, but a collection of cores can store a very large number of bits. We will discuss this idea later, after a digression on how the cores get their magnetism.

First, you must know that a pulse of electric current moving along a wire generates a magnetic field running around the wire, as shown in Figure 1-20. The strength of the magnetic field is strongest near the wire and dies away as we move further from the wire.

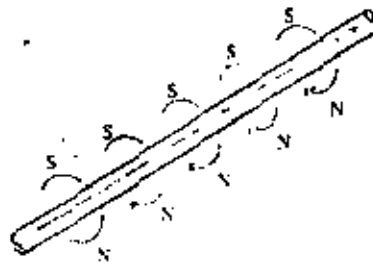
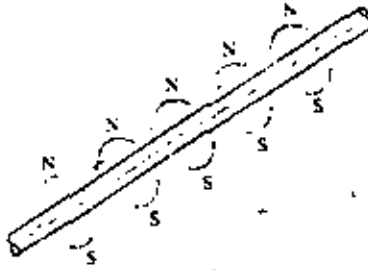


FIGURE 1-20  
A magnetic field resulting from  
a pulse of electric current.

If the direction of the current is reversed, the direction of the magnetic field is also reversed (Figure 1-21).

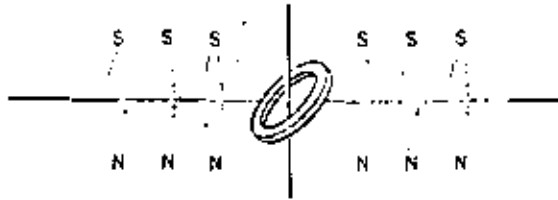
37

FIGURE 1-21  
Reversing the direction of the  
magnetic field.



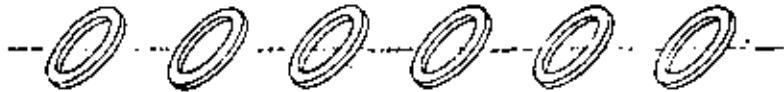
Thus, when a pulse of current passes through a core, the core will become magnetized in one direction or the other, depending on the direction of the current (Figure 1-22).

FIGURE 1-22  
A core in a magnetic field.



But how can we manage to magnetize just one core instead of the whole string of cores (Figure 1-23) through which the pulse passes? The answer lies in the magnetic properties of the material from which the core is made. In this material,

FIGURE 1-23  
A row of cores in a magnetic field.



if the pulse is too weak, the direction of magnetization of the core is only *temporarily* altered, and after the pulse of current has passed by, the core merely returns to its former magnetic condition, whatever that was.

On the other hand, if the current is strong enough, the core remains magnetized in the sense established by the direction of the current, regardless of the former magnetic condition of the core. The situation is analogous to trying to throw a ball from the ground to the flat roof of a building. If you have enough power in your throw, the ball will land on the roof; otherwise it will bounce against the wall and fall back to the ground.

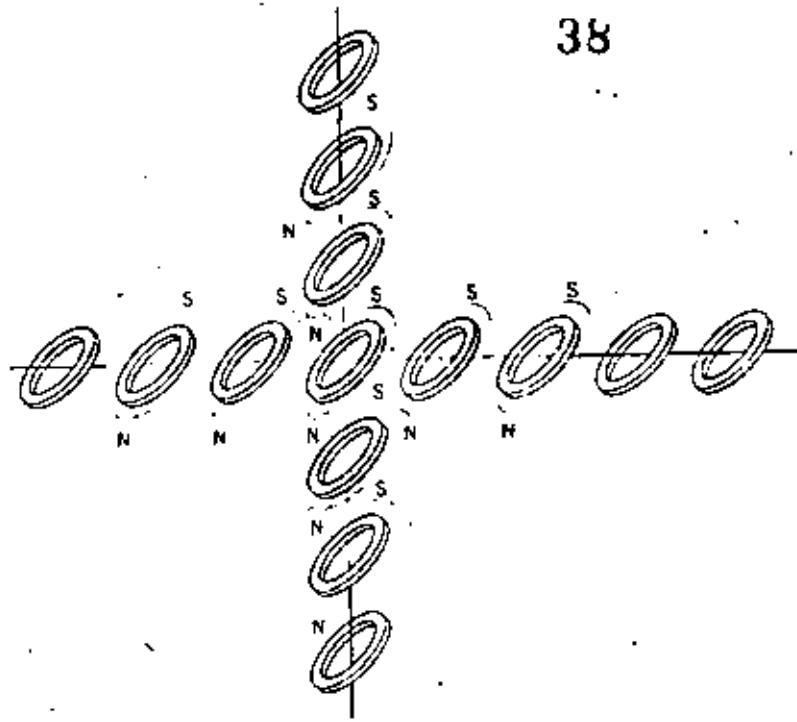


FIGURE 1-24  
Doubling the magnetic field at  
the wire crossing.

The strength of the pulses is carefully regulated so that one pulse is not sufficient to permanently magnetize a core, but two pulses acting simultaneously will exceed the threshold strength and result in permanent magnetization. Thus, pulses passing along two of the wires (Figure 1-24) will permanently magnetize just the one core that is located where the wires cross.

#### SIMPLOS and SAMOS Stores Compared

Let's leave the individual core planes and consider the entire store of the SAMOS computer, composed of the 61 core planes (Figure 1-25). Each vertical column of 61 cores constitutes a *computer word*. Thus, the storage of the computer is composed of 10,000 words. These words have addresses that are four-digit numbers from 0000 to 9999 and, like house numbers, the addresses identify the words. Each of the 10,000 dots suggested on the top of the box is the top of a vertical column of 61 cores (or a word). The method of assigning the addresses is indicated in the figure.

Each of these words corresponds to a storage box in our conceptual SIMPLOS model. For each variable in the flow-

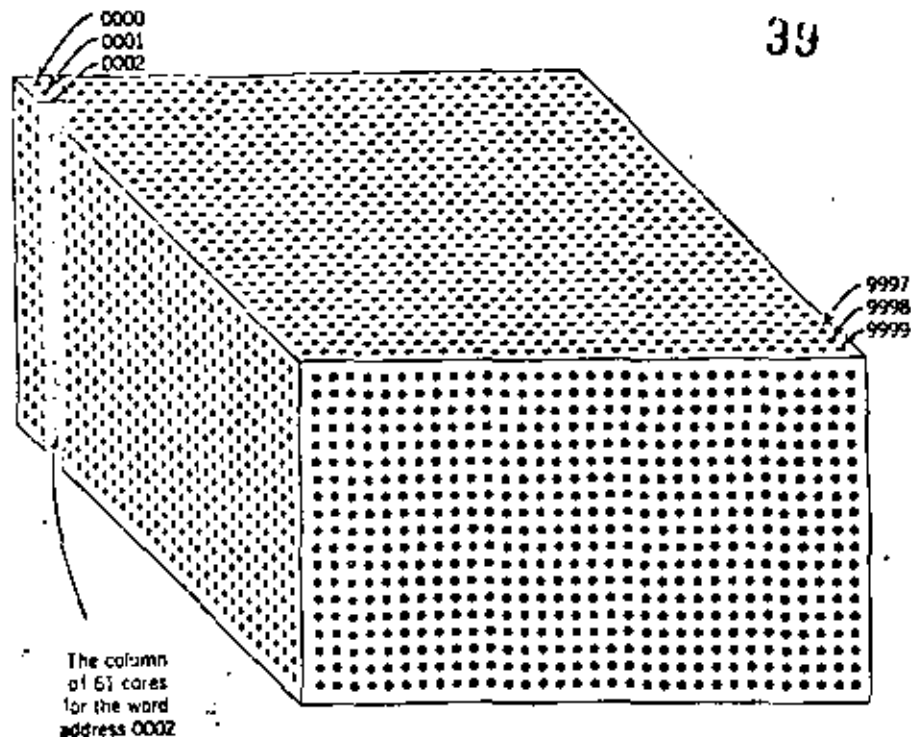


FIGURE 1-25  
Cores of one computer  
word.

chart there is a SAMOS word with a definite address. The word contains a certain pattern of bits determined by the directions of magnetization of its cores and representing the value of that variable. "Assigning a value to a variable" is effected by putting a certain pattern of bits into a word (Figure 1-26).

When we say "the Master Computer tells the Assigner to assign the value 1597 to the variable SUM," what actually takes place is this. The variable SUM is represented inside the machine by means of its address; suppose it is 0103. Now all the  $61 \times 2 = 122$  wires passing through cores in the word addressed 0103 are energized with pulses of current in the proper directions so as to achieve the pattern of bits representing the number 1597. In a modern computer this assignment process can be performed in a fraction of a microsecond; a microsecond is a millionth of a second.

### Characters

In the binary system of representation, a number such as 1597 is coded as a string of 1's and 0's, for example:

1 1 0 0 0 1 1 1 1 0 1

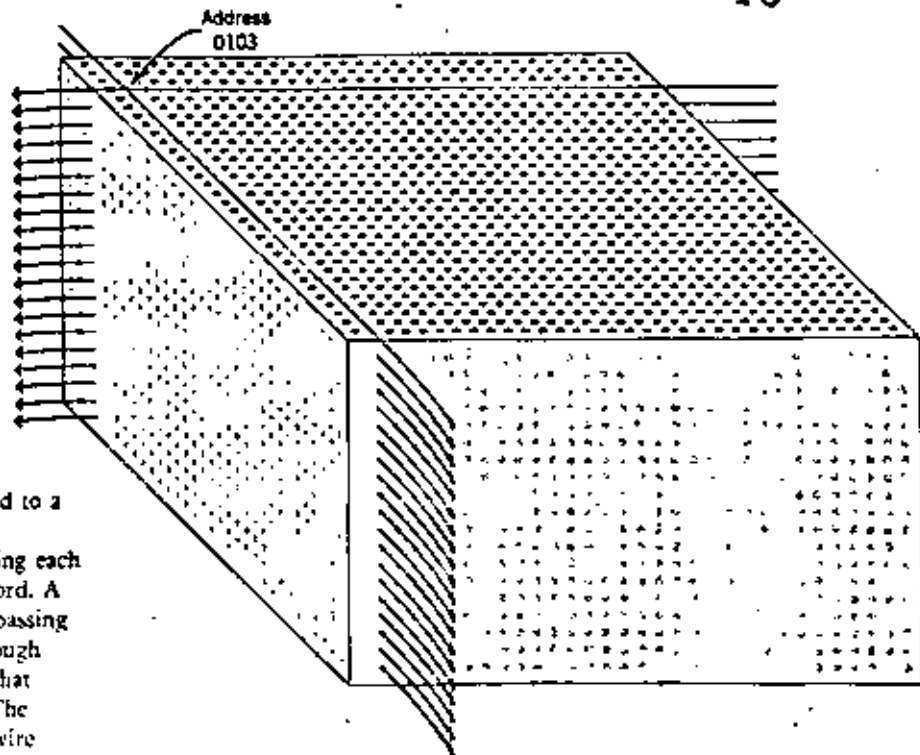
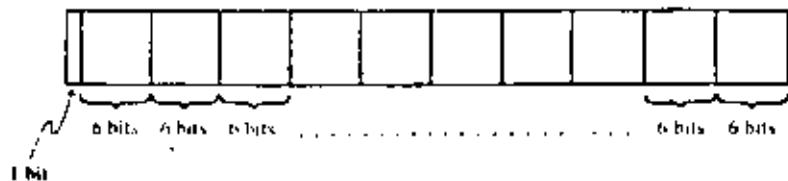


FIGURE 1-26

A bit pattern is assigned to a computer word by appropriately magnetizing each of the cores for that word. A core is magnetized by passing an electronic pulse through each of the two wires that intersect at that core. The diagram identifies the wire pairs that must be selected to assign a bit pattern for the word at address 0103.

For SAMOS any string would be preceded by a string of zeros to fill out all the bit positions of the word of storage. While numbers are coded in binary form in many computers, binary is certainly not the only choice. In a machine such as SAMOS, for instance, computation is carried out in the decimal system, which means that bit patterns in a word of storage must be coded to represent decimal digits instead of binary digits. Moreover, we want to store letters as well as decimal digits. For this reason, we subdivide our 61-bit SAMOS words into 11 character positions as shown below.



The first position (one bit only) is reserved for a code that designates the sign, + or -. Here 0 is sufficient to represent the + character and 1 signifies the - character. Each of the other positions consists of six bits and can be used to store

Character	Code	Character	Code	Character	Code	Character	Code
0	00 0000					□	11 0000
1	00 0001	A	01 0001	J	10 0001	S	11 0010
2	00 0010	B	01 0010	K	10 0010	T	11 0011
3	00 0011	C	01 0011	L	10 0011	U	11 0100
4	00 0100	D	01 0100	M	10 0100	V	11 0101
5	00 0101	E	01 0101	N	10 0101	W	11 0110
6	00 0110	F	01 0110	O	10 0110	X	11 0111
7	00 0111	G	01 0111	P	10 0111	Y	11 1000
8	00 1000	H	01 1000	Q	10 1000	Z	11 1001
9	00 1001	I	01 1001	R	10 1001		

FIGURE 1-27  
Character code

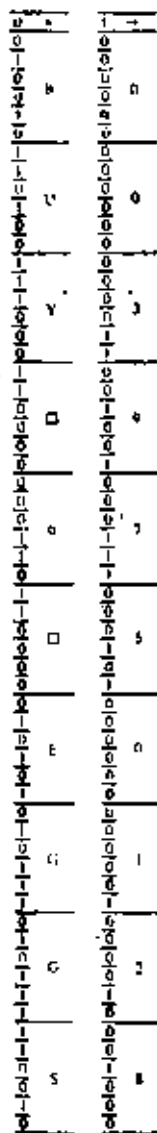


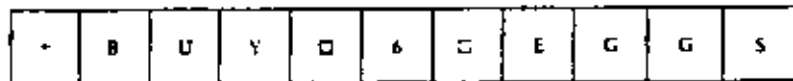
FIGURE 1-28  
Detailed bit patterns for two computer words.

a digit or a letter, that is, *character*, according to the code shown in Figure 1-27.

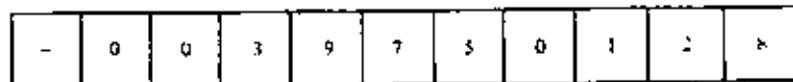
For each group of six bits,  $2^6$  or 64 distinct combinations of zeros and ones are possible. In Figure 1-27 we have used up only 37 of the 64 combinations possible with a six-bit code. This leaves 27 additional combinations for other special symbols such as +, ≥, and the like. One of the 37 combinations of special interest is the blank space, □, which is coded as

1 1 0 0 0 0

With this code you can see that the two 61-bit computer words displayed vertically in Figure 1-28 turn out to be



and



From now on we shall represent our SAMOS computer words as strings of 11 characters instead of strings of 61 bits. In a number of conventional computers of similar design eight instead of six bits are grouped to represent character codes, making it possible to distinguish among a considerably larger set of characters than is the case in SAMOS. This distinction, however, has absolutely no effect on the principles of character representation and manipulation that occur in ensuing chapters.

The construction of the main storage for any actual computer is of great interest mainly to computer engineers and designers. Storage components currently are built from various



types of physical devices and materials, including magnetic cores, magnetic thin films, and transistor flipflops. There is considerable variety in the circuitry used to organize and utilize such components and in the methods of packaging and miniaturizing them. Their physical characteristics, such as size, speed of access for storing and retrieving information, energy requirements to operate them, and cost of fabrication, vary also. Nevertheless, schemes similar to that used in the word-organized core storage of SAMOS have been used to assemble and incorporate all of these types of storage units into conventional computer systems. You might be surprised at how much understanding of this subject you can gain with a relatively small investment of study time. (See, for example, one of the references on this topic in the reading list at the end of this book.)

### SAMOS Processing Unit

Now that we have seen how the SAMOS storage is structured, we will consider how the storage is used in executing an algorithm.

Our computer has several other components besides the store. These are shown in Figure 1-29.

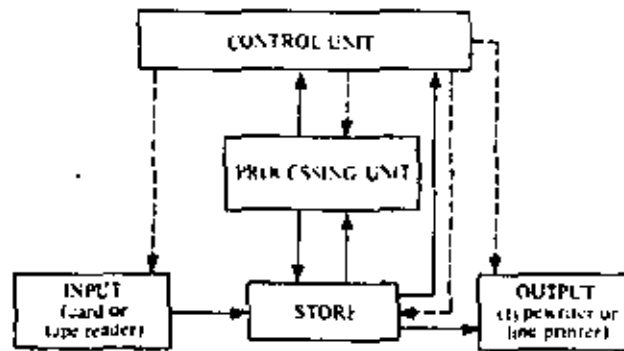
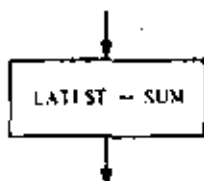


FIGURE 1-29  
The principal components of SAMOS.

The solid lines indicate the directions in which values or instructions may be transferred. The dashed lines indicate the exercise of control. The control unit and the processing unit perform the duties of the "Master Computer" and his helpers.

An important part of the processing unit is the *accumulator*. This special computer word holds the result of each arithmetic operation.

Furthermore, a simple assignment such as

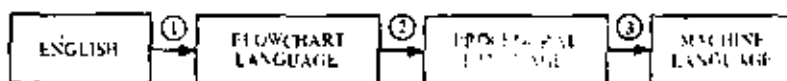


is carried out by first obtaining a copy of the value of SUM, placing it in the accumulator, and then copying the value in the accumulator into the computer word belonging to the variable LATEST. The value of SUM is unchanged in this process. Notice, however, that values to be input or output do not pass through the SAMOS accumulator but go directly into and out of storage.

When the control unit receives and interprets an *order*, some computer operation is activated. The orders are in the form of coded instructions stored in the computer; we will see about them presently.

## Machine Language

Getting an algorithm into a form a machine can execute involves several translations that we can represent as follows:



You have already had a little experience with the first translation step. The second translation step is the process of converting a flow chart into a procedural language such as FORTRAN, ALGOL, COBOL, or PL/I. You learn how to do this in your language manual. If approached properly, this translation step is quite mechanical and can be performed by a person (or by a machine) who has no idea what the algorithm is all about.

In many computers of advanced design, the third translation process can be omitted because the machine's language and the procedural language are effectively identical. When the third translation step is necessary, and it is for a computer such as SAMOS, the process is completely mechanical and is normally done by the computer itself. This process is called *compiling*.

It is not necessary right now to know how compiling is done, but it may be interesting to know the reason for doing it. Each make and style of computer has its own language—that is, its own set of instructions that it can understand. Use of a procedural language allows us to avoid a tower of Babel in which a programmer would have to learn a new language for each machine he wishes to use. A procedural language constitutes a kind of “Esperanto” that enables a programmer to communicate with many different machines in the same language. Moreover, a procedural language is generally much easier to learn to use than machine language. The programmer merely prepares, say, a FORTRAN program on punched cards and feeds it into the computer, which “compiles” a sequence of machine language instructions. This sequence, called a *machine language program*, is then placed in the computer storage. In many systems the programmer may transmit his program to the computer storage by typing it a line at a time, using a typewriter or other keyboard instrument to serve as the input device of the computer system.

### Sequencing of Computer Instructions



FIGURE 1-30  
A flowchart box.

Successive SAMOS instructions are placed in consecutively addressed storage locations starting with 0000. After the computer has executed an instruction, the control unit will always take the next instruction from the next address, unless there is a *branching* instruction providing a different address from which to take the next instruction.

To see how this works, consider the instruction taken from the Fibonacci sequence flowchart (Figure 1-11b), shown here in Figure 1-30.

The procedural language equivalent will not look much different. Thus, in FORTRAN this instruction would appear as

SUM = LATEST + NEXT

and in ALGOL as

SUM := LATEST + NEXT

and in APL as

SUM ← LATEST + NEXT

and in BASIC as

LET SUM = LATEST + NEXT

and in COBOL as

COMPUTE SUM EQUALS LATEST  
PLUS NEXT

```

+ LDA 000 0101
+ ADD 000 0100
+ STD 000 0102

```

FIGURE 1-31  
SAMOS instructions for  
Figure 1-30.

In the SAMOS machine language, a variable cannot be referred to by *name* but only by the *address* in storage associated with the variable. Suppose that NEXT, LATEST, and SUM have been given, respectively, locations 0100, 0101, and 0102. Then in the SAMOS language, the flowchart instruction translates to a sequence of three machine instructions, as shown in Figure 1-31.

These instructions have the form of 11-character words, although the first character is unimportant and the fifth, sixth, and seventh are of no interest to us here. The type of *operation* to be performed is coded using the three letters in positions two, three, and four, and the four-digit numeral at the right is the *address* associated with that operation.

The letters LDA stand for "LoaD the Accumulator." The whole instruction

```
+ L D A 0 0 0 0 1 0 1
```

means, "Make a copy of the value stored in address 0101 without altering the original, and store the copy in the accumulator." Clearly, this is the function of the Reader in our conceptual model. We will not go into the details of the electronics involved in carrying out this instruction. It is sufficient to know that when a copy of that instruction is brought to the control unit, certain switches are set by the control unit that allow a pulse current to pass through the cores of the word 0101. The magnetized cores cause a change in the current that, in turn, allows a copy to be made.

The second instruction in Figure 1-31 means, "ADD the value in the word addressed 0100 to the value already in the accumulator and place the result in the accumulator." The third instruction means, "Copy (or STOr) the value in the accumulator *into* the word addressed 0102." Executing a STO instruction is analogous to the work of the Assigner in our conceptual model. Speeds vary from machine to machine, but in modern computers, the time required to carry out such instructions is usually on the order of a millionth of a second.

### A Complete SAMOS Program

We are almost able to translate the entire flowchart for the Fibonacci sequence algorithm (repeated here in Figure 1-32) into SAMOS language. First note, however, that constants never appear explicitly in SAMOS instructions. Instead, an

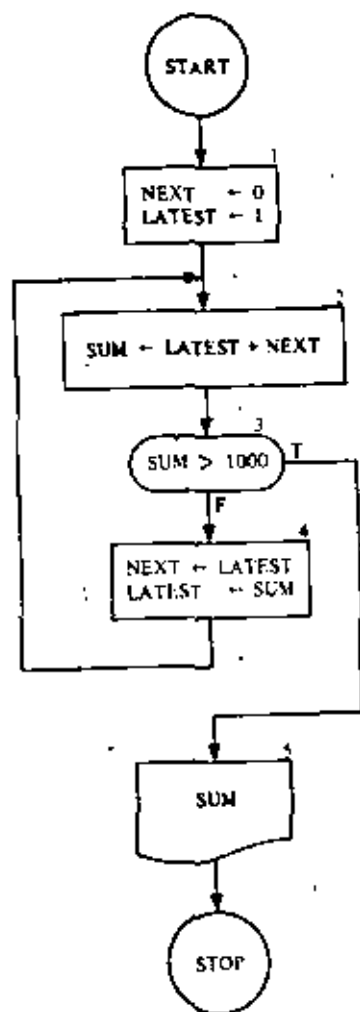


FIGURE 1-32  
Fibonacci sequence algorithm.

instruction to fetch a constant must refer to the storage address where the desired value may be found. Of course, this also applies to variables. Thus part of the compiling process involves providing storage addresses for the constants (as well as for the variables) appearing in the program. We allocate the locations 0017, 0018, and 0019 for the constants 0, 1, and 1000 appearing in the flowchart and specify the proper values for these words.

We assume that the storage locations 0100, 0101, and 0102 have been allocated for the variables NEXT, LATEST, and SUM, but that no values have been placed in these words. As execution of the SAMOS program for the Fibonacci algorithm starts, the state of storage is shown in Figure 1-33. This figure

Storage Location (Address)	Operation Code							Address				Flowchart Equivalent
	1	2	3	4	5	6	7	8	9	10	11	
0000 0001	L	D	N	0	0	0	0	0	0	1	7	1a NEXT ← 0
	S	T	O	0	0	0	0	0	1	0	0	
0002 0003	L	D	N	0	0	0	0	0	0	1	8	1b LATEST ← 1
	S	T	O	0	0	0	0	0	1	0	1	
0004 0005 0006	L	D	N	0	0	0	0	0	1	0	1	2 SUM ← LATEST + NEXT
	A	D	D	0	0	0	0	0	1	0	0	
	S	T	O	0	0	0	0	0	1	0	2	
0007 0008 0009	L	D	N	0	0	0	0	0	0	1	9	3 SUM > 1000
	S	T	O	0	0	0	0	0	1	0	2	
	H	M	L	0	0	0	0	0	0	1	5	
0010 0011	L	D	N	0	0	0	0	0	1	0	1	4a NEXT ← LATEST
	S	T	O	0	0	0	0	0	1	0	0	
0012 0013	L	D	N	0	0	0	0	0	1	0	2	4b LATEST ← SUM
	S	T	O	0	0	0	0	0	1	0	1	
0014	.	.	.	0	0	0	0	0	0	0	4	Arrow from flowchart box 4 to box 2
0015	W	W	H	0	0	0	0	0	1	0	2	5 SUM
0016	S	T	O	0	0	0	0	0	0	0	0	STOP
0017	.	.	.	0	0	0	0	0	0	0	0	The constant 0
0018	.	.	.	0	0	0	0	0	0	0	1	The constant 1
0019	.	.	.	0	0	0	0	0	0	1	0	The constant 1000
0100												The variable NEXT
0101												The variable LATEST
0102												The variable SUM

FIGURE 1-33  
Fibonacci sequence algorithm.  
The = column and columns 5, 6, and 7 may be left empty on lines containing instructions.

also illustrates a "coding form" on which one might have written the SAMOS program (gray-colored information). You will notice several new SAMOS operations not previously seen. These are explained in the following discussion.

### Discussion

The instructions in storage addresses 0004, 0005, and 0006 have already been discussed. Before looking at the other instructions, remember that the variables are in storage locations 0100 through 0102.

From previous discussions you should see that the instruction found at 0000 will, when executed, copy the value in 0017 (i.e., the number 0) into the accumulator. Next, the instruction in 0001 copies the value in the accumulator into the word at address 0100. Together these steps are equivalent to assigning 0 to the variable NEXT. Similarly, the instructions in addresses 0002 and 0003 are equivalent to assigning the value 1 to the variable LATEST.

Remember that the control unit executes the instructions in order until it comes to a branching instruction. The first branching instruction is found in address 0009, reading

	B	M	1	0	0	0	0	0	1	5
--	---	---	---	---	---	---	---	---	---	---

The code BMI stands for "Branch on a Minus." The whole instruction means, "If the value in the accumulator is negative, go to address 0015 for the next instruction; otherwise, go on as usual to the next numbered address (0010)." We will see shortly that the value in the accumulator at this time is just

$$1000 - \text{SUM}$$

so that the value in the accumulator will be negative only in the case that

$$\text{SUM} > 1000$$

is true. In this case, the branching instruction sends us to address 0015, where we see the instruction

	W	W	D	0	0	0	0	1	0	2
--	---	---	---	---	---	---	---	---	---	---

which means, "Write the Word in address 0102." This amounts to printing out the value of SUM.

Now why is it that when the instruction in address 0009 is reached, the number in the accumulator is

$$1000 - \text{SUM}$$

Well, on looking at the instruction in address 0007, we see that it instructs us to load the accumulator with the contents of address 0019, that is, to put the number 1000 in the accumulator. The next instruction, the one in 0008, tells us to "subtract the contents of address 0102 from the accumulator and put the result in the accumulator." Since the contents of 0102 are just the value of SUM, this amounts to the placing of

$$1000 - \text{SUM}$$

in the accumulator.

You should be able to verify for yourself that the instructions in addresses 0010 through 0013 accomplish the assignments indicated in the right-hand column of Figure 1-33.

The instruction in address 0014 needs to be described.

	B	R	U	0	0	0	0	0	0	4
--	---	---	---	---	---	---	---	---	---	---

BRU stands for "BRanch Unconditionally." The meaning of the entire instruction is, "Go back to address 0004 for the next instruction and continue in order from there." You can see that this corresponds to the arrow from flowchart box 4 leading back to flowchart box 2, where we repeat the summing step.

The instruction in 0016, of course, stands for HaLT and amounts to stopping the computing process.

You can best understand all this by tracing through the SAMOS program by hand, keeping a record of the following details.

1. Which instruction is being executed.
2. The value in the accumulator.
3. The values in the addresses 0100, 0101, and 0102 (the values of NEXT, LATEST, and SUM).

Notice that the instructions in addresses 0000 through 0016 are never altered, nor are the contents of the locations 0017 through 0019 (the constants 0, 1, and 1000).

EXERCISES 1.6

1. Construct a list of SAMOS instructions for the flowchart in Figure 1.14. You will need two additional types of instructions. The first is

49

OPERATION											ADDRESS										
1	2	3	4	5	6	7	8	9	10	11	1	2	3	4	5	6	7	8	9	10	11
	R	W	D	0	0	0	1	0	0	5											

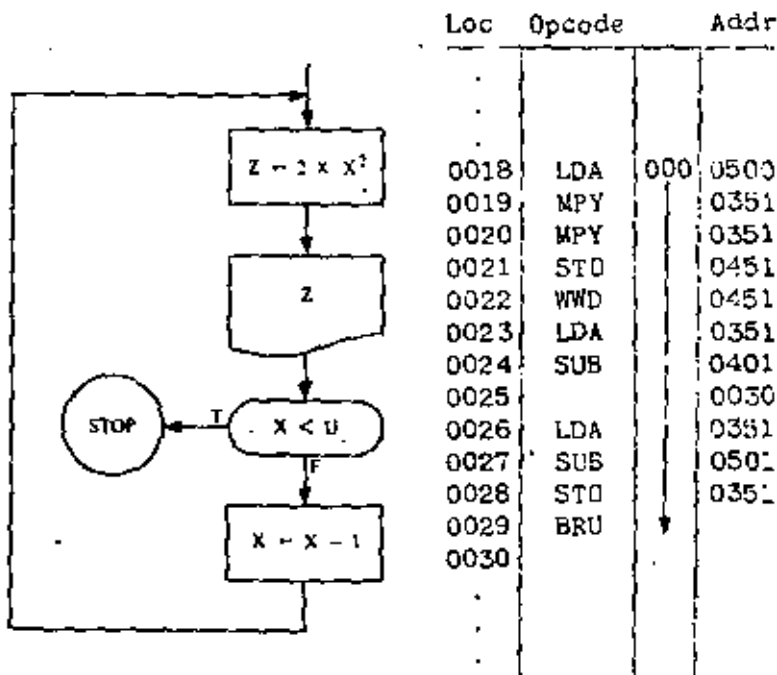
which is an instruction to read a value from a card into the computer word addressed 1005.

The second is

	M	P	Y	0	0	0	1	0	2	3
--	---	---	---	---	---	---	---	---	---	---

which is an instruction to multiply the value in the accumulator by the value in address 1023 and put the result in the accumulator. (Of course, in the address part of these instructions, we may put any address we wish.)

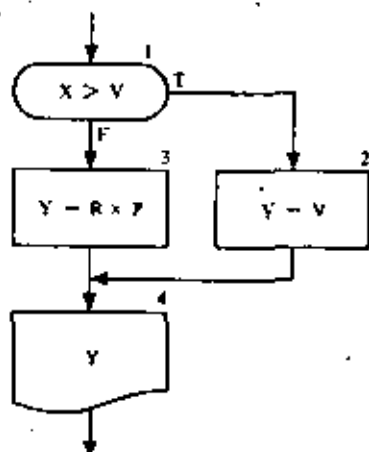
2. This question relates to the flowchart fragment and proposed SAMOS translation of it shown below. For each of your answers the assumed objective is to make the proposed SAMOS fragment consistent with the given flowchart fragment.





- (a) With what memory location must the variable X be associated?
- (b) What operand address is needed for the BRU instruction that is shown at location 0029?
- (c) What should be the operation code for the instruction at location 0025?
- (d) What operation code is needed for the instruction located at 0030?

3. This question relates to the flowchart fragment and proposed SAMOS translation of it shown below. For each of your answers, assume the objective is to make the proposed SAMOS fragment consistent with the given flowchart fragment.



Loc	Opcode	Addr	
0017	LDA	000	0100
0018	SUB	000	0200
0019	EMI	000	0024
0020	LDA	000	0105
0021	KPY	000	0107
0022	STO	000	
0023	BRU	000	
0024	LDA	000	0100
0025	STO	000	0201
0026	WWD	000	0201

- (a) With what location must the variable X be associated?
  - (b) What is the operand address that should be filled in for the BRU instruction shown at location 0023?
  - (c) What should be the value of the address field for the STO instruction at location 0022?
  - (d) If at location 0022 the STO were replaced by a BRU operation code, what then would be the appropriate value for the address field?
4. This question relates to the following SAMOS program and the four data cards displayed to the right of it; you are to assume that the given SAMOS program executes with the data cards shown. The DIV (divide) instruction produces an integer quotient (see Appendix A).

```

0000  RWD  000  0012
0001  RWD  000  0013
0002  LDA  000  0012
0003  DIV  000  0013
0004  MPY  000  0013
0005  STD  000  0014
0006  LDA  000  0012
0007  SUB  000  0014
0008  STD  000  0014
0009  RWD  000  0014
0010  BRU  000  0000
0011  HLT  000  0000

```



Data cards

## SAMOS program

- (a) Which of the following is a *false* statement?
- (1) The instruction at 0011 will never be reached.
  - (2) Only two values will be printed.
  - (3) All four data cards will be read.
  - (4) The first value printed will be 3.
  - (5) Three values will be printed.
- (b) Which of the following is a *true* statement?
- (1) The program will halt whenever the result of a division is zero.
  - (2) The instruction at 0011 would be executed using the given set of data if the instruction at 0010 were revised to BMI 000 0000.
  - (3) This program inputs two numbers, selects the larger, and prints its value.
  - (4) All three of the above statements are false.

Problems 5 through 7. The following three problems involve programs to be written in SAMOS machine language and run on a computer using a SAMOS simulator. If you do not have a computer available, your final result will be a SAMOS coding form showing your program.

5. Draw a flowchart and write and run a SAMOS program to find the areas (to the nearest integer) of circles with each of the following radii: 0, 1, 2, 3, . . . , 10, 11, 12. Use  $\pi = 22/7$ . The output is to consist of each radius value followed by the associated area, that is,

```

0 ←----- First radius
0 ←----- First area
1 ←----- Second radius
3 ←----- Second area
.
.
.
.
.
.
12

```

This SAMOS program should not execute any *input* steps. Storage locations will be required for instructions and for all constants, including 22, 7, the current radius, 1 (to increment the radius to the next value), and a number (11, 12, or 13, depending on your particular flow chart) to test against to determine when to branch to *halt*.

**Question** Will SAMOS give the same result when you compute  $(22/7) \times r^2$  as when you compute  $(22 \times r^2)/7$ ? If not, which gives a better result? Why?

6. Draw a flowchart and write and run a SAMOS program to do the following:

For the values from 1 to 10 inclusive (i.e.,  $1 \leq X \leq 10$ ), evaluate the following mathematical expression:

$$F = 5X^2 + 10X + 6$$

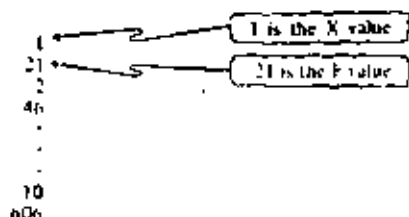
Print out the value for X and F after each evaluation.

**Example** The first value of X will be 1. For this value,

$$F = 5(1) + 10(1) + 6$$

$$F = 5 + 10 + 6 = 21$$

Thus the numbers 1 and 21 will be printed out, and F will then be evaluated for  $X = 2, 3, \dots, 10$ . The complete output will consist of 20 numbers:



**Note Additional Information for Problem 6**

1. No data cards will be needed for this program.
  2. The values from 1 to 10 need not all be stored at the beginning of the program.
  3. You must include some way to terminate your program after the final value has been processed and printed.
7. Draw a flowchart using variables C, X, TALLY, SUM, and AVG, and write and run a SAMOS program to do the following:
- (a) Read a value for the variable C.
  - (b) Read a value for the variable X.
  - (c) Check to see whether X equals 9999. If X does not equal 9999 then check whether X equals C. If X equals C, then return to

step (b). If X does not equal C, then add one to a counter called TALLY and add X to the variable SUM and then return to step (b).

If X equals 9999, then no more data cards are to be read. At this point print out the values of TALLY and SUM. Compute AVG, the quotient of SUM and TALLY ( $AVG = \text{SUM} / \text{TALLY}$ ). Print the value of AVG.

*Note Additional Information for Problem 7*

1. In your flowchart the average will be a variable AVG. The variable TALLY will hold a count of how many values of X are *not* equal to C. The assignment

$$\text{TALLY} \leftarrow \text{TALLY} + 1$$

will be needed. The sum of the values of X not equal to C will be called SUM. What should be the initial values of TALLY and SUM?

2. The value 9999 is called a *sentinel* value. Its purpose is to indicate that all the values of X have been read and processed. (In computer language a sentinel value is said to represent the end of file, i.e., the end of data.) Therefore, your data deck will consist of a value for C, the given values for X, and the value 9999. (See Section 2.2 for additional discussion of sentinels.)

3. In SAMOS the only conditional branch instruction is BMI (Branch On Minus). The programmer faces a problem when he needs to check whether the values of two variables are equal or whether the value of a variable is equal to some constant value. The following is one method of determining whether the values of the variables A and B are equal. First, subtract the value of B from the value of A and, if the result is not negative, subtract the value of A from the value of B. If this result is not negative, we can conclude that the values of A and B are equal.

*Examples*

(a)  $A = 6$  and  $B = 9$

$$A - B = 6 - 9 = -3$$

Result:  $A \neq B$  since  $A - B$  is a negative number.

(b)  $A = 5$  and  $B = 5$

$$A - B = 5 - 5 = 0$$

$$B - A = 5 - 5 = 0$$

Result:  $A = B$  since neither subtraction produced a negative number.

(c)  $A = 4$  and  $B = 3$

$$A - B = 4 - 3 = 1$$

$$B - A = 3 - 4 = -1$$

Result:  $A \neq B$  since  $B - A$  is a negative number.

4. The data for Problem 7 are as follows:

15	→ This is the value for the variable C.
5	
20	→ The remaining data values are for the variable X
21	
3	
10	
15	
12	
17	
9999	

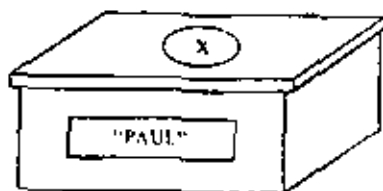
Most of the storage capacity of a 61-bit SAMOS word goes unused when a small integer, for instance, 2, is represented. Conversely, even though a number is known to very great precision, a 61-bit word has a fixed capacity to represent digits. Character strings, such as names and addresses, for instance, vary greatly in length. In general, information comes in many sizes and lengths, and it would be exceedingly convenient to have computer storage responsive to this fact.

The SAMOS language is heavily influenced (i.e., constrained) by its *word-organized* storage system. We briefly mention here another kind of computer storage called BITOS (BIT-Organized SAMOS), whose storage is structured in a more flexible and natural way—natural for the processing of different types of information. The BITOS storage is best thought of as a single sequence of bits instead of a single sequence of words that are, in turn, sequences of bits. For example, a BITOS store roughly equivalent to the SAMOS store contains 610,000 bits whose addresses are 0 through 609,999 respectively. To fetch a unit of information of some known length, one must specify the “bit address” of the beginning of the desired information unit together with its “bit length.” Thus,

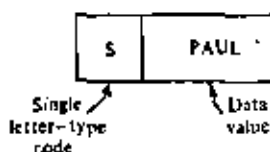
op code	address	length
LDA	24972	39

is the way one might write out a BITOS instruction to load the accumulator with a data value 39 bits long beginning at bit location 24972.

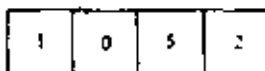
The information containers in a BITOS machine resemble the storage boxes of the conceptual model SIMPLoS in that the capacity of the containers is arbitrary.



There is a second important way in which the containers of SIMPLoS and BITOS resemble one another. In both cases, values stored in these containers are *self-describing*. Note that the SIMPLoS Reader is able to deduce that a storage box contains a character string value as opposed, say, to a numerical value, because he is able to see the quotation marks. The fetching mechanism of BITOS can convey the same type of information to its processing unit because the data object in each container consists of two parts: a code that describes the type or nature of the value and the data value itself. For example, suppose the container associated with X, is located at bit address 3901, and suppose character coding for the BITOS store employs the same 6-bit representation used in SAMOS. We might expect to see at that location:



where the type code S stands for string. Then, to represent a string of 4 characters would require 24 bits for the string itself and 6 more bits (for the letter S) to identify the 24 bits as a string. For a string of 91 characters, 546 bits are needed for the string and 6 more for the type code—or 552 bits in all. If a nonnegative integer variable, AGE, never requires more than three digits we can picture the corresponding BITOS container as



for a data value of 52. Here the type code I denotes *integer*.

To recapitulate, in BITOS one defines the size of the container to fit the need. That is, the store is divided up into containers that reflect their actual use. Every reference to a container consists of the bit address of the container and its length. The container itself holds as part of the data object a code that makes the remainder of the information in the container self-describing. Each time a new container is needed, a section of the store large enough to hold the required number of bits is "partitioned" for this purpose. When this container

is no longer needed, that section of store and others like it are repartitioned, that is, reused, typically in different container sizes, to suit new needs. To make an analogy with SIMPLoS, imagine that all storage boxes are constructed to fit dimensions of the data values they are to contain. (The Affixer who pastes the sticker on the storage box can also adjust the size of the box if necessary.)

### 1.8 Floating-point representation

Only a few of the ideas about SAMOS and BITOS need to be remembered. One of the important ideas is the sequential manner in which the computer works, that is, the step-by-step way in which the computer performs its tasks. The order in which the tasks are performed is just as important as what is accomplished.

Another property of computers that we must understand is the *finite word length*. We have seen that SAMOS words consist of 10 characters and a sign, so that the largest number representable in this coding system is

$$+ 9,999,999,999$$

a rather large number, but still finite. Although BITOS store may use very "long" containers, they are still finite, so the limitation on what can be represented, although less constricting, still exists in principle. From a practical viewpoint, integer containers, whether in a SAMOS-like or in a BITOS-like store, are sometimes very unsuitable. Consider a variable that, from time to time, has various values assigned to it, sometimes very small integers and at other times very large integers. The storage container for such a variable cannot always be used efficiently if it must be large enough for the largest possible integer value that will be assigned to it.

To cover this situation there are other ways of coding numbers that not only solve this problem but also allow us to work with real numbers as well as integers. One of the most common of these alternate codings is *floating-point* form, which is related to the so-called "scientific notation."

To see how this works, recall that any decimal numeral such as

$$- 382.519$$

can be expressed as

$$-.382519 \times 10^3 \quad 57$$

in which there is a decimal point (just after the sign, if any) followed by a string of digits (the first not zero) and multiplied by a suitable power of 10. We can code numbers in this way by reserving three character positions for the exponent. The result is shown in Figure 1-34 for  $-382.519$ .

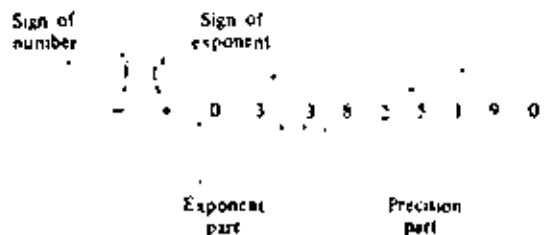


FIGURE 1-34  
Anatomy of a floating-point number for a fixed-word size store.

Some examples of how to code numbers including integers in this system are given in Figure 1-35. In this figure, we see that the 8-digit representation of  $\pi$ , as given in the first column of the third entry, has to be chopped to 7 digits of precision because of space requirements. The same holds true for  $1/3$  and  $11/7$  at the bottom of the table. Thus we see that in a computer even a simple fraction such as  $1/3$  cannot be represented exactly, but only to a close approximation. This characteristic of "finite word length" presents important prob-

Number	Floating-Point Form	Coding of Floating-Point Form
4	$4 \times 10^1$	+ + 014000000
-999999000	$-.999999 \times 10^9$	- + 099999990
3.1415926	$.31415926 \times 10^1$	+ + 013141592
-273.14	$-.27314 \times 10^3$	- + 032731400
.0008761	$.8761 \times 10^{-3}$	+ - 038761000
.73	$.73 \times 10^0$	+ + 007300000
$\frac{1}{3}$	$.33333333 \times 10^0$	+ + 003333333
$\frac{11}{7}$	$.157142857 \times 10^1$	+ + 011571428

FIGURE 1-35  
Floating-point coding of numbers in a fixed word-sized store.



EXERCISE 1-8

- Several million pocket-sized electronic calculators are now being produced annually. They are becoming relatively accessible to the average student. Many of these calculators, such as the one shown in Figure 1-36, use floating point arithmetic.

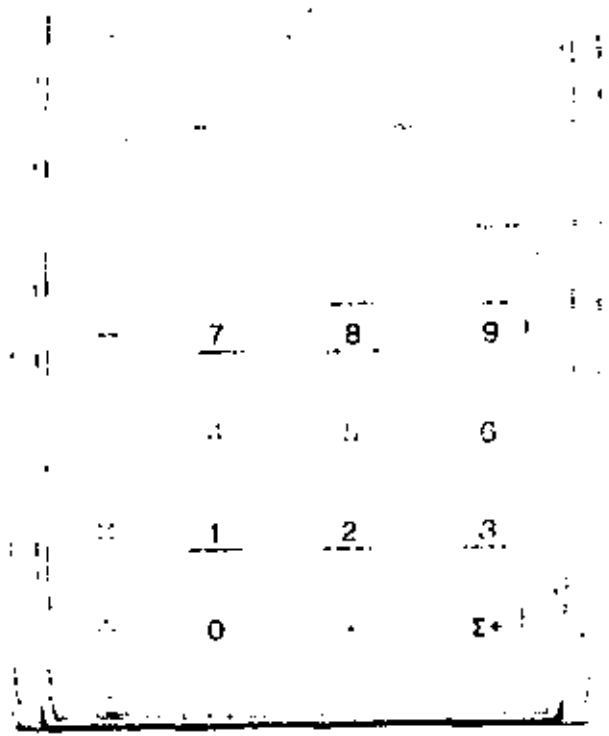


FIGURE 1-36  
A popular hand-held calculator.

- Locate an electronic calculator and compare the method it uses to represent floating-point numbers with the method used in SAMOS.

lems that will be discussed in various places in this text, especially Chapter 11.

In floating-point form we can represent large numbers, but for computers such as SAMOS with fixed-word size stores the price we pay is giving up three places of precision. Were SAMOS to use floating-point numbers, the largest number representable in floating-point form would be:

.	.	0	0	0	0	0	0	0	0	0	0
---	---	---	---	---	---	---	---	---	---	---	---

which represents the number

999,999,999,000,000,000,000,000,000  
 000,000,000,000,000,000,000,000,000  
 000,000,000,000,000,000,000,000,000  
 000,000,000,000,000,000

Similarly, there is a smallest positive number that could be represented:

-	-	0	0	0	0	0	0	0	0	0	0
---	---	---	---	---	---	---	---	---	---	---	---

.000 000 000 000 000 000 000 000 000  
 000 000 000 000 000 000 000 000 000  
 000 000 000 000 000 000 000 000 000  
 000 000 000 000 000 000 1

which is very small, indeed.

Coding in floating-point form for a BITOS-like machine could be quite similar to the scheme shown in Figure 1-35. On the other hand, since the size of the container may be chosen to fit the particular "needs" of a given variable, the size of the precision part could easily be permitted to vary as required. For that matter, the size of the exponent part could also be expanded or contracted to fit the need.

In summary, both SAMOS-like and BITOS-like machines are often built to operate on numbers coded in floating-point form. However, in our discussions of SAMOS, in particular in the description given in the Appendix, the machine is initially described as if it were not capable of dealing with numbers coded in floating-point form, but only with numbers coded as integers.



**DIVISION DE EDUCACION CONTINUA  
FACULTAD DE INGENIERIA U.N.A.M.**

INTRODUCCION A LA PROGRAMACION Y COMPUTACION ELECTRONICA

INTRODUCCION A LA COMPUTADORA DIGITAL

OCTUBRE, 1981

specifying ADD WORD (addressed by) A AND WORD (addressed by) B; PUT RESULT INTO MEMORY LOCATION (addressed by) C. But specification of three separate addresses would make the instruction word too long (even for a large digital computer, not to speak of a minicomputer). We can, however, implement the above operation in terms of several simpler instructions each referencing only a single memory address:

LOAD INTO ACCUMULATOR (the word addressed by) A  
ADD INTO ACCUMULATOR (the word addressed by) B  
STORE ACCUMULATOR (in memory location addressed by) C

The "basic" minicomputer discussed in this chapter, then, will be a single-address machine whose instructions move data between a single suitably addressed memory location and a specified processor register, or possibly between two such registers. There will also be some instructions which do not reference memory at all (e.g., COMPLEMENT ACCUMULATOR). We remark, however, that the possibility of using simplified two-address instructions and zero-address (stack) instructions in minicomputers is of the greatest interest and will be discussed in connection with more advanced designs in Chap. 6.

**2-3. The "Basic" Minicomputer.** Figure 2-1 illustrates the typical organization of a small digital computer. The machine has all the ingredients of Secs. 1-6 to 1-13, viz.,

1. A core or semiconductor memory, which will store instructions and data
2. A set of processor registers (flip-flop registers), viz.,
  - (a) Memory buffer register (memory data register): contains the instruction or data word currently leaving or entering the memory
  - (b) Memory address register: contains the address of the currently addressed memory location
  - (c) Program counter: contains the address of the instruction to be executed
  - (d) Instruction register: contains the current instruction
  - (e) General-purpose register (accumulator, arithmetic register) or registers; and, possibly, an index register (Sec. 2-7)
  - (f) One-bit registers ("flags"): indicates overflow, carry, sign bit, etc., resulting from past or current operations
3. An arithmetic/logic unit; logic circuits to combine words from two registers by addition, subtraction, bit-by-bit ANDing, etc., and to complement, shift, etc., single words
4. Control logic: decodes the 0s and 1s of the instruction currently in the instruction register to generate logic levels and time pulses, which:
  - (a) Gate (steer) words between processor registers
  - (b) Determine the function of the arithmetic/logic circuits

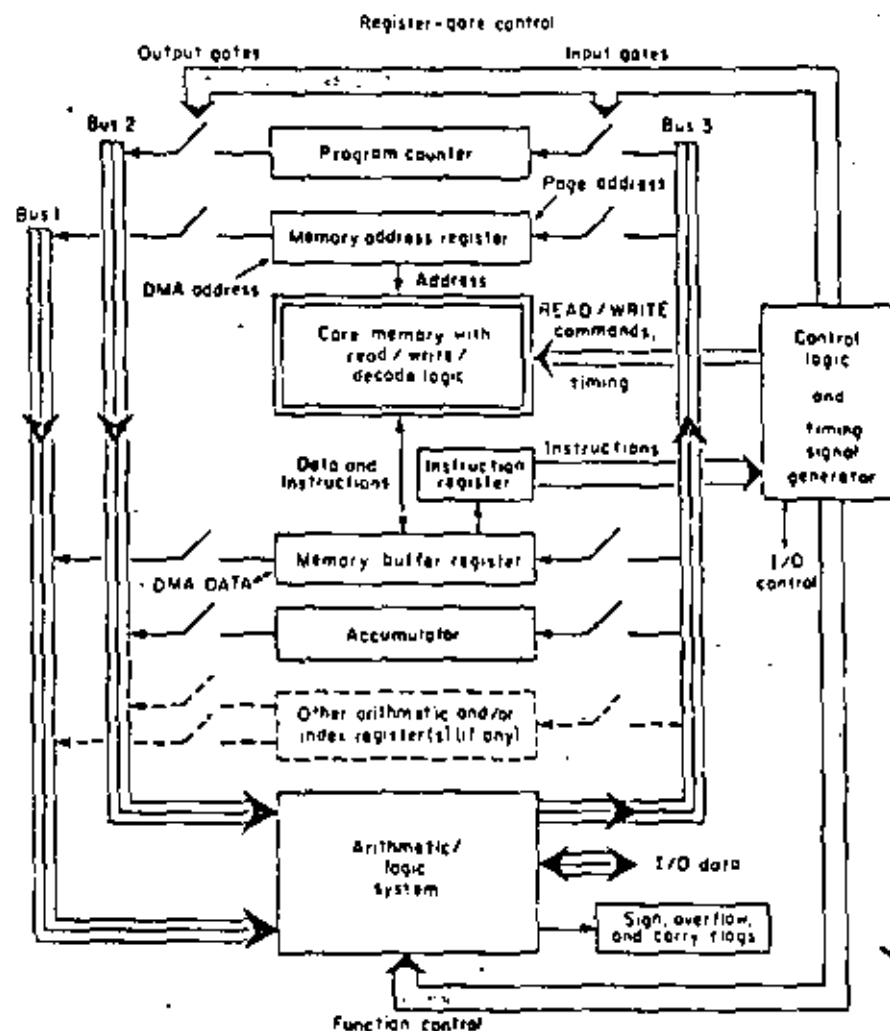


Fig. 2-1. Organization of a "basic" single-address minicomputer.

In Fig. 2-1, there are three buses for transfers between registers, always via the arithmetic/logic unit. This is a practical compromise: some extra register-to-register paths would permit more concurrent register transfers and speed computation, but we would pay for more complex interconnections and logic.

Finally, we must have input/output connections through the arithmetic/logic unit or through register gates.

**2-4. Processor Operation. (a) Instruction Fetching.** If we assume that a suitable program and data are in memory, processor operation proceeds

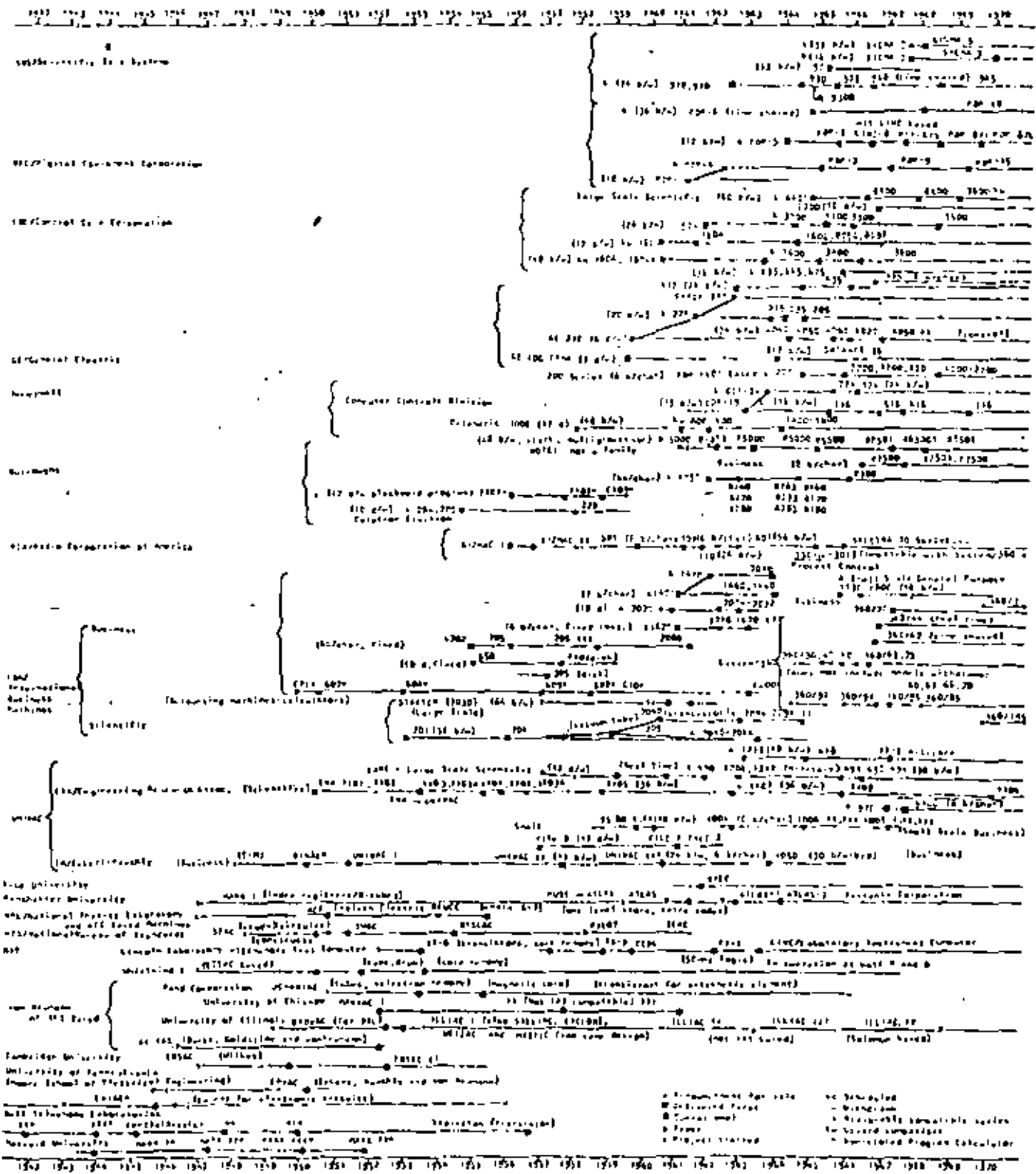


Fig. 2a. Time chart: computers by originator.

Característica	1ª Generación	2ª Generación	3ª Generación	4ª Generación
Característica				
1. Tubo de vacío				
2. Transistores, diodos de estado sólido				
3. Circuitos integrados				
4. Redes integradas a gran escala				
1952	1958	1961	1969	
tubo de vacío	transistor, diodo	circuito integrado	retículo funcional de circuitos	
1 elemento de circuito	1 elemento de circuito	8 a 100 elemento de circuito	más de 1.000 elementos de circuito	
100	5	0.25	0.02	
10 (en 1975)	1.000 (en 1962)	10.000 (en 1967)	25.000 (en 1969)	
8	1	0.10	0.04	
\$ 30.00	\$ 25.00	\$ 5.00	\$ 2.00	
1	0.01	0.001	0.0001 (proyectado para 1972)	
Característica				
1. número de sistemas				
2. complejidad electrónica básica				
3. complejidad de la parte representada				
4. número típico de un flip-flop (puñaladas cúbicas)				
5. velocidad operativa (MHz)				
6. consumo de fuerza (vatios)				
7. costo de un flip-flop (dólares)				
8. porcentaje relativo de falla				

Fig. 1 Características de cuatro generaciones de componentes electrónicos.

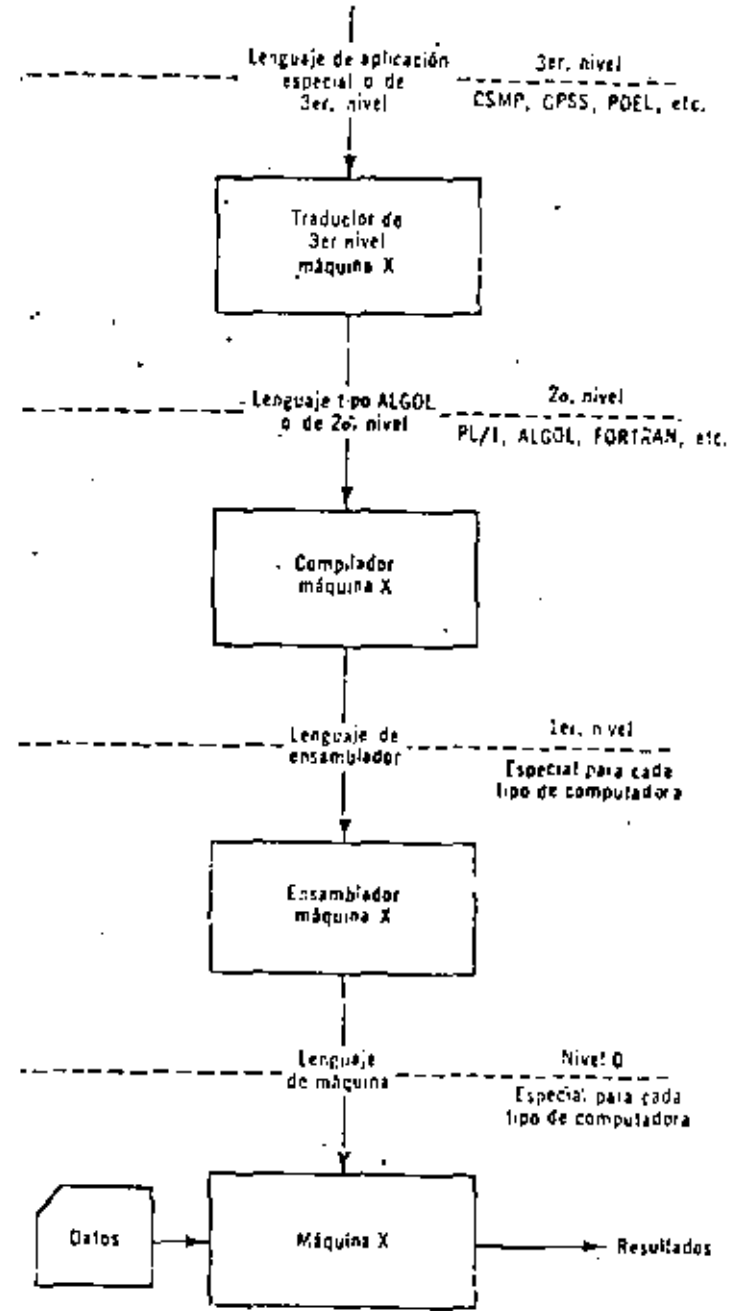


Fig. 1. El proceso de traducción común.

mente, reduciendo, muchas veces, aún más el tiempo total de solución de un problema en el área para la cual se está...

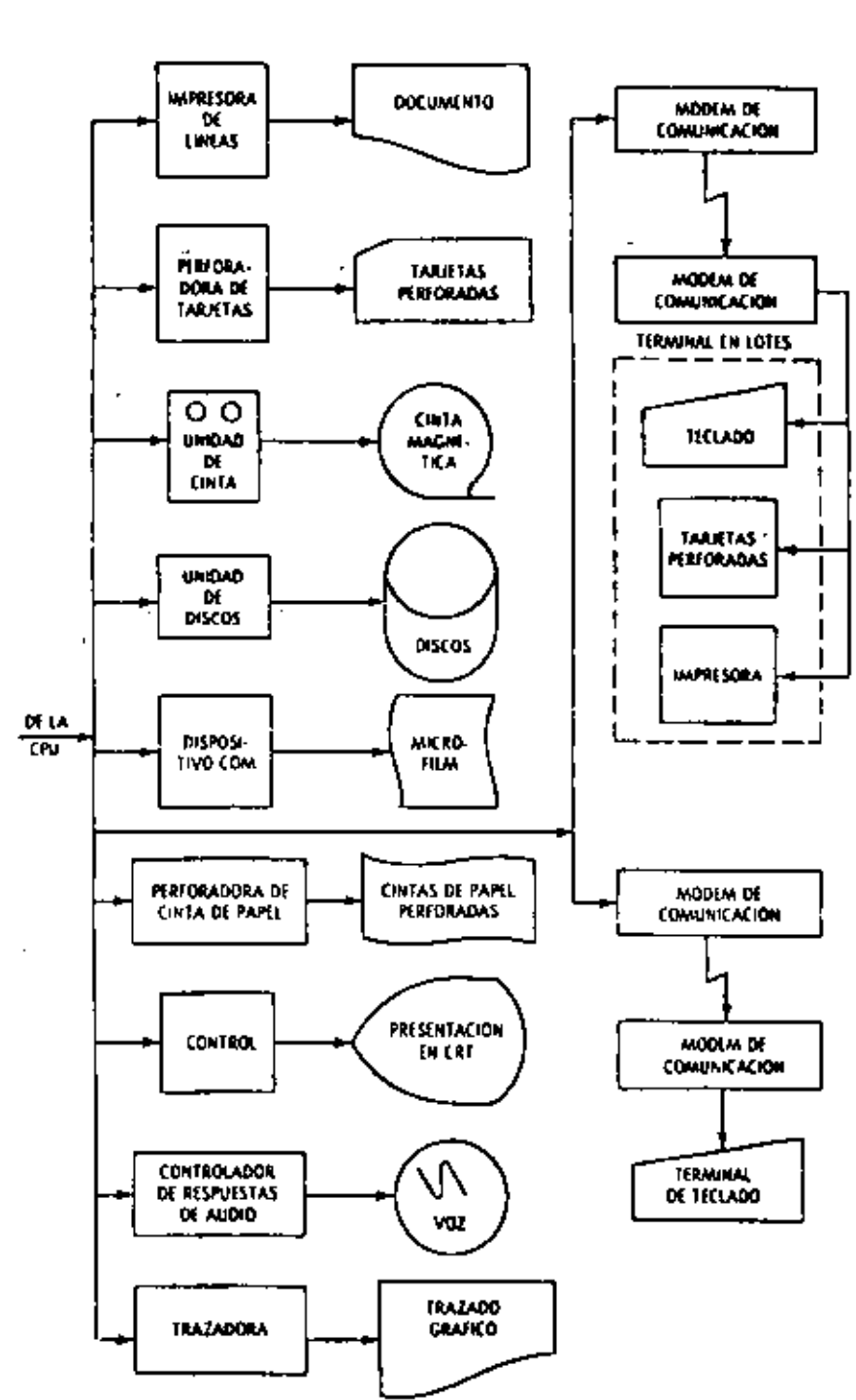
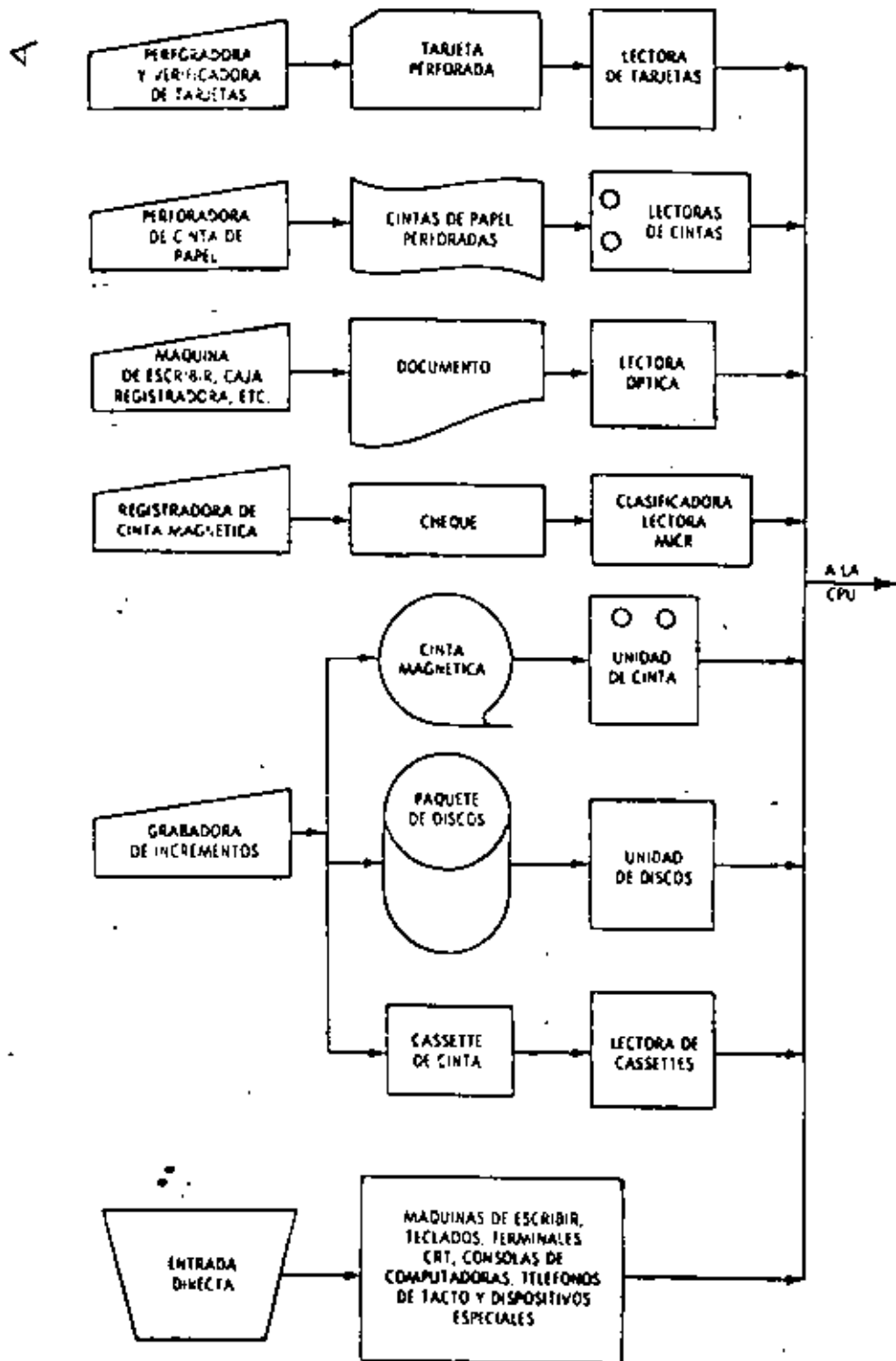


Fig. 8-2. Presentación de dispositivos y medios de salida.



**DIVISION DE EDUCACION CONTINUA  
FACULTAD DE INGENIERIA U.N.A.M.**

INTRODUCCION A LA PROGRAMACION Y COMPUTACION ELECTRONICA

LENGUAJE FORTRAN

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OCTUBRE, 1981



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RICARDO CIRIA MERCE

F O R T R A N

ELEMENTOS DE UN SUPERLENGUAJE DE PROGRAMACION: FØRTRAN

- 1.- Introducción al lenguaje FØRTRAN
  - 1.1 El alfabeto
- 2.- Números
  - 2.1 Constantes enteras
  - 2.2 Constantes reales
  - 2.3 Variables enteras
  - 2.4 Variables reales
- 3.- Operaciones aritméticas
- 4.- Expresiones aritméticas
  - 4.1 Reglas para las expresiones aritméticas
  - 4.2 Funciones predefinidas disponibles en lenguaje FØRTRAN
- 5.- Enunciados
  - 5.1 Los enunciados aritméticos de asignación
  - 5.2 Los enunciados de control
    - 5.2.1 El enunciado GØ TØ

- 5.2.2 El enunciado IF
- 5.2.3 El enunciado DO
- 5.2.4 El enunciado STOP
- 5.3 Los enunciados de entrada y salida
  - 5.3.1 El enunciado READ
  - 5.3.2 El enunciado WRITE
- 5.4 Los enunciados de especificación
  - 5.4.1 El enunciado FORMAT
    - 5.4.1.1 La especificación I : Iw
    - 5.4.1.2 La especificación F : Fw.d
    - 5.4.1.3 La especificación E : Ew.d
    - 5.4.1.4 La especificación A : Aw
    - 5.4.1.5 La especificación T : Tw
    - 5.4.1.6 Las especificaciones X, H y /
  - 5.4.2 El enunciado END
- 6.- Arreglos
  - 6.1 Variables con subíndices
    - 6.1.1 Reglas para los subíndices
  - 6.2 El enunciado DIMENSION
    - 6.2.1 Reglas para las variables con subíndices
  - 6.3 Arreglos de entrada y salida
- 7.- SUBPROGRAMAS
  - 7.1 Funciones
    - 7.1.1 Ejemplos
  - 7.2 Subrutinas
    - 7.2.1 COMMON

1.- Introducción al lenguaje FØRTRAN

El lenguaje FØRTRAN, cuyo nombre corresponde a las primeras letras de las palabras inglesas. FORMula (fØrmula) y TRANslation (traducción), es un lenguaje de programación orientado a problemas <sup>matemáticos</sup> y se emplea en casi todas las computadoras del mundo. Debido a su parecido con el lenguaje aritmético común, el FØRTRAN simplifica la preparación de problemas que pueden resolverse mediante una computadora. Los datos e instrucciones se pueden organizar mediante una secuencia de enunciados fortran; estos constituyen el llamado Programa Fuente.

Todas las computadoras que "entienden" el lenguaje FØRTRAN, tienen lo que se llama un Compilador Fortran, llamado también traductor o interprete, el cual analiza los enunciados fortran y los traduce a un Programa Objeto, el cual queda en Lenguaje de Máquina.

Un programa escrito en lenguaje FØRTRAN se puede procesar en cualquier máquina que tenga un Compilador Fortran. Esto nos indica que el lenguaje es independiente para cada máquina, o sea que el compilador se debe preparar en cada caso teniendo en cuenta la máquina que ha de usarse en particular; puesto que las máquinas difieren en su organización interna, se ha desarrollado un número de "dialectos" del lenguaje FØRTRAN, cada uno de los cuales es apropiado para una clase de máquinas. Las diferencias entre los

varios dialectos son mínimas y se ajustan el uno al otro fácilmente.

### 1.1 El alfabeto

El alfabeto FØRTRAN esta constituido de caracteres que son símbolos familiares de escritura y de teclados de máquinas de escribir, así como de dispositivos especiales de perforación; dichos caracteres son:

- Alfabéticos:    A B C D E F G H
- I J K L M N
- \* Ø P Q R S T U V W X Y Z
- Numéricos:     0 1 2 3 4 5 6 7 8 9
- Símbolos:       + - \* / = . , ( ) ' @

De este alfabeto se construyen todos nuestros símbolos, expresiones y enunciados que se utilizan en el lenguaje FØRTRAN.

### 2.- Números

Los números pueden representarse en diferentes formas, las cuales se asemejan a los símbolos de la aritmética general; pero debido a la estructura interna de las computadoras se establecen las convenciones de: Punto Fijo y Punto Flotante que proporcionan facilidades para su manejo en FØRTRAN. Los símbolos de punto fijo

\* La letra Ø la expresaremos como ø para diferenciarla del N° cero.

se usarán solamente con números enteros y los cálculos asociados se denominarán aritmética de los enteros o modo entero; mientras que la aritmética de los números reales se hará en la forma de punto flotante y se llamará aritmética de los reales o modo real. Debido a que también es necesario distinguir las constantes (números que no cambian durante toda la ejecución de un programa) de las variables (números que pueden cambiar), surgen cuatro clases de símbolos para los números.

2.1 Constantes enteras.

Dependiendo del tipo de computadora se podrán representar por un cierto número de dígitos, así para IBM-1130 se representan mediante cinco dígitos sin el punto decimal. Si el entero es negativo, los dígitos deberán ser precedidos del signo menos; si el entero es positivo el signo es opcional.

Ejem.            Símbolos para constantes enteras pueden ser entre otras:

1976    +1    0    +1976    -1976

Símbolos que no se aceptan para constantes enteras:

7483282 (más de cinco dígitos)

1976. (el punto decimal no se permite)

2.2 Constantes reales

Dependiendo del tipo de computadora, las constantes reales se podrán representar por varios dígitos, pero en el caso de la

IBM-1130 sólo se admiten siete dígitos con punto decimal pudiéndose colocar al principio de los dígitos, al final o entre dos dígitos cualesquiera. Cuando aparece un punto en una constante su tratamiento será de punto flotante. Si la constante real es precedida de un signo menos, se indicará que es negativa, si es positiva el signo es opcional.

Ejem. Símbolos para constantes reales pueden ser entre otras:

1976.	-.00001976	+12.345	-12.345
-.007	.007	5.348	0.3

Símbolos que no se aceptan para constantes reales:

123456789.32 (más de siete dígitos significativos)

5343 (falta el punto decimal)

Para representar las constantes reales existe también la llamada forma exponencial; esta la podemos representar mediante una letra E y una constante entera de uno o dos dígitos, positiva o negativa. Esta constante entera es un exponente del número diez; el signo menos es para los exponentes negativos y para los positivos, el signo es opcional. En FORTRAN, la presencia del exponente hace que el uso del punto decimal sea opcional.

Ejem. Forma exponencial Forma no exponencial

1.328E2	132.8
1.328E02	132.8

1.328E00	132.8
-4.724E-03	-.004724
+7.61E3	7610.
-6432E-3	-6.432

### 2.3 Variables enteras

Estas se representan por combinaciones de una a cinco letras y dígitos (IBM-1130), no se permiten otros caracteres y el primer carácter deberá ser una de las letras I, J, K, L, M ó N. El primer carácter de una variable es el que indica si es entera o real. Durante la ejecución de un programa, las variables enteras deberán restringirse a valores enteros.

Ejem. Símbolos para variables enteras pueden ser, entre otros:

NUMCT	KILO	N1	N2	M10	KONT
FIALC	JCLAV	MARY	KONT1	L1976	

Símbolos no aceptables para variables enteras:

CUENT (el primer carácter debe ser I, J, K, L, M ó N).

KONTADOR (demasiados caracteres)

12.34 (sólo se aceptan letras y números)

### 2.4 Variables reales

Estas se representan por combinaciones de una a cinco letras y dígitos (IBM-1130), no se permiten otros caracteres y el primer

caracter tiene que ser necesariamente una letra diferente a I, J, K, L, M ó N. Durante la ejecución de un programa dichas variables se deben restringir a valores reales.

Ejem. Símbolos para variables reales pueden ser, entre otros:

FUERZ VELOC ACEL1 CUENT A1 A2  
ALFA VIELA RA42 X1 PROD SUMA

Símbolos no aceptables para variables reales:

A3.8 (el punto no es letra o número)  
CORRIEN (demasiados caracteres)  
3 BASO (el primer caracter debe ser una letra)  
MUMCT (el primer caracter no puede ser M)

### 3.- Operaciones aritméticas

Las operaciones aritméticas y los símbolos que se utilizan en FORTRAN son:

	Ejem.	Algebra	FORTRAN
Adición	+	$a + b$	A + B
Sustracción	-	$a - b$	A - B
Multiplicación	*	$a b$	A * B
División	/	$\frac{a}{b}$	A / B
Exponenciación	**	$a^2$	A * A
		$a^2$	A ** 2

### 4.- Expresiones aritméticas

En base a lo expuesto anteriormente podemos ahora formular



1.328E00	132.8
-4.724E-03	-.004724
+7.61E3	7610.
-6432E-3	-6.432

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Ejem. Símbolos para variables enteras pueden ser, entre otros:

```
NUMCT    KILO    N1    N2    MID    KONT
FIALC    JCLAV    MARY    KONT1  L1976
```

Símbolos no aceptables para variables enteras:

CUENT (el primer carácter debe ser I, J, K, L, M ó N).

KONTADOR (demasiados caracteres)

12.34 (sólo se aceptan letras y números)

### 2.4 Variables reales

Estas se representan por combinaciones de una a cinco letras y dígitos (IBM-1130), no se permiten otros caracteres y el primer

caracter tiene que ser necesariamente una letra diferente a I, J, K, L, M ó N. Durante la ejecución de un programa dichas variables se deben restringir a valores reales.

Ejem. Símbolos para variables reales pueden ser, entre otros:

FUERZ VELOC ACEL1 CUENT A1 A2  
ALFA VIELA RA42 X1 PROD SUMA

Símbolos no aceptables para variables reales:

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	Ejem.	Algebra	FORTRAN
Adición	+	$a + b$	A + B
Sustracción	-	$a - b$	A - B
Multiplicación	*	$a b$	A * B
División	/	$\frac{a}{b}$	A / B
Exponenciación	**	$a^2$	A * A
		$a^2$	A** 2

### 4.- Expresiones aritméticas

En base a lo expuesto anteriormente podemos ahora formular

expresiones aritméticas en lenguaje FORTRAN y nos daremos cuenta que son muy similares a las expresiones aritméticas del álgebra común.

Expresiones FORTRAN	Expresiones Comunes
$A**2-B**2$	$a^2-b^2$
$B**2-4.*A*C$	$b^2-4ac$
$(A+B)/2.$	$\frac{1}{2}(a+b)$
$2*K-J+N$	$2k-j+n$
$C+B-3.*A$	$c+b-3a$

#### 4.1 Reglas para las expresiones aritméticas

Las reglas a las que debemos sujetar las expresiones aritméticas son necesarias debido a la estructura de las computadoras y al observarlas tendremos un ahorro en el tiempo de ejecución de un programa.

##### Regla 1

Si nos fijamos en las expresiones FORTRAN anteriores nos damos cuenta que: Todas las constantes y variables en una expresión deben estar en el mismo modo, esto es, todas deben ser enteras o todas deben ser reales. (Como toda regla existe su excepción que mencionaremos más adelante).

Es necesario consultar los manuales de cada máquina, ya que como hemos mencionado anteriormente dependerá esta regla del tipo de computadora. Por lo pronto la consideraremos como se ha indicado.

Regla 2  $A^{**}I$ ,  $I^{**}J$  y  $A^{**}B$  son exponenciaciones permitidas. En el caso  $A^{**}I$  se mezclan los modos y es la excepción a la Regla 1, pero sabemos que esta exponenciación significa multiplicaciones sucesivas (así  $B^{**}3 = B * B * B$ ), mientras que las potencias no enteras implican cálculos más sofisticados. Nos damos cuenta que  $I^{**}A$ , no es forma de exponenciación permitida (en algunas máquinas sí se permite).

Regla 3 Deberá tenerse en cuenta que las operaciones se ejecutarán con las siguientes prioridades:

- 1) Las operaciones indicadas dentro de los paréntesis más internos se ejecutan en primer lugar.
- 2) Exponenciación.
- 3) Multiplicación y división.
- 4) Adición y sustracción.

Entre las operaciones de igual prioridad, el orden de ejecución es de izquierda a derecha.

Ejem. Si  $A=5$ ,  $B=8$ , y  $C=2$ .

$A+B-3.*C$  se calculará en el siguiente orden:

$$3.*2=6, \quad 5.+8.=13, \quad 13.-6.=7.$$

$B^{**}2-4.*A*C$  se calcula en el siguiente

orden:

$$8.**2=64, \quad 4.*5.=20, \quad 20.*2.=40.$$

$$64.-40.=24.$$

Si  $A=5.$ ,  $B=8.$ ,  $C=2.$  y  $D=1.6$

Entonces  $(A+B)/C$  se calcula en el siguiente orden:

$$5.+8.=13. \quad 13./2.=6.5$$

Mientras que  $A+B/C$  se calcula en el siguiente orden:

$$8./2.=4. \quad 5.+4.=9.$$

Ahora si deseamos calcular  $(A+C)**2$  conducirá a:

$$5.+2.=7. \quad 7.**2=49.$$

Mientras que  $A+C**2$  conducirá a:

$$2.**2=4. \quad 5.+4.=9$$

Ahora si:  $(A*B)/(C*D)=40./3.2=12.5$

Entonces:  $A*B/C*D=40./C*D=20.*D=32.$

Finalmente si tenemos paréntesis dentro de otros paréntesis se tiene:

$$(A*(B+C))**2=(A*10.)**2=50.**2=2500.$$

$B+C$  tiene la más alta prioridad por encontrarse en el paréntesis más interno.

$$(A*B+C)**2=(40.+2)**2=42.**2=1764.$$

$$A*(B+C)**2=A*10.**2=A*100.=500.$$

$$A*B+C**2=A*B+4.=40.+4.=44$$

Debemos tener cuidado en expresar lo que deseamos realizar.

Regla 4

No deberemos colocar un signo de operación antes de un signo más o menos, esto es, no deberemos poner dos signos de operación juntos.

Ejem.  $A \pm -B$   $I + -J$   $- M - +N$   $- A / -B$

Estas expresiones deberán sustituirse por:

$A * (-B)$   $I + (-J)$   $M - (+N)$   $A / (-B)$

## 4.2 Funciones predefinidas en lenguaje FORTRAN

Estas funciones predefinidas que proporciona el lenguaje FORTRAN son de tipo de biblioteca. Para utilizarlas usaremos el nombre de la función seguido de un argumento que deberá estar entre paréntesis. Dichos argumentos pueden ser variables simples ó con subíndices, constantes, expresiones aritméticas u otras funciones predefinidas en FORTRAN.

Para IBM - 1130 tenemos: .

<u>NOMBRE</u>	<u>FUNCION EJECUTADA</u>	<u>NUM. DE ARGUMENTOS</u>	<u>TIPO DE ARGUMENTO(S)</u>	<u>TIPO DE FUNCION</u>
SIN	Seno trigonométrico (argumento en radianes)	1	Real	Real
COS	Coseno trigonométrico (argumento en radianes)	1	Real	Real
ALOG	Logaritmo natural	1	Real	Real
EXP	Argumento de potencia del número e.	1	Real	Real
SQRT	Raíz cuadrada	1	Real	Real
ATAN	Arco tangente	1	Real	Real

del libro C

## 13

ABS	Valor absoluto	1	Real	Real
IABS	Valor absoluto	1	Entero	Entero
FLOAT	Convertir argumento de entero a real	1	Entero	Real
IFIX	Convertir argumento de real a entero	1	Real	Entero
SIGN	Transferencia de signo (Arg. <sub>1</sub> recibe signo de Arg. <sub>2</sub> )	2	Real	Real
ISIGN	Transferencia de signo (Arg. <sub>1</sub> recibe signo de Arg. <sub>2</sub> )	2	Entero	Entero
TANH	Tangente Hiperbólica	1	Real	Real

Ejem.  $\text{SQRT}(B**2-4.*4.*A*C)$  indica que a lo que se encuentra entre paréntesis se le sacará la raíz cuadrada.  
 $\text{SIN}(BETA)$  Indica que se obtendrá el seno trigonométrico de el valor de la variable BETA.

## 5.- Enunciados

Los enunciados son las unidades básicas con las cuales se construyen los programas FORTRAN. Podemos clasificarlos de acuerdo a su función en grupos como:

- 1.- Aritméticos de asignación
- 2.- De control
- 3.- De entrada y salida
- 4.- De especificación

## 5.1 Los enunciados aritméticos de asignación

Se forman con las expresiones presentadas anteriormente y

nos indican los cálculos particulares que deben hacerse. Su forma es:

Variable = Expresión aritmética

El significado del signo = es el de asignación, esto es, que deberá calcularse el valor de la expresión a la derecha del signo = y su valor se asignará a la variable que se encuentre a la izquierda del signo, la cual tiene una localidad en la memoria de la computadora.

Ejem.      Si  $A=5.$ ,       $B=8.$ ,       $C=2.$       y       $D=1.6$   
 $X=(A+B)/C$  se le asignará a la X el valor 6.5  
 $ALO=(A+B)**2$  se le asignará a ALO el valor 169.  
 $RAI=SQRT(B*C)$  se le asignará a RAI el valor 4.  
 Algo diferente al algebra normal es el enunciado  $A=A+3.$  el cual no debe alarmarnos ya que indica que a la localidad de memoria con el nombre A se le asignará el nuevo valor  $A+3.$  esto es:  
 Si  $A=5.$  y  $A=A+3.$  entonces:  
 $A=5.+3.$        $A=8.$       o sea que la variable A se le asigna el valor de 8. y el valor anterior que fué 5. se pierde.

## 5.2 Los enunciados de control

Debido a que los enunciados de un programa FORTRAN se ejecutan en el orden que aparecen y que en muchas ocasiones queremos transferir la ejecución a otros enunciados si se satisface una



cierta condición, FORTRAN nos permite numerar dichos enunciados. Un número de enunciado debe ser una constante entera de uno a cinco caracteres, sin el signo más o menos; el número se coloca a la izquierda del enunciado.

Ejem.           3 CONT = CONT+1.  
                  24 RAIZ = SQRT (A\*\*2+B\*\*2)

### 5.2.1 El enunciado GO TO

Este toma la forma GO TO N en donde N es un número de enunciado.

El GO TO produce un salto incondicional; así GO TO 3 envía la ejecución al enunciado número 3 que puede ser la instrucción de conteo del ejemplo anterior. GO TO 24 pasa el control al enunciado 24 que puede ser el del ejemplo anterior.

Ejem. Supongamos que unos de los enunciados de un programa son:

I = 1	Esto nos representa la suma de
ISUM = 0	los números enteros; desde luego
1 ISUM = ISUM+I	es necesario ponerle otros enuncia-
I = I+1	dos pero por el momento nos aclara
GO TO 1	lo indicado.

### 5.2.2 El enunciado IF

Debido a que las computadoras están diseñadas a base de circuitos lógicos y el pensamiento del ser humano debe

## 16

ser de este tipo, nos concretaremos el IF lógico, además de que el alumno ya tiene elementos de algunos operadores de relación como OR, AND y NOT.

El IF lógico es de la forma:

IF (L) S

L= expresión lógica que puede tener dos valores: Verdadero o Falso.

S= cualquier enunciado FORTRAN diferente de: un DO, un enunciado de especificación o de otro IF lógico.

Si L es falso (.FALSE.) entonces se ignora S y la computación continúa al siguiente enunciado. Si L es verdadero (.TRUE.) el enunciado S se ejecuta en seguida.

Resulta interesante hacer notar que si L es relativamente complicada, éste IF puede ser el equivalente de varios IF aritméticos.

- Para formar las expresiones lógicas (L) utilizaremos los operadores de comparación y los de relación.

Operadores de comparación:

<u>Símbolo Matemático</u>	<u>Significado</u>	<u>Símbolo FORTRAN</u>	<u>Significado Inglés</u>
<	Menor que	.LT.	Less than
>	Mayor que	.GT.	Greater than
≤	Menor o igual a	.LE.	Less or equal
≥	Mayor o igual a	.GE.	Greater or equal

=	Igual a	.EQ.	Equal
≠	Diferente a ó No igual a	.NE.	Not equal

Operadores de relación:

U	Unión	.OR.	ó ('o inclusive)
∩	Intersección	.AND.	y ('al mismo tiempo)
—	Complemento	.NOT.	no

Para valuar una expresión lógica se hará con las siguientes prioridades:

- 1.- Expresiones entre paréntesis
- 2.- Operadores aritméticos
- 3.- Operadores de comparación (.LT., .GT., .LE., .GE., .EQ. y .NE.)
- 4.- .NOT.
- 5.- .AND.
- 6.- .OR.

En caso de igual jerarquía la evaluación será de izquierda a derecha.

Ejem. (1) X=5. y=0.5

IF (X.GT.3..AND. Y .LE.2.) Z=X\*\*3+X\*Y

Significa que si  $X > 3$ . y (al mismo tiempo)  $Y \leq 2$ .

se asignará a Z el valor que se obtenga al calcular  $X^3 + XY$ , esto es  $Z = 125 + 2.5 = 127.5$

(2) IF (A.LE.X.AND.B.GE. Y .OR.C.GT.Z) GO TO 12

Significa que si  $A \leq X$  y (al mismo tiempo)  $B \geq Y$  es

verdadero ó  $C > Z$  es verdadero ó ambos, entonces se transfiere el control al enunciado 12.

```

(3)  I = 1
      ISUM = 0
1    ISUM = ISUM+1
      I = I+1
      IF (I.LE.100) GO TO 1
      STOP

```

Esto nos indica que sólo sumaremos los números enteros del 1 al 100

5.2.3 El enunciado DØ

Este toma la forma:

```

DØ K I = L, M, N
DØ K I = L, M

```

La segunda forma sólo se aplica cuando  $N=1$ , lo que es bastante frecuente.

K representa un número de enunciado

I representa una variable entera

L, M, N son variables enteras ó constantes sin signo.

El DØ produce la ejecución repetida de todos los enunciados que le siguen, hasta el enunciado número K.

La primera vez que se ejecutan estos enunciados la variable I es igual a L, en cada paso subsiguiente I se incrementa en la cantidad N, hasta hacerse mayor ó igual a M en el paso final; en este momento se termina el llamado

lazo DØ y el control pasa al enunciado que está a continuación del enunciado K. Así, L es el valor inicial de la variable I y M su valor final. I se llama el índice del enunciado DØ y su valor corriente se puede usar en cálculos durante la ejecución del lazo. Todos los enunciados que le siguen al DØ hasta el número K inclusive constituyen el rango del DØ. También es posible que la variable I no se encuentre en ninguno de los enunciados del rango del DØ y esto nos indica que se realice la ejecución de todos los enunciados del rango del DØ M entre N veces (la parte entera de este cociente M/N). Debemos tomar en cuenta que: el índice I se incrementa secuencial y automáticamente durante la ejecución del lazo y que se puede, en estos momentos, tratar como cualquier variable entera; el índice I queda indefinido después de terminado el lazo del DØ y puede utilizarse para cualquier uso general. El enunciado K no debe ser un enunciado de especificación ni una transferencia de control esto incluye cosas como GØ TØ, IF y DØ, así como FORMAT, END y algunos otros. Debemos considerar que no se puede desde ningún punto del programa llegar a un enunciado dentro del rango de un DØ. Y que la entrada a un DØ deberá hacerse a través del enunciado DØ. Y por último es muy frecuente que un DØ esté completamente dentro de otro.

Ilustrando graficamente tenemos:

<u>Correcto</u>		<u>Incorrecto</u>	
DØ	DØ	DØ	DØ
DØ	DØ	DØ	DØ
DØ			DØ

Ejem. Utilizaremos un DØ para sumar los números enteros del 1 al 100, ejemplo que ya hemos visto anteriormente.

ISUM = 0

Nos damos cuenta que el DØ tie-

DØ 1 1 = 1,100

ne la misma función que un IF,

1 ISUM = ISUM+1

un GØ TØ y un contador; como po-

STOP

drá observarse con el ejemplo anterior.

#### 5.2.4 El enunciado STØP

Este aparece simplemente como STØP y es el que nos indica que ha terminado la ejecución y en el caso de IBM - 1130 la computadora se detiene y el operador tendrá que hacer que continúe trabajando. Debido a ello se recomienda que se utilice el enunciado CALL EXIT, el cual pasa el control a un programa monitor que hace que la computadora continúe ejecutando los otros programas que siguen a continuación.

Tanto el STØP como el CALL EXIT podrán aparecer después de cualquier enunciado.

### 5.3 Los enunciados de entrada y salida

Estos, como su nombre lo indica, sirven para introducir y sacar información de la computadora.

#### 5.3.1 El enunciado READ

Este enunciado tiene la forma READ (I, N) LISTA I y N son enteros sin signo y LISTA representa una lista de nombres de variables para las cuales se leerán valores. I designa el tipo de periférico de entrada que se utilice (lectora de tarjetas, consola, etc.). N es el número de un enunciado FORMAT asociado al READ.

Ejem. El enunciado READ (2, 101) J, B, H

Producirá la lectura de tres números: un entero y dos reales y se almacenarán en las localidades de la memoria de la computadora designadas con las variables J, B y H en su orden. Las comas que separan éstos nombres de variables en el READ son indispensables, 2 es la unidad de entrada y 101 un FORMAT.

#### 5.3.2 El enunciado WRITE

Este tiene la forma WRITE (I, N) LISTA I y N son enteros sin signo y LISTA representa una lista de variables para las cuales se imprimen valores. I designa el tipo de periférico de salida que se utilice (impresora, cinta, etc.). N es el número de un enunciado FORMAT aso-

ciado al WRITE.

Ejem. El enunciado WRITE (3, 108) L, X, Y

Producirá que se impriman los valores de las variables L, X y Y que se encuentren en las localidades de memoria con esos nombres, en el formato especificado por el enunciado número 108 y por la unidad de salida número 3; las comas que separan éstos nombres de variables en el WRITE son indispensables.

#### 5.4 Los enunciados de especificación

Este tipo de enunciados no inician por sí mismos los cálculos, no producen transferencia de control ni estimulan el flujo de información, pero proveen al compilador FORTRAN de los detalles esenciales para la traducción del programa fuente en FORTRAN al programa objeto en lenguaje de máquina ó para la conversión de datos a la entrada o la salida.

Si queremos introducir datos a la computadora lo podemos hacer mediante un enunciado que esté dentro del programa, como  $A = 3.1416$ , esto es lo que podríamos llamar inicializar una variable; y el programa se compilaría cada vez que quisieramos darle un valor diferente a A, lo cual resulta muy costoso, ya que las compilaciones son laboriosas. Para evitar esto se usa el enunciado READ y los valores que se le den a A podrán estar en tarjetas de datos, los cuales son independientes del programa.



ma fuente.

#### 5.4.1 El enunciado FØRMAT

Este tiene la forma: N FØRMAT ( , , , ... ) en la cual N es el número del enunciado FØRMAT y corresponde al N de los enunciados READ y WRITE. Los espacios entre las comas están disponibles para las especificaciones del tipo que se describen más adelante, siendo el número de espacios uno o más, de acuerdo a las necesidades del programador.

##### 5.4.1.1 La especificación I:lw

Aquí l indica un valor entero y w es un entero que indica el número de columnas o ancho de campo, que ocupa ese valor en la tarjeta de entrada o en el papel de impresión. El número w deberá incluir un lugar para el signo de ese valor, siendo + opcional.

Ejem. Valor de los datos

de entrada o salida: 1130 +1620 -370 0 +14

Especificación: 14 15 14 11 13

##### 5.4.1.2 La especificación F:Fw.d

Aquí F indica un valor real, w indica el número de columnas que ocupará el valor en la tarjeta de entrada o en el papel de impresión; d indica el número de cifras que se encontrarán des-

pués del punto decimal. w deberá incluir un lugar para el signo y otro para el punto decimal.

Ejem. Valor de los datos de  
entrada ó salida: 32.787 -.007 1130: +3.70  
Especificación: F6.3 F5.3 F5.0 F5.2

5.4.1.3 La especificación E:Ew.d

Aquí E indica un valor real en forma exponencial y w indica la anchura de campo para ese valor y debe de incluir el signo, si lo hay, el punto decimal, el lugar para la letra E, un lugar para el signo del exponente, si es negativo, y dos lugares para el exponente; d indica el número de dígitos a la derecha del punto decimal.

Ejem. Valor de los datos  
de entrada o salida: .1403E04 -.7E-02 .1442E+04  
Especificación: .E8.4 E7.1 E9.4

Es conveniente que cuando deseemos sacar información de la computadora, tomemos en cuenta para el ancho del campo lo siguiente:

- 1.- El signo, aún cuando el + generalmente no se imprime.
- 2.- El punto decimal para las especificaciones F y E.
- 3.- Por lo menos un dígito a la izquierda

del punto decimal, puesto que muchas máquinas imprimirán allí un cero si otro dígito no ocurre.

- 4.- Suficientes lugares para todos los dígitos significativos deseados, debido a que para los dígitos que no se les deja espacio se truncan o redondean.
- 5.- Cuatro lugares para el exponente de la especificación E.
- 6.- El primer lugar se deja en blanco para el control de carro.

5.4.2 El enunciado END

Este se lee simplemente END e informa al compilador que el programa fuente ha terminado y debe ser el último enunciado de cualquier programa FORTRAN.

6.- Arreglos

Frecuentemente tratamos con un grupo de variables que forman o pertenecen a una clase o colección. Cuando las variables forman un conjunto ordenado, pueden relacionarse unas con otras por la notación de subíndices; entonces designamos esa colección como arreglo y las variables que pertenecen a ésta serie son los elementos del arreglo. A veces se emplea como sinónimo de

arreglo el nombre de matriz y, en consecuencia, hablamos de elementos de la matriz.

6.1 Variables con subíndices

Un conjunto de números que pueda arreglarse en un renglón ó columna se considera como un arreglo lineal ó unidimensional, y ésta serie puede llamarse vector. Identificamos los elementos de un vector renglón ó columna por un sólo subíndice.

Ejem. La columna de números del vector llamado A, consiste de los elementos A<sub>1</sub> hasta A<sub>N</sub> inclusive y se representa como sigue:

Notación asoctumbrada	Notación FORTRAN
A <sub>1</sub>	A (1)
A <sub>2</sub>	A (2)
A <sub>3</sub>	A (3)
A <sub>i</sub>	A (i)
A <sub>N</sub>	A (N)

Cada una de estas A(i), en donde i varía de 1 a N, son el nombre de una variable, el conjunto de todas ellas es lo que llamamos arreglo.

Si se usan dos subíndices para identificar los elementos de un arreglo se considera éste como un arreglo bidimensional. Los cuadros de un tablero de ajedrez, pueden considerarse como un arreglo bidimensional. Y si llamamos a cualquiera de los cua-

dros con la variable CTAJ tendremos 64 variables; pero como el tablero tiene 8 renglones y 8 columnas, podemos referirnos al cuadro que se encuentra en el renglón 3 y la columna 5 con la variable CTAJ(3,5).

Dependiendo del tipo de computadora será el número de subíndices que podremos asignarle a un arreglo; en IBM - 1130 sólo se admiten arreglos con un máximo de tres subíndices.

Las variables que se utilicen para designar arreglos deberán observar las reglas que se dieron anteriormente al hablar de variables enteras y reales considerando que para los cinco caracteres alfanuméricos son independientes de los índices que se encuentran entre paréntesis.

#### 6.1.1 Reglas para los subíndices.

Regla 1 Un subíndice debe ser un entero, puede ser constante, variable ó una de las expresiones aritméticas siguientes:

$$A * V + b \quad A * V - b$$

en donde v es una variable entera y a y b son constantes enteras sin signo.

Ejem. Algunos subíndices pueden ser:

1 1972 10\*KONT 2\*1 J

1976\*N-8 2\*1-4 2\*1+3

No se pueden usar como subíndice:

1+1 -1 2-10\*CONT -1932 -KILG

Regla 2 Un subíndice sólo debe tomar valores positivos.

Regla 3 Un subíndice en sí no debe ser una variable con subíndices. Así X(1(2)) no es permitido.

Regla 4 Un símbolo que representa un arreglo, una variable con subíndice, no debe usarse sin subíndices para representar otra variable diferente en el mismo programa. Esto es A(1) y A no deben referirse a variables diferentes. Como siempre hay una excepción que por ahora no tocaremos.

Ejem. Los símbolos para variables reales con subíndices podrían incluir:

X(I) SUM(K+2) A(I, 2\*J+1) B(INT) C(I,J)

Para variables enteras con subíndices podemos tener:

INT(M,N) I(J) ICTA(J,2\*1)

6.2 El enunciado DIMENSION

Siempre que en un programa utilicemos variables con subíndices deberemos poner como primer enunciado el DIMENSION, el cual indica al compilador qué tanto espacio de memoria se debe reservar para las variables con subíndices. Su forma es:

DIMENSION u, v, w, ...

Donde u, v, w, ... son nombres de variables, cada una de las cuales va seguida por el máximo número de elementos en el

arreglo correspondiente. Deberán observarse las siguientes reglas:

Regla 1 Cada variable con subíndices se debe mencionar en un enunciado DIMENSION antes de su primer uso en el programa.

Regla 2 Los símbolos representados anteriormente por u, v, w, ... deben tener la forma:

nombre de variable (máximo número de elementos)

el número entre paréntesis debe ser una constante entera sin signo.

Ejem. DIMENSION A(20), B(4,8), CARR(5,3,4)

Esto indica que el compilador reservará 20 localidades para el arreglo A, sus veinte variables serán A(1), A(2), ..., A(20) al mismo tiempo se reservarán 32 (4x8) localidades para las variables B(1,1), B(1,2), B(1,3), ..., B(1,8), B(2,1), B(2,2), ..., B(2,8), B(3,1), B(3,2), ..., B(3,8), B(4,1), B(4,2), ..., B(4,8) y por último se reservarán 60 (5x3x4) localidades para las variables del arreglo CAR, con tres subíndices cada una.

Regla 3 El arreglo que se use en particular, dentro del programa podrá tener menos elementos que los especificados en la magnitud del enunciado DIMENSION, pero no más.

Regla 4

La variable tal como aparece en el enunciado DIMEN-  
SION debe tener exactamente el mismo número de sub-  
índices que en cualquier otra parte del programa.



## 7.- SUBPROGRAMAS.

Los subprogramas; también llamados subrutinas, son programas que pueden ser puestos en uso por otros programas cuando sea necesario.

Las funciones de biblioteca ó funciones del sistema constituyen una variedad de subprogramas.

### 7.1- FUNCIONES

Cuando el valor de una variable depende de una ó más variables ó constantes y además de una serie de cálculos, y dicha variable ha de calcularse repetidamente y en diferentes puntos de un programa, es posible definirla como una función. En otras palabras, Además de las funciones con que cuenta la biblioteca del sistema, el usuario puede escribir sus propias funciones para uso específico de su programa.

Tomemos un ejemplo para visualizar lo anterior:

Supongamos que para un programa en especial, en el cual trabajamos con grados en lugar de radianes, deseamos calcular continuamente  $\text{SENØ} (X)$ , sin el uso de funciones sería necesario transformar el argumento deseado de grados a radianes y después llamar a la función del sistema  $\text{SIN} (X)$ . A continuación presentamos una función que calculará  $\text{SENØ} (X)$ , ( $X$  en grados) :

```

FUNCTION SENØ ( X )
  X = X * 3.14 15 92/180.
  SENØ = SIN (X)
  RETURN
END

```

que es llamada desde el programa como:

```
GRAD= SENØ (GRADØS)
```

En base a éste ejemplo podemos generalizar el uso de la proposición FUNCTION .

- Debe ser codificada en forma independiente del programa que la usará, es decir, no debe aparecer "dentro" del programa.
- Debe empezar con la palabra FUNCTION

· FUNCTION nombre (parámetro )

- c) A continuación se escribe el nombre con que será llamada.  
 d) Después, entre paréntesis y separados por comas, aparecen los argumentos.

### 7.1.1 EJEMPLOS.-

```

FUNCTION RAIZ1 (A,B,C )
RAIZ1= (-B + SQRT (B **2 - 4. * A * C )) / ( 2.* A )
RETURN
END
FUNCTION RAIZ2 ( A, B, C )
RAIZ2 = ( -B - SQRT (B**2.4.* A * C )) / (2.* A )
RETURN
END

```

---

```

C      EC. SEGUNDO GRADO
      READ ( 2,100) A, B, C
100    FORMAT ( 3F10.5)
      X1 = RAIZ1 (A,B,C)
      X2 = RAIZ2 (A,B,C)
      WRITE (3,200) A,B,C, X1,X2
200    FORMAT ( 5 ( : ,F10.5' )
      CALL EXIT
      END

```

Este ejemplo es solamente para mostrar el uso de la proposición FUNCTION y no contempla algunas situaciones como raíces complejas, etc.

### 7.2 SUBROUTINAS

Como es fácil notar, la proposición FUNCTION nos "regresa" un sólo valor y lo hace a través de su nombre. En muchos casos es conveniente ó necesario que se nos regrese más de un valor, para éstos casos usamos la proposición o enunciado:

#### SUBROUTINE.

Una subrutina es un subprograma que puede "recibir" cualquier número de parámetros ( desde cero hasta un número determinado por el tipo de compilador) y puede "regresar" diferentes valores calculados.

Veamos algunos ejemplos:

Supongamos que al imprimir resultados de un cierto programa tenemos que - escribir algún título usando los primeros renglones de la hoja. En tal caso podemos hacer uso de una subrutina como sigue:

```

SUBROUTINE ENCA
WRITE (3,200)
200--  FORMAT-(/,1X, 'REPORTE SEMANAL' , / )
RETURN
END

```

Como vemos no hemos pasado ningún parámetro ó valor a la subrutina. Para - que se ejecute ésta se debe hacer uso de la proposición CALL, de la siguiente forma:

```
CALL ENCA
```

dentro del programa y en el lugar donde deseemos que ocurra la impresión.

Discutamos ahora un ejemplo muy simple para ejemplificar el uso de parámetros. Hagamos una subrutina que "reciba" como entrada dos números, los sume y el resultado lo "regrese" en otra variable. Sean A y B los números a sumar, y C la variable en donde se pondrá el resultado.

```

SUBROUTINE SUMA (A,B,C )
C = A + B
RETURN
END

```

Es importante detenerse a ver el significado de los parámetros para las subrutinas:

La subrutina anterior SUMA puede ser llamada de diversas formas:

```

CALL SUMA (AA, BB, CC)
CALL SUMA (4, 7, X )
etc.

```

Como vemos, las variables A, B y C que aparecen en la subrutina son variables

mudas o dormidas y solo tienen sentido dentro de la subrutina. Veamos lo anterior:

Supóngase el siguiente programa:

```

      X1= 3.
      X2= 4.
      CALL SUMA ( X1,X2,X3)
      SUM= X3
      WRITE (3,200) X1,X2,X3, SUM
200   FORMAT(4 F10.5)
      CALL EXIT
      END

```

Se propone como ejercicio al lector que haga las veces de la máquina y escriba lo que ésta imprimiría.

La máquina imprimirá :

```

3.0      4.0      7.0      7.0

```

Una de las facilidades más útiles en subrutinas es la de <sup>pasar</sup> arreglos como parámetros, ej:

```

SUBROUTINE MAXIM (A, MAX)
  DIMENSION      A ( 10)
  -----
  -----
  -----
  -----
  -----
  RETURN
END

```

Supóngase que ésta subrutina encuentra el elemento del arreglo A (10) con mayor valor y lo regresa a través de la variable MAX. Es importante notar que si pasamos como parámetro uno ó más arreglos hay que dimensionarlos otra vez dentro de la subrutina, lo cual se puede hacer de al menos dos formas: 1) poniendo la dimensión que aparece en el programa que lo llama;

2) Poniéndole dimensión 1 (uno)

Ejemplo:

DIMENSION A (10) , B (20).

-----  
-----  
-----  
-----

CALL ØRDEN (A)

CALL MAXIM (B)

CALL MAXIM (A)

-----  
-----  
-----  
-----

CALL EXIT

END

Caso 1:

SUBROUTINE ØRDEN (X)

DIMENSION X (10)

-----  
-----  
-----  
-----

RETURN

END

Caso 2:

SUBROUTINE MAXIM (Y)

DIMENSION Y (1)

-----  
-----  
-----

RETURN

END

## 7.2.1 COMMON.-

Como es posible visualizar en los párrafos anteriores, las variables usadas en las subrutinas, o mejor dicho, dentro de las subrutinas, son totalmente independientes a las variables usadas en el programa principal. Muchas veces es conveniente que tanto las subrutinas como el programa que las llama tengan variables en COMUN. Para lograr esto existe la declaración

COMMON

La forma general de ésta proposición es:

COMMON lista de variables

donde "lista de variables" es un conjunto de variables y/o arreglos separados por comas a las cuales queremos adjudicarles la propiedad anterior, es decir, sean comunes a varios subprogramas.

Ej.

COMMON A,B, X (10), AB (30)

Esta declaración debe aparecer al principio de cualquier programa o subrutina en que se desee usar. Veamos un ejemplo:

```

C   SUMA DE DOS NUMEROS
COMMON A, B, C
A= 3
B= 7
CALL SUMA
Z = C
WRITE (3,200) A, B, C, Z
200 FORMAT( 4 F10.5 )
CALL EXIT
END

```

```
SUBROUTINE SUMA
COMMON A, B, C
C = A + B
RETURN
END
```

Este programa debe imprimir :

```
3.0    7.0    10.0    10.0
```

Una propiedad importante del COMMON es que si un arreglo es especificado en COMMON que dá automáticamente dimensionado, es decir, no hay que especificar dicho arreglo a través de la declaración DIMENSION .

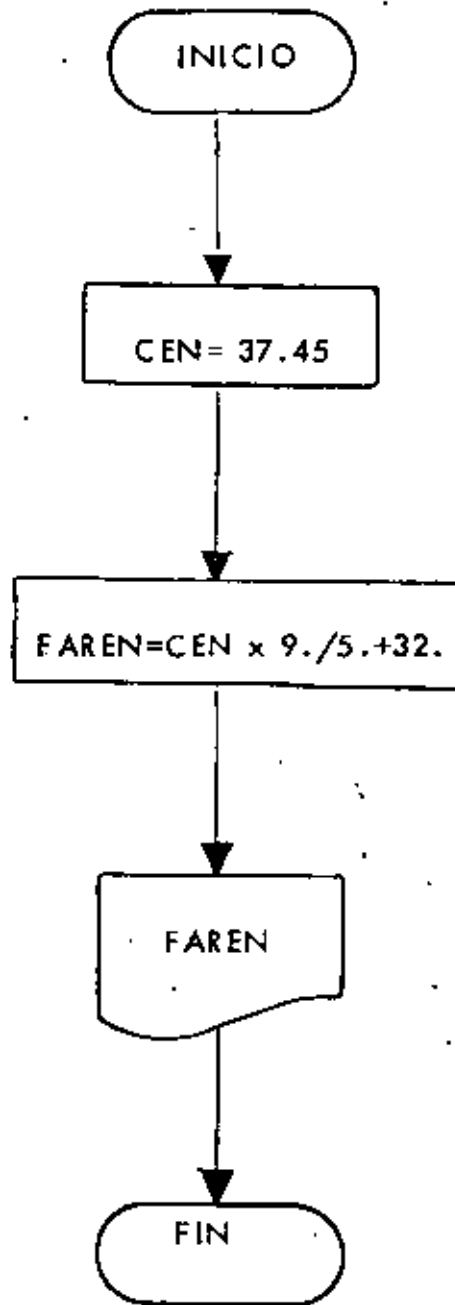
En las siguientes páginas se muestran veintidós programas, que incluyen sus diagramas de flujo, codificaciones, datos y resultados; el objeto es que el lector pueda complementar la parte teórica con la práctica, amén de que debe rá hacer los propios y procesarlos en una computadora a su alcance.

## REFERENCIAS BIBLIOGRAFICAS:

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- 3.- E.I. Organick : Fortran IV  
Fondo Educativo Interamericano, S. A.  
1966
- 4.- Francis Scheid : Introducción a la Ciencia de  
las Computadoras.  
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- 5.- W.Schick y Ch. J.  
Merz, Jr. : Fortran para Ingeniería.  
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- 6.- R.E. Smith y D.E.  
Johnson : Fortran, Texto Programado.  
Limusa Wiley - 1971



"CONVERSION DE GRADOS CENTIGRADOS A  
GRADOS FARENHEIT"

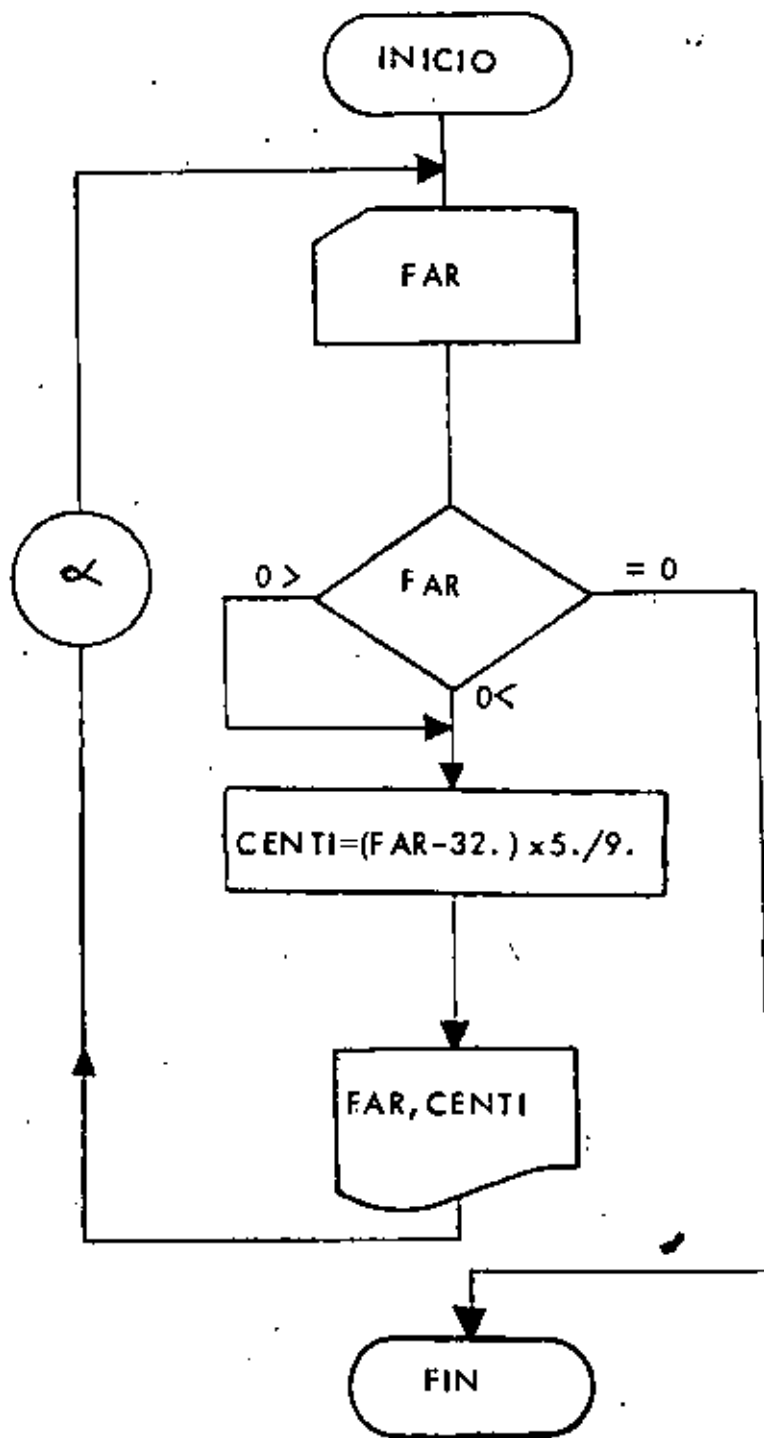


```
// JOB T  
// FOR  
*LIST SOURCE PROGRAM  
*ONE WORD INTEGERS  
*IOCS(CARD,1132,PRINTER)
```

```
C-----U N 0-----  
C   CONVERSION DE GRADOS CENTIGRADOS A  
C   GRADOS FARENHEIT  
 100 FORMAT(F10.4)  
    IMP=3  
    CEN=37.45  
    FAREN=CEN*9./5.+32.  
    WRITE(IMP,100)FAREN  
    CALL EXIT  
    END  
// XEQ  
/*
```

RESULTADOS


99.4100



```

// JOB T
// FOR
*LIST SOURCE PROGRAM
*ONE WORD INTEGERS
*IOCS(CARD,1132 PRINTER)
C-----D O S-----
C      CONVERSION DE GRADOS FAHENEHT A
C      GRADOS CENTIGRADOS
100 FORMAT(F10.4)
101 FORMAT(F10.4,22H GRADOS FAHENEHT SON ,F10.4,20H GRADOS CENTIGRADO
1S.)
LEE=2
IMP=3
200 READ(LEE,100)FAR
C      FAR IGUAL CERO INDICA TERMINO DE DATOS.
      IF(FAR)210,220,210
210   CENTI=(FAR-32.)*5./9.
      WRITE(IMP,101)FAR,CENTI
      GO TO 200
220 CALL EXIT
      END
// XEQ
1260000
126.
-14.
18.26
0.0
/*

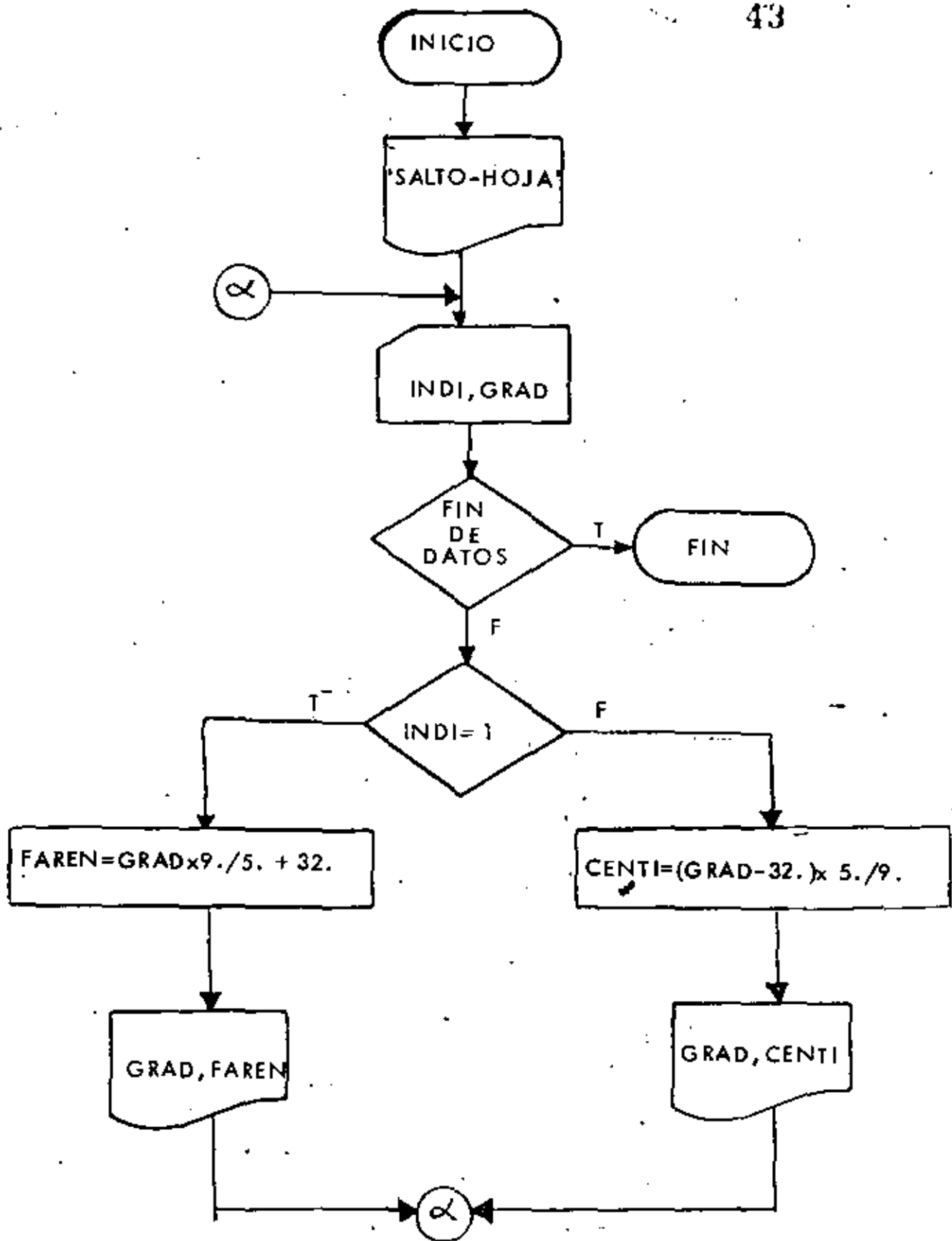
```

RESULTADOS

126.0000 GRADOS FAHENEHT SON	52.2222 GRADOS CENTIGRADOS.
126.0000 GRADOS FAHENEHT SON	52.2222 GRADOS CENTIGRADOS.
-14.0000 GRADOS FAHENEHT SON	-25.5556 GRADOS CENTIGRADOS.
18.2600 GRADOS FAHENEHT SON	7.1633 GRADOS CENTIGRADOS.

"CONVERSION ENTRE GRADOS FARENHEIT Y GRADOS CENTIGRADOS"

43



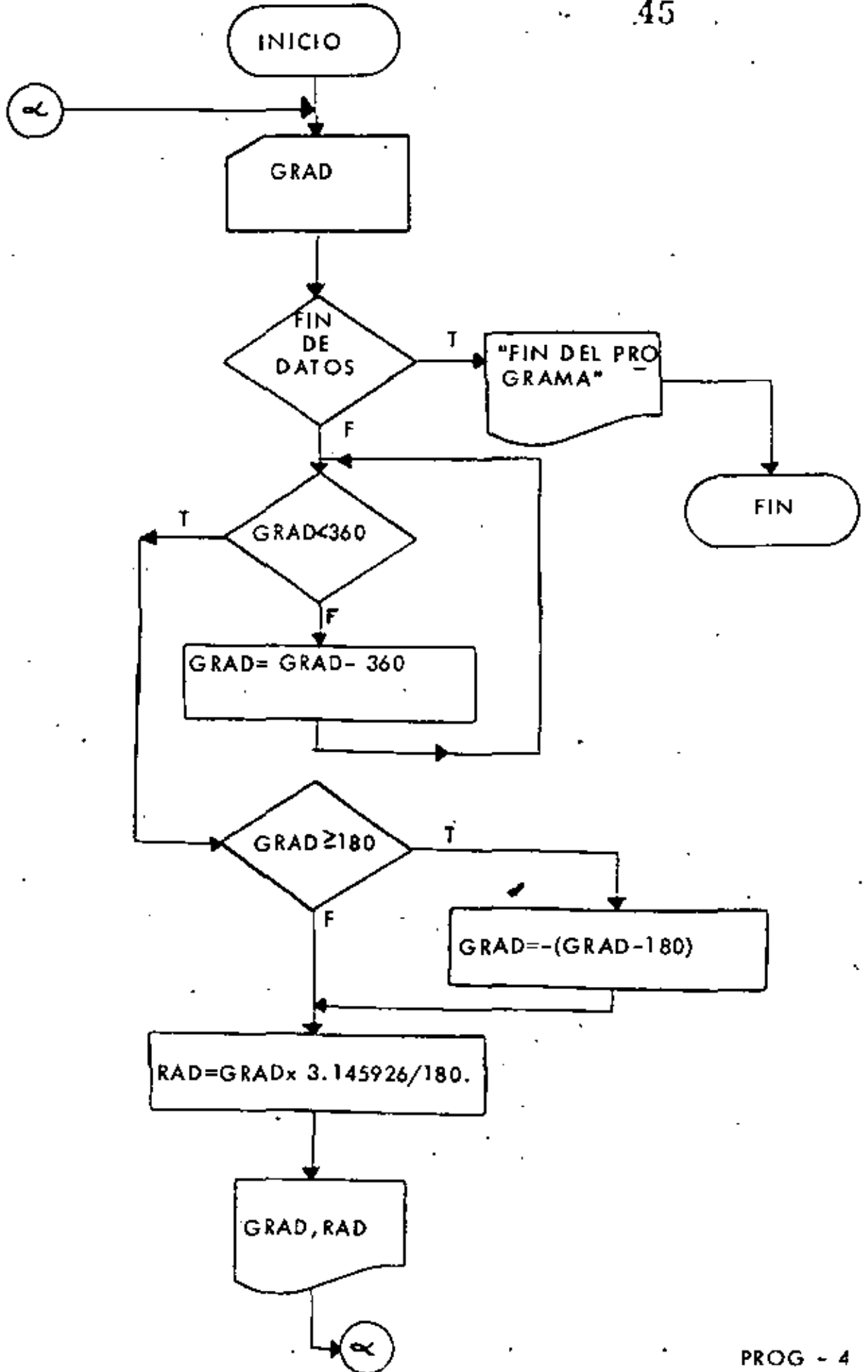
```
// JOB T
// FOR
*LIST SOURCE PROGRAM
*ONE WORD INTEGERS
*IOCS(CARD,1132 PRINTER)
```

```
C-----T R E S-----
C   CONVERSION ENTRE GRADOS FARENHEIT
C           Y GRADOS CENTIGRADOS
100 FORMAT(1H1)
101 FORMAT(11,F10.3)
102 FORMAT(F10.2,15H FARENHEIT SON ,F11.3,13H CENTIGRADOS.)
103 FORMAT(F10.2,17H CENTIGRADOS SON ,F9.3,11H FARENHEIT.)
   LEE=2
   IMP=3
   WRITE(IMP,100)
200 READ(LEE,101,END=220)INDI,GRAD
   IF(INDI.EQ.1)GO TO 210
C   INDI DIFERENTE DE 1 DATO EN GRADOS FARENHEIT.
C   SE CONVIERTE A CENTIGRADOS.
   CENTI=(GRAD-32.1)*5./9.
   WRITE(IMP,102)GRAD,CENTI
   GO TO 200
210 CONTINUE
C   EL DATO ES EN GRADO CENTIGRADO.
C   SE CONVIERTE A FARENHEIT.
   FAREN=GRAD*9./5.+32.
   WRITE(IMP,103)GRAD,FAREN
   GO TO 200
220 CALL EXIT
   END
```

```
// XEQ
1   12000
0   11.48
1   0.
2   32.00
1  -16.
1   18.
/*
```

RESULTADOS

12.00	CENTIGRADOS SON	53.600	FARENHEIT.
11.48	FARENHEIT SON	-11.400	CENTIGRADOS:
0.00	CENTIGRADOS SON	32.000	FARENHEIT.
32.00	FARENHEIT SON	0.000	CENTIGRADOS:
-10.00	CENTIGRADOS SON	3.200	FARENHEIT.
10.00	CENTIGRADOS SON	68.400	FARENHEIT.



```
// JOB T
// FOR
*LIST SOURCE PROGRAM
*ONE WORD INTEGERS
*IOCS(CARD,1132 PRINTER)
C-----C U A T R O-----
```

```
C      CONVERSION DE GRADOS A RADIANTES
101  FORMAT(F8.3)
102  FORMAT(F9.3,12H GRADOS SON ,F6.3,10H RADIANTES.)
103  FORMAT(///,10X,16HFIN DEL PROGRAMA)
      LEE=2
      IMP=3
200  READ(LEE,101,END=230)GRAD
210  IF(GRAD.LT.360)GO TO 220
C      EL DATO ES IGUAL O SOBREPASA LOS 360-GRADOS(SE AJUSTA).
      GRAD=GRAD-360.
      GO TO 210
220  CONTINUE
C      SE TRABAJA ENTRE +180 Y -180 GRADOS.
      IF(GRAD.GE.180.)GRAD=-1GRAD-180.)
      RAD=GRAD*3.1415926/180.
      WRITE(IMP,102)GRAD,RAD
      GO TO 200
230  WRITE(IMP,103)
      CALL EXIT
      END
```

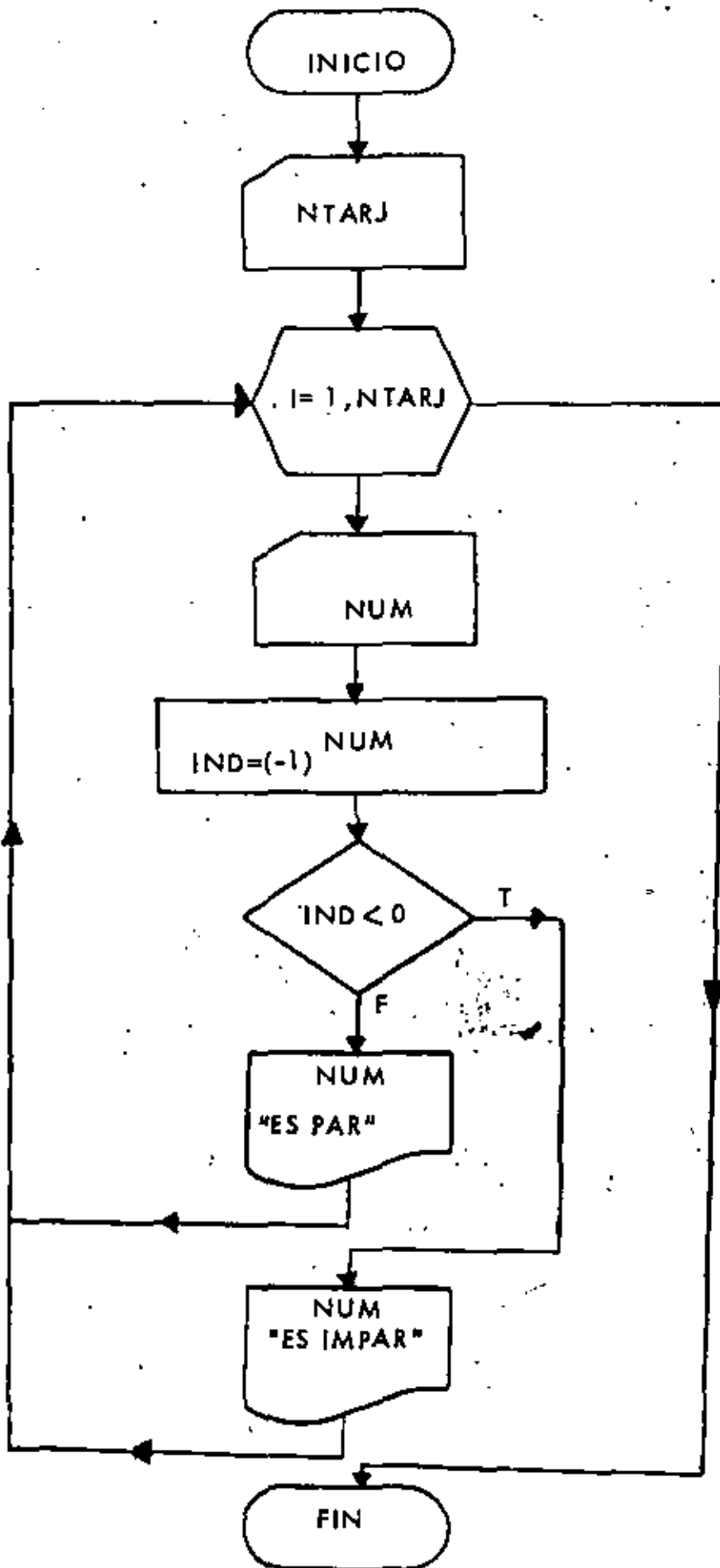
```
// XEQ
90000
-90.
3600.
-380.
0.0
185.27
132.4
-79.9
/*
```

### RESULTADOS

GRADOS	SON	RADIANTES
-90.000	SON	-1.571 RADIANTES.
90.000	SON	1.571 RADIANTES.
0.000	SON	0.000 RADIANTES.
-380.000	SON	-6.632 RADIANTES.
0.000	SON	0.000 RADIANTES.
51270	SON	6.642 RADIANTES.
132.400	SON	2.311 RADIANTES.
-79.900	SON	-1.395 RADIANTES.

FIN DEL PROGRAMA





// JOB T  
// FOR

48

48

\*LIST SOURCE PROGRAM  
\*ONE WORD INTEGERS  
\*IOCS(CARD,1132 PRINTER)

C-----C I N C O-----

C DETERMINACION DE NUMEROS PARES  
C E IMPARES

100 FORMAT(I3)  
101 FORMAT(I4, 'H ES PAR. )  
102 FORMAT(I4, 'H ES IMPAR. )

LEE=2  
IMP=3  
READ(LEE,100)NTARJ

C NTARJ INDICA NO. DE TARJETAS CON DATOS.  
DO 202 I=1,NTARJ

READ(LEE,100)NUM  
IND=(-1)\*\*NUM  
IF(IND.LT.0)GO TO 200

C EL NUMERO ES PAR.  
WRITE(IMP,101)NUM  
GO TO 201

200 CONTINUE  
C EL NUMERO ES IMPAR.  
WRITE(IMP,102)NUM

201 CONTINUE

202 CONTINUE  
CALL EXIT  
END

// XEQ

005

17

1

14

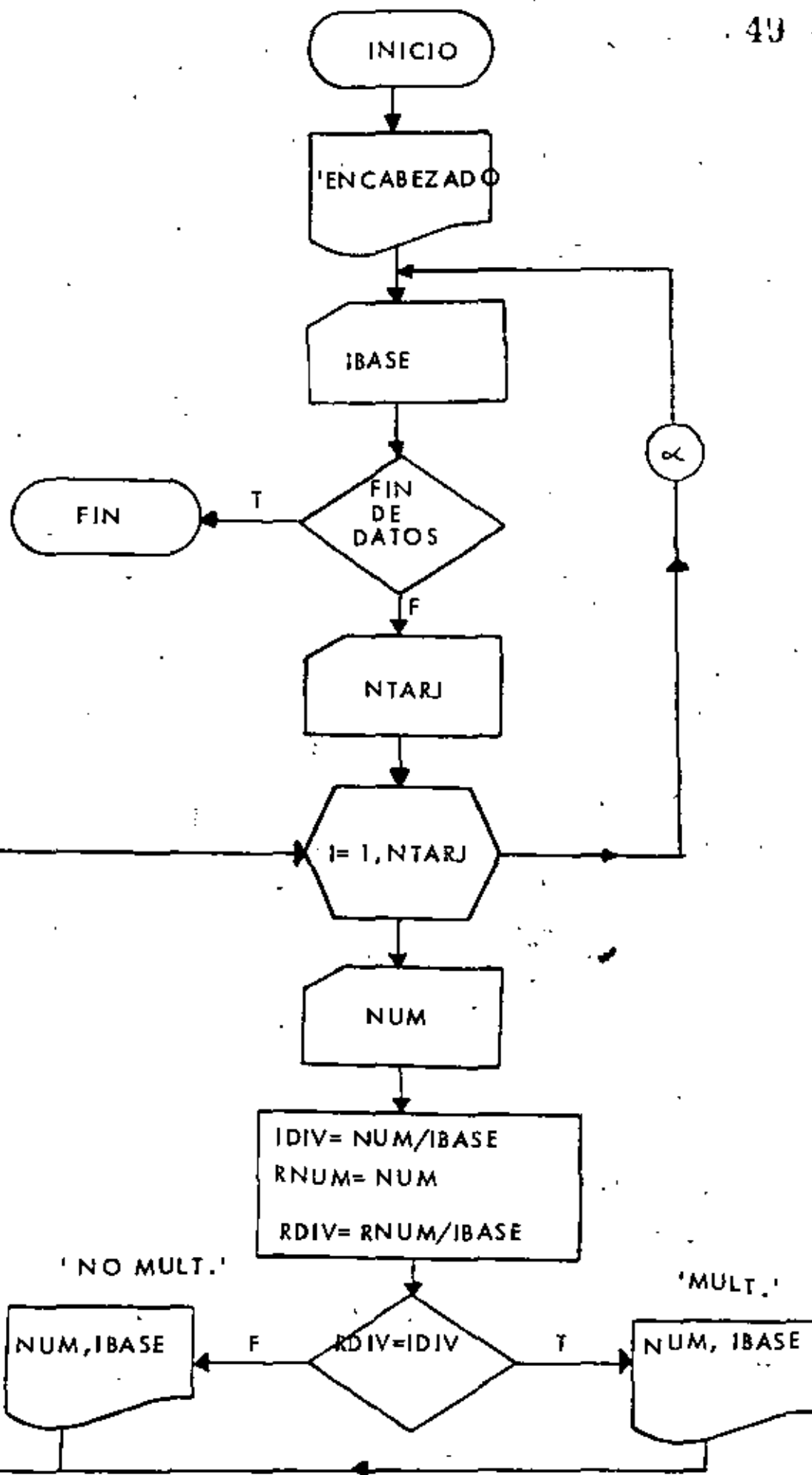
291

8

/\*

### RESULTADOS

17	ES	IMPAR.
1	ES	IMPAR.
14	ES	PAR.
291	ES	IMPAR.
8	ES	PAR.



```
// JOB T
// FOR
*LIST SOURCE PROGRAM
*ONE WORD INTEGERS
*IOCS(CARD,1132 PRINTER)
```

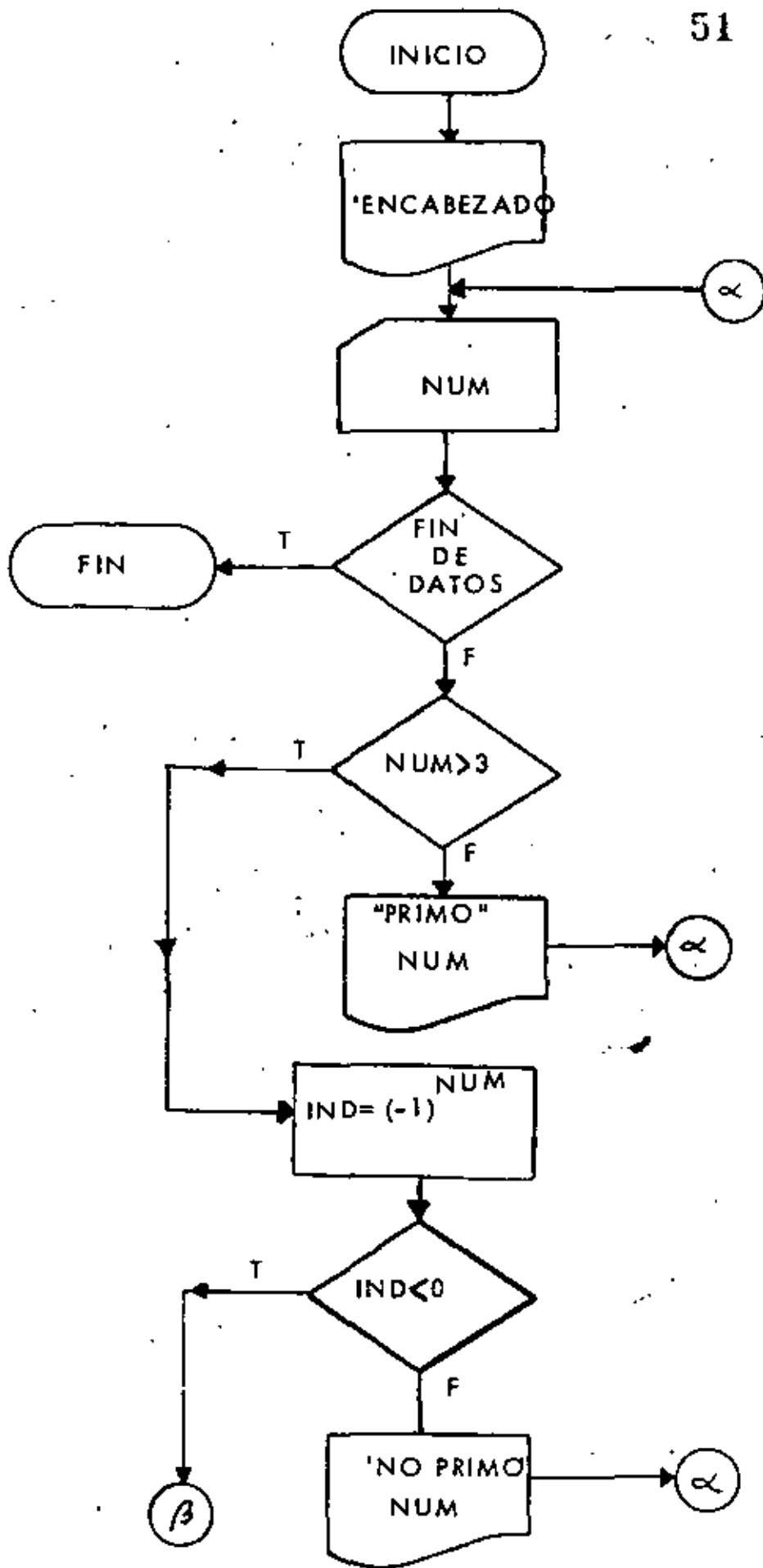
50

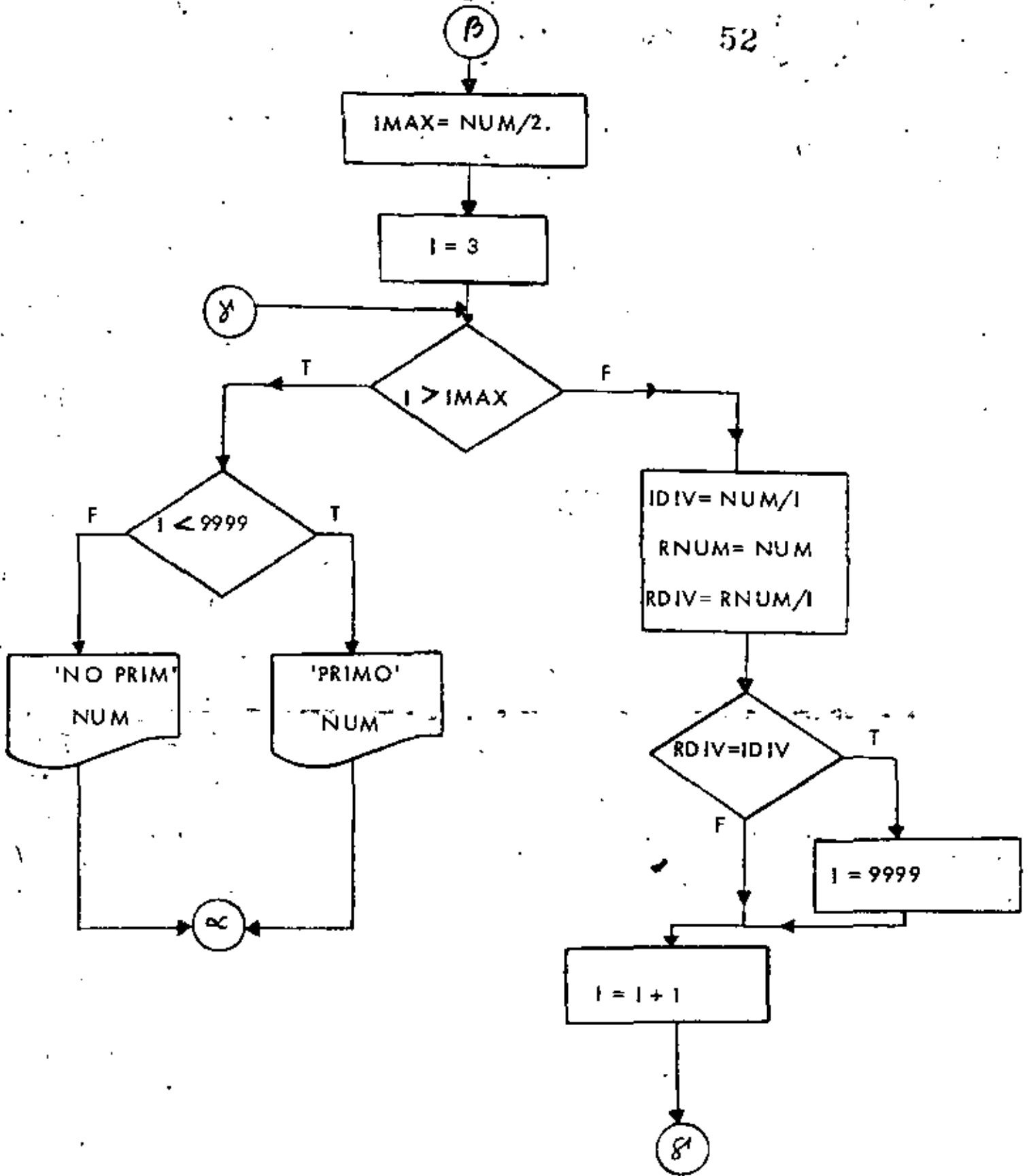
```
C-----S E I S-----
C   DETERMINACION DE MULTIPLOS
C   DE UN NUMERO
100 FORMAT(I3)
101 FORMAT(34H|NUMERO-MULTIPLO DE=NO MULTIPLO DE)
102 FORMAT(2X,I3,7X,I3)
103 FORMAT(2X,I3,21X,I3)
    LEE=2
    IMP=3
    WRITE(IMP,101)
200 READ(LEE,100,END=240)IBASE
    HEAD(LEE,100)NTARJ
    DO 230 I=1,NTARJ
      READ(LEE,100)NUM
      IDIV=NUM/IBASE
      RNUM=NUM
      RDIV=RNUM/IBASE
      IF(RDIV.EQ.IDIV)GO TO 210
C     NUM NO ES MULTIPLO DE IBASE.
      WRITE(IMP,103)NUM,IBASE
      GO TO 220
210  CONTINUE
C     NUM SI ES MULTIPLO DE IBASE.
      WRITE(IMP,102)NUM,IBASE
220  CONTINUE
230  CONTINUE
      GO TO 200
240  CALL EXIT
      END
```

```
// XEQ
002
005
17
001
14
291
8
003
002
9
11
005
001
009
/*
```

### RESULTADOS

NUMERO	MULTIPLO DE	NO MULTIPLO DE
1	2	2
14	2	2
291	3	3
8	3	3
11	3	3
9	3	3





// JOB T  
// FOR

\*LIST SOURCE PROGRAM  
\*ONE WORD INTEGERS  
\*10CS(CARD,1132 PRINTER)

C-----S I E T E-----

```
C      NUMEROS PRIMOS
.100  FORMAT(I3)
.101  FORMAT(19H1PRIMOS -NO PRIMOS)
.102  FORMAT(2X,I3)
.103  FORMAT(14X,I3)
      LEE=2
      IMP=3
      WRITE(IMP,101)
200  READ(LEE,100,END=290)NUM
      IF(NUM.GT.3)GO TO 210
C      NUM ES MENOR O IGUAL A 3(TODO NUMERO NATURAL MENOR O IGUAL A 3 ES
      WRITE(IMP,102)NUM
      GO TO 280
210  CONTINUE
C      NUM ES MAYOR QUE 3.
      IND=(-1)**NUM
      IF(IND.LT.0)GO TO 220
C      NUM ES PAR(TODO NUMERO PAR MAYOR QUE 3 NO ES PRIMO.).
      WRITE(IMP,103)NUM
      GO TO 270
220  CONTINUE
C      NUM ES IMPAR(SE INICIA PROCESO DE PRIMO O NO-PRIMO).
      IMAX=NUM/2
      I=3
230  IF(I.GT.IMAX)GO TO 240
C      SE OBTIENEN LAS DIVISIONES ENTERA Y REAL DE NUM/I
C      CON I DE 3 HASTA NUM/2.
      IDIV=NUM/I
      RNUM=NUM
      RDIV=RNUM/I
      IF(RDIV.EQ.IDIV)I=9999
C      I=9999 INDICA QUE NUM ES PRIMO.
      I=I+1
      GO TO 230
240  CONTINUE
      IF(I.LT.9999)GO TO 250
C      NUM NO ES PRIMO.
      WRITE(IMP,103)NUM
      GO TO 260
250  CONTINUE
C      NUM ES PRIMO.
      WRITE(IMP,102)NUM
260  CONTINUE
270  CONTINUE
280  CONTINUE
      GO TO 200
290  CALL EXIT
      END
```

// XEQ  
1  
2  
3  
4  
5  
6  
7  
8

10  
11  
12  
13  
15  
17  
19  
21

RESULTADOS

PRIMOS	NO PRIMOS
1	
2	
3	
5	4
7	6
	8
	10
11	12
13	15
17	
19	21



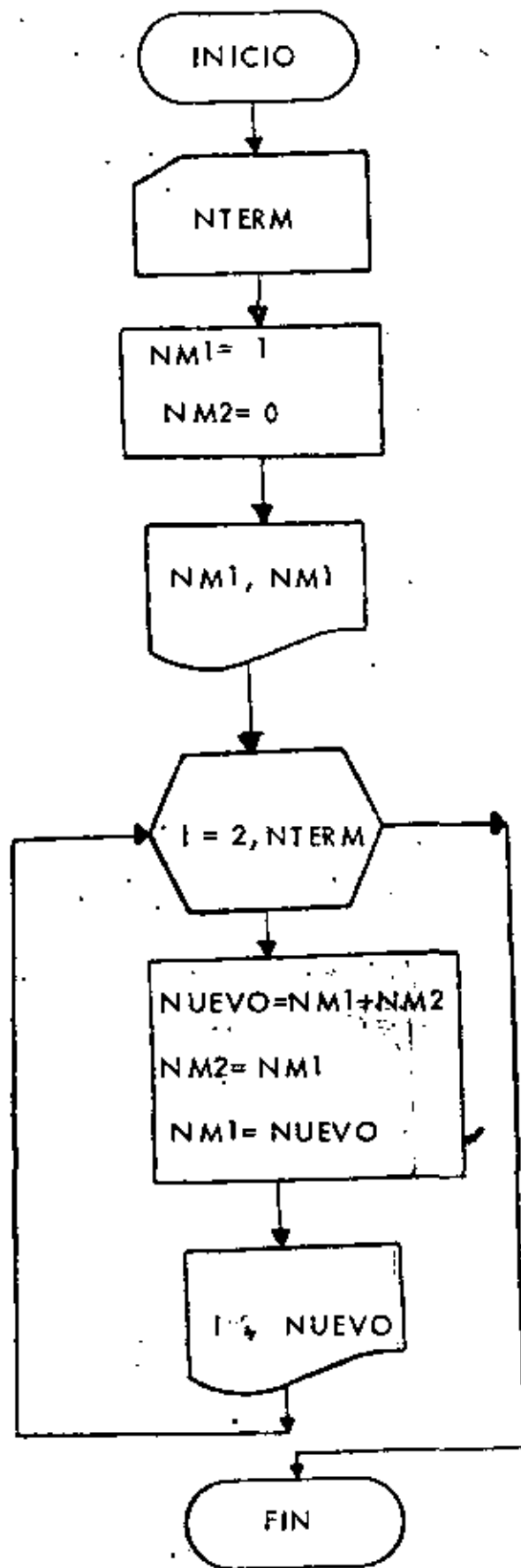
```

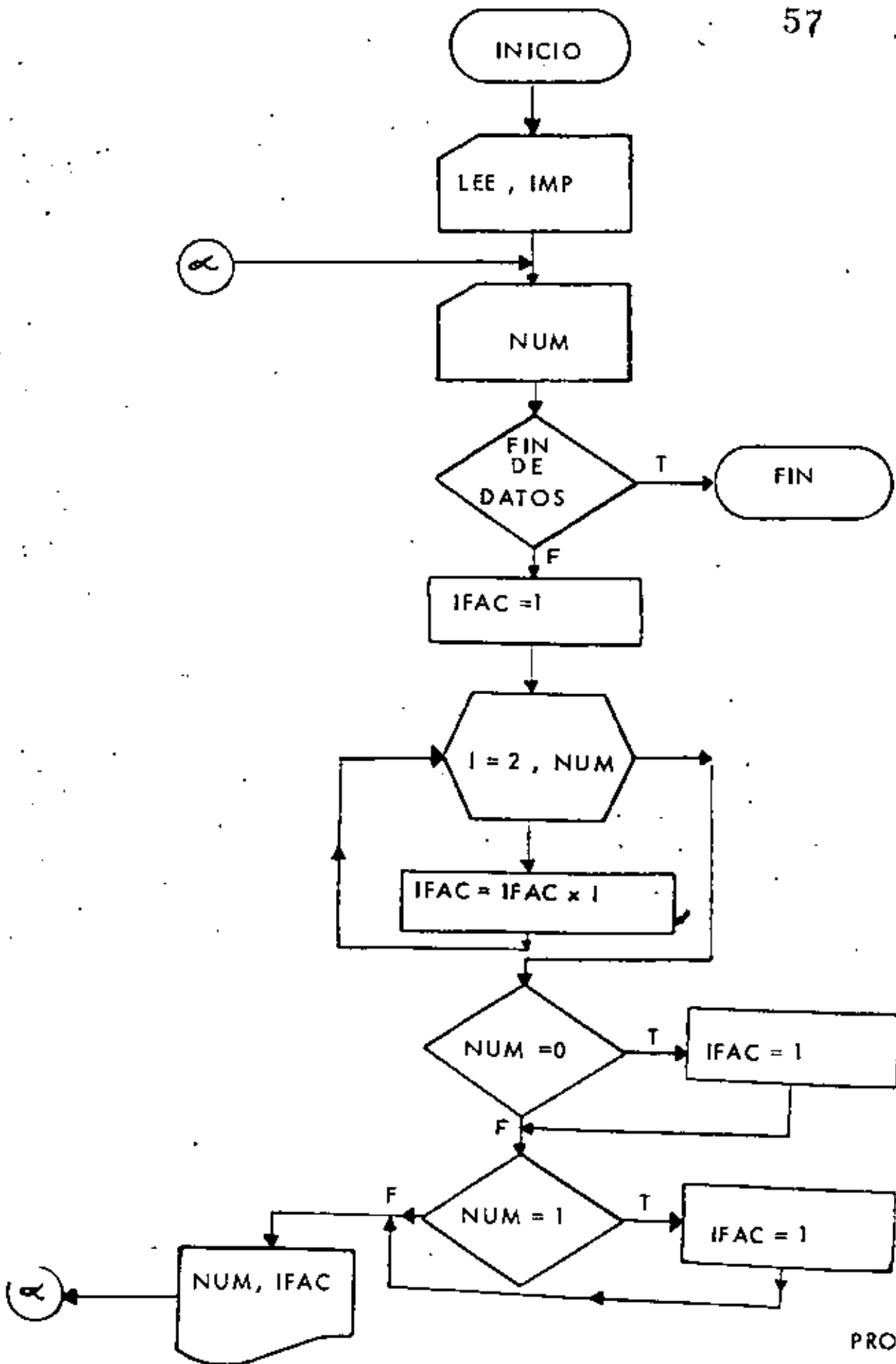
// JOB 1
// FOR
*LIST SOURCE PROGRAM
*ONE WORD INTEGERS
*IDCS(CARD,1132 PRINTER)
C-----O C H O-----
C   SERIE DE FIBONACCI
   100 FORMAT(13)
   101 FORMAT(I4,3X,I5)
   LEE=2
   IMP=3
   READ(LEE,100)NTERM
C   NTERM REPRESENTA EL NUMERO DESEADO DE TERMINOS
   NM1=1
   NM2=0
   WRITE(IMP,101)NM1,NM1
   DO 200 I=2,NTERM
     NUEVO=NM1+NM2
     NM2=NM1
     NM1=NUEVO
C   SE IMPRIME LA POSICION Y EL VALOR DEL TERMINO
   WRITE(IMP,101)I,NUEVO
   200 CONTINUE
   CALL EXIT
   END
// XEQ
015
/*

```

RESULTADOS

Posición	Valor del término
1	1
2	2
3	3
4	5
5	8
6	13
7	21
8	34
9	55
10	89





58

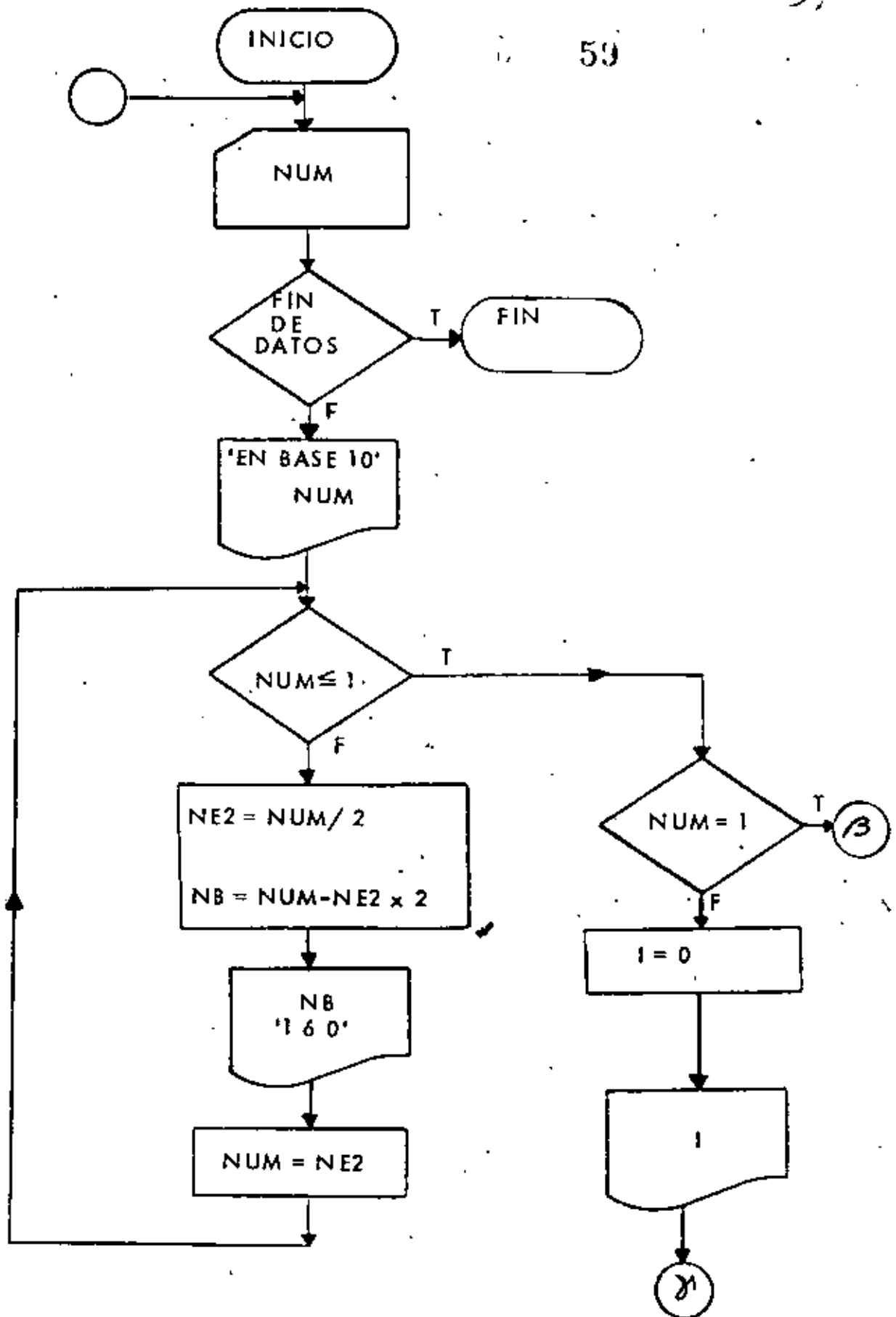
```
// JOB T
// FOR
*LIST SOURCE PROGRAM
*ONE WORD INTEGERS
*IOCS(CARD,1132 PRINTER)
-----N U E V E-----
```

```
C FACTORIAL
 100 FORMAT(2I1)
 101 FORMAT(I2)
 102 FORMAT(I3,3X,I5)
C SE LEEN LAS UNIDADES LOGICAS DE LECTURA E IMPRESIONN
  READ(2,100)LEE,IMP
 200 READ(LEE,101,END=220)NUM
     IFAC=1
     DO 210 I=2,NUM
        IFAC=IFAC*I
 210 CONTINUE
     IF(NUM.EQ.0)IFAC=1
     IF(NUM.EQ.1)IFAC=1
C SE IMPRIME EL NUMERO Y SU FACTORIAL
  WRITE(IMP,102)NUM,IFAC
  GO TO 200
 220 CALL EXIT
     END
```

```
// XEG
23
01
02
03
04
05
00
/*
```

R.E.S.U.L.T.A.D.O.S

NUM	IFAC
0	1
1	1
2	2
3	24
4	120
5	1



```
// JOB T
// FOR
*LIST SOURCE PROGRAM
*ONE WORD INTEGERS
*IOCS(CARD,1132 PRINTER)
C-----D I E Z-----
```

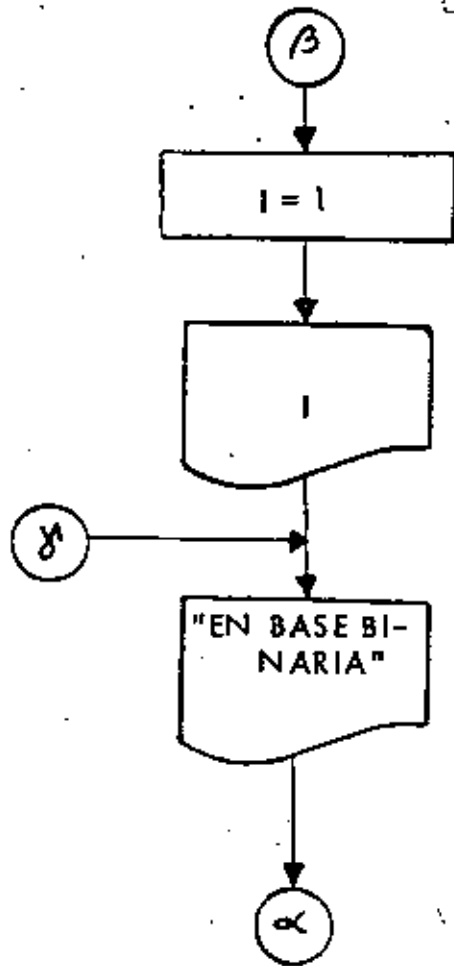
60

66

```
C CAMBIO DE BASE : DECIMAL A BINARIA
100 FORMAT(I5)
101 FORMAT(IX,I5,19H EN BASE DECIMAL ES)
102 FORMAT(IX,I1)
103 FORMAT(17H EN BASE BINARIA.)
LEE=2
IMP=3
200 READ(LEE,100,END=250)NUM
WRITE(IMP,101)NUM
210 IF(NUM,LE,1)GO TO 220
C NUM ES MAYOR QUE UNO. SE SIGUE DESCOMPONRIENDO
NE2=NUM/2
NB=NUM-NE2*2
C NB ES UNO O CERO
WRITE(IMP,102)NB
NUM=NE2
GO TO 210
220 CONTINUE
IF(NUM,EQ,1)GO TO 230
C SE IMPRIME EL ULTIMO CERO EN LA REPRESENTACION BINARIA
I=0
WRITE(IMP,102)I
GO TO 240
230 CONTINUE
C SE IMPRIME EL ULTIMO 1 EN LA REPRESENTACION BINARIA
I=1
WRITE(IMP,102)I
240 CONTINUE
WRITE(IMP,103)
GO TO 200
250 CALL EXIT
END
```

```
// XEQ
12
163
10
00001
011
-131
0
1
13
/*
```

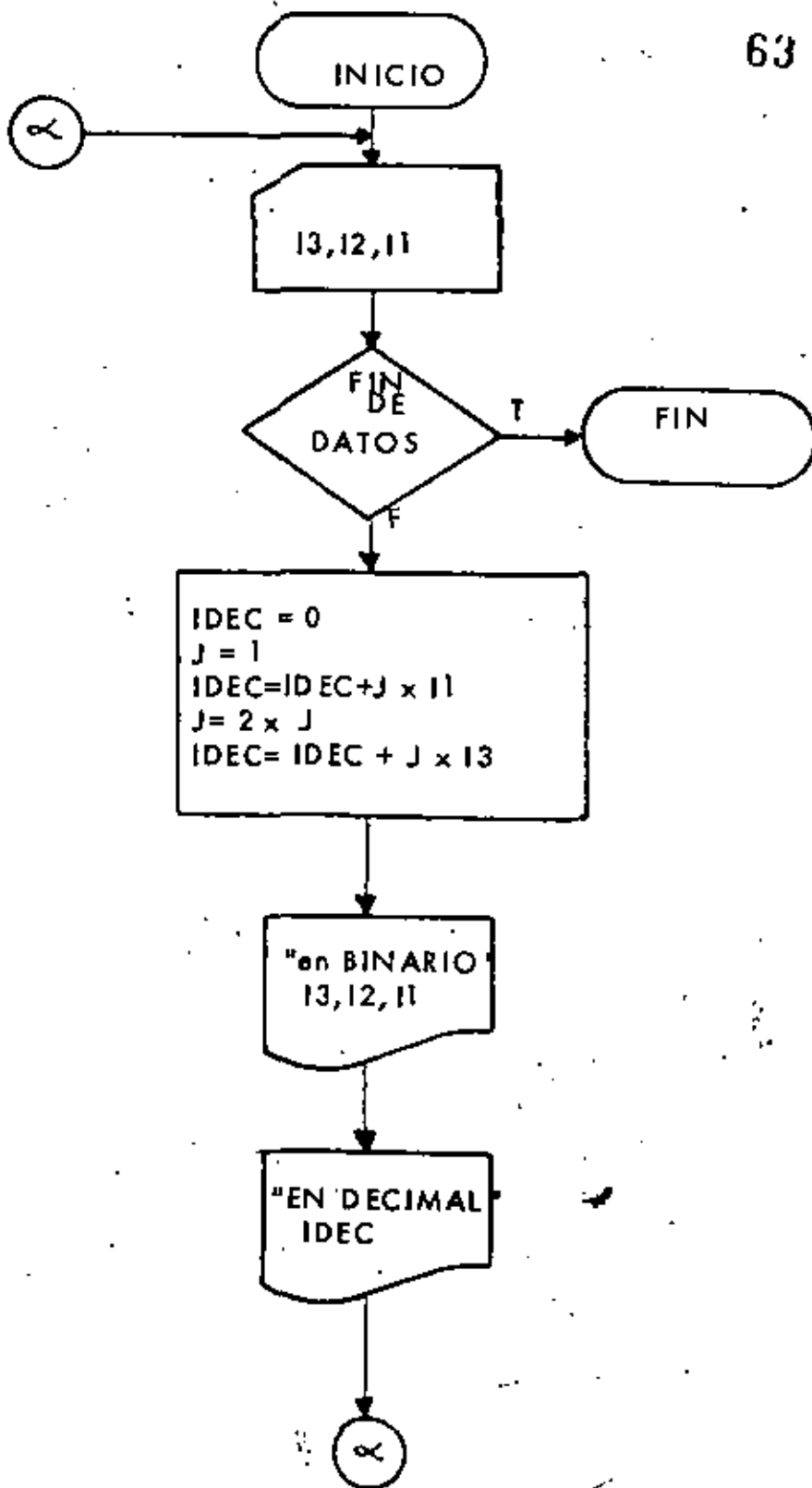
61



RESULTADOS 62

0
12 EN BASE DECIMAL ES
0
1
EN BASE BINARIA.
163 EN BASE DECIMAL ES
0
0
0
0
0
0
0
0
1
EN BASE BINARIA.
10 EN BASE DECIMAL ES
0
0
0
1
EN BASE BINARIA.
1 EN BASE DECIMAL ES
1
EN BASE BINARIA.
11 EN BASE DECIMAL ES
1
0
0
EN BASE BINARIA.
-131 EN BASE DECIMAL ES
0
EN BASE BINARIA.
0 EN BASE DECIMAL ES
0
EN BASE BINARIA.
1 EN BASE DECIMAL ES
1
EN BASE BINARIA.
13 EN BASE DECIMAL ES
1
0
1
EN BASE BINARIA.





```

// JOB T
// FOR
*LIST SOURCE PROGRAM
*ONE WORD INTEGERS
*IOCS(CARD.1132 PRINTER)

```

64

64

```

-----O N C E-----
C   CAMBIO DE BASE 1 BINARIA A DECIMAL
    100 FORMAT(3I1)
    101 FORMAT(1X, 3I1,19H EN BASE BINARIA ES)
    102 FORMAT(1X,15,17H EN BASE DECIMAL.)
        LEE=2
        IMP=3
    200 READ(2,100,END=210)I3,I2,I1
        IDEC=0
C   J CONTIENE LAS POTENCIAS DE 2.
        J=1
        IDEC=IDEC+J*11
        J=2*J
        IDEC=IDEC+J*12
        J=2*J
        IDEC=IDEC+J*13
        WRITE(IMP,101)I3,I2,I1
C   IDEC CONTIENE LA REPRESENTACION DECIMAL DEL NUMERO BINARIO.
        WRITE(IMP,102)IDEC
        GO TO 200
    210 CALL EXIT
        END

```

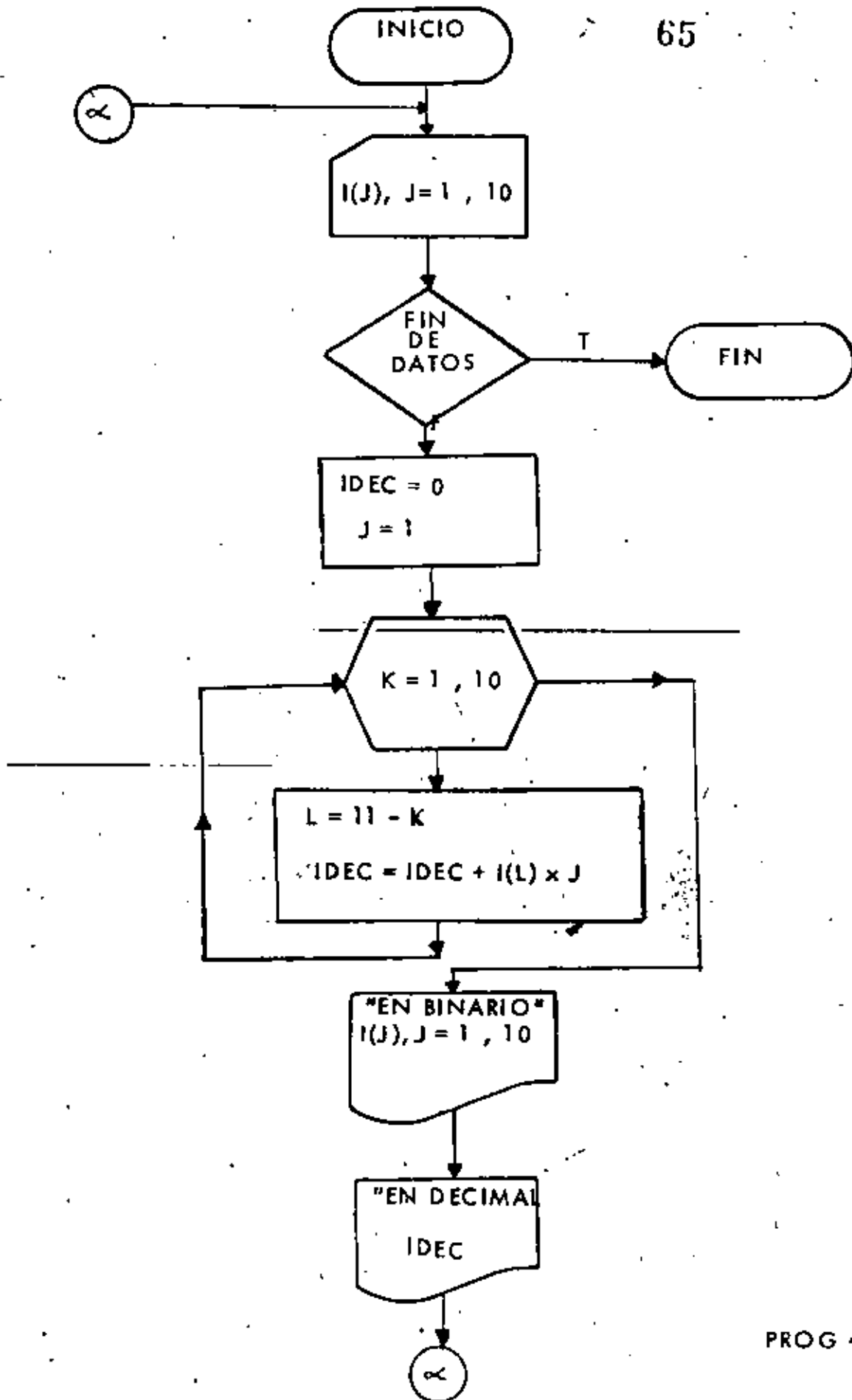
```

// XEQ
001
010
011
100
101
110
111
/*

```

RESULTADOS

001	EN BASE BINARIA ES
1	EN BASE DECIMAL.
010	EN BASE BINARIA ES
2	EN BASE DECIMAL.
011	EN BASE BINARIA ES
3	EN BASE DECIMAL.
100	EN BASE BINARIA ES
4	EN BASE DECIMAL.
101	EN BASE BINARIA ES
5	EN BASE DECIMAL.
110	EN BASE BINARIA ES
6	EN BASE DECIMAL.
111	EN BASE BINARIA ES
7	EN BASE DECIMAL.



```

// JOB T
// FOR
*LIST SOURCE PROGRAM
*ONE WORD INTEGERS
*IOCS(CARD,1132 PRINTER)

```

66

```

-----D O C E-----
C CAMBIO DE BASE : BINARIA A DECIMAL
C USANDO ARREGLOS
  DIMENSION I(10)
  100 FORMAT(10I1)
  101 FORMAT(1X,10I1,19H EN BASE BINARIA ES)
  102 FORMAT(1X,15,17H EN BASE DECIMAL.)
  LEE=2
  IMP=3
  200 READ(2,100,END=220)I
  IDEC=0
  J=1
  DO 210 K=1,10
C SE ANALIZA EL VECTOR I DE DERECHA A IZQUIERDA
  L=11-K
  IDEC=IDEC+I(L)*J
C J CONTIENE LAS POTENCIAS DE 2
  J=J*2
  210 CONTINUE
  WRITE(IMP,101)(I(J),J=1,10)
  WRITE(IMP,102)IDEC
  GO TO 200
  220 CALL EXIT
  END

```

// XEQ

```

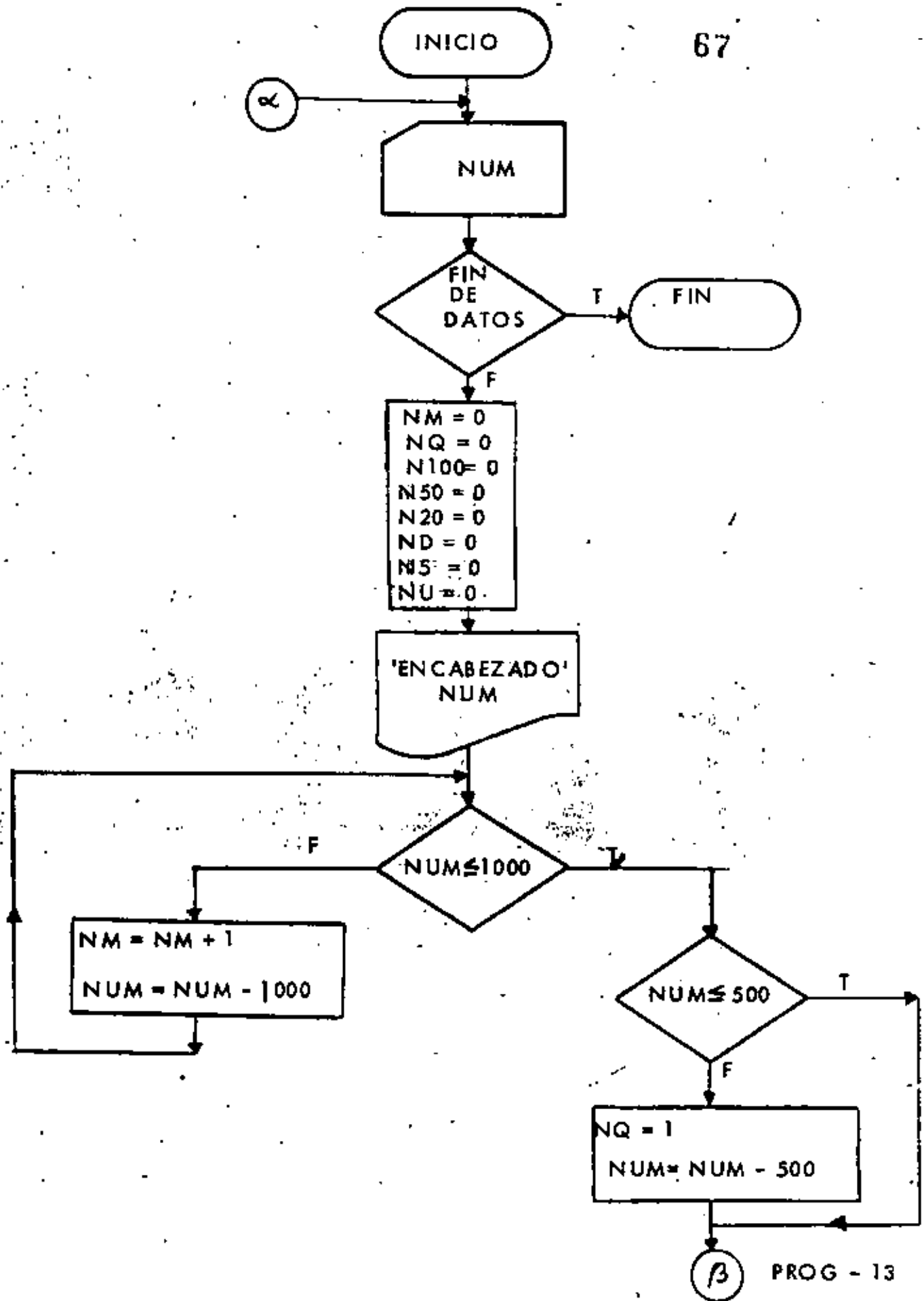
1
11
1000100010
1
1
1001001
00

```

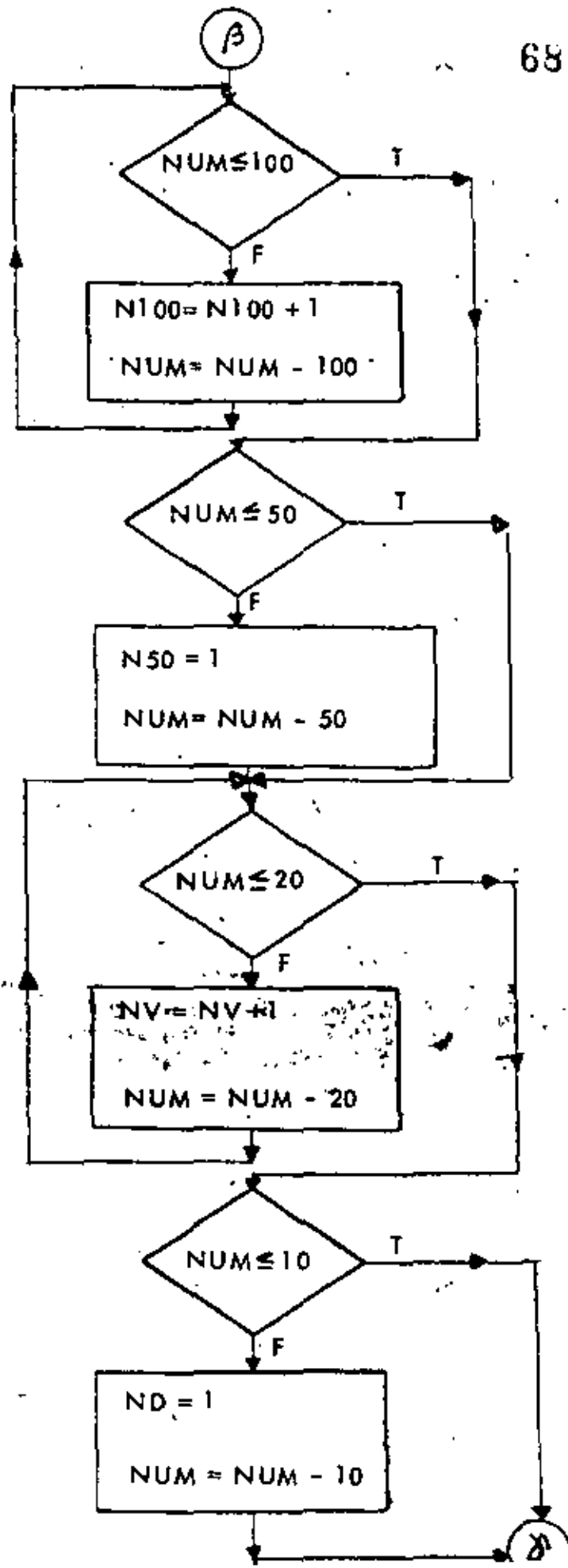
### RESULTADOS

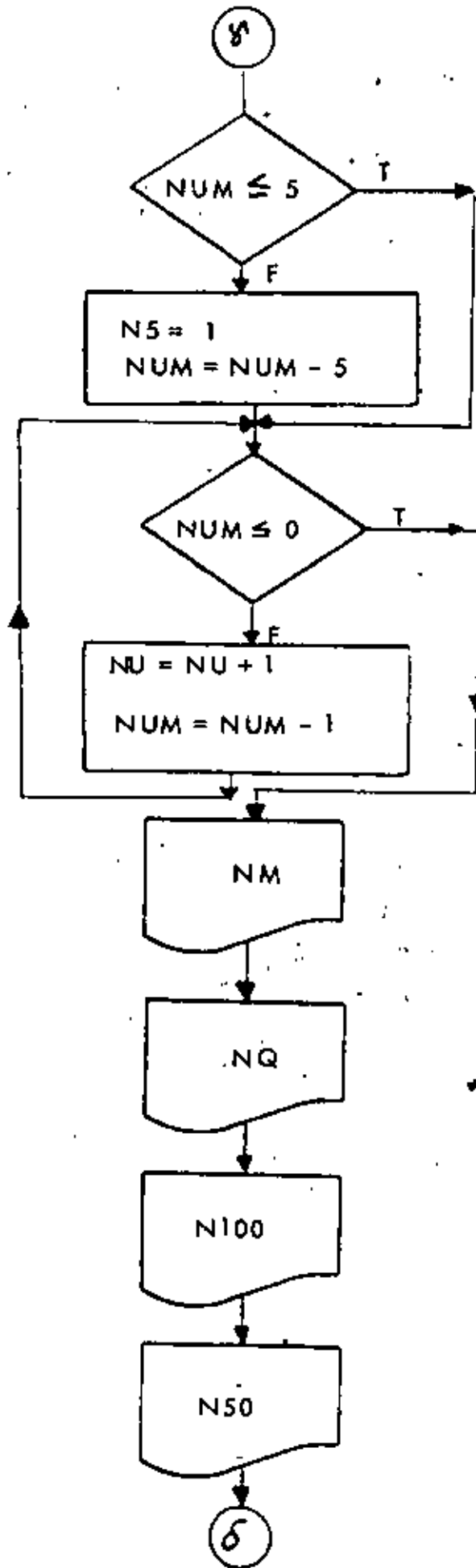
000000001	EN BASE BINARIA ES
1	EN BASE DECIMAL.
0000000110	EN BASE BINARIA ES
6	EN BASE DECIMAL.
1000100010	EN BASE BINARIA ES
546	EN BASE DECIMAL.
1000000000	EN BASE BINARIA ES
512	EN BASE DECIMAL.
1000000001	EN BASE BINARIA ES
513	EN BASE DECIMAL.
0001001001	EN BASE BINARIA ES
73	EN BASE DECIMAL.
000000000	EN BASE BINARIA ES
0	EN BASE DECIMAL.

67



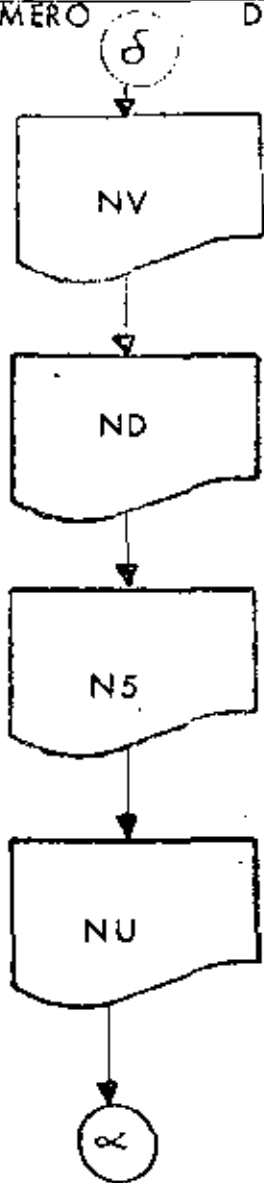
68





70

70





// JOB T  
// FOR

71

71

\*LIST SOURCE PROGRAM  
\*ONE WORD INTEGERS  
\*IOCS(CARD,1132 PRINTER)

C-----T R E C E-----

C CALCULO DEL NUMERO DE BILLETES

```
100 FORMAT(I4)
101 FORMAT(/,11H EL NUMERO-,I4,24H.00=PUEDA DESGLOSARSE EN)
102 FORMAT(I5, 7H DE MIL)
103 FORMAT(I5,14H DE QUINIENTOS)
104 FORMAT(I5, 8H DE CIEN)
105 FORMAT(I5,13H DE CINCUENTA)
106 FORMAT(I5,10H DE VEINTE)
107 FORMAT(I5, 8H DE DIEZ)
108 FORMAT(I5, 9H DE CINCO)
109 FORMAT(I5, 7H DE UNO)
    LEE=2
    IMP=3
200 READ(LEE,100,END=330)NUM
    NM=0
    ND=0
    N100=0
    N50=0
    NV=0
    ND=0
    N5=0
    NU=0
    WRITE(IMP,101)NUM
210 IF(NUM.LE.1000)GO TO 220
C    NUM ES MAYOR QUE 1000
    NM=NM+1
    NUM=NUM-1000
    GO TO 210
220 CONTINUE
C    IF(NUM.LE.500)GO TO 230
    NUM ES MAYOR QUE 500 (MAXIMO UN BILLETE DE 500)
C    NUM ES MAYOR QUE 20
    NV=NV+1
    NUM=NUM-20
    GO TO 270
280 CONTINUE
C    IF(NUM.LE.10)GO TO 290
    NUM ES MAYOR QUE 10 (MAXIMO UN BILLETE DE 10)
    ND=1
    NUM=NUM-10
290 CONTINUE
    IF(NUM.LE.5)GO TO 300
```

PROG - 13

C NUM ES MAYOR QUE 5 (MAXIMO UN BILLETE DE 5)

N5=1  
NUM=NUM-5

300 CONTINUE

310 IF (NUM.LE.0) GO TO 320

72

C NUM ES MAYOR QUE 1

NU=NU+1  
NUM=NUM-1  
GO TO 310

320 CONTINUE

WRITE (IMP,102) NM  
WRITE (IMP,103) NQ  
WRITE (IMP,104) N100  
WRITE (IMP,105) N50  
WRITE (IMP,106) NV  
WRITE (IMP,107) NO  
WRITE (IMP,108) N5  
WRITE (IMP,109) NU  
GO TO 200

330 CALL EXIT  
END

// XEQ  
9000  
1314  
6893  
1000  
500  
13  
/\*

EL NUMERO 9000.00 PUEDE DESGLOSARSE EN

9 DE MIL  
 0 DE QUINIENTOS  
 0 DE CIEN  
 0 DE CINCUENTA  
 0 DE VEINTE  
 0 DE DIEZ  
 0 DE CINCO  
 0 DE UNO

EL NUMERO 3314.00 PUEDE DESGLOSARSE EN

3 DE MIL  
 3 DE QUINIENTOS  
 1 DE CIEN  
 4 DE CINCUENTA  
 0 DE VEINTE  
 0 DE DIEZ  
 0 DE CINCO  
 4 DE UNO

EL NUMERO 6093.00 PUEDE DESGLOSARSE EN

6 DE MIL  
 0 DE QUINIENTOS  
 9 DE CIEN  
 3 DE CINCUENTA  
 0 DE VEINTE  
 0 DE DIEZ  
 0 DE CINCO  
 3 DE UNO

EL NUMERO 1000.00 PUEDE DESGLOSARSE EN

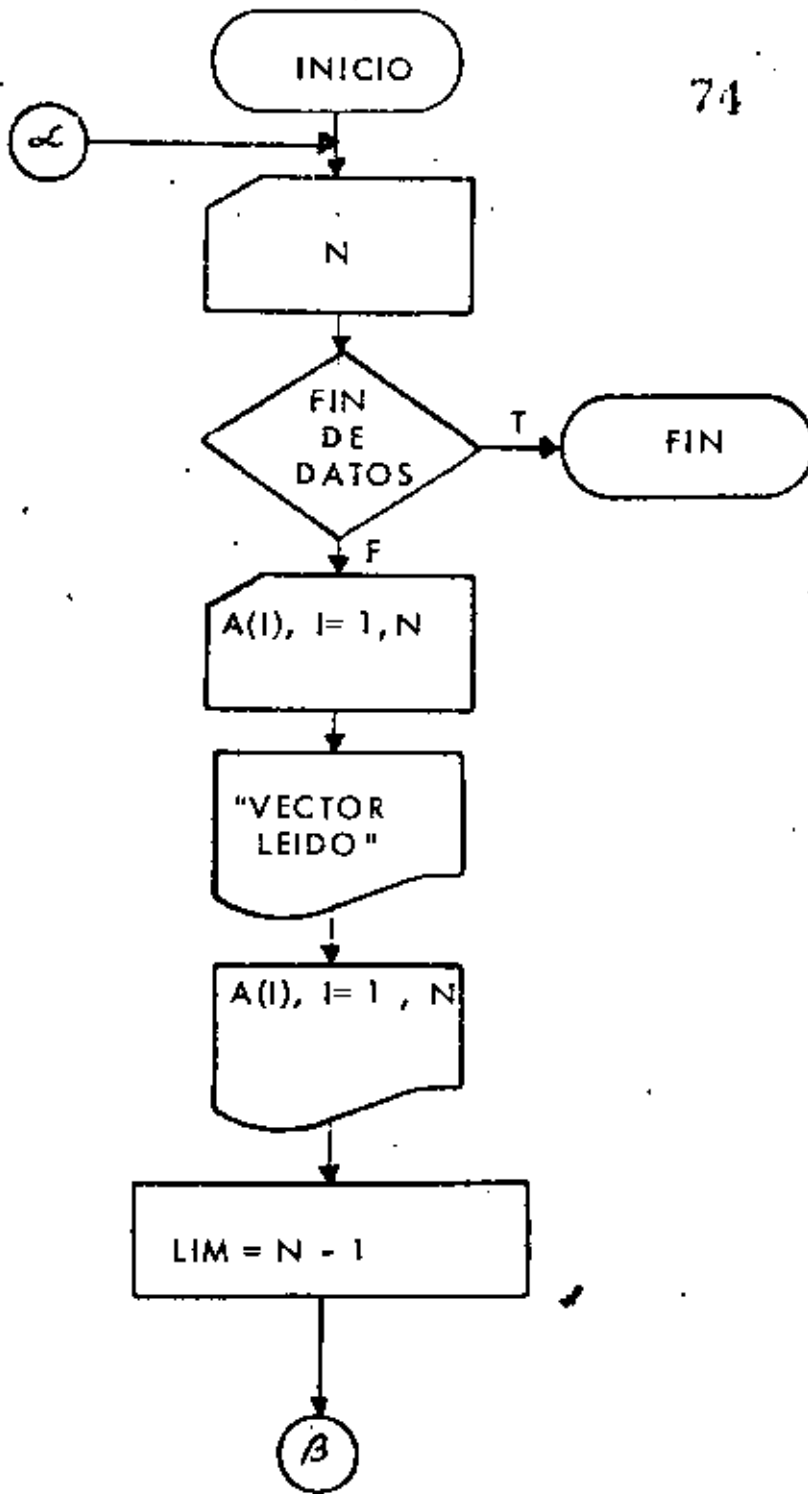
1 DE MIL  
 0 DE QUINIENTOS  
 0 DE CIEN  
 0 DE CINCUENTA  
 0 DE VEINTE  
 0 DE DIEZ  
 0 DE CINCO  
 0 DE UNO

EL NUMERO 500.00 PUEDE DESGLOSARSE EN

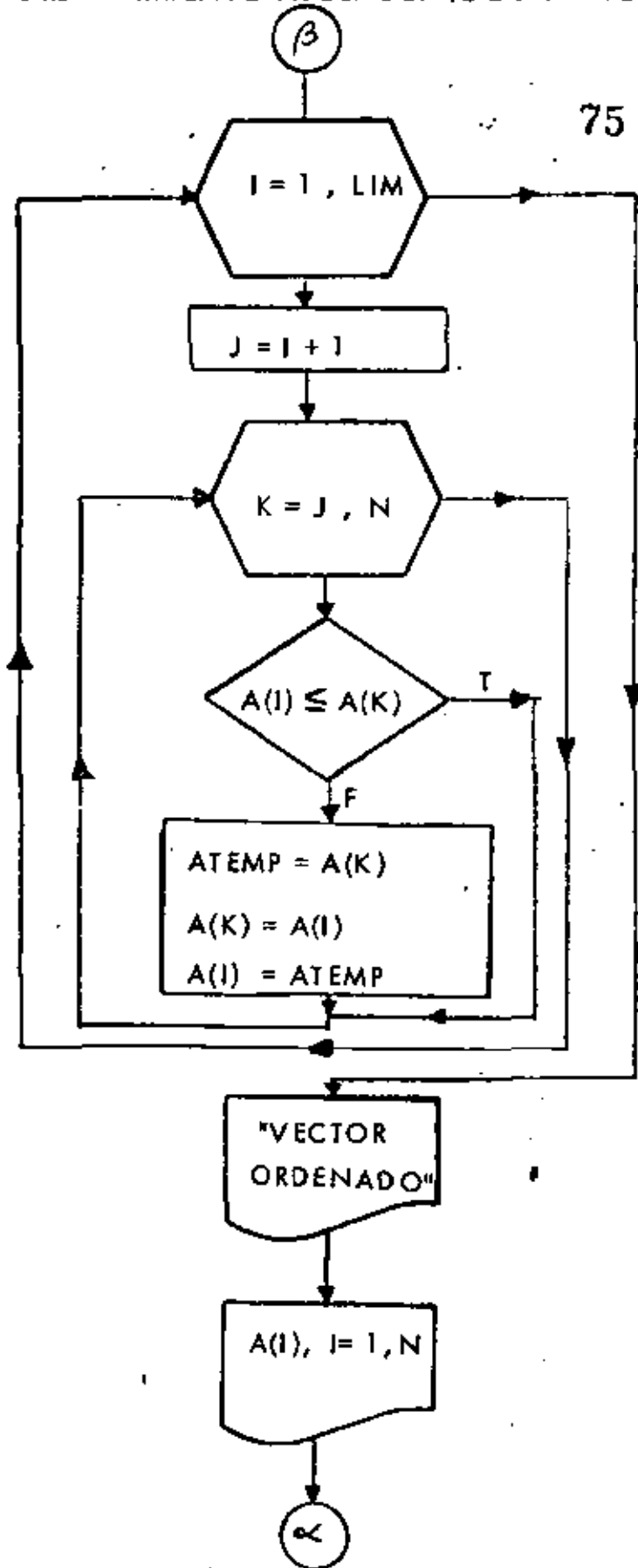
0 DE MIL  
 5 DE QUINIENTOS  
 0 DE CIEN  
 0 DE CINCUENTA  
 0 DE VEINTE  
 0 DE DIEZ  
 0 DE CINCO  
 0 DE UNO

EL NUMERO 13.00 PUEDE DESGLOSARSE EN

0 DE MIL  
 0 DE QUINIENTOS  
 0 DE CIEN  
 0 DE CINCUENTA  
 0 DE VEINTE  
 1 DE DIEZ  
 0 DE CINCO  
 3 DE UNO



75



// JOB T

// FOR

\*LIST SOURCE PROGRAM

\*ONE WORD INTEGERS

\*IOCS(CARD,1132 PRINTER)

C-----C A T O R C E---

C ORDENAMIENTO ASCENDENTE DE UN VECTOR  
DIMENSION A(100)

100 FORMAT(I2)

101 FORMAT(BF10.0)

102 FORMAT(13H VECTOR LEIDO,//)

103 FORMAT(10(IX,F11.4))

104 FORMAT(16H VECTOR ORDENADO,//)

LEE=2

IMP=3

200 READ(LEE,100,END=240)N

C N REPRESENTA EL NUMERO DE ELEMENTOS A ORDENAR

READ(LEE,101)(A(I),I=1,N)

WRITE(IMP,102)

WRITE(IMP,103)(A(I),I=1,N)

LIM=N-1

DO 230 I=1,LIM

J=I+1

C SE ASUME QUE A(I) ES EL MENOR

DO 220 K=J,N

IF(A(I).LE.A(K))GO TO 210

C A(I) FUE MAYOR QUE A(K)

ATEMP=A(K)

A(K)=A(I)

A(I)=ATEMP

210 CONTINUE

220 CONTINUE

C AHORA SE TIENE EN A(I) EL MENOR

230 CONTINUE

WRITE(IMP,104)

WRITE(IMP,103)(A(I),I=1,N)

GO TO 200

240 CALL EXIT

END

// XEQ

04

-4. 1. -3. 17.

03

0. -287. 32.

04

-28. -32. 11. 0.

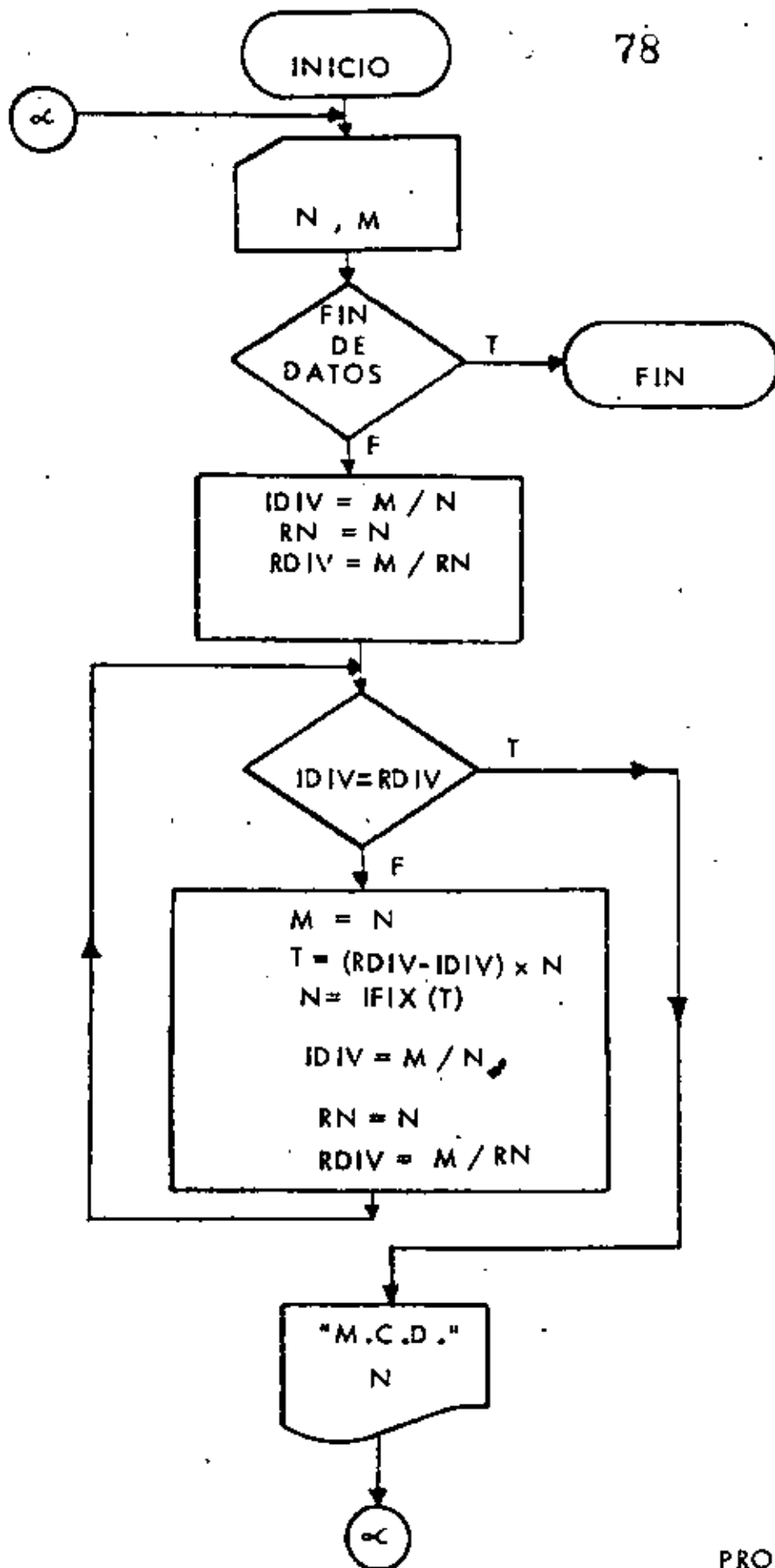
/\*

76

76

RESULTADOS

VECTOR LEIDO			
-4.0000	1.0000	-3.0000	17.0000
VECTOR ORDENADO			
-4.0000	-3.0000	1.0000	17.0000
VECTOR LEIDO			
0.0000	-287.0000	32.0000	
VECTOR ORDENADO			
-287.0000	0.0000	32.0000	
VECTOR LEIDO			
-28.0000	-32.0000	11.0000	0.0000
VECTOR ORDENADO			
-32.0000	-28.0000	0.0000	11.0000





// JOB T  
// FOR

79

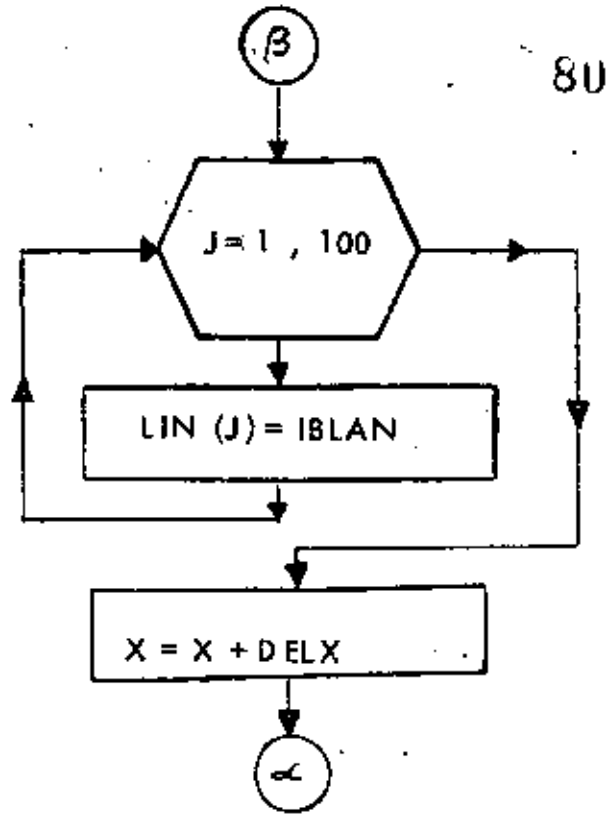
79

```
*LIST SOURCE PROGRAM  
*ONE WORD INTEGERS  
*IOCS(CARD,1132-PRINTER)  
C-----Q U I N C E-----  
C   MAXIMO COMUN MULTIPLO  
C   ALGORITMO DE EUCLIDES  
100 FORMAT(2I3)  
101 FORMAT(3H N=,I3,3H M=,I3)  
102 FORMAT(8H M.C.D.=,I3,//)  
   LEE=2  
   IMP=3  
200 READ(LEE,100,END=230)N,M  
C   SE CALCULA EL RESIDUO  
   IDIV=M/N  
   RN=N  
   RDIV=M/RN  
210 IF(IDIV.EQ.RDIV)GO TO 220  
   M=N  
   T=(RDIV-IDIV)*N  
   N=IFIX(T)  
   IDIV=M/N  
   RN=N  
   RDIV=M/RN  
   GO TO 210  
220 CONTINUE  
C   N REPRESENTA EL MAXIMO COMUN DIVISOR  
   WRITE(IMP,102)N  
   GO TO 200  
230 CALL EXIT  
   END
```

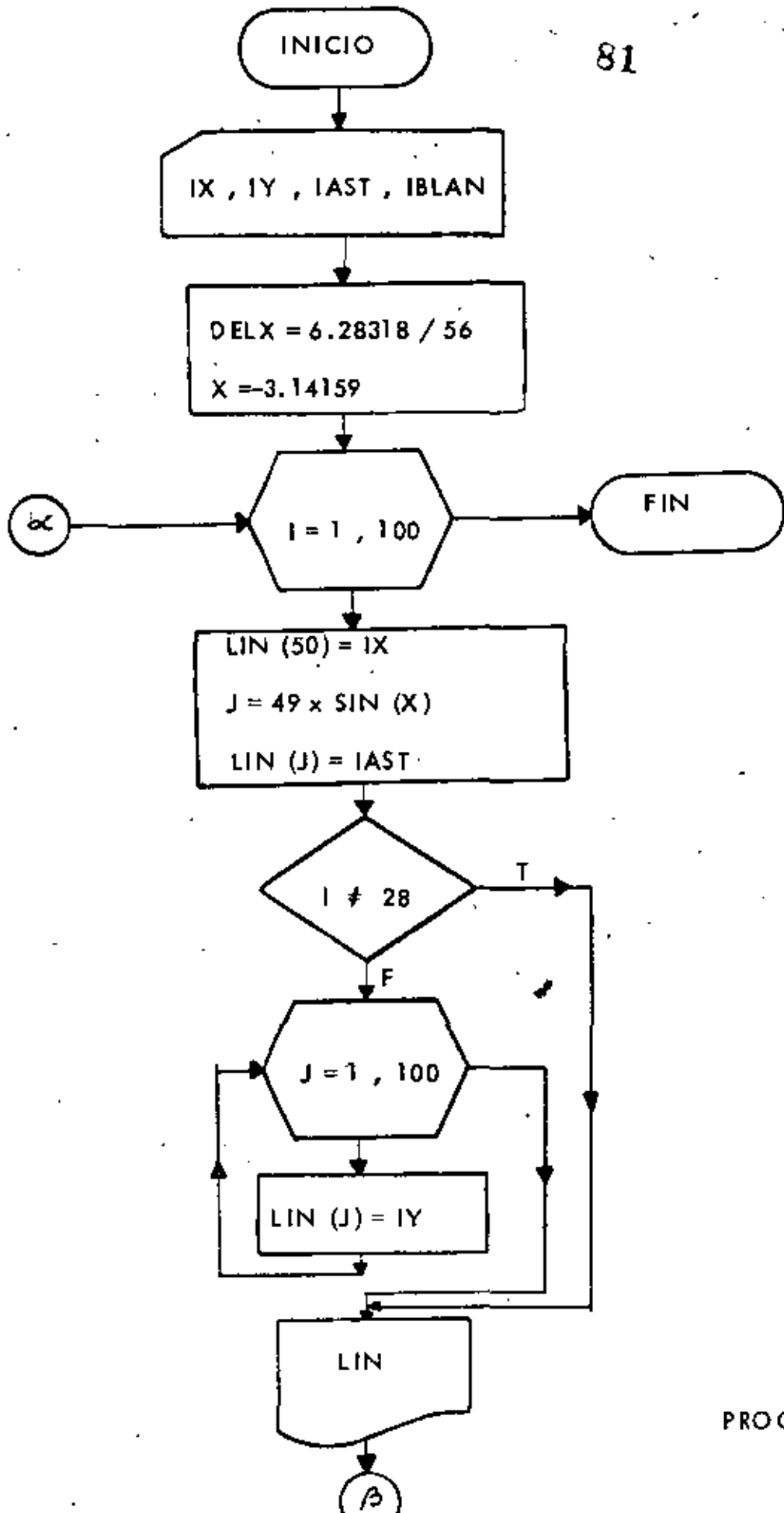
```
// XEQ  
5 7  
3 6  
8 16  
11 98  
16 24  
8 12  
/.
```

### RESULTADOS

M.C.D.=	1
M.C.D.=	3
M.C.D.=	8
M.C.D.=	1
M.C.D.=	8
M.C.D.=	4



81



R E S U L T A D O S

82

YYY

82

```

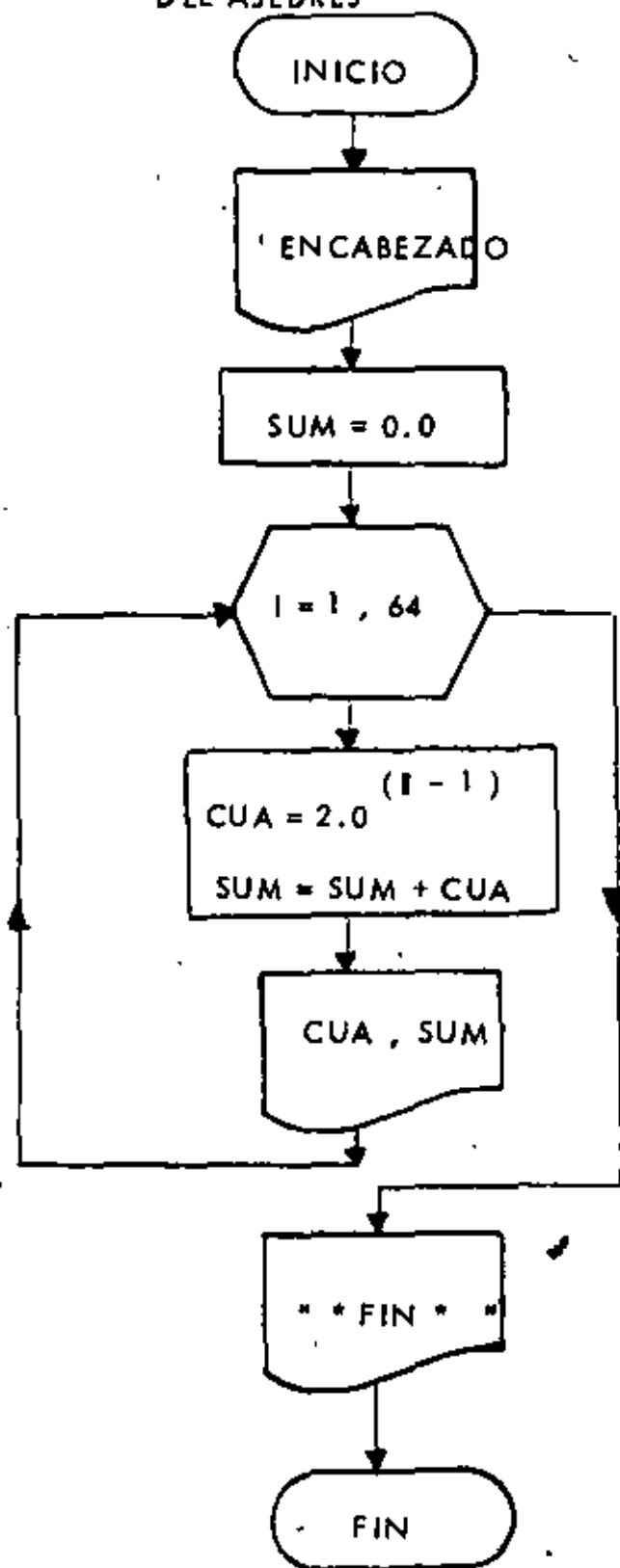
// JOB T
// FOR
*LIST SOURCE PROGRAM
*ONE WORD INTEGERS
*IOCS(CARD,1132 PRINTER)
C-----D I E C I S E I S-----
C   GRAFICA DE SEN(X)
    DIMENSION LIN(100)
100  FORMAT(4A1)
101  FORMAT(10X,100A1)
    LEE=2
    IMP=3
    READ(LEE,100)IX,IY,IAST,IBLAN
    DELX=6.28318/56
    X =-3.14159
    DO 200 I=1,100
      LIN(I)=IBLAN
200  CONTINUE
    DO 240 I=1,56
      LIN(50)=IX
      J=49*SIN(X)+50
      LIN(J)=IAST
      IF(I.NE.28)GO TO 220
      DO 210 J=1,100
        I FUE IGUAL A 28, SE IMPRIME EL EJE Y
        LIN(J)=IY
210  CONTINUE
220  CONTINUE
      WRITE(IMP,101)LIN
      DO 230 J=1,100
        LIN(J)=IBLAN
230  CONTINUE
      X=X+DELX
240  CONTINUE
      CALL EXIT
      END
// XEQ
XY*
/*

```

```

// JOB T
// FOR
*LIST SOURCE PROGRAM
*IOCS(CARD,1132 PRINTER)
*ONE WORD INTEGERS
C-----D I E C I S I E T E-----
C ESTE PROGRAMA CALCULA EL NUMERO DE GRANOS DE MAIZ QUE COBRO EL
C INVENTOR DE AJEDRES
C FILES
      LEE=2
      IMP=3
C FORMATOS
100 FORMAT(10X,6HCUADRO,9X,4HSUMA,/)
101 FORMAT(3X,I2,2E15.7)
102 FORMAT(///)
103 FORMAT(53X,11H*****;)
104 FORMAT(53X,11H* FIN *)
      WRITE(IMP,100)
      SUM=0.0
      DO 200 I=1,64
        CUA=2.0** (I-1)
        SUM=SUM+CUA
        WRITE(IMP,101) I,CUA,SUM
200 CONTINUE
      WRITE(IMP,102)
      WRITE(IMP,103)
      WRITE(IMP,104)
      WRITE(IMP,103)
      CALL EXIT
      END
// XEQ
/*

```



CUADRO

SUMA

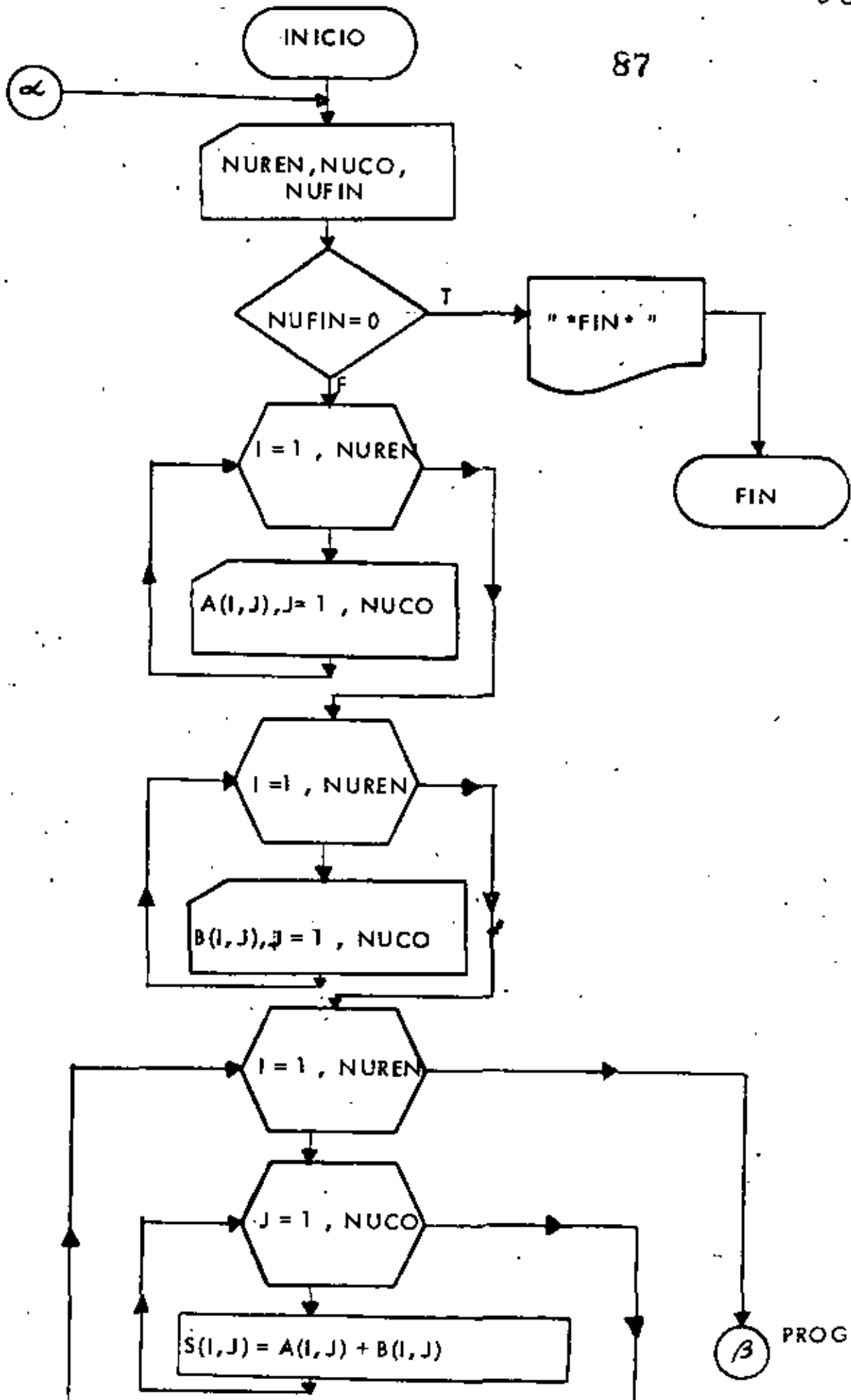
RESULTADOS

1	10000000	+01	10000000	+01
2	20000000	+01	20000000	+01
3	30000000	+01	30000000	+01
4	40000000	+01	40000000	+01
5	50000000	+01	50000000	+01
6	60000000	+01	60000000	+01
7	70000000	+01	70000000	+01
8	80000000	+01	80000000	+01
9	90000000	+01	90000000	+01
10	100000000	+03	100000000	+03
11	110000000	+03	110000000	+03
12	120000000	+03	120000000	+03
13	130000000	+03	130000000	+03
14	140000000	+03	140000000	+03
15	150000000	+03	150000000	+03
16	160000000	+03	160000000	+03
17	170000000	+03	170000000	+03
18	180000000	+03	180000000	+03
19	190000000	+03	190000000	+03
20	200000000	+03	200000000	+03
21	210000000	+04	210000000	+04
22	220000000	+04	220000000	+04
23	230000000	+04	230000000	+04
24	240000000	+04	240000000	+04
25	250000000	+04	250000000	+04
26	260000000	+04	260000000	+04
27	270000000	+04	270000000	+04
28	280000000	+04	280000000	+04
29	290000000	+04	290000000	+04
30	300000000	+04	300000000	+04
31	310000000	+04	310000000	+04
32	320000000	+04	320000000	+04
33	330000000	+04	330000000	+04
34	340000000	+04	340000000	+04
35	350000000	+04	350000000	+04
36	360000000	+04	360000000	+04
37	370000000	+04	370000000	+04
38	380000000	+04	380000000	+04
39	390000000	+04	390000000	+04
40	400000000	+04	400000000	+04
41	410000000	+04	410000000	+04
42	420000000	+04	420000000	+04
43	430000000	+04	430000000	+04
44	440000000	+04	440000000	+04
45	450000000	+04	450000000	+04
46	460000000	+04	460000000	+04
47	470000000	+04	470000000	+04
48	480000000	+04	480000000	+04
49	490000000	+04	490000000	+04
50	500000000	+04	500000000	+04
51	510000000	+04	510000000	+04
52	520000000	+04	520000000	+04
53	530000000	+04	530000000	+04
54	540000000	+04	540000000	+04
55	550000000	+04	550000000	+04
56	560000000	+04	560000000	+04
57	570000000	+04	570000000	+04
58	580000000	+04	580000000	+04
59	590000000	+04	590000000	+04
60	600000000	+04	600000000	+04
61	610000000	+04	610000000	+04
62	620000000	+04	620000000	+04
63	630000000	+04	630000000	+04
64	640000000	+04	640000000	+04
65	650000000	+04	650000000	+04
66	660000000	+04	660000000	+04
67	670000000	+04	670000000	+04
68	680000000	+04	680000000	+04
69	690000000	+04	690000000	+04
70	700000000	+04	700000000	+04
71	710000000	+04	710000000	+04
72	720000000	+04	720000000	+04
73	730000000	+04	730000000	+04
74	740000000	+04	740000000	+04
75	750000000	+04	750000000	+04
76	760000000	+04	760000000	+04
77	770000000	+04	770000000	+04
78	780000000	+04	780000000	+04
79	790000000	+04	790000000	+04
80	800000000	+04	800000000	+04
81	810000000	+04	810000000	+04
82	820000000	+04	820000000	+04
83	830000000	+04	830000000	+04
84	840000000	+04	840000000	+04
85	850000000	+04	850000000	+04
86	860000000	+04	860000000	+04
87	870000000	+04	870000000	+04
88	880000000	+04	880000000	+04
89	890000000	+04	890000000	+04
90	900000000	+04	900000000	+04
91	910000000	+04	910000000	+04
92	920000000	+04	920000000	+04
93	930000000	+04	930000000	+04
94	940000000	+04	940000000	+04
95	950000000	+04	950000000	+04
96	960000000	+04	960000000	+04
97	970000000	+04	970000000	+04
98	980000000	+04	980000000	+04
99	990000000	+04	990000000	+04
100	1000000000	+04	1000000000	+04

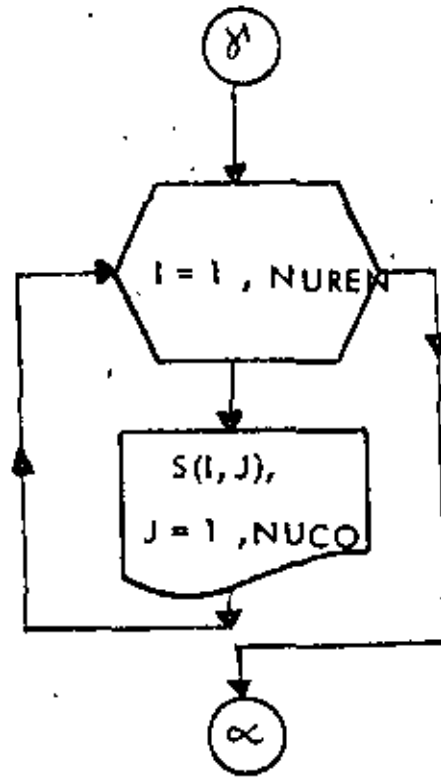
\*\*\*\*\*  
\* FIN \*  
\*\*\*\*\*

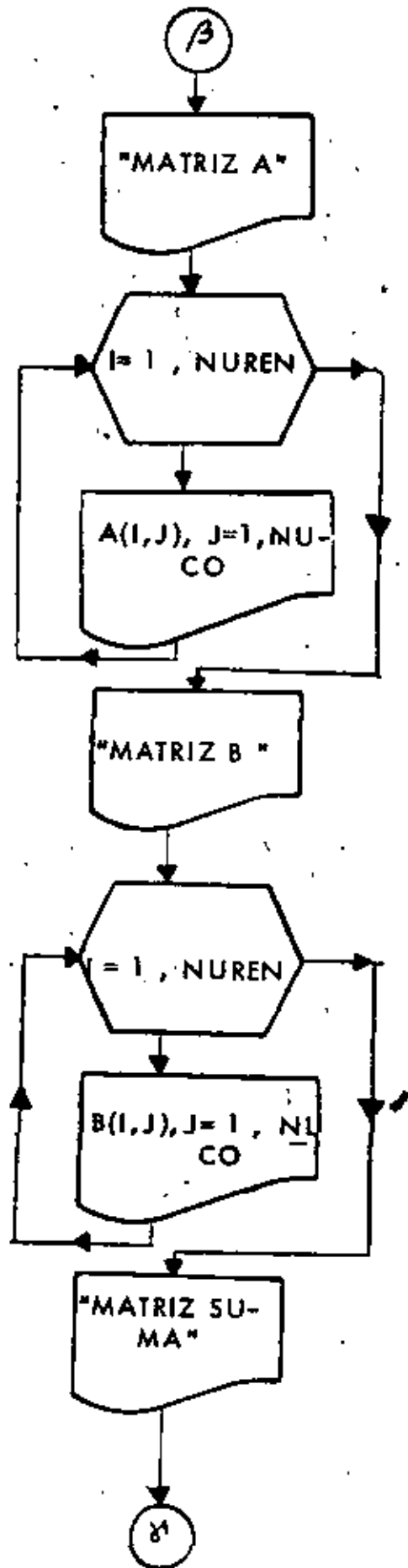


87



88





CALL EXIT  
END

90

90

// XEQ  
2 2 1  
5.0 0.0  
12.2 3.4  
-4.7 2.1  
0.0 -1.2  
2 2 1  
90.15 -87.02  
5.478 12.22  
-90.15 87.02  
-5.478 -12.22  
2 2 0

RESULTADOS

MATRIZ A:

5.000 0.000  
12.200 3.400

MATRIZ B:

-4.700 -2.100  
0.000 -1.200

LA MATRIZ SUMA ES:

0.300 2.100  
12.200 2.200

MATRIZ A:

90.150 -87.020  
5.478 12.220

MATRIZ B:

-90.150 87.020  
-5.478 -12.220

LA MATRIZ SUMA ES:

0.000 0.000  
0.000 0.000

PROG - 18

\*\*\*\*\*  
\* FIN \*  
\*\*\*\*\*

// JOB T  
// FOR

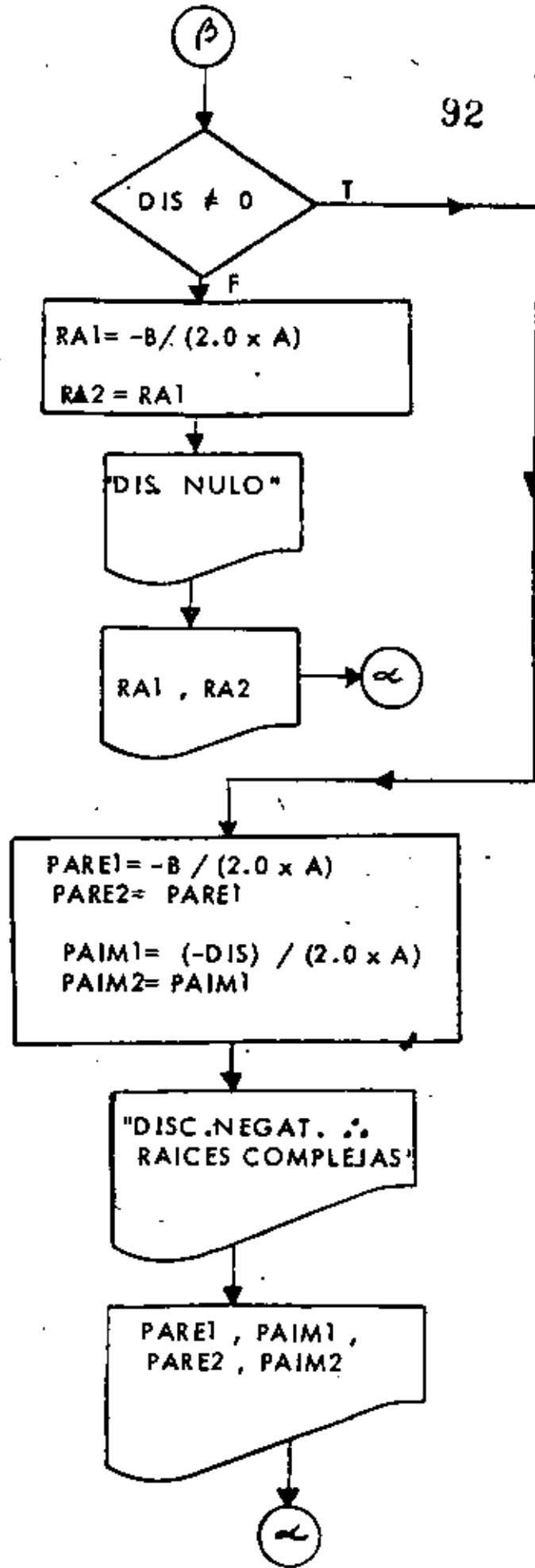
91

\*IOCS(CARD,1132 PRINTER)  
\*ONE WORD INTEGERS  
\*LIST SOURCE PROGRAM

91

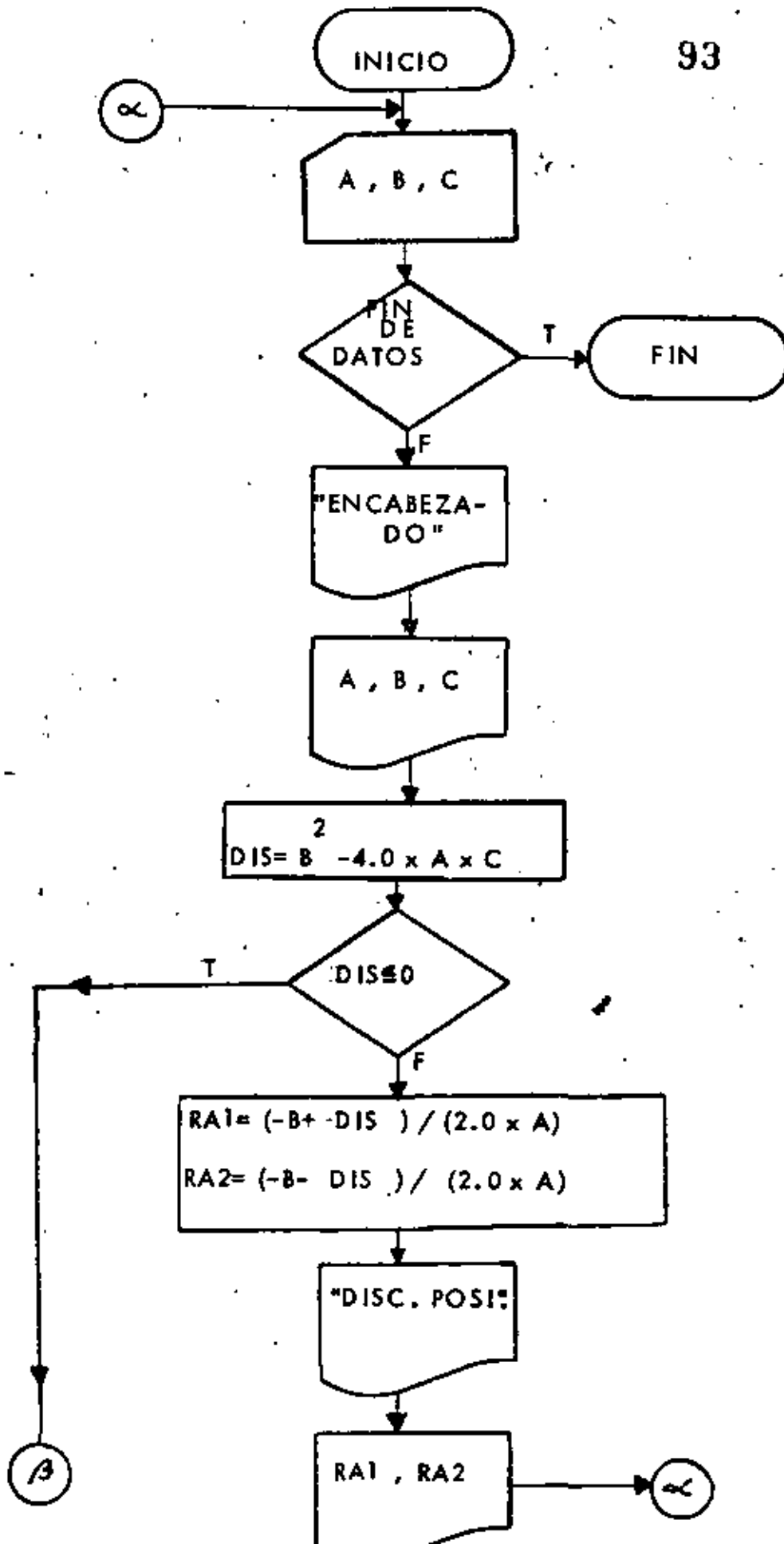
C-----D I E C I O C H O-----

```
C      SUMA DE DOS MATRICES: A Y B
C      EL PROGRAMA ESTA HECHO PARA SUMAR DOS MATRICES DE 10X 10 MAXIMO.
C      SE RESERVAN LUGARES EN LA MEMORIA PARA LAS MATRICES A SUMAR Y PARA
C      LA MATRIZ SUMA.
C      DIMENSION A(10,10),B(10,10),S(10,10)
C      FILES
C          LEE=2
C          IMP=3
C      FORMATOS
100  FORMAT(3I2)
101  FORMAT(10F8,3)
102  FORMAT(///,5X,9HMATRIZ A:,///)
103  FORMAT(5X,10(F8,3,2X),/)
104  FORMAT(///,5X,9HMATRIZ B:,///)
105  FORMAT(///,5X,18HLA MATRIZ SUMA ES:,///)
106  FORMAT(53X,11H*****;
107  FORMAT(53X,11H*   FIN   *)
C      LECTURA DEL NUMERO DE RENGLONES DE LAS MATRICES (NUREN) Y DEL NUME
C      RO DE COLUMNAS (NUCO).Y DE UN DETECTOR (NUFIN)
199  READ(LEE,100)NUREN,NUCO,NUFIN
C      ANALISIS DE NUFIN. SI VALE CERO YA NO SE EJECUTA EL PROGRAMA,DE LO
C      CONTRARIO SI.
      IF(NUFIN.EQ.0)GO TO 1000
C      LECTURA POR RENGLONES DE LA MATRIZ A.
      DO 200 I=1,NUREN
      READ(LEE,101)(A(I,J),J=1,NUCO)
200  CONTINUE
C      LECTURA POR RENGLONES DE LA MATRIZ B.
      DO 201 I=1,NUREN
      READ(LEE,101)(B(I,J),J=1,NUCO)
201  CONTINUE
C      SE HARA LA SUMA ELEMENTO A ELEMENTO
      DO 203 I=1,NUREN
      DO 202 J=1,NUCO
      S(I,J)=A(I,J)+B(I,J)
202  CONTINUE
203  CONTINUE
C      IMPRESION DE LA MATRIZ A POR RENGLONES
      WRITE(IMP,102)
      DO 204 I=1,NUREN
      WRITE(IMP,103)(A(I,J),J=1,NUCO)
204  CONTINUE
C      IMPRESION DE LA MATRIZ B POR RENGLONES
      WRITE(IMP,104)
      DO 205 I=1,NUREN
      WRITE(IMP,103)(B(I,J),J=1,NUCO)
205  CONTINUE
C      IMPRESION DE LA MATRIZ S POR RENGLONES
      WRITE(IMP,105)
      DO 206 I=1,NUREN
      WRITE(IMP,103)(S(I,J),J=1,NUCO)
206  CONTINUE
      GO TO 199
1000 CONTINUE
      WRITE(IMP,106)
      WRITE(IMP,107)
      WRITE(IMP,106)
```



92

93



3.0

20.0

1.0

1.

44

94

## RESULTADOS

LOS COEFICIENTES DE LA ECUACION SON

A= 1.00000 B= 2.00000 C= 3.00000

EL DISCRIMINANTE ES NEGATIVO, POR TANTO RAICES COMPLEJAS

X1= -1.00000 + 1.41421 IMA X2= -1.00000 - 1.41421 IMA

LOS COEFICIENTES DE LA ECUACION SON

A= 5.00000 B= 10.00000 C= 5.00000

EL DISCRIMINANTE ES NULO, POR TANTO RAICES IGUALES

X1= -1.00000 X2= -1.00000

LOS COEFICIENTES DE LA ECUACION SON

A= 1.00000 B= 10.00000 C= 27.00000

EL DISCRIMINANTE ES NEGATIVO, POR TANTO RAICES COMPLEJAS

X1= -5.00000 + 1.41421 IMA X2= -5.00000 - 1.41421 IMA

LOS COEFICIENTES DE LA ECUACION SON

A= 3.00000 B= 20.00000 C= 1.00000

EL DISCRIMINANTE ES POSITIVO, POR TANTO RAICES REALES

X1= 0.05038 X2= -6.61629



// JOB T  
// FOR  
\*LIST SOURCE PROGRAM  
\*ONE WORD INTEGERS  
\*IOCS(CARD,1132-PRINTER)

95

C-----D I E C I N U E V E-----

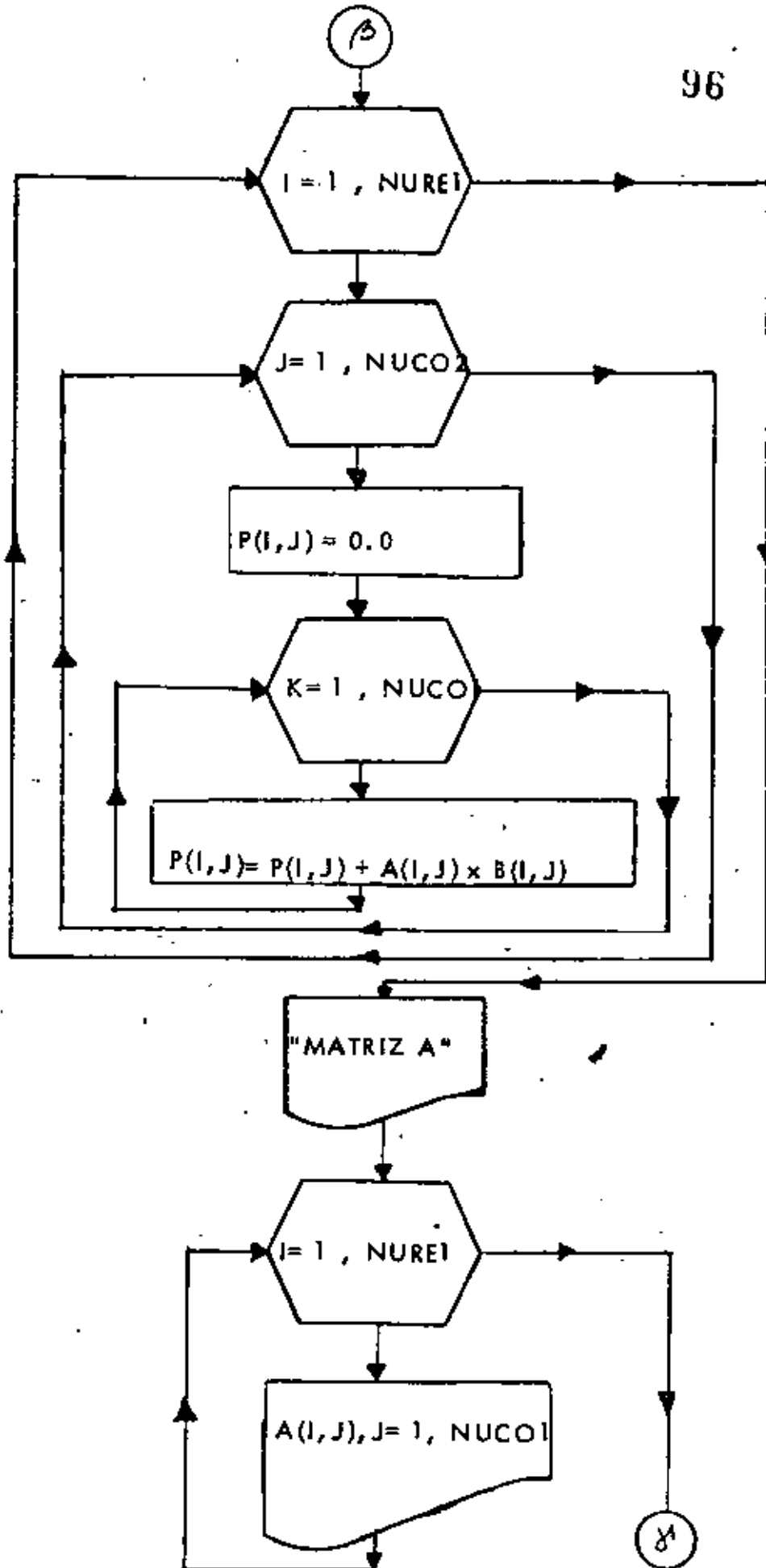
```

C      SOLUCION DE ECUACIONES CUADRATICAS.
      200 FORMAT(3F11.5)
101  FORMAT(///,2X,36HLOS COEFICIENTES DE LA ECUACION SON,///)
102  FORMAT(2X,3HA= ,F11.5,2X,3HB= ,F11.5,2X,3HC= ,F11.5,///)
103  FORMAT(2X,52HEL DISCRIMINANTE ES POSITIVO,POR TANTO RAICES REALES,
      1//)
104  FORMAT(5X,3HX1=,F11.5,10X,3HX2=,F11.5,///)
105  FORMAT(2X,49HEL DISCRIMINANTE ES NULO,POR TANTO RAICES IGUALES,///)
106  FORMAT(5X,3HX1=,F11.5,10X,3HX2=,F11.5,///)
107  FORMAT(2X,55HEL DISCRIMINANTE ES NEGATIVO,POR TANTO RAICES COMPLEJ
      1AS,///)
108  FORMAT(5X,3HX1=,F11.5,2H +,F11.5,4H IMA,10X,3HX2=,F11.5,2H -,F11.5
      1,4H IMA,///)
      LEE=2
      IMP=3
C      LEE LOS COEFICIENTES
200  READ(LEE,100,END=240)A,B,C
C      IMPRIME LA ECUACION
      WRITE(IMP,101)
      WRITE(IMP,102)A,B,C
C      CALCULO DEL DISCRIMINANTE
      DIS=B**2-4.0*A*C
      IF(DIS.LE. 0.0)GO TO 210
C      RAICES REALES DIFERENTES
      RA1=(-B+SQRT(DIS))/(2.0*A)
      RA2=(-B-SQRT(DIS))/(2.0*A)
      WRITE(IMP,103)
      WRITE(IMP,104)RA1,RA2
      GO TO 230
210  CONTINUE
      IF(DIS.NE.0.0)GO TO 220
C      RAICES REALES IGUALES
      RA1=-B/(2.0*A)
      RA2=RA1
      WRITE(IMP,105)
      WRITE(IMP,106)RA1,RA2
      GO TO 230
220  CONTINUE
C      RAICES COMPLEJAS
      PARE1=-B/(2.0*A)
      PARE2=PARE1
      PAIM1=SQRT(-DIS)/(2.0*A)
      PAIM2=PAIM1
      WRITE(IMP,107)
      WRITE(IMP,108)PARE1,PAIM1,PARE2,PAIM2
      GO TO 230
C      ENDIF
C      ENDIF
230  CONTINUE
      GO TO 200
240  CONTINUE
      CALL EXIT
      END

```

// XEQ  
1.0            2.0            3.0            1.  
5.0            10.0           5.0            1.  
1.0            10.0           27.0           1.

96

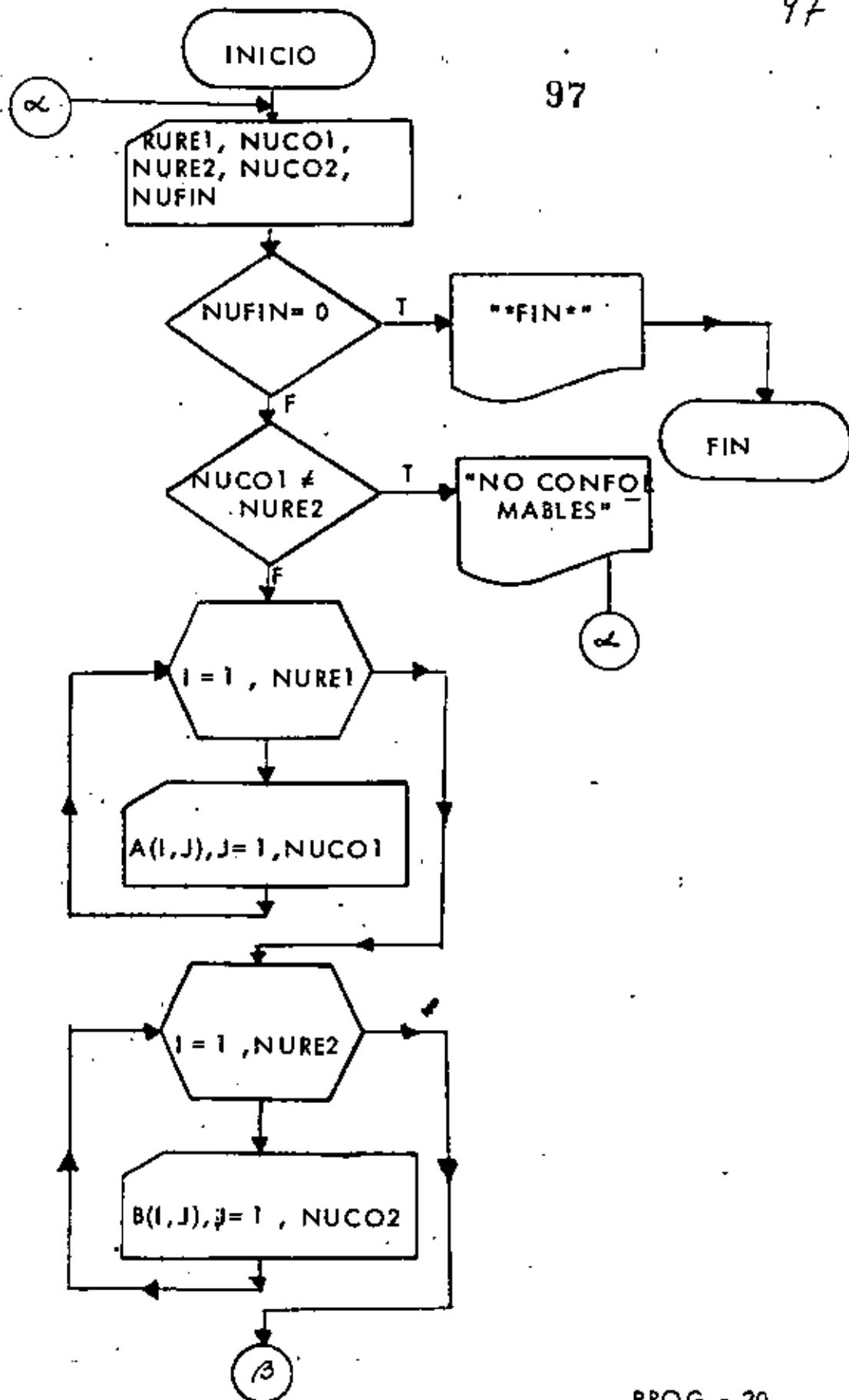


" PRODUCTO DE DOS MATRICES "

1a.

47

97



// JOB T  
// FOR

98

\*LIST SOURCE PROGRAM  
\*ONE WORD INTEGERS  
\*IOCS(CARD.1132 PRINTER)

98

C-----V E I N T E-----

C EL PROGRAMA REALIZA EL PRODUCTO DE DOS MATRICES DE 10 X 10 MAXIMO.  
C UNA ES LA MATRIZ A(NURE1,NUCO1).  
C LA OTRA ES LA MATRIZ B(NURE2,NUCO2).  
C SE RESERVAN LUGARES EN LA MEMORIA PARA LAS MATRICES QUE SE VAN A  
C MULTIPLICAR Y PARA LA MATRIZ PRODUCTO.  
C DIMENSION A(10,10),B(10,10),P(10,10)  
C FILES

LEE=2  
IMP=3

C FORMATOS

100 FORMAT(5I2)  
101 FORMAT(10F8,3)  
102 FORMAT(///,5X,9HMATRIZ A:,//)  
103 FORMAT(5X,10(F8,3,2X),//)  
104 FORMAT(///,5X,9HMATRIZ B:,//)  
105 FORMAT(///,5X,22HLA MATRIZ PRODUCTO ES:,//)  
106 FORMAT(5X,10E15,7,//)  
107 FORMAT(///,5X,76HEL PRODUCTO NO SE PUEDE LLEVAR A CABO YA QUE LAS  
1 MATRICES NO SON CONFORMABLES,///)  
108 FORMAT(///)  
109 FORMAT(53X,11H\*\*\*\*\*)  
110 FORMAT(53X,11H\* FIN \*)

C LECTURA DE LOS NUMEROS DE RENGLONES Y DE COLUMNAS DE CADA MATRIZ  
C Y DEL DETECTOR NUFIN.

199 READ(LEE,100)NURE1,NUCO1,NURE2,NUCO2,NUFIN

C ANALISIS DEL VALOR DE NUFIN. SI VALE CERO EL PROGRAMA NO SE LLEVA  
C A CABO, DE LO CONTRARIO SI.

IF(NUFIN.EQ.0)GO TO 1000

C SE VE SI LAS MATRICES SON CONFORMABLES.  
C IF(NUCO1.NE.NURE2)GO TO 900

C LECTURA POR RENGLONES DE LA MATRIZ A.  
C DO 200 I=1,NURE1

200 READ(LEE,101)(A(I,J),J=1,NUCO1)

CONTINUE

C LECTURA POR RENGLONES DE LA MATRIZ B.

201 DO 201 I=1,NURE2

201 READ(LEE,101)(B(I,J),J=1,NUCO2)

CONTINUE

C SE REALIZA EL PRODUCTO

202 DO 204 I=1,NURE1

203 DO 203 J=1,NUCO2

P(I,J)=0.0

204 DO 202 K=1,NUCO1

P(I,J)=P(I,J)+A(I,K)\*B(K,J)

CONTINUE

205 CONTINUE

206 CONTINUE

C IMPRESION DE LA MATRIZ A POR RENGLONES

WRITE(IMP,102)

207 DO 205 I=1,NURE1

208 WRITE(IMP,103)(A(I,J),J=1,NUCO1)

CONTINUE

C IMPRESION DE LA MATRIZ B POR RENGLONES.

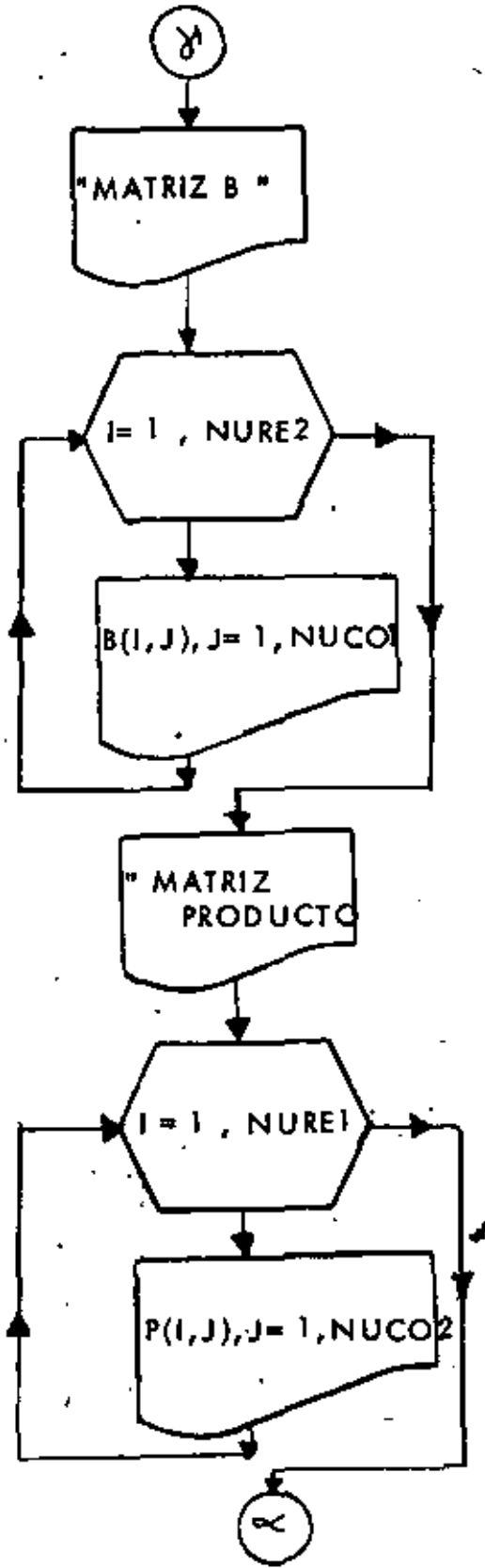
WRITE(IMP,104)

209 DO 206 I=1,NURE2

210 WRITE(IMP,103)(B(I,J),J=1,NUCO1)

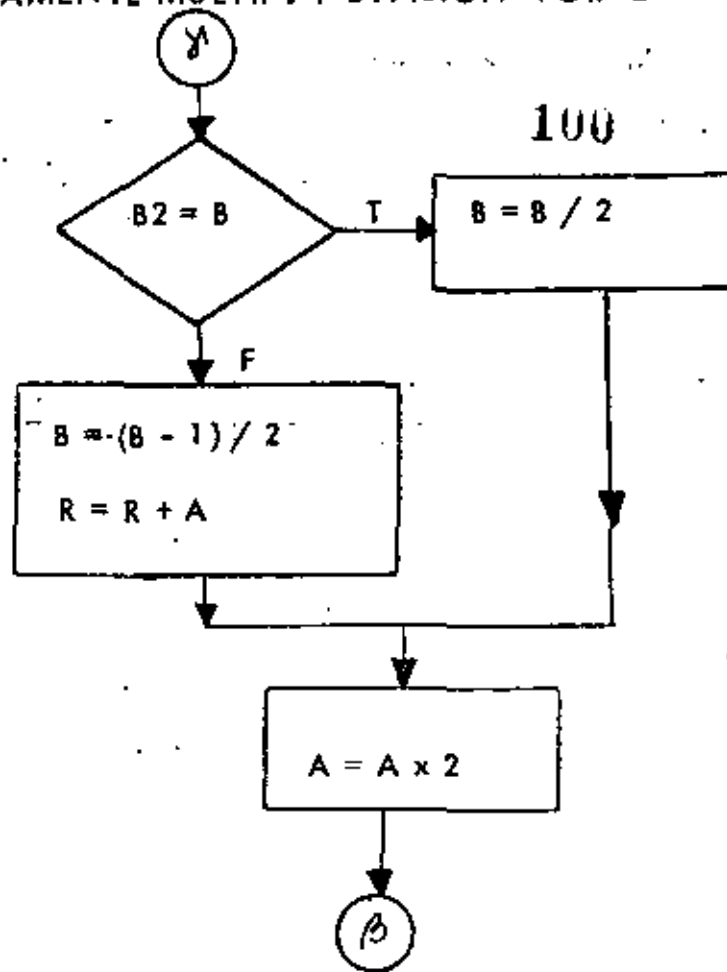
CONTINUE

99



" MULTIPLICACION DE DOS NUMEROS UTILIZANDO EXCLUSIVAMENTE MULTIP. Y DIVISION POR 2 "

2a. 100



C

IMPRESION DE LA MATRIZ P POR RENGLONES.

101

```

WRITE(IMP,105)
DO 207 I=1,NURE1
  WRITE(IMP,106)(P(I,J),J=1,NUCO2)

```

101

```

207 CONTINUE
  GO TO 199

```

```

900 CONTINUE
  WRITE(IMP,107)
  GO TO 199

```

```

1000 CONTINUE
  WRITE(IMP,108)
  WRITE(IMP,109)
  WRITE(IMP,110)
  WRITE(IMP,109)
  CALL EXIT
  END

```

```

// XEQ
2 2 2 210
  15.54 -42.07
  -1.22  0.0
1950.75 -12.0
  0.001  5.0
2 2 2 210
  0.2    98.75
 -12.5   32.52
1000.01  0.0
  -1.52  15.51
2 3 2 210
2 2 2 200
/*

```

RESULTADOS

102

102

MATRIZ A:

15.548    -2.070  
0.000    -1.220

MATRIZ B:

1950.750    -12.000  
0.001        5.000

LA MATRIZ PRODUCTO ES:

.3031461E+05    -.3968300E+03  
-.1220000E+02    -.6100000E+01

MATRIZ A:

0.200        98.750  
0.000        -12.500

MATRIZ B:

1000.010        0.000  
-1.520        15.510

LA MATRIZ PRODUCTO ES:

.4990200E+02    .1531613E+04  
.1900000E+02    -.1938750E+03

EL PRODUCTO NO SE PUEDE LLEVAR A CABO YA QUE LAS MATRICES NO SON CONFORMABLES

\*\*\*\*\*  
\*    FIN    \*  
\*\*\*\*\*

P-20



```

// JOB T
// FOR
*LIST SOURCE PROGRAM
*ONE WORD INTEGERS
*IOCS(CARD,1132 PRINTER)
C-----V E I N T I U N O -----
C   MULTIPLICACION DE DOS NUMEROS
C   UTILIZANDO SOLO MULTIPLICACIONES Y
C   DIVISIONES POR 2
C   INTEGER A,B,C,R,AA,BB
C   WRITE (3,101)
101 FORMAT (1H1)
C   WRITE (3,102)
102 FORMAT (9X,1HA,3X,1HX,4X,1HB,4X,1H=,4X,1HC)
200 READ (2,100,END=260)A,B
100 FORMAT (2I3)
C   R=0
C   AA=A
C   BB=B
210 IF(B.EQ.1) GO TO 240
C   B1=B/2
C   B2=B1*2
C   IF(B2.EQ.B) GO TO 220
C   ES IMPAR
C   B=(B-1)/2
C   R=R+A
C   GO TO 230
220 CONTINUE
C   ES PAR
C   B=B/2
230 CONTINUE
C   A=A*2
C   GO TO 210
240 CONTINUE
C   C=A+R
C   WRITE (3,103) AA,BB,C
103 FORMAT (3I10)
C   GO TO 200
260 CALL EXIT
END

```

```

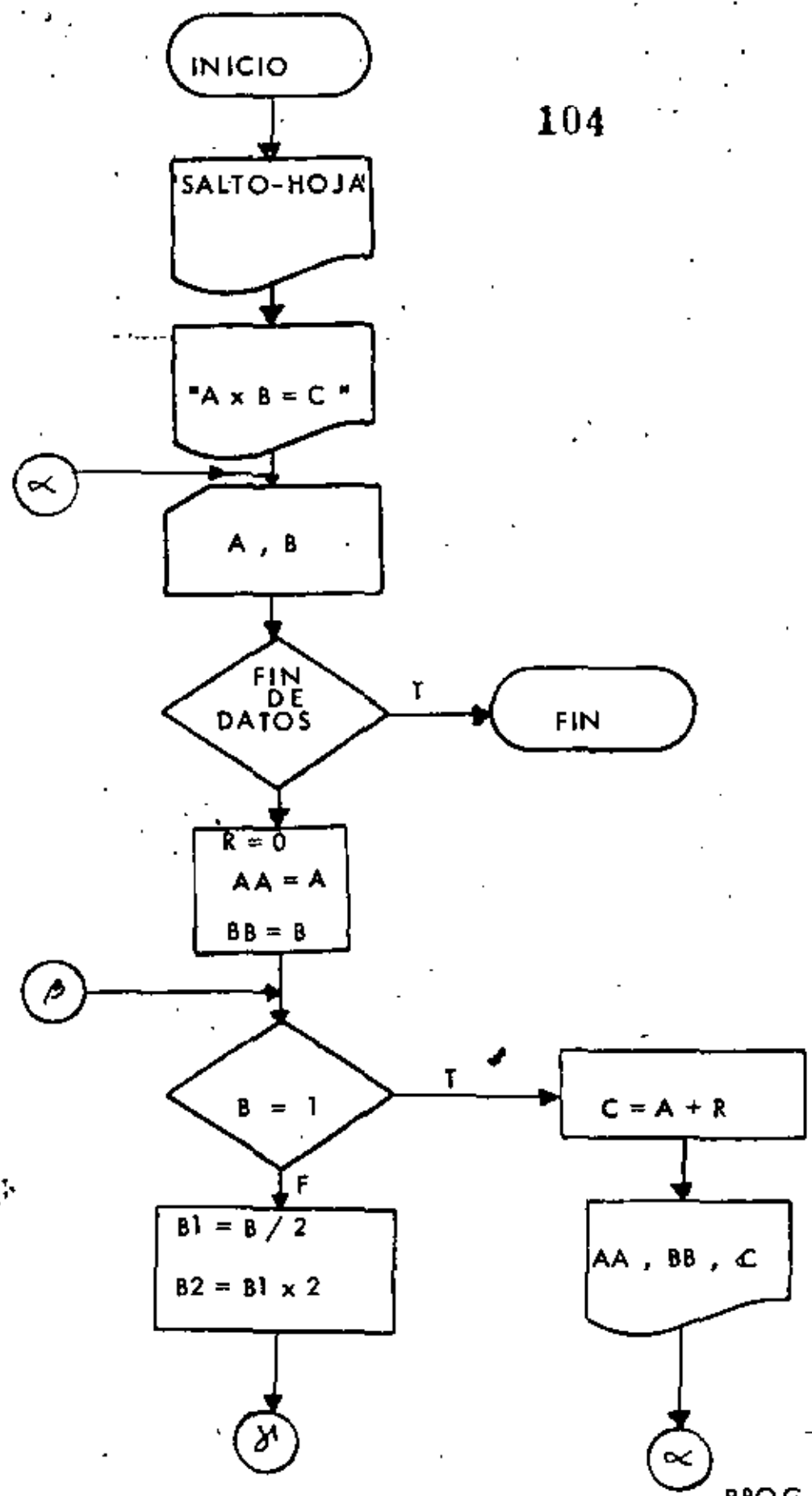
// XEQ
60 80
19 17
68 35
40 11
77 99
/*

```

RESULTADOS

	A	X	R	C
60	80		80	4800
19	17		17	323
68	35		35	2380
40	11		11	440
77	99		99	7623

104



```

// JOB T
// FOR
*LIST SOURCE PROGRAM
*ONE WORD INTEGERS
*IOCS(CARD,1132 PRINTER)
C-----V E I N T I U N O -----
C   MULTIPLICACION DE DOS NUMEROS
C   UTILIZANDO SOLO MULTIPLICACIONES Y
C   DIVISIONES POR 2
C   INTEGER A,B,C,R,AA,BB
C   WRITE (3,101)
101 FORMAT (1H1)
C   WRITE (3,102)
102 FORMAT (9X,1HA,3X,1HX,4X,1HB,4X,1H=.4X,1HC)
200 READ (2,100,END=260)A,B
100 FORMAT (2I3)
C   R=0
C   AA=A
C   BB=B
210 IF(B.EQ.1) GO TO 240
C   B1=B/2
C   R2=B1*2
C   IF(B2.EQ.B) GO TO 220
C   ES IMPAR
C   B=(B-1)/2
C   R=R+A
C   GO TO 230
220 CONTINUE
C   ES PAR
C   B=B/2
230 CONTINUE
C   A=A*2
C   GO TO 210
240 CONTINUE
C   C=A+R
C   WRITE (3,103) AA,BB,C
103 FORMAT (3I10)
C   GO TO 200
260 CALL EXIT
END

```

```

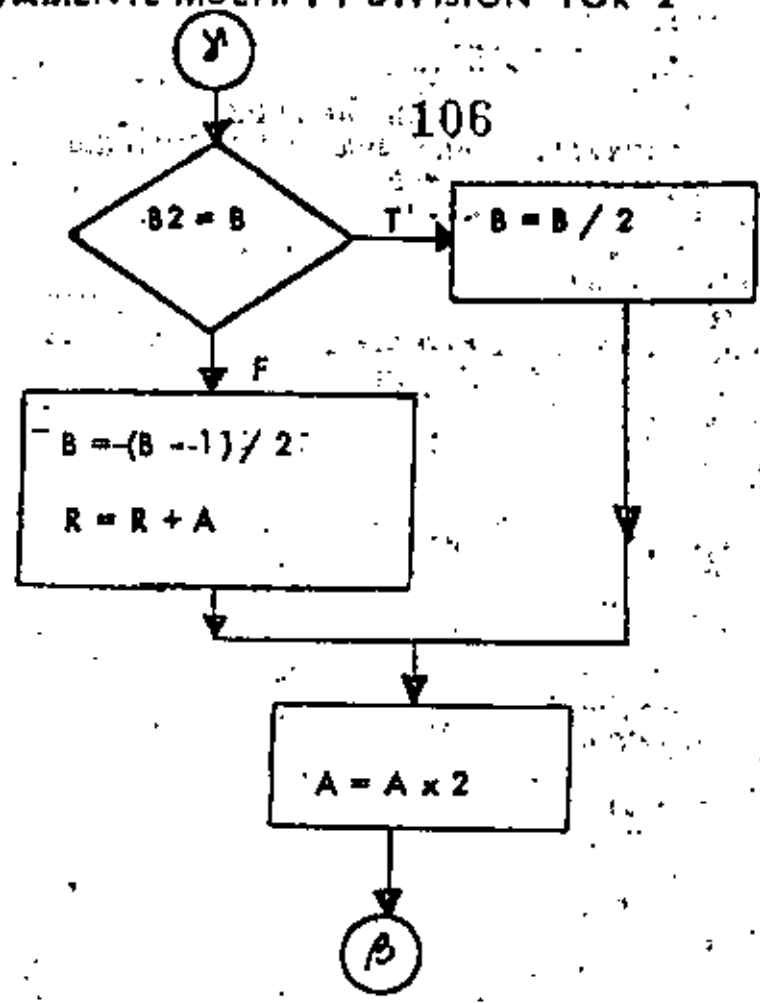
// XEQ
60 80
19 17
68 35
40 11
77 99
//X

```

RESULTADOS

A	B	C
60	80	4800
19	17	323
68	35	2380
40	11	440
77	99	7623

\* MULTIPLICACION DE DOS NUMEROS UTILIZANDO EXCLUSIVAMENTE MULTIP. Y DIVISION POR 2 \*



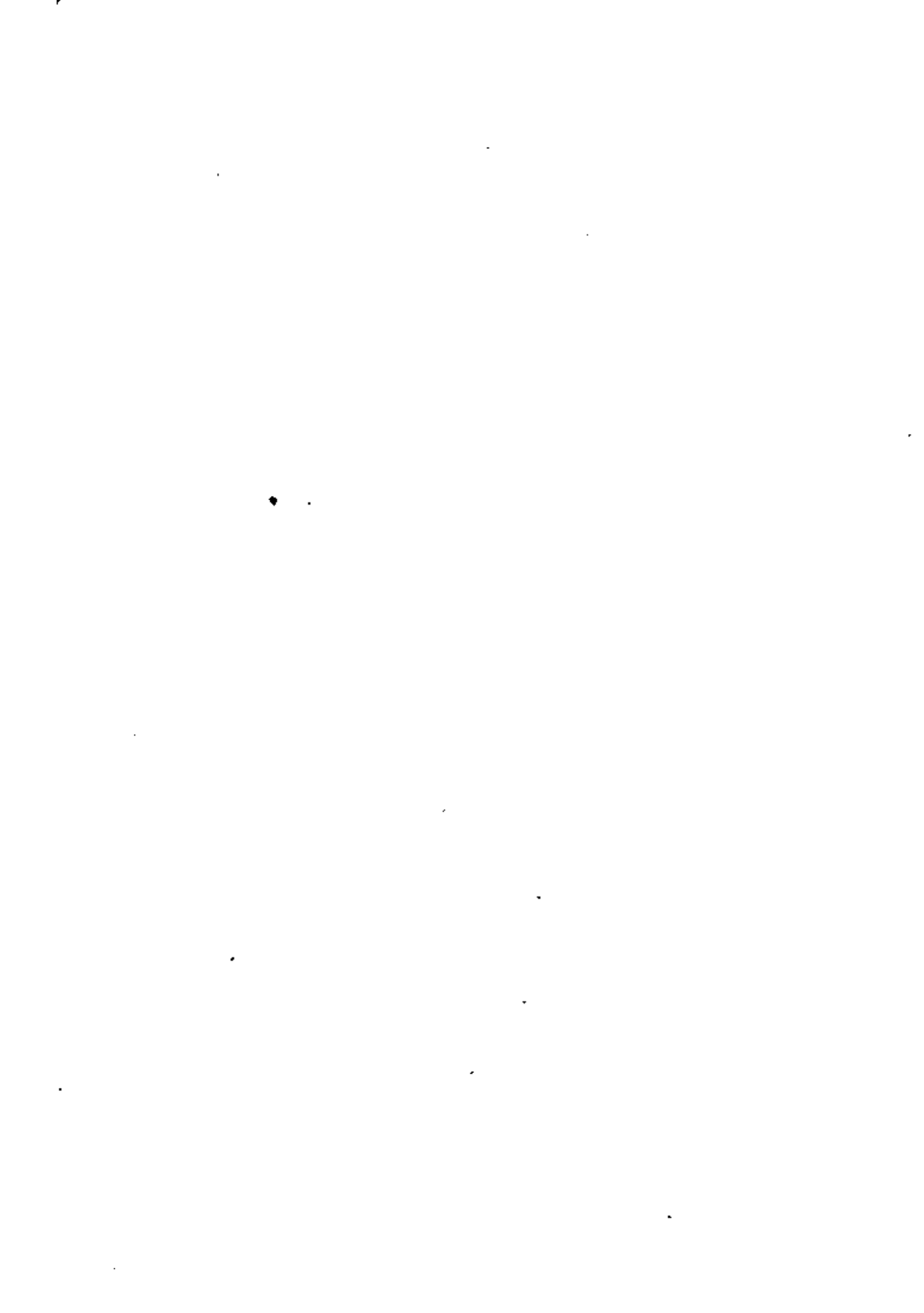


**DIVISION DE EDUCACION CONTINUA  
FACULTAD DE INGENIERIA U.N.A.M.**

INTRODUCCION A LA PROGRAMACION Y COMPUTACION ELECTRONICA

SISTEMAS DE ECUACIONES CON FORTAN  
SOLUCION DE APLICACIONES MATEMATICAS

OCHUBRE, 1981



## 2. ALGEBRA MATRICIAL

### 1

#### 2.1 Introducción

Una matriz es un arreglo rectangular de elementos distribuidos en "m" renglones y "n" columnas, si a la matriz se le denota por la letra  $A$ , entonces al elemento del "i-ésimo" renglón y de la "j-ésima" columna se le representará por el símbolo  $a_{ij}$ . Generalmente una matriz se representa mediante paréntesis cuadrados como se muestra a continuación:

$$\underline{A} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \cdot & & & \cdot \\ \cdot & & & \cdot \\ \cdot & & & \cdot \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix} \quad [2.1]$$

Los elementos que componen una matriz pueden ser de diversos tipos: números reales, números complejos, funciones en el dominio del tiempo, etc..

Al ser una matriz un arreglo ordenado de elementos, permite que al aplicar cierta metodología a dicho arreglo se obtenga una serie de resultados que responden a las interrogantes por las que se originó el arreglo; entre algunos de los procesos en los que se utilizan arreglos matriciales se tiene: jerarquización de actividades, almacenamiento de datos, inventarios, representación de sistemas dinámicos, sistemas de ecuaciones, etc..

Existen ciertas distribuciones típicas de los elementos de una matriz y de acuerdo a ellas se clasifica a las matrices en diferentes tipos, entre los que se tienen:

#### Matriz Cuadrada

Es una matriz en la que el número de renglones es igual al número de columnas, es decir,  $m=n$ . Por ejemplo:

$$\underline{A} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \quad [2.2]$$

## 2

## Matriz Nula

Es una matriz de orden cualquiera, en la que todos los elementos son nulos; por ejemplo:

$$\underline{B} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{bmatrix} \quad (2.3)$$

Se acostumbra denotarla por el símbolo  $\underline{0}$ .

## Matriz Identidad

Es una matriz cuadrada en la cual los elementos de la diagonal principal son unitarios y el resto son nulos, es decir:

$$\delta_{ij} = \begin{cases} 0 & , i \neq j \\ 1 & , i = j \end{cases}$$

Se suele denotarla como  $\underline{I}_n$  donde "n" indica el orden de la matriz y al símbolo  $\delta_{ij}$  se le conoce como delta de Kronecker. Por ejemplo:

$$\underline{I}_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad (2.4)$$

## Matriz Diagonal

Es una matriz cuadrada en la que los elementos que no pertenecen a la diagonal principal son nulos, es decir:

$$a_{ij} = 0 \quad \text{si } i \neq j \quad (2.5)$$

Un ejemplo de este tipo de matriz sería:

$$\underline{A} = \begin{bmatrix} 5 & 0 & 0 \\ 0 & 10 & 0 \\ 0 & 0 & 20 \end{bmatrix} \quad (2.6)$$

## Matriz Transpuesta

Es una matriz cuadrada que se obtiene a partir de una matriz dada  $\underline{A}$  intercambiando renglones con columnas. Se le denota con el símbolo  $\underline{A}^T$  y se cumple que:

$$a_{ij}^T = a_{ji} \quad (2.7)$$

## Matriz Simétrica

Es una matriz cuadrada  $\underline{B}$  para la que se cumple:

$$\underline{B} = \underline{B}^T \quad (2.8)$$



o equivalentemente:

$$b_{ij} = b_{ji} \quad (2.9)$$

Entre las matrices se definen dos operaciones básicas:

- suma o resta de matrices,
- multiplicación matricial.

## 2.2 Suma Matricial

### 2.2.1 Objeto

Obtener la suma de dos matrices de igual orden, o sea:

$$\underline{C} = \underline{A} + \underline{B} \quad (2.10)$$

### 2.2.2 Método

Para poder efectuar la suma de dos matrices ( $\underline{A} + \underline{B}$ ) se requiere que sean conformables para la suma, lo cual implica que el orden de las dos matrices es igual. En otras palabras:

si  $\underline{A}$  es de orden  $(m \times n)$

y  $\underline{B}$  es de orden  $(r \times s)$

la suma  $\underline{C} = \underline{A} + \underline{B}$  es posible solo si  $m=r$  y  $n=s$ .

Los elementos de la matriz suma están dados por la siguiente relación:

$$c_{ij} = a_{ij} + b_{ij} \quad (2.11)$$

El restar dos matrices equivale a cambiar el signo de todos los elementos de una de ellas y efectuar la suma, esto es:

$$\underline{W} = \underline{X} - \underline{Y} = \underline{X} + \{-\underline{Y}\} \quad (2.12)$$

### 2.2.3 Descripción del Programa

a) Subrutinas requeridas:

SUBROUTINE SUMAT(A, B, C, N, M), esta subrutina efectúa la suma matricial, el programa principal lee e imprime resultados.

b) Descripción de las variables:

Para la subrutina SUMAT:

N cantidad de renglones de cada una de las matrices que se desea sumar.  
 M cantidad de columnas de cada una de las matrices que se desea sumar.  
 A(I, J) matriz sumando de orden NxM  
 B(I, J) matriz sumando de orden NxM  
 C(I, J) matriz suma

Para el programa principal:

N cantidad de renglones de las matrices  
 M cantidad de columnas de las matrices  
 A(I, J) matriz sumando de orden NxM  
 B(I, J) matriz sumando de orden NxM  
 C(I, J) matriz suma

c) Dimensiones:

La proposición DIMENSION deberá ser modificada tanto en el programa principal como en la subrutina cuando:

$N > 10$  y/o  $M > 10$

d) Formatos para los datos de entrada:

SEC. TARJETAS	FORMATO	INFORMACION
1	(2I5)	N, M
2	(8F10.0)	A(I, J), se dan los elementos de la matriz renglón por renglón. Emplear tantas tarjetas como se requiera.
3	(8F10.0)	B(I, J), igual que para la matriz A.

-----  
 otros paquetes de datos (opcional)  
 -----

n . . . . . TARJETA EN BLANCO, al finalizar toda la información.

e) Diagrama de bloques

Fig. 2.1 Diagrama de bloques para el programa principal

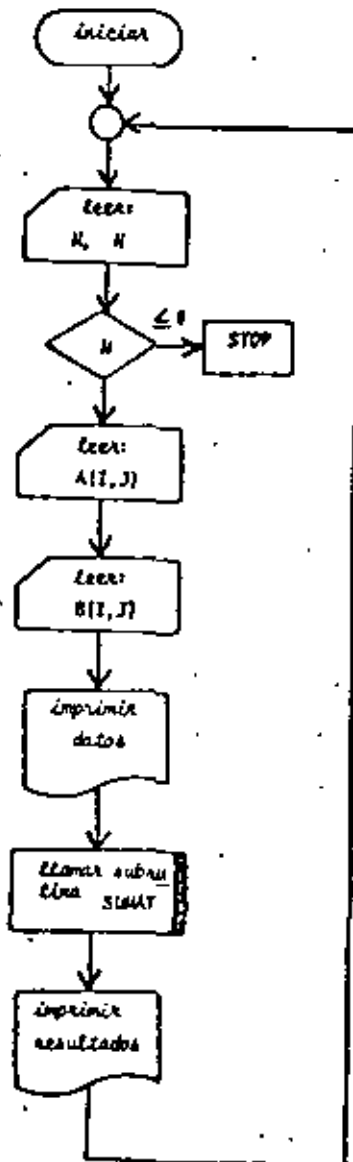
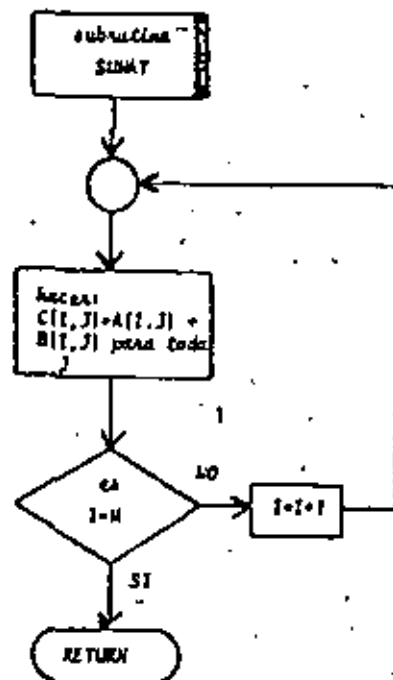


Fig. 2.2 Diagrama de bloques para la subrutina SUMAT



```

PROGRAMA PARA EFECTUAR LA SUMA DE DOS MATRICES
EL SIGNIFICADO DE LAS VARIABLES EMPLEADAS ES
CANTIDAD DE RENGLONES DE LAS MATRICES
CANTIDAD DE COLUMNAS DE LAS MATRICES
A Y B MATRICES QUE SERAN SUMADAS
C MATRIZ SUMA

DIMENSION A(10,10),B(10,10),C(10,10)
LECTURA DE DATOS
1 READ(5,100) M,N
  IF(N) 2,2,S
2 CALL EXIT
3 DO 4 I=1,M
4 READ(5,150) (A(I,J),J=1,N)
  DO 5 J=1,N
5 READ(5,150) (B(I,J),J=1,N)

IMPRESION DE DATOS
WRITE(6,200)
DO 6 I=1,M
6 WRITE(6,250) (A(I,J),J=1,N)
  WRITE(6,300)
  DO 7 J=1,N
7 WRITE(6,250) (B(I,J),J=1,N)

LLAMADO DE SUBROUTINA PARA EFECTUAR LA SUMA
CALL SUMATA(B,C,M,N)

IMPRESION DE RESULTADOS
WRITE(6,350)
DO 8 I=1,M
8 WRITE(6,250) (C(I,J),J=1,N)
  GO TO 1

FORMATOS DE LECTURA E IMPRESION
100 FORMAT(2I5)
150 FORMAT(7F10.0)
200 FORMAT(1H1,5I/,10X,'LAS MATRICES POR SUMAR SON',3I/,10X,'MATRIZ',
1H/,/)
250 FORMAT(1,3Y,10(E10.3,2X))
300 FORMAT(3I/,10X,'MATRIZ',1H/,/)
350 FORMAT(6I/,10X,'MATRIZ SUMA',/)
END

```

Fig. 2.3 Listado del programa principal

```

SUBROUTINE SUMATA(B,C,M,N)
SUBROUTINA PARA SUMAR MATRICES
SIGNIFICADO DE LAS VARIABLES EMPLEADAS
A Y B MATRICES QUE SE DESEA SUMAR
CANTIDAD DE RENGLONES DE LAS MATRICES
CANTIDAD DE COLUMNAS DE LAS MATRICES
DIMENSION A(10,10),B(10,10),C(10,10)
DO 1 I=1,M
DO 2 J=1,N
1 C(I,J)=A(I,J)+B(I,J)
RETURN
END

```

Fig. 2.4 Listado de la subrutina SUMAT

## 2.2.4 Ejemplo

En una tienda de artículos eléctricos se venden resistencias, eléctricas de 1/4, 1/2 y 1 Watt de potencia en seis diferentes valores resistivos.

Si las existencias un viernes por la tarde son:

	1/4	1/2	1
100 $\Omega$	200	380	275
150 $\Omega$	400	250	275
1.0 K	500	175	325
1.5 K	800	225	150
10.0 K	600	380	180
15.0 K	550	250	220

y el sábado se recibe una remesa con las siguientes características:

	1/4	1/2	1
100 $\Omega$	80	90	50
150 $\Omega$	90	100	55
1.0 K	75	90	60
1.5 K	65	95	55
10.0 K	80	100	60
15.0 K	75	110	60

Determine las resistencias que tendrá en inventario el establecimiento el lunes por la mañana dado que ni el sábado ni el domingo hubo ventas.

## \* SOLUCION

TABLA 2.1 Datos para el problema del ejemplo 2.2.4

$N=6$

$M=3$

<u>A</u> =	200	380	275
	400	250	275
	500	175	325
	800	225	150
	600	380	180
	550	250	220

8

$$B = \begin{bmatrix} 80 & 90 & 50 \\ 90 & 100 & 55 \\ 75 & 90 & 60 \\ 65 & 95 & 55 \\ 80 & 100 & 60 \\ 75 & 110 & 60 \end{bmatrix}$$

TABLA 2.2 Resultados del problema del ejemplo 2.2.4.

LAS MATRICES POR SUMAR SON

---

MATRIZ A

---

.200E+03	.350E+03	.275E+03
.400E+03	.250E+03	.275E+03
.500E+03	.175E+03	.325E+03
.800E+03	.225E+03	.150E+03
.600E+03	.300E+03	.100E+03
.550E+03	.250E+03	.220E+03

---

MATRIZ B

---

.800E+02	.900E+02	.500E+02
.900E+02	.100E+03	.550E+02
.750E+02	.900E+02	.600E+02
.650E+02	.950E+02	.550E+02
.800E+02	.100E+03	.600E+02
.750E+02	.110E+03	.600E+02

---

MATRIZ SUMA

---

.280E+03	.470E+03	.320E+03
.490E+03	.350E+03	.330E+03
.575E+03	.265E+03	.385E+03
.865E+03	.320E+03	.205E+03
.680E+03	.400E+03	.240E+03
.625E+03	.360E+03	.280E+03

## 2.3 Multiplicación Matricial

### 2.3.1 Objeto

Dadas dos matrices A y B, obtener el producto matricial C de la forma:

$$\underline{C} = \underline{A} \times \underline{B} \quad (2.13)$$

### 2.3.2 Método

Para efectuar el producto entre dos matrices (AxB) se requiere que las matrices sean conformables para la multiplicación, lo que equivale a que el número de columnas de la matriz premultiplicadora (A) sea igual al número de renglones de la postmultiplicadora (B), es decir:

si A es de orden (m x n)

y B es de orden (n x s)

el producto matricial AB será posible solo si  $n=n$  y el orden de la matriz producto será (m x s).

Si la matriz C representa la matriz resultante del producto matricial AB, entonces el elemento  $c_{ij}$  está dado por:

$$c_{ij} = \sum_{l=1}^n a_{il} b_{lj}, \quad \begin{matrix} i=1, \dots, m \\ j=1, \dots, s \end{matrix} \quad (2.14)$$

Es importante hacer notar que el producto matricial no es conmutativo, esto es:

$$\underline{A} \times \underline{B} \neq \underline{B} \times \underline{A}$$

### 2.3.3 Descripción del Programa

a) Subrutinas requeridas:

SUBROUTINE MULTMA(A, B, N, M, L, X), esta subrutina efectúa el producto matricial AxB. El programa principal se emplea para la lectura de datos e impresión de resultados.

b) Descripción de las variables:

Para la subrutina MULTMA:

A(I, J)      matriz premultiplicadora de orden NxM

## 10

B(I, J)        matriz postmultiplicadora de orden  $M \times L$   
 X(I, J)        matriz producto de orden  $N \times L$   
 Para el programa principal:  
 A(I, J)        matriz premultiplicadora de orden  $N \times M$   
 B(I, J)        matriz postmultiplicadora de orden  $M \times L$   
 X(I, J)        matriz producto de orden  $N \times L$

## c) Dimensiones:

La proposición DIMENSION deberá ser modificada tanto en el programa principal como en la subrutina cuando:

$N > 10$  y/o  $M > 10$  y/o  $L > 10$

## d) Formatos para los datos de entrada:

SEC. TARJETAS	FORMATO	INFORMACION
1	(3I5)	N, M, L
2	(BF10.0)	A(I, J), los elementos de la matriz se dan renglón por renglón. Emplear la cantidad de tarjetas que sea necesaria.
3	(BF10.0)	B(I, J), igual que en el caso anterior.

-----  
 otros paquetes de datos (opcional)  
 -----

n

TARJETA EN BLANCO, al finalizar toda la información

## e) Diagrama de bloques:



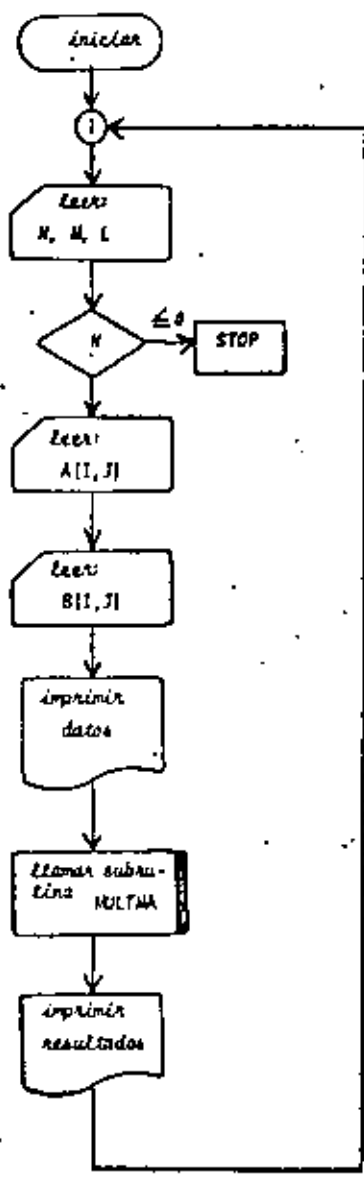


Fig. 2.5 Diagrama de bloques para el programa principal

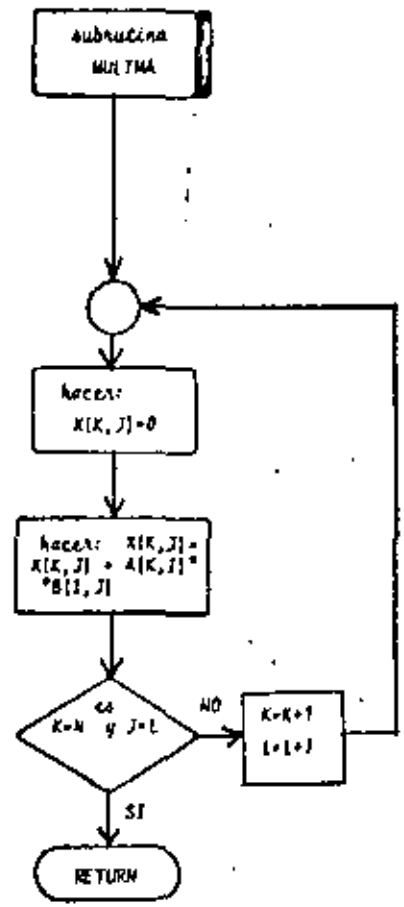


Fig. 2.6 Diagrama de bloques para la subrutina MULTMA

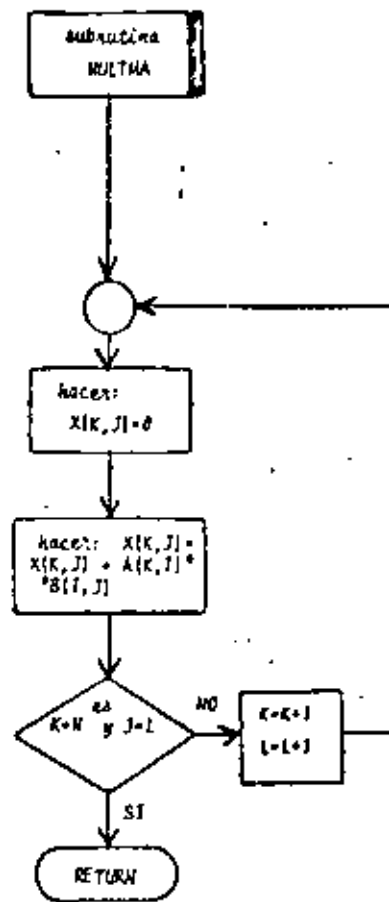


Fig. 2.6 Diagrama de bloques para la subrutina MULTMA

6) Listado:

```

C   PROGRAMA PARA EFECTUAR PRODUCTOS MATRICIALES
C   SIGNIFICADO DE LAS VARIABLES EMPLEADAS
C   A=MATRIZ PREMULTIPLICADORA DE ORDEN (M*N)
C   B=MATRIZ MULTIMPLICADORA DE ORDEN (N*L)
C   X=MATRIZ PRODUCTO DE ORDEN (M*L)

DIMENSION A(10,10),B(10,10),X(10,10)
IR=5
IN=6
C   LECTURA DE DATOS
1  READ(IR,10) N,M,L
   IF(N) 2,2,3
2  CALL EXIT
3  GO 4 10,10
4  READ(IR,11) (A(I,J),J=1,M)
   GO 5 10,10
5  READ(IR,11) (B(I,J),J=1,L)
C   IMPRESION DE DATOS
WRITE(1,12)
DO 6 10,10
6  WRITE(1,13) (A(I,J),J=1,M)
   WRITE(1,14)
   GO 7 10,10
7  WRITE(1,15) (B(I,J),J=1,L)
   WRITE(1,15)
C   LLAMADA DE SUBROUTINA PARA EFECTUAR PRODUCTO MATRICIAL
CALL MULTHA(A,B,N,M,L,X)
C   IMPRESION DE RESULTADOS
DO 8 10,10
8  WRITE(1,16) (X(I,J),J=1,L)
   GO 9 1
C   FORMATS DE LECTURA E IMPRESION
10 FORMAT (I15)
11 FORMAT(2F10.0)
12 FORMAT(4F7.5), 'MATRIZ A', //
13 FORMAT(//2X,10(10.0), //)
14 FORMAT(//2X,5), 'MATRIZ B', //
15 FORMAT(//2X,5), 'MATRIZ PRODUCTO', //
END

```

Fig. 2.7 Listado del programa principal

```

C   SUBROUTINE MULTHA(A,B,N,M,L,X)
C   SUBROUTINA PARA MULTIPLICAR DOS MATRICES
C   AL SIGNIFICADO DE LAS VARIABLES EMPLEADAS ES
C   A=MATRIZ PREMULTIPLICADORA DE ORDEN (M*N)
C   B=MATRIZ MULTIMPLICADORA DE ORDEN (N*L)
C   X=MATRIZ PRODUCTO
C
DIMENSION A(10,10),B(10,10),X(10,10)
DO 1 10,10
DO 1 10,10
X(I,J)=0
DO 1 10,10
1 X(I,J)=X(I,J) + A(I) * B(1,J)
RETURN
END

```

Fig. 2.8 Listado de la subrutina MULTHA

## 2.3.4 Ejemplo

Cuatro componentes de un automóvil requieren como materia prima de hule, aluminio y acero. Las unidades que se requieren de cada material para formar una unidad de cada componente del automóvil se proporcionan a continuación:

	hule	aluminio	acero
comp. 1	8	5	3
comp. 2	3	4	5
comp. 3	20	2	4
comp. 4	1	8	10

si los costos unitarios de cada material son:

	\$
hule	25.00
aluminio	30.00
acero	40.00

Determine el costo total de cada componente debido a la materia prima de que está compuesto.

## \*SOLUCION

TABLA 2.3 Datos para el problema del ejemplo 2.3.4

$$N=4$$

$$M=3$$

$$L=1$$

$$\underline{A} = \begin{bmatrix} 8 & 5 & 3 \\ 3 & 4 & 5 \\ 20 & 2 & 4 \\ 1 & 8 & 10 \end{bmatrix}$$

$$\underline{B} = \begin{bmatrix} 25 \\ 30 \\ 40 \end{bmatrix}$$

TABLA 2.4 Resultados del problema del ejemplo 2.3.4

MATRIZ A

.800E+01	.500E+01	.300E+01
.300E+01	.400E+01	.500E+01
.200E+02	.700E+01	.600E+01
.100E+01	.800E+01	.100E+02

MATRIZ B

.250E+02
.300E+02
.400E+02

MATRIZ PRODUCTO

.470E+01
.395E+01
.720E+01
.465E+01

### 2.4 Inversión de Matrices

#### 2.4.1 Objeto

Dada una matriz cuadrada  $\underline{A}$  obtener su matriz inversa  $\underline{A}^{-1}$ .

#### 2.4.2 Método

La matriz inversa de una matriz cuadrada  $\underline{A}$  es otra matriz cuadrada que se representa por  $\underline{A}^{-1}$  y que cumple la siguiente propiedad si la matriz  $\underline{A}$  es de orden  $(n \times n)$ :

$$\underline{A} \underline{A}^{-1} = \underline{I}_n = \underline{A}^{-1} \underline{A} \tag{2.15}$$

Se define a la matriz inversa como:

$$\underline{A}^{-1} = \frac{\underline{A}^+}{|\underline{A}|} \tag{2.16}$$

donde  $\underline{A}^+$  se conoce como la matriz adjunta de la matriz  $\underline{A}$  y  $|\underline{A}|$  representa el determinante de la matriz  $\underline{A}$ .

De la ecuación (2.16) se infiere que para que exista la inversa de una matriz se requiere que  $|\underline{A}| \neq 0$ , es decir, que la matriz sea no singular.

Para la obtención numérica de la matriz inversa es necesario acudir al método de Gauss-Jordan modificado. Esto se hace debido a que para obtener  $\underline{A}^{-1}$  en una computadora digital mediante la ecuación (2.16) se requiere una gran cantidad de operaciones y consecuentemente de tiempo. Para obtener la inversa de una matriz  $(10 \times 10)$  se requieren más de 340 millones de operaciones con el método directo.

El método de Gauss-Jordan es un método de eliminación sistemática mediante el cual se transforma la matriz original  $\underline{A}$  en una matriz identidad  $\underline{I}_n$  y al mismo tiempo esta última se transforma en la matriz inversa  $\underline{A}^{-1}$ , es decir, partiendo del arreglo:

$$\left[ \begin{array}{c|c} \underline{A} & \underline{I}_n \end{array} \right] \tag{2.17}$$

y aplicando algunas de las siguientes transformaciones al arreglo (2.17):

- intercambio de renglones,
  - multiplicación de un renglón por un escalar  $\lambda \neq 0$ ,
  - suma de equimúltiplos de un renglón a otro renglón.
- se llega al siguiente arreglo:

$$\left[ \begin{array}{c|c} I_n & A^{-1} \\ \hline & \end{array} \right] \quad (2.18)$$

El método parte de la suposición de que  $A$  es una matriz no singular, lo cual implica que sus columnas son vectores linealmente independientes, en caso de no serlo el método lo puede detectar; en dicha situación se presenta que todos los elementos de un renglón de la matriz  $A$  o de sus matrices transformadas, son nulos.

A fin de minimizar los errores de redondeo, la eliminación de elementos se efectúa pivoteando sobre los mayores elementos que quedan en la matriz  $A$  o en las matrices obtenidas a partir de esta última por transformación; debe tenerse cuidado de no emplear como pivotes elementos de renglones que ya hayan sido utilizados como pivotes.

### 2.4.3 Descripción del Programa

#### a) Subrutinas requeridas:

SUBROUTINE MATINV[A,N,EPS,DET], obtiene la matriz inversa de la matriz  $A$ . El programa principal se emplea para la lectura de datos e impresión de resultados.

#### b) Descripción de las variables:

Para la subrutina MATINV:

A[I,J]        matriz de la que se buscará la inversa, durante el proceso se convierte en la matriz inversa.

N              orden de la matriz  $A$

EPS            criterio para determinar si el determinante de la matriz es nulo

DET            parámetro que indica si el determinante de la matriz es nulo

C[I,J]        matriz identidad que se emplea para obtener la matriz inversa

MVR[I] y  
MVC[I]        contadores que indican cuáles renglones y cuáles columnas de la matriz  $A$  ya fueron empleados como pivotes



RAMAX	mayor elemento de la matriz <u>A</u> o de sus transformaciones que se emplea como elemento pivote
TEMP	variable de localización temporal
Para el programa principal:	
A(I, J)	matriz de la que se busca la inversa, durante el proceso se convierte en la matriz inversa
N	orden de la matriz <u>A</u>
EPS	criterio para determinar si el determinante de la matriz <u>A</u> es nulo.
DET	variable que indica si el determinante de <u>A</u> es o no nulo

c) Dimensiones:

La proposición DIMENSION del programa principal y de la subrutina deberá ser modificada cuando:

$$N > 10$$

d) Formatos para los datos de entrada:

SEC. TARJETAS	FORMATO	INFORMACION
1	(I5)	N
2	(8F10.0)	A(I, J), se proporcionan los elementos de la matriz renglón por renglón. Emplear tantas tarjetas como se requir <u>e</u> ran.
-----		
	otros paquetes de datos (opcional)	
-----		
n	TARJETA EN BLANCO, al finalizar toda la infor <u>m</u> ación.	

e) Diagrama de bloques:

Fig. 2.9 Diagrama de bloques del programa principal

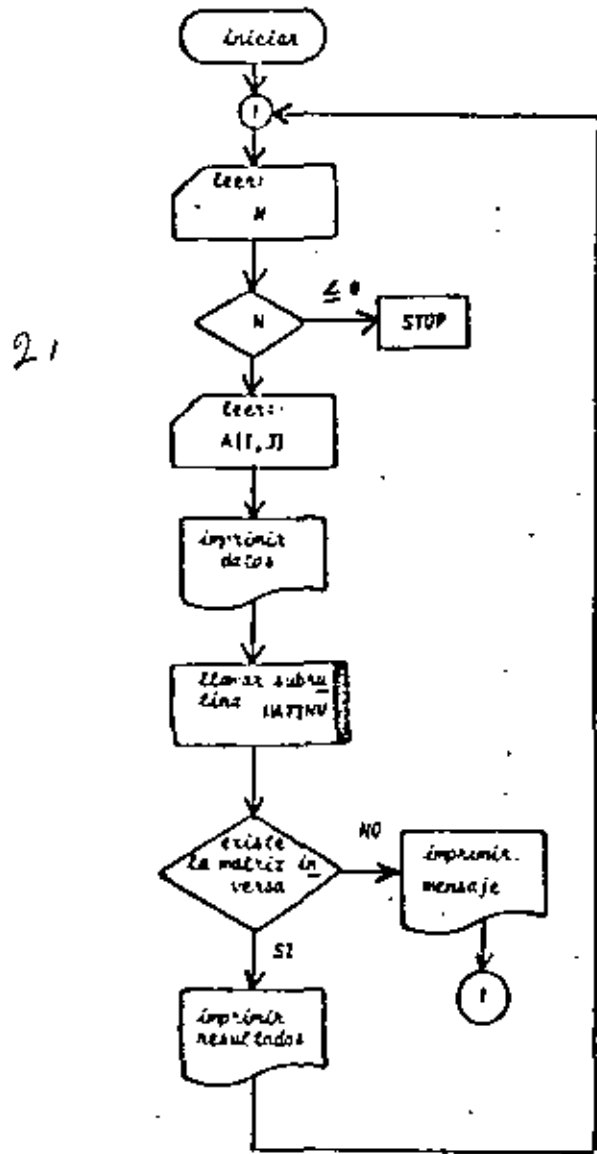
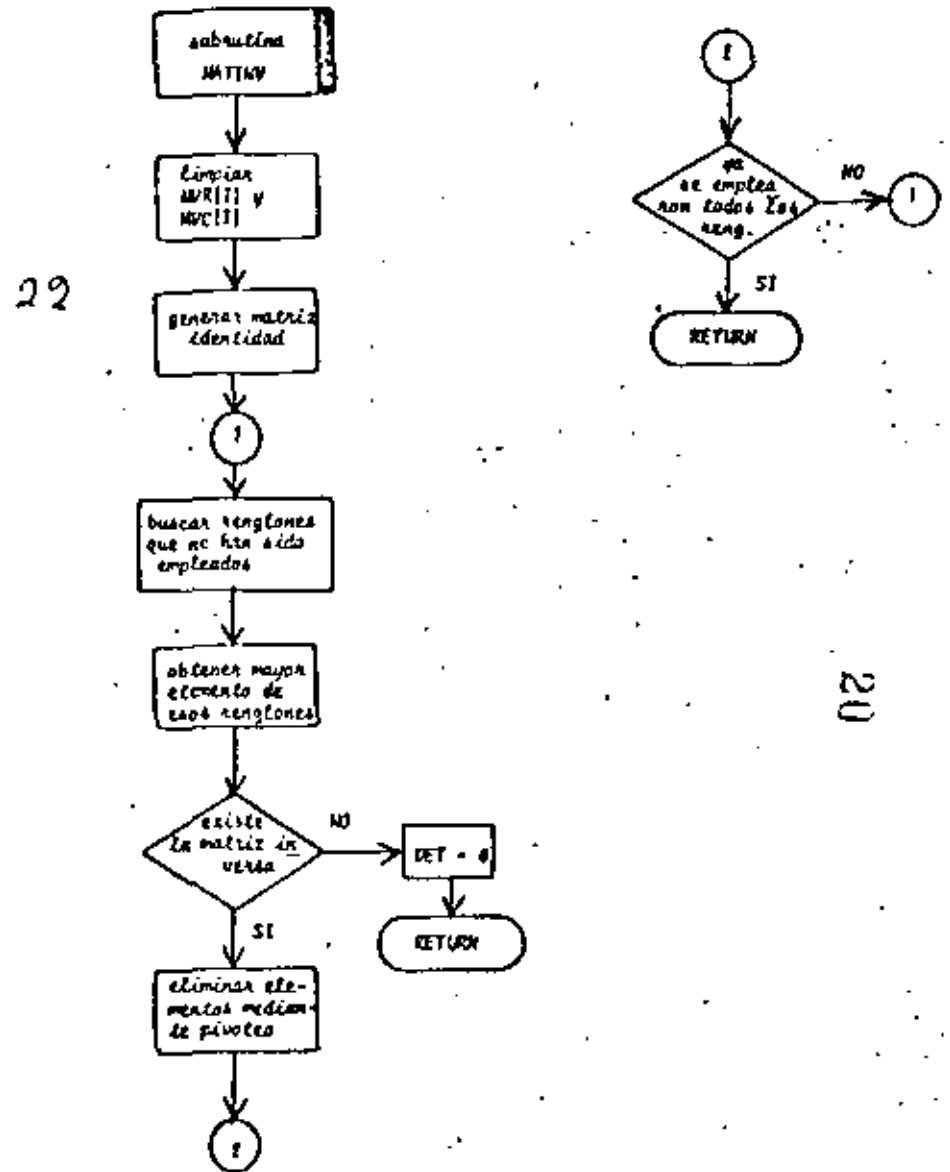


Fig. 2.10 Diagrama de bloques de la subrutina MATINV



## 6) Listado:

```

1  PROGRAMA PARA INVERTIR MATRICES POR EL METODO DE GAUSS-JORDAN
2  SIGNIFICADO DE LAS VARIABLES EMPLEADAS
C  MODIFICACION DE LA MATRIZ A
C  MATRIZ DE LA QUE SE BUSCA SU INVERSA
C  CRITERIO PARA DETERMINAR SI EXISTE O NO LA INVERSA DE LA MATRIZ
C  DETERMINANTE QUE INDICA SI EXISTE O NO LA INVERSA DE LA MATRIZ

-----
DIMENSION A(10,10);C(10,10)
10*5
-----
EPS=0.00001
C  LECTURA DE DATOS
1  READ(19,10) N
-----
IF(N) 2,2,3
-----
2  CALL EXIT
-----
3  DO 4 I=1,N
4  READ(19,20) (A(I,J),J=1,N)
-----
C  IMPRESION DE DATOS
WRITE(19,21)
DO 5 I=1,N
5  WRITE(19,22) (A(I,J),J=1,N)
-----
C  LLAMADO DE SUBROUTINA PARA OBTENER LA MATRIZ INVERSA
CALL MATINVA(4,EPS,DET)
IF(CD1.GT.EPS) GO TO 7
WRITE(19,23)
-----
GO TO 1
-----
7  WRITE(19,24)
DO 6 I=1,N
8  WRITE(19,22) (A(I,J),J=1,N)
-----
GO TO 1
-----
C  FORMATOS DE LECTURA E IMPRESION
19  FORMAT(ES)
-----
20  FORMAT(10F10.0)
-----
21  FORMAT(4F7.5X,'MATRIZ A1,')
-----
22  FORMAT(4F7.5X,10(10F7.5Y))
-----
23  FORMAT(4F7.5X,'NO EXISTE LA MATRIZ INVERSA')
-----
24  FORMAT(4F7.5X,'INVERSA DE LA MATRIZ A1)
-----
END

```

Fig. 2.11 Listado del programa principal

```

SUBROUTINE MATINV(N,M,EP5,CET)
C
C ALGORITMO PARA OBTENER LA INVERSA DE UNA MATRIZ
C EL SIGNIFICADO DE LAS VARIABLES EMPLEADAS ES
C A=MATRIZ A LA QUE SE BUSCARA SU INVERSA Y JIC DURANTE EL PROCESO
C SE CONVIERTE EN LA MATRIZ INVERSA
C M=ORDEN DE LA MATRIZ
C EP5=CONTENIDOR PARA DETERMINAR SI EL DETERMINANTE DE LA MATRIZ ES
C NULO
C L=VALOR ABSOLUTO DEL DETERMINANTE DE LA MATRIZ
C MATRIZ IDENTIDAD QUE SE UTILIZA PARA OBTENER LA MATRIZ INVERSA
C POR EL METODO DE GAUSS-JORDAN MODIFICADO
C MVR Y MVM=CONTADORES QUE INDICAN CUALES FILAS Y COLUMNAS YA
C FUERON UTILIZADAS COMO PIVOTES
C
C DIMENSION JIC(10),CIC(10),MVR(10),MVM(10)
C
C OBTENCION DE LA MATRIZ IDENTIDAD Y ACTUALIZACION DE VALORES PARA
C INICIAR EL PROCESO
C
C DO 1 I=1,M
MVR(I)=0
MVM(I)=0
C DO 4 J=1,M
IF(I,CO,JI) GO TO 2
C(I,J)=0
C DO 10 J
2 C(I,J)=1
3 CONTINUE
4 CONTINUE
C
C OBTENCION DE LA MATRIZ INVERSA
C
C DO 17 M=1,M
MVM=0
L=0
LR=0
C DO 8 I=1,M
IF(MVR(I),CO,1) GO TO 6
C DO 5 J=1,M
IF(MVM(J),CO,1) GO TO 5
IF(MABS(C(I,J),GE,MABS(C(L,J))) GO TO 5
MVM=MVM+1
LR=J
L=J
5 CONTINUE
6 CONTINUE
GETMPS(MVM)
IF(CET+L*EP5) GO TO 14
IF(LR=CO,1) GO TO 8
C DO 7 I=1,M
TEMP=C(L,I)
A(L,I)=A(L,I)
A(L,I)=TEMP
TEMP=C(I,LR)
C(L,I)=C(L,I)
7 C(L,I)=TEMP
C DO 9 I=1,M
A(L,I)=A(L,I)/MVM
9 C(L,I)=C(L,I)/MVM
C DO 11 I=1,M
IF(I,CO,1) GO TO 11
TEMP=A(L,I)
C DO 10 J=1,M
A(I,J)=A(I,J)-TEMP*A(L,J)
10 C(I,J)=C(I,J)-TEMP*C(L,J)
11 CONTINUE
MVR(L)=1
MVM(LR)=0
12 CONTINUE
C DO 13 I=1,M
C DO 14 J=1,M
13 A(I,J)=C(I,J)
14 RETURN
END

```

Fig. 2.12 Listado de la subrutina MATINV

2.4.4 Ejemplo

Obtener la inversa de la matriz:

$$\underline{A} = \begin{bmatrix} 10 & 2 & 3 & -1 \\ 1 & -20 & -1 & 3 \\ 1 & 1 & -10 & 2 \\ 2 & -1 & -1 & 30 \end{bmatrix}$$

\*SOLUCION

TABLA 2.5 Datos para el problema del ejemplo 2.4.4

N=4

$$\underline{A} = \begin{bmatrix} 10 & 2 & 3 & -1 \\ 1 & -20 & -1 & 3 \\ 1 & 1 & -10 & 2 \\ 2 & -1 & -1 & 30 \end{bmatrix}$$

TABLA 2.6 Resultados del problema del ejemplo 2.4.4

MATRIZ A			
.100E+02	.200E+01	.300E+01	-.100E+01
.100E+01	-.200E+02	-.100E+01	.300E+01
.100E+01	.100E+01	-.100E+02	.200E+01
-.200E+01	-.100E+01	-.100E+01	.300E+02
INVERSA DE LA MATRIZ A			
.961E-01	.112E-01	.277E-01	.253E-01
-.307E-02	-.490E-01	.555E-02	.871E-02
.276E-02	-.637E-02	-.977E-01	.726E-02
-.600E-02	-.251E-02	-.442E-02	.337E-01

1. CARNAHAN B., LUTHER H., WILKES J., "Applied Numerical Methods". New York: John Wiley and Sons Inc., 1969.  
pp.210-218, 282-296.
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pp.60-131.
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pp.366-367.
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pp.95-157.
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pp.718-803.
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pp.176-179, 189-194.

## 3. SOLUCION DE SISTEMAS DE ECUACIONES LINEALES

25

## 3.1 Introducción

Por sistemas de ecuaciones lineales se entiende un grupo de ecuaciones que presentan la siguiente estructura:

$$\left. \begin{array}{l} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m \end{array} \right\} \quad (3.1)$$

donde  $a_{ij}$  y  $b_i$  son constantes y las incógnitas del sistema son los valores  $x_i$ , donde  $1 \leq i \leq n$ .

Dichos sistemas se pueden representar en la forma:

$$\underline{A} \underline{X} = \underline{B} \quad (3.2)$$

donde  $\underline{A}$  se conoce como la matriz de coeficientes del sistema,  $\underline{B}$  como vector de términos independientes y  $\underline{X}$  como vector de incógnitas.

Si el vector de términos independientes es diferente de cero se habla de sistemas de ecuaciones no homogéneas y en caso contrario de sistemas homogéneos.

Antes de proceder a resolver un sistema de ecuaciones es necesario determinar si dicho sistema tiene solución y en caso de tenerla, cuántas posibles soluciones tiene. En base a lo anterior se tiene la siguiente clasificación:

$$\text{Sistema de ecuaciones lineales} \left\{ \begin{array}{l} \text{no homogéneo} \left\{ \begin{array}{l} \text{compatible} \left\{ \begin{array}{l} \text{determinado} \\ \text{indeterminado} \end{array} \right. \\ \text{incompatible} \end{array} \right. \\ \text{homogéneo} \left\{ \begin{array}{l} \text{compatible} \left\{ \begin{array}{l} \text{determinado} \\ \text{[Sol. trivial]} \\ \text{indeterminado} \end{array} \right. \end{array} \right. \end{array} \right.$$

Sistema compatible es aquél que sí tiene solución y para que esto se cumpla se requiere:

$$\text{rango } [A] = \text{rango } [A|B] \quad (3.3)$$

donde a la matriz  $[A|B]$  se le conoce como la matriz ampliada del sistema.

Sistema incompatible es aquél que no tiene solución y se cumple que:

$$\text{rango } [A] < \text{rango } [A|B] \quad (3.4)$$

Sistema determinado es un sistema compatible que presenta solución única y se verifica que:

$$\text{rango } [A] = \text{número de incógnitas} \quad (3.5)$$

Cuando se presenta esta situación en sistemas homogéneos se habla de solución trivial, ya que  $X = 0$ .

Un sistema compatible que presenta infinidad de soluciones se conoce como sistema indeterminado y se caracteriza por:

$$\text{rango } [A] < \text{número de incógnitas} \quad (3.6)$$

Para la solución de sistemas de ecuaciones lineales existen diversos métodos de los cuales solo se tratarán: Método de Gauss-Jordan modificado y el Método de Gauss-Seidel.

### 3.2 Método de Gauss-Jordan modificado.

#### 3.2.1 Objeto

Obtener la solución de sistemas de ecuaciones lineales de la forma:

$$\underline{A} \underline{X} = \underline{B} \quad (3.7)$$

#### 3.2.2 Método

Dado el sistema de ecuaciones:

$$\underline{A} \underline{X} = \underline{B} \quad (3.8)$$

---

\* rango  $[A]$  es la cantidad de vectores linealmente independientes del conjunto de vectores columna que forman la matriz  $A$ .



el método consiste en trabajar con la matriz de coeficientes y el vector de términos independientes, es decir, con la matriz ampliada del sistema:

$$\left[ \begin{array}{c|c} \underline{A} & \underline{B} \end{array} \right] \quad (3.9)$$

A dicha matriz se le aplican una serie de transformaciones que conducen a obtener otra matriz ampliada equivalente:

$$\left[ \begin{array}{c|c} \underline{I}_n & \underline{C} \end{array} \right] \quad (3.10)$$

donde  $\underline{C}$  representa la solución de cada una de las incógnitas del sistema.

El proceso equivale a premultiplicar la ecuación (3.9) por  $\underline{A}^{-1}$ , es decir, el método de la matriz inversa, solo que este método consiste en una eliminación sistemática de valores.

La transformación de la matriz (3.9) en la matriz (3.10) se efectúa basándose en tres operaciones que no alteran el sistema de ecuaciones sino que proporcionan sistemas de ecuaciones equivalentes, ellas son:

- intercambio de dos renglones, lo cual equivale a intercambiar dos ecuaciones.
- multiplicación de un renglón por un escalar diferente de cero, lo cual equivale a multiplicar ambos miembros de una ecuación por la misma constante.
- suma de equimúltiplos de un renglón a otro renglón, es decir, multiplicar una ecuación por una constante "K" y sumarla a otra ecuación.

Para aplicar las operaciones anteriores se procede en la siguiente forma:

- ① Seleccionar un renglón pivote y un elemento pivote dentro de dicho renglón.
- ② Normalizar el elemento pivote, es decir, convertirlo en unitario.
- ③ Cancelar elementos que se encuentren en la columna arriba y/o abajo del elemento pivote mediante la suma de equimúltiplos.
- ④ Regresar al paso ① y así sucesivamente hasta que se transforma la matriz de coeficientes  $\underline{A}$  en una matriz --

identidad  $I_n$ .

Debido a que durante el proceso se presentan errores por redondeo, la forma óptima de escoger los elementos pivote es seleccionando el mayor elemento que quede en la matriz  $A$  o en sus transformaciones. Hay que tener presente que los elementos de un renglón que ya fue seleccionado como línea pivote no se pueden usar como pivotes, aún cuando el mayor elemento quede colocado en dicho renglón.

Al seleccionar los pivotes en la forma antes mencionada el error se reduce al mínimo y, debido a que puede quedar una matriz no identidad al término de las iteraciones, es necesario efectuar un intercambio de líneas hasta obtener  $I_n$ .

Cabe mencionar que el presente método es un método directo de solución que no requiere que se determine con anterioridad si el sistema es compatible y determinado, el método durante el proceso proporciona dicha información.

Si el sistema es compatible y determinado, el procedimiento descrito se puede llevar a cabo sin contratiempos hasta llegar a  $\left[ I_n \mid C \right]$ .

Si el sistema es compatible pero indeterminado, la matriz ampliada adquirirá la configuración:

$$\left[ \begin{array}{ccc|c} 1 & 0 & 2 & 1 \\ 0 & 1 & 2 & 2 \\ \hline 0 & 0 & 0 & 0 \end{array} \right] \quad (3.11)$$

es decir, un renglón será nulo; en esta situación se obtienen las ecuaciones independientes que restan en el sistema y se aplica la metodología correspondiente a sistemas indeterminados.

Si el sistema es incompatible, se presentará lo siguiente:

$$\left[ \begin{array}{ccc|c} 1 & 1 & 2 & 1 \\ 0 & 2 & 3 & 2 \\ \hline 0 & 0 & 0 & \lambda \neq 0 \end{array} \right], \quad (3.12)$$

o sea,  $0 = \lambda \neq 0$ , lo cual es una contradicción.

### 3.2.3 Descripción del Programa

a) Subrutinas requeridas:

SUBROUTINE GAUTOR (A, B, N, EPS, DET), esta subrutina obtiene la solución del sistema de ecuaciones por el método de Gauss-Jordan modificado, el programa principal solo sirve para entrada y salida de datos.

b) Descripción de las variables:

Para la subrutina GAUTOR:

- A(I, J)      matriz de coeficientes del sistema de ecuaciones.
- B(I)        vector de términos independientes del sistema de ecuaciones, durante el proceso se transforma en la solución.
- N            orden del sistema de ecuaciones.
- RAMAX      mayor elemento de la matriz A que se emplea como pivote.
- MVR(I) y    contadores que indican qué renglón y columnas ya fueron empleados.
- MVC(I)
- EPS        criterio para determinar si el determinante de la matriz A es nulo.
- DET        parámetro que indica si el determinante de A es nulo.
- LR y LC    indicadores del renglón y columna que se utilizan.
- TEMP      variable de localización temporal.

Para el programa principal:

- A(I, J)      matriz de coeficientes del sistema de ecuaciones.
- B(I)        vector de términos independientes.
- N            orden del sistema de ecuaciones.
- EPS        criterio para determinar si el determinante de A es nulo.
- DET        parámetro que indica si el determinante de A es nulo.

c) Dimensiones:

La proposición DIMENSION del programa principal y de la subrutina se deberán modificar en el caso de que:

$$N > 10$$

d) Formatos para los datos de entrada:

SEC. TARJETAS	FORMATO	INFORMACION
1	(I5)	N
2	(8F10.0)	A(I,J), se dan los elementos de <u>A</u> renglón por renglón, empleando tantas -- tarjetas como sean necesarias para cada renglón.
3	(8F10.0)	B(I), el vector de términos independientes se da en una tarjeta o más según la cantidad de elementos.

-----  
 otros paquetes de datos (opcional)  
 -----

n

TARJETA EN BLANCO, al finalizar toda la información.

e) Diagrama de bloques:

Fig. 3.1 Diagrama de bloques del programa principal:

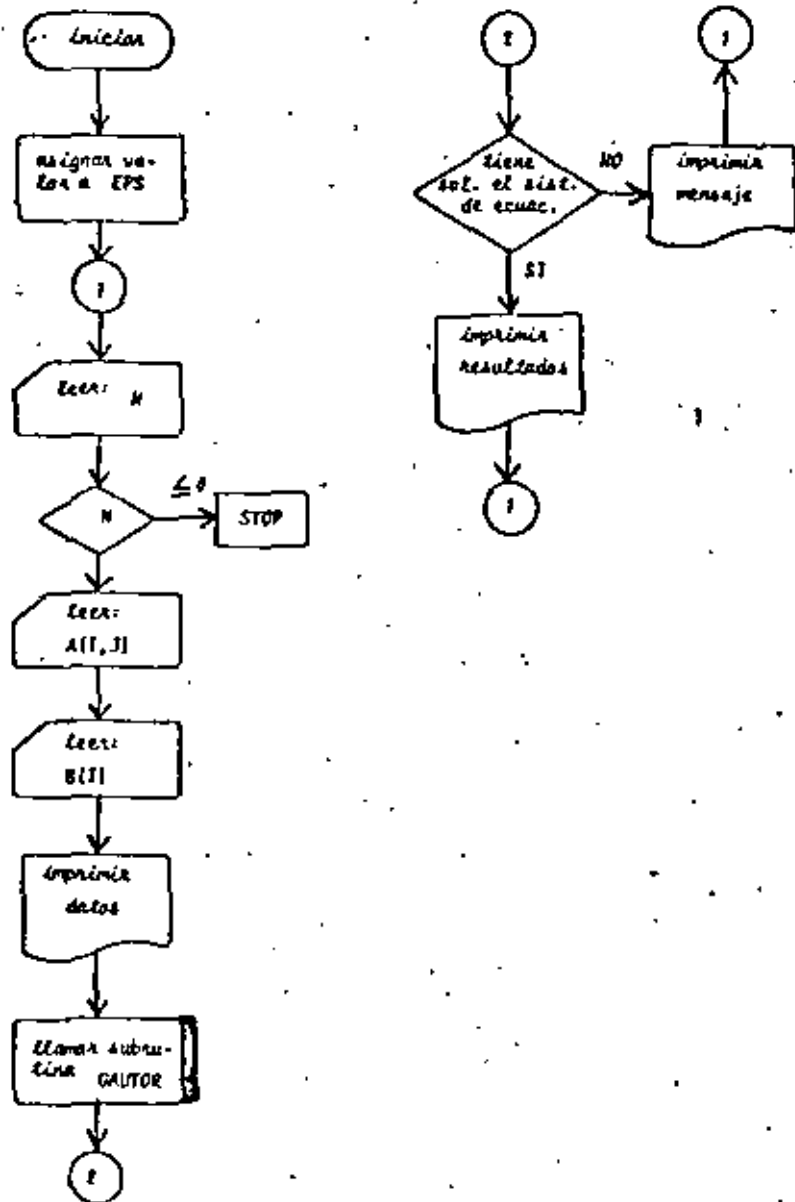
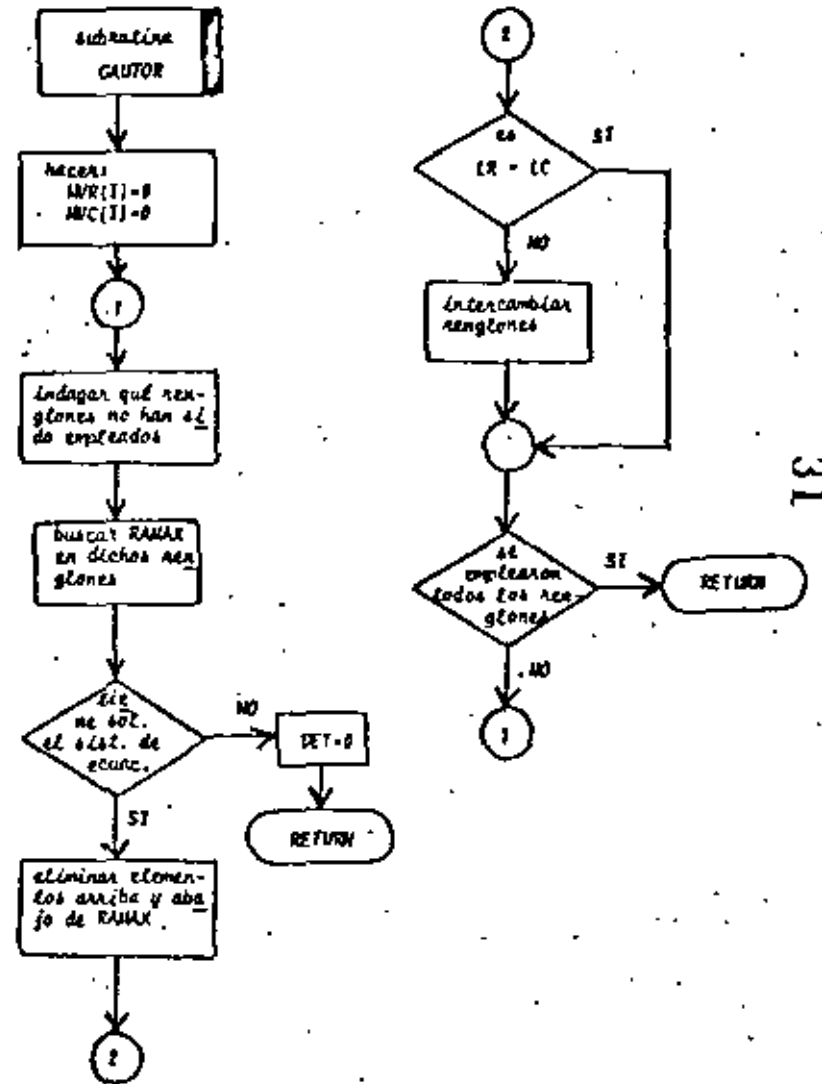


Fig. 3.2 Diagrama de bloques de la subrutina GAUTOR:



6) Listado:

```

C   PROGRAMA PARA RESOLVER SISTEMAS DE ECUACIONES LINEALES POR EL METO
C   DO DE GAUSS-JORDAN
C   SIGNIFICADO DE LAS VARIABLES EMPLEADAS
C   MODOEM DEL SISTEMA DE ECUACIONES
C   ARREGLOS DE COEFICIENTES DEL SISTEMA DE ECUACIONES
C   VECTORES DE TERMINOS INDEPENDIENTES, SE CONVIERTE EN LA SOLUCION
C   CRITERIO PARA DETERMINAR SI EL DETERMINANTE DE A ES DIFERENTE DE 0
C   DET=VARIABLE QUE INDICA SI EL SISTEMA TIENE O NO SOLUCION

DIMENSION A(10,10),B(10)
I=5
I=6
EPS=0.00001
C   LECTURA DE DATOS
1  READ(1,20) N
   IF(1) 2,2,3
2  CALL EXIT
3  DO 4 I=1,N
4  READ(1,21) (A(I,J),J=1,N)
   READ(1,21) (B(I),I=1,N)
C   IMPRESION DE DATOS
   WRITE(1,22)
   DO 5 I=1,N
5  WRITE(1,23) (A(I,J),J=1,N),B(I)
C   LLAMADA DE SUBROUTINA PARA RESOLVER EL SISTEMA DE ECUACIONES
   CALL GAUSSJ(A,B,N,EPS,DET)
   IF(ABS(DET)-EPS) GO TO 7
C   IMPRESION DE RESULTADOS
   WRITE(1,24)
   DO 6 I=1,N
6  WRITE(1,25) (B(I))
   GO TO 1
7  WRITE(1,26)
   GO TO 1
C   FORMATOS DE LECTURA E IMPRESION
20  FORMAT(I5)
21  FORMAT(FF10.0)
22  FORMAT(A(//),5X,'EL SISTEMA DE ECUACIONES ES',/)
23  FORMAT(//2X,10E10.3,1Y)
24  FORMAT(A(//),5X,'LA SOLUCION DEL SISTEMA DE ECUACIONES ES',//,5X,'E
1',5X,'(//)',/)
25  FORMAT(//5X,12,4X,E12.5)
26  FORMAT(A(//),5X,'EL SISTEMA DE ECUACIONES NO TIENE SOLUCION')
   END

```

Fig. 3.3 Listado del programa principal

```

SUBROUTINE GAUTOR(A,N,AV,EP,DET)
C
C SUBROUTINA PARA RESOLVER UN SISTEMA DE ECUACIONES POR EL METODO DE
C GAUSS-JORDAN MODIFICADO
C EL SIGNIFICADO DE LAS VARIABLES EMPLEADAS ES
C AV(1:N) DE COEFICIENTES DEL SISTEMA DE ECUACIONES
C B(1:N) DE TERMINOS INDEPENDIENTES QUE DURANTE EL PROCESO SE
C TRANSFORMA EN LA SOLUCION DEL SISTEMA DE ECUACIONES
C N ORDEN DEL SISTEMA DE ECUACIONES
C MVR(1:N) ELEMENTO DE LA MATRIZ A QUE SE USA COMO PIVOTE
C MVR Y MVRCONTADORES QUE INDICAN QUE RENGLON Y QUE COLUMNA YA FUE-
C RON UTILIZADOS
C EPS CONSTANTINICO PARA DETERMINAR SI EL DETERMINANTE DE LA MATRIZ A ES
C CERO
C DET=VALOR ABSOLUTO DEL DETERMINANTE DE LA MATRIZ A
C
C DIMENSION A(10,10),B(10),MVR(10),MVRCONT(10)
C
C ACTUALIZACION DE VALORES PARA INICIAR EL PROCESO
C
C DO 1 I=1,N
MVR(I)=0
MVRCONT(I)=0
1 MVRCONT(I)=1
C
C SOLUCION DEL SISTEMA DE ECUACIONES
C
C DO 2 I=1,N
RAV(I)=0
LC=0
LR=0
C DO 3 J=1,N
IF(MVR(I).EQ.0) GO TO 3
C DO 2 J=1,N
IF(MVR(J).EQ.0) GO TO 2
IF(A(I,RAV)+A(I,LC).GT.0) GO TO 2
MVR(I)=A(I,J)
LR=J
C DO 2 J=1,N
2 CONTINUE
3 CONTINUE
DET=ABS(A(I,RAV))
IF(ABS(DET-LE*EPS) GT 0) GO TO 10
IF(LR.NE.LC) GO TO 5
C DO 4 I=1,N
TEMP=A(I,LC)
A(I,RAV)=A(I,LC)
4 A(I,LC)=TEMP
TEMP=A(I,LR)
A(I,LR)=A(I,LC)
A(I,LC)=TEMP
C DO 5 I=1,N
5 A(I,LC)=A(I,LC)/RAV
A(I,LR)=A(I,LR)/RAV
C DO 6 I=1,N
IF(I.NE.LC) GO TO 6
TEMP=A(I,LC)
B(I)=B(I) + TEMP*B(LC)
C DO 7 J=1,N
7 A(I,J)=A(I,J) + TEMP*A(LC,J)
8 CONTINUE
MVR(LC)=LC
MVRCONT(LC)=LC
9 CONTINUE
10 RETURN
END

```

Fig. 3.4 Listado de la subrutina GAUTOR

## 3.2.4 Ejemplo

Empleando las leyes de Kirchhoff (ver referencia 2), se obtuvieron las siguientes ecuaciones lineales para el circuito mostrado en la figura 3.5:

$$\begin{aligned}
 i_8 - i_4 - I_A &= 0 \\
 i_4 + i_5 + I_A - i_1 - i_3 &= 0 \\
 i_1 - i_2 - I_B &= 0 \\
 i_2 + I_B + i_3 + i_6 - i_7 &= 0 \\
 I_C - i_8 - i_5 - i_6 - i_9 &= 0 \\
 R_1 i_1 + R_2 i_2 - R_3 i_3 &= 0 \\
 R_4 i_4 - R_5 i_5 + R_8 i_8 &= 0 \\
 R_5 i_5 + R_3 i_3 - R_6 i_6 &= 0 \\
 R_6 i_6 + R_7 i_7 - R_9 i_9 &= 0
 \end{aligned}$$

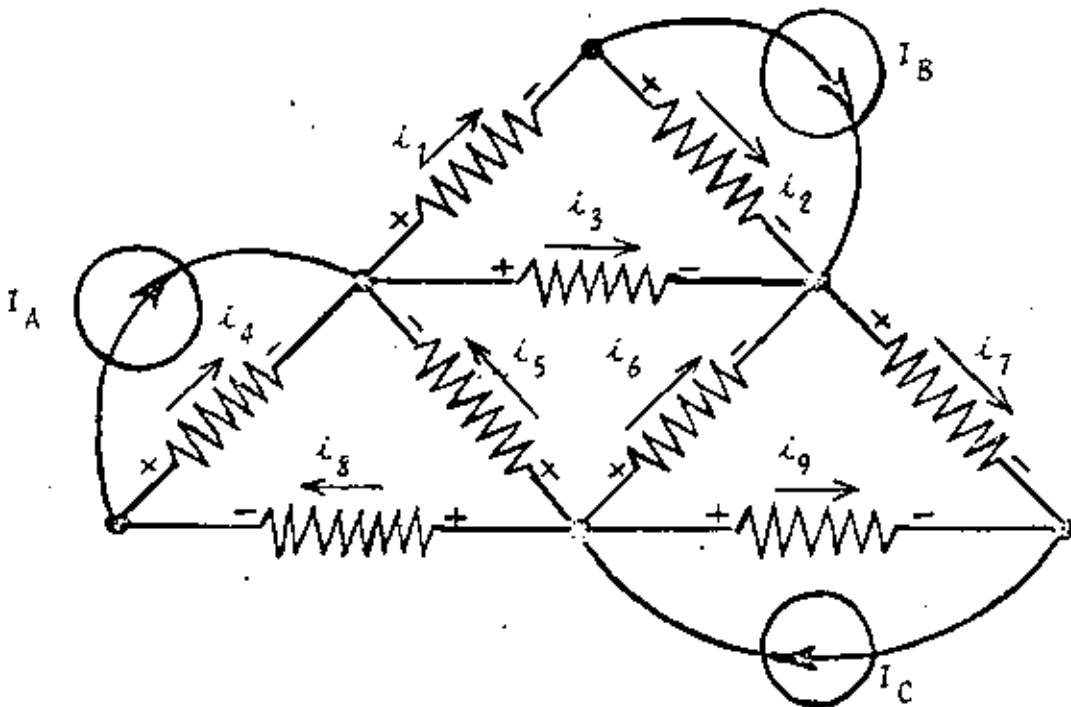


Fig. 3.5 Circuito del ejemplo 3.2.4



Si el valor de las fuentes es  $I_A = 2A$ ,  $I_B = 6A$ ,  $I_C = 4A$  y el de las resistencias:

$$R_1 = R_2 = 2 \Omega$$

$$R_4 = R_8 = 3 \Omega$$

$$R_5 = R_6 = 5 \Omega$$

$$R_7 = R_9 = 4 \Omega$$

$$R_3 = 6 \Omega$$

Obtenga las corrientes de rama  $i_1, i_2, i_3, i_4, i_5, i_6, i_7, i_8, i_9$ .

• SOLUCION

TABLA 3.1 Datos para el problema del ejemplo 3.2.4

$$N = 9$$

$$A = \begin{bmatrix} 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 & 0 \\ -1 & 0 & -1 & 1 & 1 & 0 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & 0 & 1 & 1 \\ 2 & 2 & -6 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 3 & -5 & 0 & 0 & 3 & 0 \\ 0 & 0 & 6 & 0 & 5 & -5 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 5 & 4 & 0 & -4 \end{bmatrix}$$

$$B = \begin{bmatrix} 2 \\ -2 \\ 6 \\ -6 \\ 4 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

TABLA 3.2 Resultados del problema del ejemplo 3.2.4

EL SISTEMA DE ECUACIONES ES

0.	C.	0.	-100E+01	0.	0.	0.	-100E+01	0.	-200E+01
+100E+01	C.	-100E+01	-100E+01	+100E+01	0.	0.	0.	0.	-200E+01
+100E+01	-100E+01	0.	0.	0.	0.	0.	0.	0.	-800E+01
0.	+100E+01	-100E+01	0.	0.	-100E+01	+100E+01	0.	0.	-800E+01
0.	0.	0.	0.	-100E+01	-100E+01	0.	-100E+01	-100E+01	-400E+01
+200E+01	+200E+01	-600E+01	0.	0.	0.	0.	0.	0.	0.
0.	C.	0.	+100E+01	-500E+01	0.	0.	-300E+01	0.	0.
0.	C.	-600E+01	C.	-500E+01	+500E+01	0.	0.	0.	0.
0.	0.	0.	0.	0.	+500E+01	+400E+01	0.	-400E+01	C.

LA SOLUCION DEL SISTEMA DE ECUACIONES ES

I R(I)

1	+73761E+01
2	+36239E+01
3	+13568E+00
4	-58358E+00
5	+52370E+00
6	+24548E+01
7	+19647E+01
8	+18364E+01
9	+20357E+01

### 3.3 Método de Gauss-Seidel

#### 3.3.1 Objeto

Obtener la solución de sistemas de ecuaciones lineales -- con la configuración:

$$\begin{aligned} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n &= b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n &= b_2 \\ &\vdots \\ a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n &= b_n \end{aligned} \quad (3.13)$$

empleando el método de Gauss-Seidel.

#### 3.3.2 Método

El método de Gauss-Seidel es un método de tipo iterativo que sirve para la solución de sistemas de ecuaciones lineales del tipo:

$$\underline{A} \underline{X} = \underline{B} \quad (3.14)$$

cuando los valores numéricos de los elementos de la diagonal -- principal son mayores que los demás de su correspondiente renglón.

- Para asegurar la convergencia del método se requiere que:
- los elementos no nulos de la matriz de coeficientes  $\underline{A}$  se acumulen en la diagonal principal.
  - los elementos de la diagonal principal de la matriz de coeficientes  $\underline{A}$  sean mayores en valor absoluto que la sumatoria de los valores absolutos de los elementos -- restantes del renglón correspondiente, es decir:

$$|a_{ii}| > \sum_{\substack{j=1 \\ j \neq i}}^n |a_{ij}|, \quad i = 1, 2, \dots, n \quad (3.15)$$

Para aplicar el método se procede a despejar una incógnita

ta de cada ecuación del arreglo (3.13), es decir, despejar la incógnita  $x_i$  de la "*i*-ésima" ecuación, o sea:

$$\left. \begin{aligned} x_1 &= \frac{1}{a_{11}} \left[ b_1 - a_{12}x_2 - a_{13}x_3 - \dots - a_{1n}x_n \right] \\ x_2 &= \frac{1}{a_{22}} \left[ b_2 - a_{21}x_1 - a_{23}x_3 - \dots - a_{2n}x_n \right] \\ &\vdots \\ x_n &= \frac{1}{a_{nn}} \left[ b_n - a_{n1}x_1 - a_{n2}x_2 - \dots - a_{n,n-1}x_{n-1} \right] \end{aligned} \right\} (3.16)$$

y se establecen las siguientes ecuaciones iterativas:

$$\left. \begin{aligned} x_1^{(k+1)} &= \frac{1}{a_{11}} \left[ b_1 - a_{12}x_2^{(k)} - a_{13}x_3^{(k)} - \dots - a_{1n}x_n^{(k)} \right] \\ x_2^{(k+1)} &= \frac{1}{a_{22}} \left[ b_2 - a_{21}x_1^{(k+1)} - a_{23}x_3^{(k)} - \dots - a_{2n}x_n^{(k)} \right] \\ &\vdots \\ x_n^{(k+1)} &= \frac{1}{a_{nn}} \left[ b_n - a_{n1}x_1^{(k+1)} - a_{n2}x_2^{(k+1)} - \dots - a_{n,n-1}x_{n-1}^{(k+1)} \right] \end{aligned} \right\} (3.17)$$

donde  $x_i^{(k+1)}$  indica el valor de la "*i*-ésima" incógnita en la iteración "*k* + 1"

Para arrancar el método se establece una solución inicial  $x_0$ :

$$x_0 = \begin{bmatrix} x_1^0 \\ x_2^0 \\ \vdots \\ x_n^0 \end{bmatrix} \quad (3.18)$$

dichos valores se sustituyen en el lado derecho de la ecuación (3.17) para obtener la siguiente solución aproximada:

$$\underline{x}_1 = \begin{bmatrix} x_1^{(1)} \\ x_2^{(1)} \\ \cdot \\ \cdot \\ x_n^{(1)} \end{bmatrix} \quad (3.19)$$

y así sucesivamente hasta que

$$\left| \underline{x}_{n+1} - \underline{x}_n \right| < \underline{\epsilon} \quad (3.20)$$

Para poder emplear este método es necesario verificar con anterioridad que el sistema sea compatible y determinado; además de que cumpla con las condiciones de convergencia del método. - Afortunadamente la mayoría de los problemas de tipo ingenieril cumplen los requisitos mencionados.

Ciertos sistemas que a primera vista no cumplen los requisitos del método pueden llenar los requisitos mediante un simple intercambio en la posición de las ecuaciones.

### 3.3.3 Descripción del programa

a) Subrutinas requeridas:

Ninguna.

b) Descripción de las variables.

A(I, J)	matriz de coeficientes del sistema
B(I)	vector de términos independientes
N	orden del sistema de ecuaciones
X(I)	valor inicial de las incógnitas del sistema y variable de localización temporal
Y(I)	valor de las incógnitas en la iteración "n"
XN(I)	valor de las incógnitas en la iteración "n + 1"

M            máximo número de iteraciones a efectuar  
 E            criterio de convergencia  
 NCON        contador de iteraciones efectuadas  
 SUM         sumador

e) Dimensiones:

La proposición DIMENSION deberá modificarse cuando se presente el caso de que  $N > 20$ .

d) Formatos para los datos de entrada:

SEC. TARJETAS	FORMATO	INFORMACION
1	(2I5,F10.0)	N, M, E
2	(10F8.0)	A(I,J), los elementos de la matriz A se dan renglón por renglón empleando la cantidad de tarjetas necesaria para cada renglón.
:		
.		
.		
3	(10F8.0)	B(I) el vector de términos independientes se da en una tarjeta o más según el orden del sistema.
.		
.		
.		
4	(10F8.0)	X(I), la solución para arrancar el método se da en una tarjeta o más según sea el tamaño de N.
.		
.		
.		

-----  
 otros paquetes de datos (opcional)  
 -----

n            TARJETA EN BLANCO, al finalizar toda la información.

e) Diagrama de bloques:

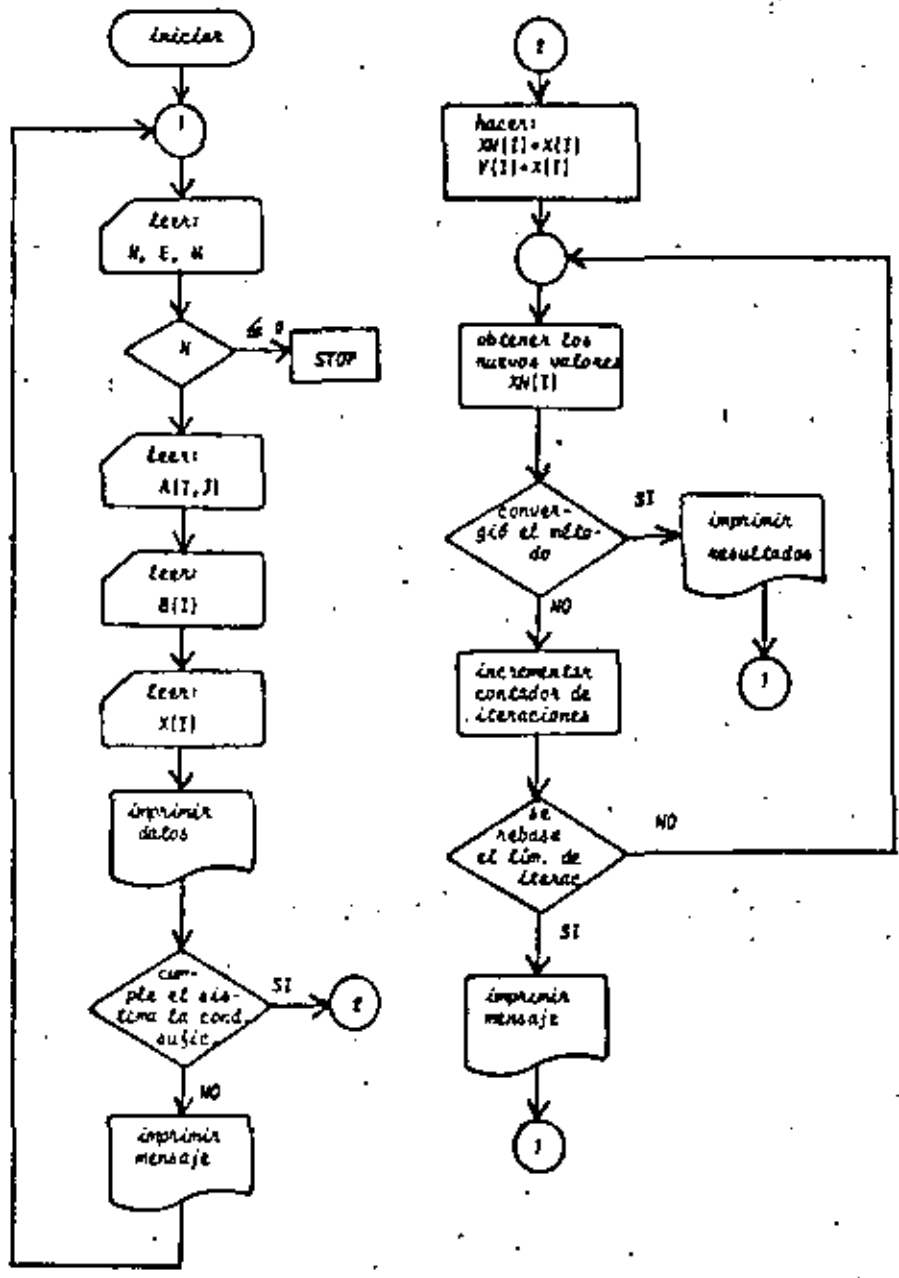


Fig. 3.6 Diagrama de bloques para el programa

## f) Listado:

```

C   PROGRAMAS PARA RESOLVER SISTEMAS DE ECUACIONES POR EL METODO DE
C   GAUSS-JORDAN
C   SIGNIFICADO DE LAS VARIABLES EMPLEADAS
C   MATRIZ DE COEFICIENTES DEL SISTEMA DE ECUACIONES
C   VECTOR DE TERMINOS INDEPENDIENTES
C   VALOR INICIAL DE LA SOLUCION DEL SISTEMA
C   SOLUCION DEL SISTEMA DE ECUACIONES EN LA SIGUIENTE ITERACION
C   NUMERO DEL SISTEMA
C   VALOR DE LA SOLUCION DEL SISTEMA DE ECUACIONES EN LA ITERACION
C   ANTERIOR
C   MAXIMO NUMERO DE ITERACIONES
C   CRITERIO DE CONVERGENCIA
C
L
C   DIMENSION A(20,20),B(20),C(20),X(20),XN(20)
C   LECTURA DE DATOS
1  READ(5,200) M,N,C
  IF(N) 2,2,3
2  CALL EXIT
3  GO TO 1,1,N
4  READ(5,300) (A(I,J),J=1,N)
  READ(5,300) (B(I),I=1,N)
  READ(5,300) (X(I),I=1,N)
C   IMPRESION DE DATOS
C   WRITE(6,400)
  DO 5 I=1,N
5  WRITE(6,500) (A(I,J),J=1,N),B(I)
  WRITE(6,600) (X(I),I=1,N)
C   SE PREGUNTA SI EL SISTEMA CUMPLE LA CONDICION SUFICIENTE DE CONVER-
C   GENCIA
  DO 7 I=1,N
  DO 6 J=1,N
  IF(ABS(A(I,J)) * ABS(C(I,J))) 9,6,8
6  CONTINUE
7  CONTINUE
  GO TO 9
8  WRITE(6,700) (J,1)
  GO TO 4
C   OBTENCION DEL VALOR DE LAS INCOGNITAS
9  NCON=1
  DO 10 I=1,N
  X(I)=X(I)
10  Y(I)=X(I)
11  DO 14 K=1,N
  SUM=0.
  DO 13 J=1,N
  IF(K=J) 12,13,12
12  SUM=SUM + A(K,J)*X(J)
13  CONTINUE
  XN(I)=(B(I)-SUM)/A(K,K)
14  CONTINUE
  DO 15 I=1,N
C   SE VERIFICA SI YA CONVERGIO EL METODO
  IF(ABS(XN(I)-Y(I))) 15,16,16
15  CONTINUE
C   IMPRESION DE RESULTADOS
  WRITE(6,800) (XN(I),I=1,N)
  WRITE(6,900) NCON
  GO TO 1
16  NCON=NCON + 1
  IF(NCON=9) 18,17,17
17  WRITE(6,900) (XN(I),I=1,N)
  WRITE(6,900) NCON
  GO TO 1
18  DO 19 I=1,N
  Y(I)=XN(I)
  GO TO 11
C   FORMATOS DE LECTURA E IMPRESION
200  FORMAT (2I5,F10.0)
300  FORMAT (10F5.0)
400  FORMAT(1M,10F5.1,15A,'MATRIZ APLICADA')
500  FORMAT (2//10F5.0(F5.1),F5.1)
600  FORMAT(4//15A,'PRIMERA APROXIMACION DE LA SOLUCION',///,10X,10F
16.2,5F3)
700  FORMAT(4//15A,'EL METODO PUEDE NO CONVERGER DADO QUE',///,15A,'A
2',12',12',12') ES MAYOR QUE 44',12',12',12',12',12')
800  FORMAT(4//15A,'LA SOLUCION DEL SISTEMA ES',///,5X,10E12.5,2X)
900  FORMAT(4//15A,'SE LLEGA A LA SOLUCION',///,15A,'LA ULTIMA APROX
IMACION ENCONTRADA FUE',///,5X,10E12.5,2X)
950  FORMAT(4//15A,'ITERACIONES REALIZADAS=',1A)
END

```

Fig. 3.7 Listado del programa



## 3.3.4 Ejemplo

Para el circuito eléctrico de la fig. 3.8 se sabe que ---  
 $I_1 = 1A$  e  $I_2 = 2A$ ,  $R_1 = R_2 = R_3 = R_4 = R_5 = R_6 = 1 \Omega$ .

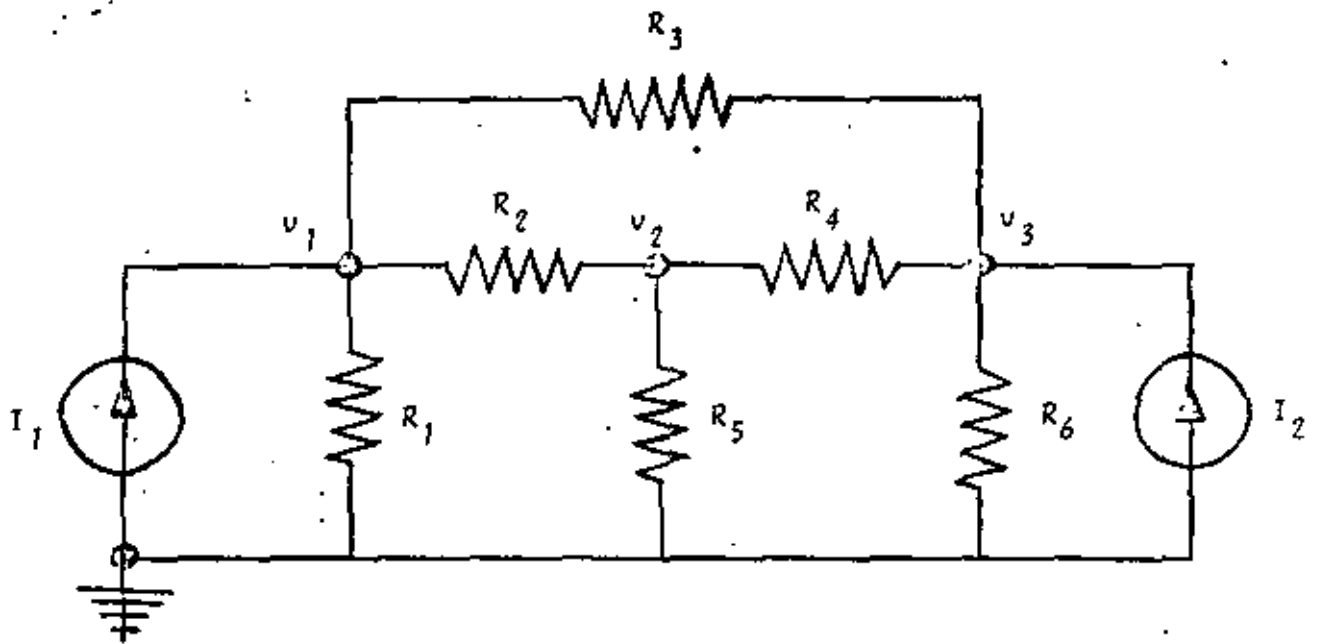


Fig. 3.8 Circuito eléctrico del problema del ejemplo  
3.3.4

Se desea obtener el voltaje de los nodos  $V_1$ ,  $V_2$  y  $V_3$ .  
 Aplicando análisis nodal al circuito se obtiene:

$$3V_1 - V_2 - V_3 = 1$$

$$-V_1 + 3V_2 - V_3 = 0$$

$$-V_1 - V_2 + 3V_3 = 2$$

arreglo que es un sistema de ecuaciones lineales con todas las características propias para aplicar el método de Gauss-Seidel.

Se seleccionará como solución inicial al siguiente vector:

$$\begin{bmatrix} V_1^0 \\ V_2^0 \\ V_3^0 \end{bmatrix} = \begin{bmatrix} 0.5 \\ 0.5 \\ 0.5 \end{bmatrix}$$

\* SOLUCION

TABLA 3.3 Datos del problema del ejemplo 3.3.4

$$N = 3$$

$$M = 50$$

$$EPS = 0.0001$$

$$A = \begin{bmatrix} 3 & -1 & -1 \\ -1 & 3 & -1 \\ -1 & -1 & 3 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}$$

$$\underline{X} = \begin{bmatrix} 0.5 \\ 0.5 \\ 0.5 \end{bmatrix}$$

TABLA 3.4 Resultados del problema del ejemplo 3.3.4

MATRIZ AMPLIADA

1.000	-1.000	-1.000	1.000
-1.000	3.000	-1.000	0.000
-1.000	-1.000	3.000	2.000

PRIMERA APROXIMACION DE LA SOLUCION

0.50      0.50      0.50

LA SOLUCION DEL SISTEMA ES

\*10000E+01    \*75000E+00    \*12500E+01

ITERACIONES REALIZADAS= 16

## 3.4 Bibliografía

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## 7. APROXIMACION POLINOMIAL Y COEFICIENTE DE CORRELACION

## 7.1 Introducción

En muchas ocasiones a partir de una serie de valores muestrales, donde existe una variable dependiente y una o varias -- variables independientes, es necesario ajustar dichos puntos -- por una curva tal que permita determinar el valor de la variable dependiente para cualquier valor de las variables independientes. La curva de ajuste por el método de los mínimos cuadrados puede ser un polinomio de grado "n", una función de tipo logarítmico, etc.; dicha curva se escoge de acuerdo a la distribución de los puntos muestrales y en forma tal que se minimice la suma de los cuadrados de los errores. En procesos estadísticos a tal tipo de ajuste se le denomina regresión simple o múltiple de la variable dependiente sobre las variables independientes. El grado de relación existente entre la variable dependiente y la independiente se denomina correlación y a la medida de tal relación se le llama coeficiente de correlación, el cual se suele denotar con el símbolo  $\rho$  ó  $r_{1(2,3...n)}$ . Donde:

$$\rho = \sqrt{\frac{\text{Variación explicada}}{\text{Variación total}}} \quad (7.1)$$

Si se considera a Y como la variable dependiente, las -- variaciones se definen en la siguiente forma:

$$\text{variación total} = \sum (Y - \bar{Y})^2 \quad (7.2)$$

$$\text{variación explicada} = \sum (Y_{est} - \bar{Y})^2 \quad (7.3)$$

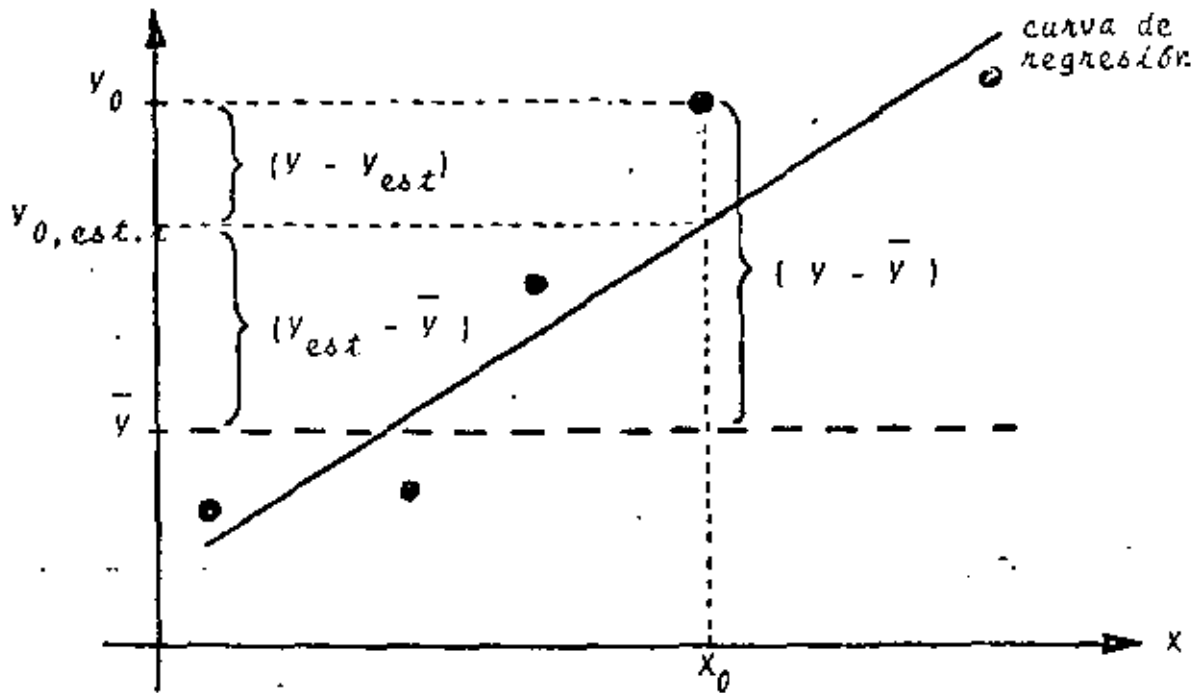
$$\text{variación no explicada} = \sum (Y - Y_{est})^2 \quad (7.4)$$

$$\sum (Y - \bar{Y})^2 = \sum (Y_{est} - \bar{Y})^2 + \sum (Y - Y_{est})^2 \quad (7.5)$$

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$$\bar{Y} = \frac{\sum_{i=1}^N Y_i}{N}, \text{ para } N \text{ puntos muestrales}$$

Gráficamente, para el caso de regresión simple se tendrá:



## 7.2 Método de los Mínimos Cuadrados

### 7.2.1 Objeto

Efectuar la regresión lineal o exponencial, simple o múltiple, de la variable  $X_1$  sobre la(s) variable(s)  $X_2, \dots, X_n$  a partir de una tabla de "m" puntos muestrales con la siguiente configuración:

Punto	$X_1$	$X_2$	...	$X_n$
1				
.				
.				
.				
m				

Para efectuar el ajuste se emplea el método de los mínimos cuadrados. Además, se proporciona el coeficiente de correlación y las desviaciones estándar de los parámetros de la cur

va.

Las curvas de ajuste serán del tipo:

$$\left. \begin{aligned} X_1 &= A_1 + A_2 X_2 + A_3 X_3 + \dots + A_n X_n \\ \delta \quad X_1 &= e^{A_1} e^{A_2 X_2} e^{A_3 X_3} \dots e^{A_n X_n} \end{aligned} \right\} \quad (7.6)$$

Si se desea como curva de ajuste un polinomio de grado " $(n-1)$ " o sea:

$$X_1 = A_1 + A_2 X_2 + A_3 X_2^2 + \dots + A_n X_2^{n-1} \quad (7.7)$$

solo se requerirá efectuar el siguiente cambio de variable:

$$\left. \begin{aligned} X_2 &= X_2 \\ X_3 &= X_2 \\ X_4 &= X_2 \\ &\vdots \\ X_n &= X_2^{n-1} \end{aligned} \right\} \quad (7.8)$$

en el momento de proporcionar los datos.

### 7.2.2 Método

Dadas un conjunto de " $m$ " observaciones de la variable dependiente  $X_1$  sobre una o varias variables independientes  $X_2, \dots, X_n$  se busca ajustar los datos mediante la siguiente curva:

$$\hat{f}(X) = \hat{X}_1 = A_1 + A_2 X_2 + A_3 X_3 + \dots + A_n X_n \quad (7.9)$$

El valor de la variable dependiente correspondiente al valor de las variables independientes en un punto muestral  $X_i$  es  $X_{1,i}$ , por lo que el error será:

$$e_i = \hat{f}(X_i) - X_{1,i} \quad (7.10)$$

$$e_i = A_1 + A_2 X_{2,i} + A_3 X_{3,i} + \dots + A_n X_{n,i} - X_{1,i} \quad (7.11)$$

\*  $\hat{X}_1$  = valor estimado de  $X_1$

y la suma de los cuadrados de los errores considerando todos los puntos muestrales es:

$$\sum_{i=1}^m e_i^2 = \sum_{i=1}^m \left[ A_1 + A_2 X_{2,i} + A_3 X_{3,i} + \dots + A_n X_{n,i} - X_{1,i} \right]^2 \quad (7.12)$$

para obtener el mínimo de la suma de los cuadrados de los errores se deriva la expresión (7.12) con respecto a los parámetros  $A_j$  y cada una de las derivadas se iguala a cero para toda  $j$ :

$$\begin{aligned} \frac{\partial}{\partial A_j} \sum_{i=1}^m e_i^2 &= \frac{\partial}{\partial A_j} \sum_{i=1}^m \left[ A_1 + A_2 X_{2,i} + \dots + A_n X_{n,i} - X_{1,i} \right]^2 \\ &= \sum_{i=1}^m 2 \left[ A_1 + A_2 X_{2,i} + \dots + A_n X_{n,i} - X_{1,i} \right] X_{j,i} = 0 \end{aligned} \quad (7.13)$$

lo cual se cumple solo si:

$$\begin{aligned} A_1 \sum_{i=1}^m X_{j,i} + A_2 \sum_{i=1}^m X_{2,i} X_{j,i} + \dots + A_n \sum_{i=1}^m X_{n,i} X_{j,i} &= \sum_{i=1}^m X_{1,i} X_{j,i} \end{aligned} \quad (7.14)$$

al evaluar (7.14) para toda "j" se tiene:

$$\begin{aligned} m A_1 &+ A_2 \sum X_2 &+ A_3 \sum X_3 &+ \dots &+ A_n \sum X_n &= \sum X_1 \\ A_1 \sum X_2 &+ A_2 \sum X_2^2 &+ A_3 \sum X_3 X_2 &+ \dots &+ A_n \sum X_n X_2 &= \sum X_1 X_2 \\ \vdots & & & & & \vdots \\ A_1 \sum X_n &+ A_2 \sum X_2 X_n &+ A_3 \sum X_3 X_n &+ \dots &+ A_n \sum X_n^2 &= \sum X_1 X_n \end{aligned} \quad (7.15)$$

expresando en forma matricial:

$$\begin{bmatrix} m & \Sigma X_2 & \dots & \Sigma X_n \\ \Sigma X_2 & \Sigma X_2^2 & \dots & \Sigma X_2 X_n \\ \vdots & \vdots & \ddots & \vdots \\ \Sigma X_n & \Sigma X_2 X_n & \dots & \Sigma X_n^2 \end{bmatrix} \begin{bmatrix} A_1 \\ A_2 \\ \vdots \\ A_n \end{bmatrix} = \begin{bmatrix} \Sigma X_1 \\ \Sigma X_1 X_2 \\ \vdots \\ \Sigma X_1 X_n \end{bmatrix} \quad (7.16)$$

Al resolver el sistema de ecuaciones (7.16) se obtienen los parámetros  $A_j$  de la curva de regresión.

Dentro del programa se plantea el sistema de ecuaciones, obteniendo la sumatoria de los puntos muestrales para cada variable, para el cuadrado de la variable y para los productos cruzados. El sistema de ecuaciones se resuelve por el método de Gauss-Jordan modificado.

El coeficiente de correlación se obtiene de la siguiente forma:

$$\begin{aligned} r_{1(23\dots n)} &= \sqrt{\frac{\text{variación explicada}}{\text{variación total}}} \\ &= \sqrt{\frac{\Sigma x_{1(23\dots n)}^2}{\Sigma x_1^2}} \quad (7.17) \end{aligned}$$

donde:

$$\Sigma x_1^2 = \Sigma x_{1.23\dots n}^2 + \Sigma x_{1(23\dots n)}^2 \quad (7.18)$$

var. total    var. no explicada    var. explicada

Las componentes de la ecuación (7.16) están dadas por:

$$\Sigma_{i=1}^m x_{1,i}^2 = \Sigma_{i=1}^m X_{1,i} - \frac{(\Sigma_{i=1}^m X_{1,i})^2}{m} \quad (7.19)$$

\*  $x = X - \bar{X}$



$$\sum_{j=2}^n x_j^2 = A_2 \sum x_1 x_2 + A_3 \sum x_1 x_3 + \dots + A_n \sum x_1 x_n \quad (7.20)$$

$$\left. \begin{aligned} \sum x_1 x_2 &= \frac{\sum X_1 X_2}{m} \\ \sum x_1 x_3 &= \frac{\sum X_1 X_3}{m} \\ &\vdots \\ \sum x_1 x_n &= \frac{\sum X_1 X_n}{m} \end{aligned} \right\} \quad (7.21)$$

A los términos de las ecuaciones (7.19) y (7.21) se les denomina elementos de variación y covariación respectivamente, ya que  $x = X - \bar{X}$  y la variancia y covariancia se definen como:

$$\sigma_x^2 = E [X - \bar{X}]^2 \quad (7.22)$$

$$cov_{xy} = E [X - \bar{X}] [Y - \bar{Y}] \quad (7.23)$$

A continuación se describe la obtención de la desviación estándar de los parámetros  $A_j$ .

Se define a los productos  $X'X$  y  $X'Y$  como:

$$\begin{aligned} \underline{X}'\underline{X} &= \begin{bmatrix} 1 & 1 & \dots & 1 \\ X_{2,1} & X_{2,2} & \dots & X_{2,m} \\ \vdots & \vdots & \ddots & \vdots \\ X_{n,1} & X_{n,2} & \dots & X_{n,m} \end{bmatrix} \begin{bmatrix} 1 & X_{2,1} & \dots & X_{n,1} \\ 1 & \vdots & \ddots & \vdots \\ 1 & X_{2,m} & \dots & X_{n,m} \end{bmatrix} \\ &= \begin{bmatrix} n & \sum X_2 & \dots & \sum X_n \\ \sum X_2 & \sum X_2^2 & \dots & \sum X_2 X_n \\ \vdots & \vdots & \ddots & \vdots \\ \sum X_n & \sum X_2 X_n & \dots & \sum X_n^2 \end{bmatrix} \end{aligned} \quad (7.24)$$

$$\underline{X}' \underline{Y} = \begin{bmatrix} 1 & 1 & \dots & 1 \\ x_{2,1} & & & x_{2,m} \\ \vdots & & & \vdots \\ x_{n,1} & & & x_{n,m} \end{bmatrix} \begin{bmatrix} x_{1,1} \\ x_{1,2} \\ \vdots \\ x_{1,m} \end{bmatrix} = \begin{bmatrix} \Sigma X_1 \\ \Sigma X_1' X_2 \\ \vdots \\ \Sigma X_1' X_n \end{bmatrix} \quad (7.25)$$

Sea  $\underline{A}$  el vector de los parámetros de la ecuación de regresión, el sistema de ecuaciones (7.16) se puede denotar en base a lo anterior como:

$$(\underline{X}' \underline{X}) \underline{A} = \underline{X}' \underline{Y} \quad (7.26)$$

donde  $\underline{Y}$  representa el vector de valores muestrales de la variable dependiente. Por lo tanto:

$$\underline{Y} = \underline{X} \underline{A} + \underline{e} \quad (7.27)$$

$$\underline{A} = (\underline{X}' \underline{X})^{-1} \underline{X}' \underline{Y} \quad (7.28)$$

Se asume que la ecuación de regresión es de la forma:

$$\underline{Y} = \underline{X} \underline{\alpha} + \underline{E} \quad (7.29)$$

A partir de las expresiones anteriores se puede demostrar (ver ref. 1) que la variancia de los parámetros  $A_i$  está dada por:

$$E (\underline{A} - \underline{\alpha}) (\underline{A} - \underline{\alpha})' = \sigma^2 \underline{I} (\underline{X}' \underline{X})^{-1} \quad (7.30)$$

El valor de  $\sigma^2$  se obtiene mediante la expresión:

$$\sigma^2 = S_{1.23 \dots n}^2 = \frac{\Sigma x_{1.23 \dots n}^2}{m-n} \quad (7.31)$$

donde "m" representa la cantidad de puntos muestrales y "n" la cantidad de variables independientes.

Para efectos de regresión exponencial del tipo:

$$x_j = e^{A_1} e^{A_2 X_1} \dots e^{A_{n+1} X_n} \quad (7.32)$$

$\underline{e}$  : es el vector de diferencias entre los valores estimados y los valores reales.

el programa aplica el operador "ln" en ambos términos de la ecuación (7.32) con lo que dicha expresión se linealiza y esta expresión linealizada es la que se utiliza para la obtención de los parámetros  $A_j$ .

### 7.2.3 Descripción del Programa

#### a) Subrutinas requeridas:

SUBROUTINE SISTOR(N,M,C,A,B), plantea el sistema de ecuaciones requerido para la obtención de los parámetros de la curva de regresión.

SUBROUTINE GAUTOR(A,B,M,EPS,DET), obtiene la solución del sistema de ecuaciones mediante el método de Gauss-Jordan. Consultar el capítulo 3.

SUBROUTINE MULTMA(A,B,N,M,L,X), efectúa productos matriciales. Consultar el capítulo 2.

SUBROUTINE MATINV(A,N,EPS,DET), obtiene la inversa de una matriz por el método de Gauss-Jordan. Consultar el capítulo 2.

SUBROUTINE GRAFT(A,N,M), obtiene la gráfica de los valores muestrales y de los valores estimados. Consultar el capítulo 1.

#### b) Descripción de las variables:

Para la subrutina SISTOR:

N cantidad de puntos muestrales

M cantidad de variables, incluyendo la dependiente

C(I,J) valor de la variable  $X_j$  para el punto muestral "i"

A(I,J) matriz de coeficientes del sistema de ecuaciones

B(I) vector de términos independientes del sistema de ecuaciones

SUM variable que guarda la sumatoria de los puntos muestrales

Para el programa principal:

N cantidad de puntos muestrales

M cantidad de variables incluyendo la de-

	pendiente
NTIPO	variable que indica el tipo de regresión a efectuar
C(I, J)	valor de la variable $X_j$ para el punto muestral "i"
A(I, J)	matriz de coeficientes del sistema de ecuaciones
B(I)	vector de términos independientes del sistema de ecuaciones
EPS	criterio para determinar si el determinante de <u>A</u> es nulo
DET	variable que indica si el determinante de la matriz <u>A</u> es o no nulo
PROD(I)	sumatorias de los productos cruzados $X_i X_j$
CN(I, J)	matriz modificada de la matriz <u>C</u> donde $CN(I, 1) = 1$
XTR(I, J)	matriz transpuesta de la matriz CN
XI(I, J)	matriz inversa del producto matricial $(XTR)(CN)$
AI	coeficiente de correlación
VAR	variancia no explicada
BVAR(I)	desviación estándar de los parámetros de la curva de regresión
ATEMP(I)	variable de reemplazo

c) Dimensiones:

El programa está estructurado para trabajar como máximo con cinco variables independientes. La proposición DIMENSION deberá modificarse en el caso de que la cantidad de puntos muestrales sea mayor de 30.

d) Formatos para los datos de entrada:

SEC. TARJETAS	FORMATO	INFORMACION
1	(215, A4)	N, M, NTIPO, para la variable NTIPO se deberá perforar LINE en el caso de regresión lineal y EXPO para regresión exponencial.

2 (8F10.0) C(I,J), los elementos de  
la matriz se dan columna  
por columna. Emplear tan-  
tas tarjetas como sean ne-  
cesarias.

-----  
otros paquetes de datos (opcional)  
-----

n

TARJETA EN BLANCO, al fi-  
nalizar toda la informa-  
ción

e) Diagrama de bloques:

Fig. 7.1 Diagrama de bloques para el programa principal

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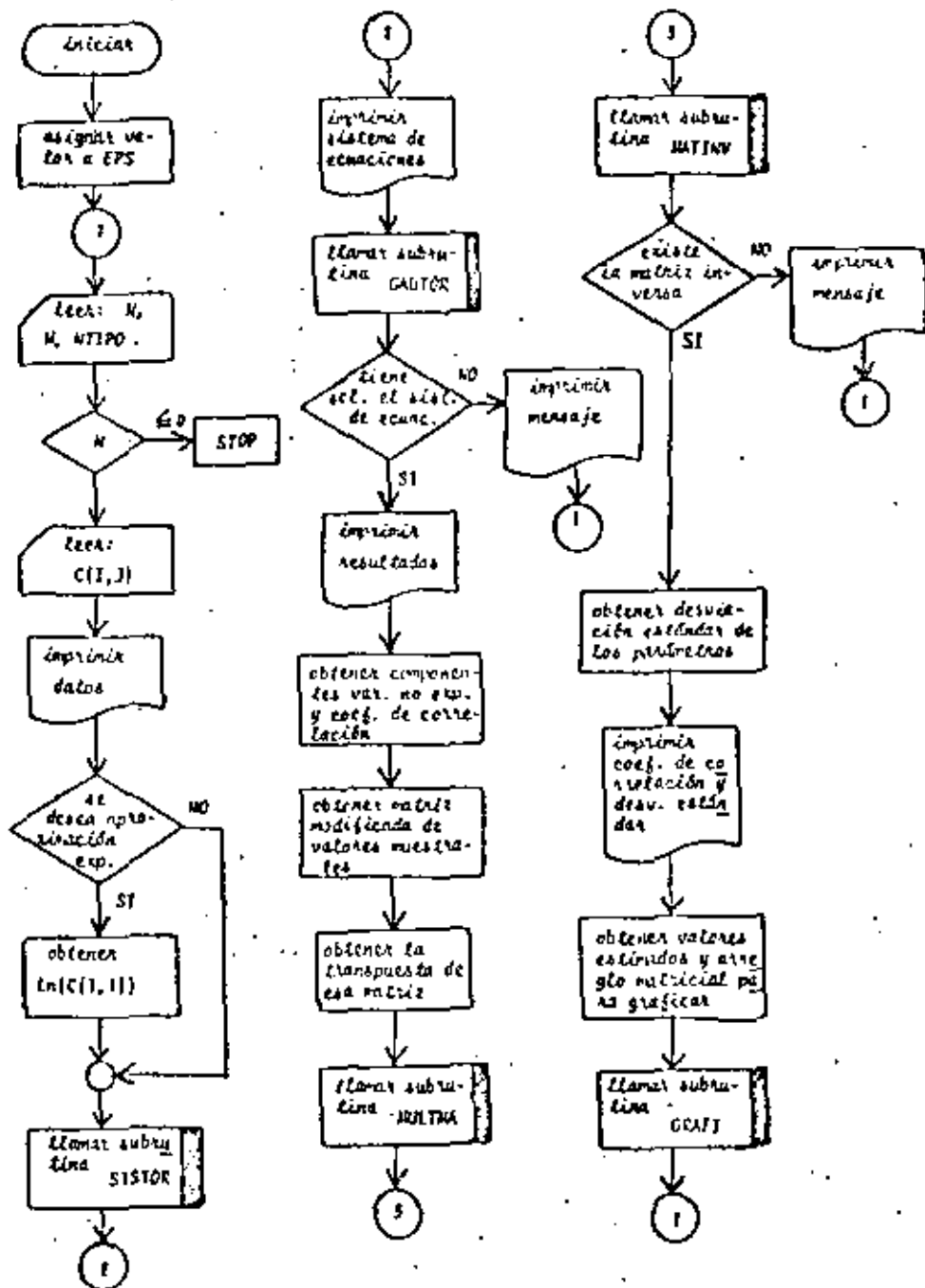
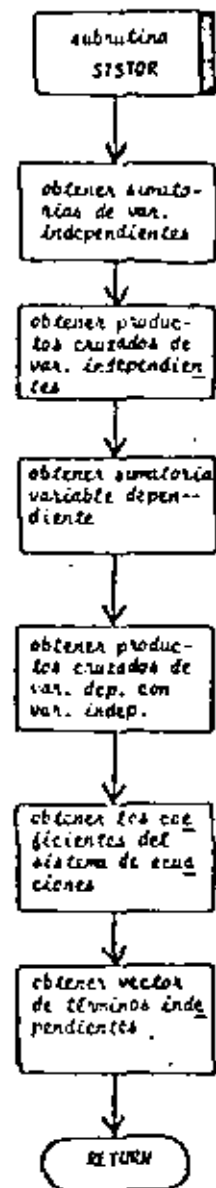


Fig. 7.2 Diagrama de bloques para la subrutina SISTOR.

61



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C
C PROGRAMA PARA EFECTUAR REGRESION LINEAL O EXPONENCIAL MULTIPLE
C EL SIGNIFICADO DE LAS VARIABLES EMPLEADAS ES
C REPRESENTACION DE PUNTOS MUESTRALES
C MODALIDAD DE VARIABLES INDEPENDIENTES LA V. DEPENDIENTE
C TIPO DE VARIABLE QUE INDICA EL TIPO DE REGRESION A EFECTUAR (XPO O
C XINC)
C C(1,J) VALOR DE LA VARIABLE X(1,J) PARA EL PUNTO MUESTRAL I
C C(2,I) VARIABLE DEPENDIENTE
C MATRIZ DE COEFICIENTES DEL SISTEMA DE ECUACIONES QUE SIRVEN PA-
C RA ENCONTRAR LOS PARAMETROS DE LA FUNCION DE REGRESION
C PARAMETROS DE LA FUNCION DE REGRESION
C EPS VALOR CON EL QUE SE CONSIDERA NULO EL DETERMINANTE DE LA MA-
C TRIZ A
C DETERMINANTE ABSOLUTO DEL DETERMINANTE DE LA MATRIZ A
C PRODUCTORIAS DE LOS PRODUCTOS CRUZADOS CON LA V. DEPENDIENTE
C MATRIZ MODIFICADA DE LA MATRIZ C DONDE C=(1,I)
C MATRIZ INVERSA DE LA MATRIZ C
C MATRIZ INVERSA DEL PRODUCTO MATRICIAL X*Y+C
C DESVIACION ESTANDAR DE LOS PARAMETROS B
C VARIACION NO EXPLICADA
C COEFICIENTE DE CORRELACION
C
C LA FUNCION DE REGRESION ES DEL SIGUIENTE TIPO
C  $Y(1) = B(1) + B(2)X(2) + B(3)X(3) + \dots + B(N)X(N)$ 
C
C DIMENSIONES PARA OBTENER LOS PARAMETROS DE LA FUNCION DE REGRESION
C
C DIMENSION (30,10) X(10) B(10) A(10,10) ATMP(10)
C DIMENSIONES PARA OBTENER LA DESVIACION ESTANDAR DE B(1)
C DIMENSION PROD(10) C(10,10) XTR(10,10) X(10,10) BVAR(10)
C
C DATA X(1,1) X(1,2) X(1,3) X(1,4) X(1,5) X(1,6) X(1,7) X(1,8) X(1,9) X(1,10)
C B(1) BVAR(1)
C
C LECTURA DE DATOS
C
C EPS=0.000001
C READ(5,51) N,N,XTIPO
C IF(N) 2,2,3
C CALL EXIT
C DO 1 J=1,N
C READ(5,51) (C(1,J),I=1,N)
C LIN=LIN+1
C
C IMPRESION DE
C
C WRITE(6,52) N,N
C WRITE(6,53) (X(1),I=1,N)
C DO 5 I=1,N
C WRITE(6,54) (C(1,J),J=1,N)
C
C LLAMADO DE SUBROUTINA PARA FORMAR EL SISTEMA DE ECUACIONES
C
C IF(NTIP=10-LIN) GO TO 24
C DO 25 I=1,N
C ATMP(I)=C(1,I)
C 25 C(1,I)=ALC(1,I)
C 26 CALL SISTR(N,N,C,ATMP)
C
C IMPRESION DEL SISTEMA DE ECUACIONES
C
C WRITE(6,55)
C LC 6 I=1,N
C WRITE(6,56) (X(1),J=1,N) B(1)
C
C LLAMADO DE SUBROUTINA PARA RESOLVER EL SISTEMA DE ECUACIONES
C
C CALL GAUCR(A,B,N,EPS,DET)
C IF(DET=0) GO TO 8
C
C IMPRESION DE RESULTADOS
C
C WRITE(6,55)
C DO 7 I=1,N
C WRITE(6,56) I,B(1)
C WRITE(6,57) N,IPO
C
C OBTENCION DE SUMX(I)=X(I)
C
C A1=0
C DO 9 I=1,N
C A1=A1 + C(2,I)

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C
C
C   OBTENCION DE SUMA(XI)+Y(CI)+A2, SUMA(XI)*A3
C
C   DO 11 I=1,N
C   A2=0.0
C   A3=0.0
C   DO 10 J=1,M
C   A2=A2 + C(J,I)*C(J,I)
C   A3=A3 + C(J,I)
10  PRODCI=A2 + (A3*I)/FLOCATEN
11  CONTINUE
C   WRITE(6,54) (PRDCI),I=1,M)
C
C
C   OBTENCION DE VAR. NO EXPLICADA Y DEL COEF. DE CORRELACION
C
C   VAR=0.0
C   DO 12 I=2,M
12  VAR=VAR + UCI)*PRDCI)
C   A1=SQRT(VAR/PRDCI)
C   VAR=PRDCI) - VAR
C   VAR=VAR/FLOCATEN**2
C   WRITE(6,55) VAR
C
C
C   OBTENCION DE LA MATRIZ MODIFICADA DE VALORES MUESTRALES
C
C   DO 13 I=1,N
C   UC 14 J=1,M
C   IF(J.EQ.1) GO TO 13
C   C(I,J)=C(I,J)
C   UC 10 14
13  C(I,J)=1.0
14  CONTINUE
15  CONTINUE
C
C
C   OBTENCION DE CM TRANSPUESTA
C
C   DO 16 I=1,M
C   DO 16 J=1,M
16  X(I,J)=C(I,J)
C
C
C   LLAMADO DE SUBROUTINA PARA EFECTUAR PRODUCTO MATRICIAL
C
C   CALL MULTMACHR(CM,M,N,M,XI)
C
C   LLAMADO DE SUBROUTINA PARA OBTENER LA MATRIZ INVERSA
C
C   CALL MATINVERSI(M,EPSP,DET)
C   IF(DET.LE.EPSP) GO TO 19
C   DO 201 I=1,M
201  WRITE(6,56) (X(I,J)),J=1,M)
C
C
C   OBTENCION DE LA DESVIACION ESTANDAR DE LOS PARAMETROS
C
C   DO 17 I=1,M
C   BYAR(I)=VAR*X(I,I)
17  BYPRCI=SQRT(BYAR(I))
C
C
C   IMPRESION DE COEFICIENTES Y DESVIACIONES ESTANDAR
C
C   WRITE(6,57)
C   DO 18 I=1,M
18  WRITE(6,59) P(I),BYAR(I)
C   WRITE(6,60) A1
C
C
C   REACORDO DE DATOS PARA GRAFICAR VALORES REALES Y VALORES ESTIMA-
C   DOS CON LA FUNCION DE REGRESION
C
C   IF(LT190.NE.LIN) GO TO 27
C   DO 21 I=1,N
C   C(I,1)=FLOCAT(I)
C   C(I,2)=C(I,1)
C   SUM=0.0
C   DO 20 J=2,M
20  SUM=SUM + C(I,J)*B(J)
C   C(I,3)=C(I,1) + SUM
21  CONTINUE
C   GO TO 21
27  DO 24 I=1,N
C   C(I,1)=FLOCAT(I)
C   C(I,2)=FLOCAT(I)
C   SUM=EXP(B(I))
C   DO 22 J=2,M
22  SUM=SUM*(C(I,J)+B(J))
24  C(I,3)=SUM
29  CONTINUE

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C
C
C   LLAMADO DE SUBROUTINA PARA GRAFICAR
30 CALL GRAFIC(N,N,3)
   GO TO 1
6  WRITE(A,57)
   GO TO 1
39 WRITE(A,61)
   GO TO 1
C
C   FORMATS DE LECTURA E IMPRESION
50 FORMAT(15,A4)
51 FORMAT(2F10,0)
52 FORMAT(1M,5(//),5X,15M4 CANTIDAD DE PUNTOS MUESTRALES ES +15+15//
   1,5X,7M4 CANTIDAD DE VARIABLES ES +15)
53 FORMAT(///5(//),10,2M5 VALORES MUESTRALES SON+///5M,AS,9(7M,4
   15)///)
54 FORMAT(//2X,10(1PE11,4,1X))
55 FORMAT(///5(//),5M,47+LOS COEFICIENTES DE LA FUNCION DE REGRESION
   1 SCH+//46X,1M,17,4,3M(//)
56 FORMAT(//45X,17,10,1PE15,0)
57 FORMAT(5(//),5M,42MEL SISTEMA DE ECUACIONES NO TIENE SOLUCION)
58 FORMAT(1M,1,3(//),10,4M4 DESVIACIONES ESTANDAR DE LOS COEFICIENT
   1LS SON+//46X,4M(1),21X,4D,5,///)
59 FORMAT(//40X,2(1PE15,9,1D1))
60 FORMAT(5(//),5X,14MEL COEFICIENTE DE CORRELACION ES +1PE15,0)
61 FORMAT(5(//),5X,82MNO EXISTE LA INVERSA DE LA MATRIZ EMPLEADA PARA
   1CALCULAR LAS DESVIACIONES ESTANDAR)
550 FORMAT(//2X,1PE10,3,10(1X,1PE10,3))
551 FORMAT(1M,5(//),5X,27MEL SISTEMA DE ECUACIONES (S//)
552 FORMAT(//5X,21M TIPO DE REGRESION +A4)
   END

```

Fig. 7.3 Listado del programa principal

```

SUBROUTINE SISTOR(N,1,C,4,0)
C
C   SUBROUTINA PARA PLANTEAR EL SISTEMA DE ECUACIONES QUE PERMITE OBTEN
C   ER LOS PARAMETROS DE UNA FUNCION DE REGRESION LINEAL MULTIPLE
C   EL SIGNIFICADO DE LAS VARIABLES EMPLEADAS ES
C   N=CANTIDAD DE PUNTOS MUESTRALES
C   M=CANTIDAD DE VARIABLES INCLUYENDO LA DEPENDIENTE)
C   C=C VALOR DE LA VARIABLE X(1) PARA EL PUNTO MUESTRAL 1
C   A=MATRIZ DE COEFICIENTES DEL SISTEMA DE ECUACIONES
C   B=VECTOR DE TERMINOS INDEPENDIENTES DEL SISTEMA DE ECUACIONES
C
C   EL PLANTEAMIENTO APROVECHA LAS CARACTERISTICAS DE SIMETRIA DE LA
C   MATRIZ A
C
C   DIMENSION C(30,10),A(10,10),B(10)
C
C   OBTENCION DEL SISTEMA DE ECUACIONES
C
C   A(1,1)=N
C   DO 8 J=1,M
C   IF(C,AC,1) GO TO 4
C   SUM=0
C   DO 1 J=1,N
C   1 SUM=SUM + C(J,1)
C   B(1)=SUM
C   IF(1)=1
C   DO 1 J=1,M
C   SUM=0
C   DO 2 K=1,M
C   2 SUM=SUM + C(K,J)
C   A(1,J)=SUM
C   A(J,1)=SUM
C   3 CONTINUE
C   GO TO 5
C   4 SUM=0
C   GO 5 J=1,M
C   5 SUM=SUM + C(J,1)*C(J,1)
C   B(1)=SUM
C   DO 7 J=1,M
C   SUM=0
C   GO 6 K=1,M
C   6 SUM=SUM + C(K,1)*C(K,J)
C   A(1,J)=SUM
C   A(J,1)=SUM
C   7 CONTINUE
C   8 CONTINUE
C   RETURN
C   END

```

Fig. 7.4 Listado de la subrutina SISTOR

## 7.2.4 Ejemplo

Los valores observados para la demanda de energía eléctrica en el sector residencial desde 1962 hasta 1973 son:

ANO	DEMANDA RESIDENCIAL (MWH)
1962	1418.757
1963	1578.572
1964	1816.236
1965	1970.987
1966	2256.216
1967	2548.05
1968	2803.79
1969	3152.095
1970	3582.568
1971	3979.667
1972	4431.655
1973	4930.197

Si se sabe que la demanda de energía eléctrica se encuentra estrechamente relacionada con el tiempo, el PNB, la población y el producto bruto del sector eléctrico del año anterior. Obtenga una curva de tipo lineal y otra de tipo exponencial que se ajuste lo mejor posible a los valores muestrales de la demanda residencial de energía eléctrica.

## \* SOLUCION

TABLA 7.1 Datos del problema del ejemplo 7.2.4

$$N = 12$$

$$M = 4$$

NTIPO = LINE & EXPO

DEMANDA RESID. TIEMPO PNB 61 POBLACION PR CFE -1

1418.757	62.	165310.	37439.	1609.
1578.572	63.	178516.	38727.	1753.
1816.236	64.	199390.	40059.	2170.
1970.987	65.	212320.	41437.	2529.
2256.216	66.	227037.	42863.	2769.
2548.05	67.	241272.	44338.	3157.
2803.79	68.	260901.	45863.	3533.
3152.095	69.	277400.	47441.	4228.
3582.568	70.	296600.	49031.	4812.
3979.667	71.	306800.	50778.	5357.
4431.655	72.	329100.	52539.	5784.
4930.197	73.	354100.	54560.	6297.

TABLA 7.2 Resultados del problema del ejemplo 7.2.4

68

EL SISTEMA DE RELACIONES ES

1.250E+01	2.100E+02	3.000E+06	5.451E+C5	8.400E+04	3.447E+08
8.120E+C8	5.482E+04	2.789E+08	3.701E+07	1.031E+08	2.372E+08
3.049E+06	2.082E+08	8.348E+11	1.422E+11	1.224E+10	8.518E+08
5.451E+05	3.701E+07	1.422E+11	2.510E+10	2.007E+09	1.436E+09
4.400E+04	3.033E+04	1.224E+10	40.274E+C9	1.807E+08	1.467E+08

LOS COEFICIENTES DE LA FUNCION DE REGRESION SON

1	1.25536780E+04
2	4.60828709E+02
3	7.28920666E-04
4	4.61541007E-01
5	1.74602042E-01

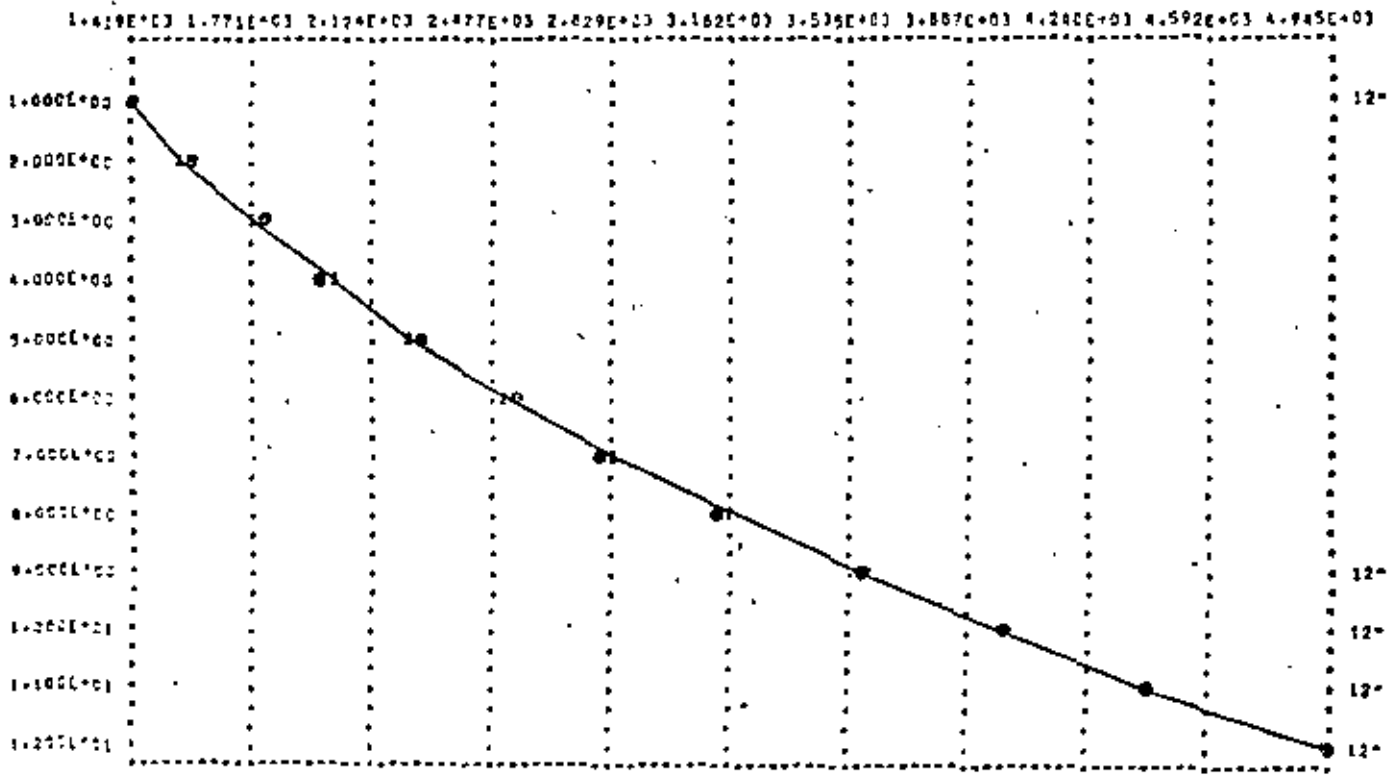
TIPO DE REGRESION LINE

LAS DESVIACIONES ESTANDAR DE LOS COEFICIENTES SON

1.25536780E+04	2.34876970E+C3
4.60828709E+02	9.72181327E+01
7.28920666E-04	3.95854067E-03
4.61541007E-01	8.74428802E-02
1.74602042E-01	8.48344206E-02

EL COEFICIENTE DE CORRELACION ES 9.99738818E-01

69



62

EL SISTEMA DE ECUACIONES ES

1.200E+01	8.100E+02	3.044E+04	5.451E+05	4.400E+04	9.464E+01
8.170E+02	5.462E+04	2.097E+08	3.701E+07	3.013E+04	6.405E+03
1.047E+04	7.062E+08	8.146E+11	1.422E+11	1.224E+10	2.432E+07
5.451E+05	1.701E+07	1.422E+11	7.510E+10	2.097E+09	4.324E+04
4.400E+04	3.013E+04	1.224E+10	2.097E+09	1.097E+04	3.542E+05

LOS COEFICIENTES DE LA FUNCION DE REGRESION SON

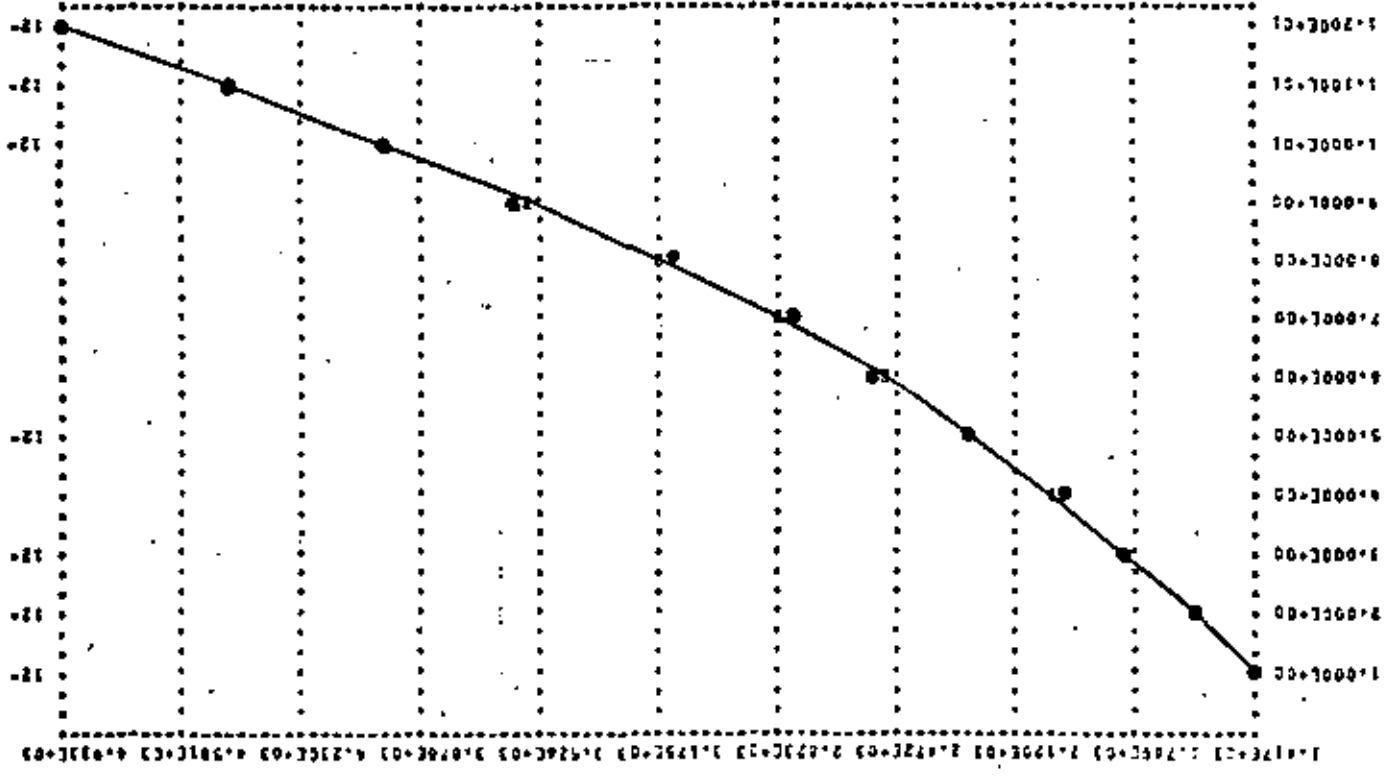
i	B(i)
1	-4.11430552E-01
2	1.38567095E-01
3	5.55134606E-07
4	-2.80140415E-05
5	2.00932652E-05

TIPO DE REGRESION CRP

LOS DEVIACIONES ESTANDAR DE LOS COEFICIENTES SON

B(i)	S.B.
-4.11430552E-01	7.91875704E-01
1.38567095E-01	1.92910641E-02
5.55134606E-07	1.33460103E-04
-2.80140415E-05	2.2054432E-05
2.00932652E-05	3.66014915E-05

EL COEFICIENTE DE CORRELACION ES 9.9765159E-01



## 7.3 Bibliografía

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## VI) SOLUCION ECUACIONES DIFERENCIALES ORDINARIAS.

Las ecuaciones diferenciales ordinarias son aquellas en las que la variable dependiente es función de una sola variable independiente :

$$* Y^{(n)} = (X, Y, Y', \dots, Y^{(n-1)})$$

### a) Método de Euler

Se tratará el caso de ecuaciones diferenciales ordinarias de primer orden :

$$dy = y' dx$$

Substituyendo por los incrementos en la expresión anterior se tiene :

$$\Delta y = y' \Delta X \quad (VI.0)$$

Tomando un punto inicial para arrancar y conservando un incremento constante  $\Delta x$  se obtiene la siguiente fórmula iterativa :

$$\begin{array}{l} Y_1 = Y_0 + Y' \left| \begin{array}{l} \Delta x \\ (X_0, Y_0) \end{array} \right. \\ Y_2 = Y_1 + Y' \left| \begin{array}{l} \Delta x \\ (X_1, Y_1) \end{array} \right. \\ \vdots \\ Y_{n+1} = Y_n + Y' \left| \begin{array}{l} \Delta x \\ (X_n, Y_n) \end{array} \right. \end{array} \quad (VI.1)$$

---


$$* Y^{(n)} \equiv \frac{d^n Y}{dX^n}$$



La ecuación VI.1 nos da la fórmula recursiva de Euler. Para aplicar el método se requiere que  $\Delta x$  sea pequeño y además contar con un punto de inicio  $(X_0, Y_0)$ . El error producido es del orden de  $\Delta x^2$ .

b) Euler modificado

El procedimiento básico es el mismo solo que para cada  $Y_{i+1}$  se hace una serie de iteraciones con los valores obtenidos sucesivamente de  $Y_{i-1}$  a fin de obtener el valor más exacto de  $Y_{i+1}$ .

Al tener :

$$Y_{i+1} = Y_i + Y' \Big|_{(X_i, Y_i)} \Delta X \quad (VI.2)$$

se efectúan las siguientes iteraciones :

$$Y'_{i+1} = F(X_{i+1}, Y_{i+1})$$

$$\hat{Y}_{i+1} = Y_i + \frac{(Y'_{i+1} + Y'_{i+1})}{2} \Delta X$$

$$\hat{Y}'_{i+1} = F(X_{i+1}, \hat{Y}_{i+1})$$

$$\hat{\hat{Y}}_{i+1} = Y_i + \frac{(Y'_{i+1} + \hat{Y}'_{i+1})}{2} \Delta X$$

⋮

y así sucesivamente hasta que :

$$\left| \hat{\hat{Y}}_{i+1} - \hat{Y}_{i+1} \right| < \epsilon \quad (VI.5)$$

al cumplirse, se procede a obtener  $Y_{i+2}$  y así sucesivamente.

Al igual que en el método anterior es necesario emplear incrementos ( $\Delta x$ ) pequeños. El error producido es del orden  $\Delta x^3$ .

c) Método de Runge - Kutta

Este método utiliza las fórmulas de integración antes vista para llegar a la obtención de su propia fórmula recursiva. Dicho proceso es bastante laborioso por lo que no se tratará.

La solución para una ecuación diferencial de primer orden  $Y' = f(x, y)$  está dada por :

$$Y_{n+1} = Y_n + \Delta Y_n$$

donde :

$$\Delta Y_n = \frac{\Delta X}{6} (K_0 + 2K_1 + 2K_2 + K_3)$$

$$K_0 = f(X_n, Y_n)$$

$$K_1 = f\left(X_n + \frac{\Delta X}{2}, Y_n + \frac{K_0 \Delta X}{2}\right)$$

$$K_2 = f\left(X_n + \frac{\Delta X}{2}, Y_n + \frac{K_1 \Delta X}{2}\right)$$

$$K_3 = f(X_n + \Delta X, Y_n + K_2)$$

## 69

La fórmula anterior es la de Runge-Kutta de 4o. orden, hay otras fórmulas con mayor cantidad de términos que se obtienen empleando diferencias de mayor orden al deducir la fórmula.

Los parámetros  $K_i$  representan la pendiente de la función en los puntos en que se está evaluando. El método da un error del orden de  $\Delta x^5$  y es uno de los más precisos.

Ejemplo

Obtener la solución de la ecuación diferencial  $Y' = 1 - X + 4Y$  y para 5 puntos consecutivos empleando los métodos de Euler, Euler mejorado y Runge - Kutta usando un incremento  $\Delta x = 0.1$ . Comparar dichos valores con la solución real si  $X_0 = 0, Y_0 = 1$ .

Sol.

La solución exacta está dada por :

$$Y' - 4Y = 1 - X$$

$$Y_h = C e^{4X}$$

$$Y_p = A + BX$$

$$\therefore -4A - 4BX = 1 - X$$

$$A = -\frac{1}{4} \quad ; \quad B = \frac{1}{4}$$

$$Y(x) = C e^{4X} - \frac{1}{4} + \frac{1}{4} X$$

$$Y(0) = 1 = C - \frac{1}{4}$$

$$C = \frac{5}{4}$$

$$Y(x) = \frac{5}{4} e^{4x} - \frac{1}{4} + \frac{1}{4} X$$

las fórmulas de solución para los métodos son :

$$Y_n = Y_{n-1} + Y' ]_{n-1} \Delta X \quad \text{(Euler)}$$

$$\left. \begin{aligned} Y_n &= Y_{n-1} + Y' ]_{n-1} \Delta X \\ \hat{Y}_n &= Y_{n-1} + \left( \frac{Y' ]_{n-1} + Y' ]_n}{2} \right) \Delta X \end{aligned} \right\} \text{Euler mejorado}$$

$$Y_n = Y_{n-1} + \frac{\Delta X}{6} [K_1 + 2K_2 + 2K_3 + K_4]$$

$$K_1 = f(X_{n-1}, Y_{n-1})$$

$$K_2 = f\left(X_{n-1} + \frac{\Delta X}{2}, Y_{n-1} + \frac{K_1 \Delta X}{2}\right) \quad \text{Runge Kutta}$$

$$K_3 = f\left(X_{n-1} + \frac{\Delta X}{2}, Y_{n-1} + \frac{K_2 \Delta X}{2}\right)$$

$$K_4 = f(X_{n-1} + \Delta X, Y_{n-1} + K_3 \Delta X)$$

las soluciones se muestran en la siguiente tabla:

K	$X_k$	Euler	E. Mej.	R.Kutta	Real
0	0	1.	1.	1.	1.
1	0.1	1.5	1.595	1.608	1.609
2	0.2	2.19	2.463	2.505	2.505
3	0.3	3.146	3.737	3.829	3.830
4	0.4	4.774	5.609	5.792	5.794
5	0.5	6.324	8.369	8.709	8.712

#### d) Diferencias finitas

Este método se emplea cuando se tienen problemas con valores en la frontera.

El procedimiento consiste en lo siguiente : dividir el intervalo de integración en "n" espacios iguales, emplear las fórmulas de derivación de diferencias finitas en la ecuación diferencial (todas las diferencias deben ser del mismo orden), substituir las condiciones de frontera y por último resolver el sistema de ecuaciones planteado. Se tiene que aplicar el operador diferencial a todos los pivotes del intervalo.

#### Ejemplo

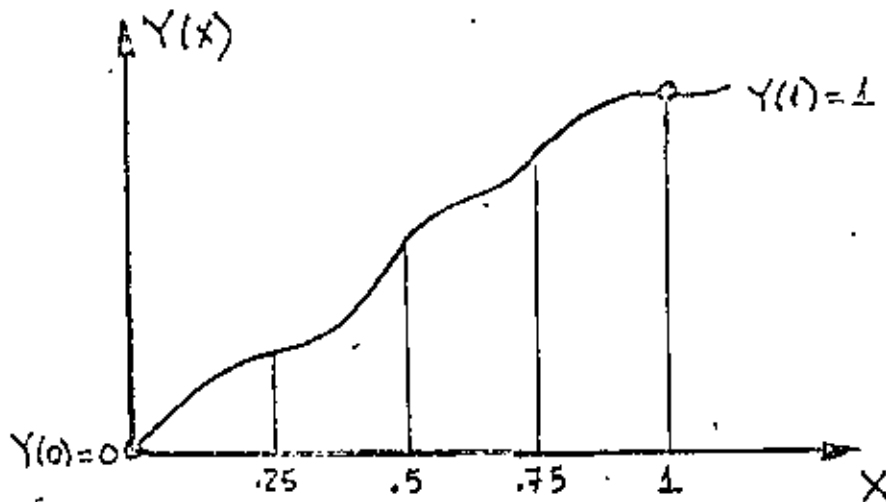
Resolver la ecuación diferencial  $\frac{d^2 y}{dx^2} - y = 0$ , en el intervalo (0,1) si  $y(0) = 0$ ,  $y(1) = 1$

Sol.

72

Se divide el intervalo en "n" partes iguales, sean 4 en este caso :

$$\Delta X = \frac{1 - 0}{4} = 0.25$$



empleando diferencias de 2o. orden :

$$Y_i'' = \frac{1}{(\Delta X)^2} [Y_{i-1} - 2Y_i + Y_{i+1}]$$

substituyendo en la ecuación diferencial :

$$\frac{1}{\Delta X^2} [Y_{i-1} - 2Y_i + Y_{i+1}] - Y_i = 0$$

$$Y_{i-1} - 2.0625 Y_i + Y_{i+1} = 0 \quad (VI.4)$$

las condiciones de frontera son :

$$Y_0 = 0$$

$$Y_4 = 1$$

aplicando VI.4 en los pivotes :

$$X_1 = 0.25$$

$$Y_0 - 2.0625 Y_1 + Y_2 = 0$$

$$- 2.0625 Y_1 + Y_2 = 0 \quad (\text{VI.5})$$

$$X_2 = 0.5$$

$$Y_1 - 2.0625 Y_2 + Y_3 = 0 \quad (\text{VI.6})$$

$$X_3 = 0.75$$

$$Y_2 - 2.0625 Y_3 + Y_4 = 0$$

$$Y_2 - 2.0625 Y_3 = -1 \quad (\text{VI.7})$$

el sistema de ecuaciones es :

$$- 2.062 Y_1 + Y_2 = 0$$

$$Y_1 - 2.062 Y_2 + Y_3 = 0$$

$$Y_2 - 2.062 Y_3 = -1$$

de donde :

$$Y_1 = 0.216$$

$$Y_2 = 0.445$$

$$Y_3 = 0.701$$

NOTA: Cuando se trata de ecuaciones diferenciales de mayor orden y se cuenta como condiciones  $y'' = 0$ , etc., hay que substituir en dichas ecuaciones las fórmulas de diferencias y despejar de ahí las condiciones de frontera desconocidas.

## 10.4 Solución de Sistemas de Ecuaciones Diferenciales Lineales No Homogéneas de Primer Orden

### 10.4.1 Objeto

Obtener la solución de sistemas de ecuaciones diferenciales no homogéneas, lineales, de primer orden mediante el método de Variación de Parámetros.

La representación en forma matricial para este tipo de sistemas de ecuaciones diferenciales es:

$$\begin{aligned}\dot{\underline{x}}(t) &= \underline{A} \underline{x}(t) + \underline{B} \underline{u}(t) \\ \underline{x}(t_0) &= \underline{x}_0\end{aligned}\quad (10.16)$$

donde  $\underline{u}(t)$  representa el vector de entradas externas si se habla de sistemas físicos.

Debido a que cuando se modelan sistemas dinámicos lineales las salidas no siempre corresponden a las variables empleadas en las ecuaciones diferenciales, en este programa se considera la representación completa mediante variables de estado de un sistema lineal, la cual es:

$$\left. \begin{aligned}\dot{\underline{x}}(t) &= \underline{A} \underline{x}(t) + \underline{B} \underline{u}(t) \\ \underline{y}(t) &= \underline{C} \underline{x}(t) + \underline{D} \underline{u}(t) \\ \underline{x}(t_0) &= \underline{x}_0\end{aligned}\right\} \quad (10.17)$$

donde  $\underline{y}(t)$  representa el vector de salidas del sistema.

### 10.4.2 Método

El método de variación de parámetros establece que la solución del sistema de ecuaciones diferenciales lineales (10.17) tiene por solución:

$$\underline{x}(t) = e^{\underline{A}(t-t_0)} \underline{x}_0 + \int_{t_0}^t e^{\underline{A}(t-\sigma)} \underline{B} \underline{u}(\sigma) d\sigma \quad (10.18)$$



donde la matriz  $e^{\underline{A}(t - t_0)}$  es la matriz de transición definida en la sección 10.3.2.

Por lo tanto la solución total será la suma de la respuesta debida a las condiciones iniciales más la respuesta debida a las excitaciones externas. Para la primera parte de la solución se discutió su obtención en la sección 10.3.2.

Dado que el primer término de la solución se evalúa mediante una evolución de estados a incrementos iguales de tiempo, la segunda parte de la solución:

$$\int_{t_0}^t e^{\underline{A}(t - \sigma)} \underline{B} \underline{u}(\sigma) d\sigma \quad (10.19)$$

también se evaluará a incrementos iguales de tiempo.

Para poder evaluar la expresión (10.19) mediante la computadora se requiere discretizar el vector de entradas  $\underline{u}(t)$ , aproximando cada entrada  $u(t)$  mediante pulsos o rectas como se muestra a continuación:

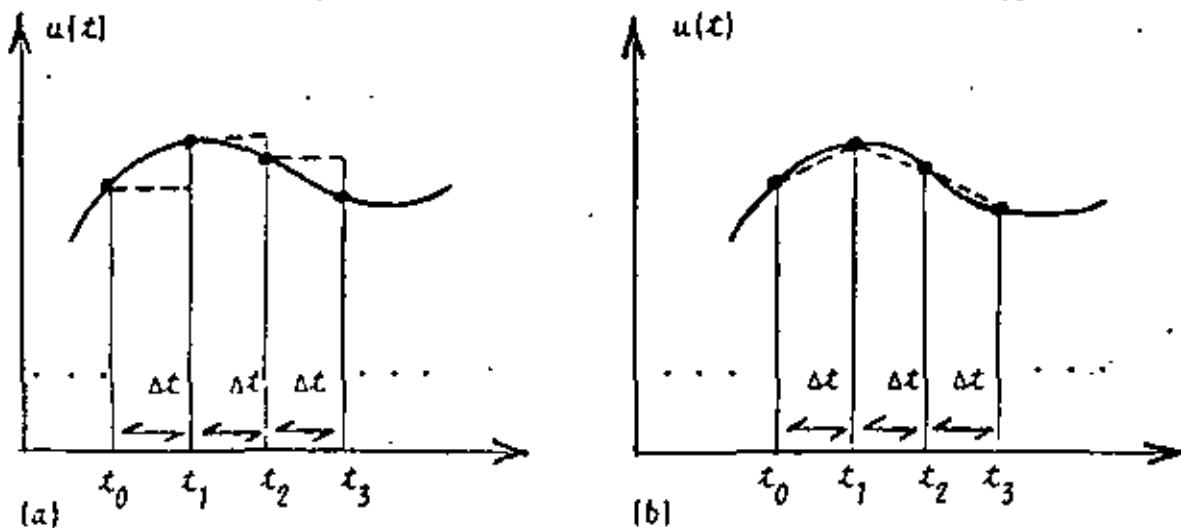


Fig. 10.10 Aproximación de una función mediante:  
a) pulsos      b) rectas

En el programa se aproxima la función  $u(t)$  mediante rectas, las ecuaciones necesarias para la evaluación de (10.19) se desarrollan a continuación.

Sea la función  $u(t)$  mostrada en la figura 10.11 :

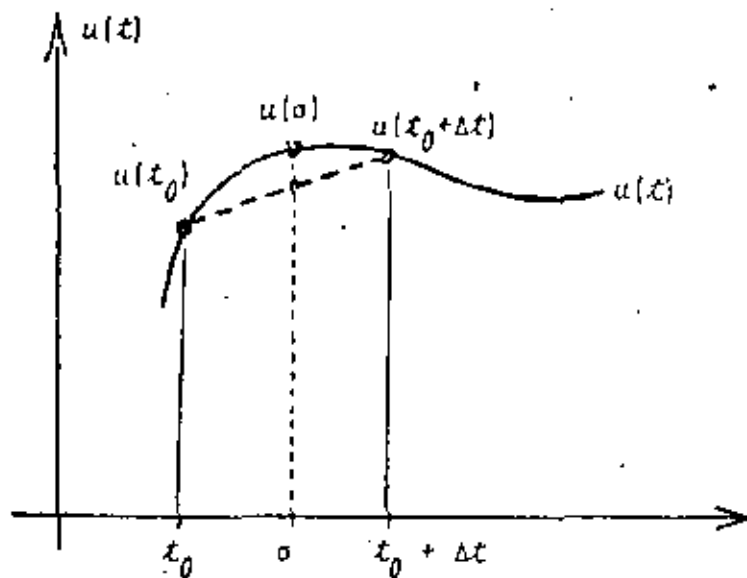


Fig. 10.11 Función  $u(t)$  y su aproximación mediante una recta en el intervalo  $t_0$  a  $t_0 + \Delta t$

Se desea evaluar la expresión (10.19) pero:

$$\int_{t_0}^t e^{\underline{A}(t-\sigma)} \underline{B} \underline{u}(\sigma) d\sigma = e^{\underline{A}t} \int_{t_0}^t e^{-\underline{A}\sigma} \underline{B} \underline{u}(\sigma) d\sigma \quad (10.20)$$

evaluando de  $t_0$  a  $t_0 + \Delta t$ :

$$\int_{t_0}^{t_0 + \Delta t} e^{\underline{A}(t-\sigma)} \underline{B} \underline{u}(\sigma) d\sigma = e^{\underline{A}\Delta t} \int_0^{\Delta t} e^{-\underline{A}\sigma} \underline{B} \underline{u}(\sigma) d\sigma \quad (10.21)$$

de la figura 10.11 se observa que:

$$\underline{u}(\sigma) \cong \frac{\underline{u}(t_0 + \Delta t) - \underline{u}(t_0)}{\Delta t} \cdot \sigma + \underline{u}(t_0) \quad (10.22)$$

substituyendo (10.22) en (10.21):

$$\Delta t \int_0^{\Delta t} e^{-\underline{A}\sigma} \underline{B} \underline{u}(\sigma) d\sigma = \left\{ e^{\underline{A}\Delta t} \int_0^{\Delta t} e^{-\underline{A}\sigma} d\sigma \right\} \cdot \frac{\underline{u}(t_0 + \Delta t) - \underline{u}(t_0)}{\Delta t} + \left\{ e^{\underline{A}\Delta t} \int_0^{\Delta t} e^{-\underline{A}\sigma} d\sigma \right\} \underline{B} \underline{u}(t_0) \quad (10.23)$$

empleando la siguiente relación:

$$e^{-A\sigma} = 1 - \frac{A\sigma}{1!} + \frac{A^2\sigma^2}{2!} - \frac{A^3\sigma^3}{3!} + \dots \quad (10.24)$$

en los términos entre corchetes se llega a:

$$e^{\frac{A}{\Delta t} \Delta t} \int_0^{\Delta t} e^{-A\sigma} \text{odo} = \frac{I(\Delta t)^2}{2!} + \dots + \frac{A^n(\Delta t)^{n+2}}{(n+2)!} + \dots \quad (10.25)$$

$$e^{\frac{A}{\Delta t} \Delta t} \int_0^{\Delta t} e^{-A\sigma} d\sigma = I(\Delta t) + \dots + \frac{A^n(\Delta t)^{(n+1)}}{(n+1)!} + \dots \quad (10.26)$$

Para la evaluación de las series (10.25) y (10.26) la cantidad de términos a emplear dependerá de la exactitud deseada. Se fija un criterio de convergencia  $\epsilon$  tal que si  $\underline{z}$  representa a la matriz de la serie (10.25) y  $\underline{w}$  a la matriz de la serie (10.26), se cumpla que:

$$\begin{aligned} \left| z_{ij}^{(n+1)} - z_{ij}^{(n)} \right| &< \epsilon, \text{ para toda } ij \\ \left| w_{ij}^{(n+1)} - w_{ij}^{(n)} \right| &< \epsilon, \text{ para toda } ij \end{aligned} \quad (10.27)$$

Como las series (10.25) y (10.26) solo dependen del espaciamiento, se tendrán que evaluar una sola vez.

En el programa para obtener la relación (10.24) hay que evaluar el vector de entradas  $\underline{U}(t)$  en cada uno de los puntos en que se subdivide el intervalo de integración.

En términos generales el proceso a seguir es:

- ① evaluar la matriz de transición  $e^{\frac{A}{\Delta t} \Delta t}$
- ② evaluar las series de las ecuaciones (10.25) y (10.26)
- ③ obtener la respuesta debida a las condiciones iniciales para  $t_i$ .

\*  $z_{ij}^{(n)}$  representa el elemento  $z_{ij}$  de la matriz  $\underline{z}$  compuesta por la sumatoria de "n" términos.

- 4) evaluar  $u(t)$  en  $t_i$  y  $t_{i+1}$
- 5) obtener la respuesta debida a las excitaciones externas mediante la relación (10.23)
- 6) hacer  $i=i+1$  y regresar al paso 3) hasta haber todo el intervalo de integración.

### 10.4.3 Descripción del Programa

#### a) Subrutinas requeridas:

SUBROUTINE EXPMA(DELTA, M, A, EXPO), obtiene la matriz de transición. Consultar sección 10.3.3.

SUBROUTINE INTPE(DELTA, M, A, SUMA), obtiene la matriz de la serie (10.26); esta expresión se emplea para evaluar la respuesta debida a las excitaciones externas

SUBROUTINE INTRE(DELTA, M, A, RECTA), evalúa la expresión dada por la serie de la ecuación (10.25); esta expresión se utiliza para calcular la respuesta debida a las excitaciones externas.

SUBROUTINE MULTMA(A, B, N, M, L, X), obtiene el producto matricial AB. Consultar el capítulo 2.

SUBROUTINE GRAFI(A, N, M), grafica las soluciones de las variables dependientes y de las respuestas del sistema. Consultar el capítulo 1.

SUBROUTINE EXCITA(T, F), evalúa el vector de entradas  $u(t)$  en el instante  $t_i$ .

#### b) Descripción de las variables:

Para la subrutina INTPE:

DELTA	espaciamiento entre los valores de la variable independiente
M	cantidad de ecuaciones diferenciales
A(I, J)	matriz de coeficientes constantes del sistema de ecuaciones diferenciales
EPS	criterio de convergencia
SUMA(I, J)	matriz resultante de evaluar la serie
CN	contador de iteraciones
DIV	factorial divisor
TNEW	incremento de la variable independiente elevado a la potencia "n"
CUAT(I, J)	matriz identidad

B(I, J) matriz A elevada a la potencia "n"  
 X(I, J) matriz resultante del producto AB

Para la subrutina INTRE:

DELT espaciamento entre los valores de la variable independiente

M cantidad de ecuaciones diferenciales

A(I, J) matriz de coeficientes del sistema de ecuaciones diferenciales

RECTA(I, J) matriz resultante de evaluar la serie

CMA(I, J) matriz identidad

B(I, J) matriz A elevada a la potencia "n"

X(I, J) matriz resultante del producto AB

EPS criterio de convergencia

TNEW incremento de la variable independiente elevado a la potencia "n"

CN contador

DIV factorial divisor

Para la subrutina EXCITA:

T valor del instante de tiempo en el cual se desea evaluar la expresión U(t)

F(1, 1) valor del primer renglón de la expresión U(t) en el instante  $t_i$

F(2, 1) valor del segundo renglón de la expresión U(t) en el instante  $t_i$

F(3, 1) valor del tercer renglón de la expresión U(t) en el instante  $t_i$

F(4, 1) valor del cuarto renglón de la expresión U(t) en el instante  $t_i$

F(5, 1) valor del quinto renglón de la expresión U(t) en el instante  $t_i$

Para el programa principal:

M cantidad de ecuaciones diferenciales

N cantidad de subintervalos en que se divide el intervalo de integración

NS cantidad de salidas del sistema

NU<sub>i</sub> cantidad de entradas del sistema

PERIO intervalo de integración

DELT	magnitud de los subintervalos de integración
A(I, J)	matriz <u>A</u> del sistema de ecuaciones
B(I, J)	matriz <u>B</u> del sistema de ecuaciones
C(I, J)	matriz <u>C</u> del sistema de ecuaciones
D(I, J)	matriz <u>D</u> del sistema de ecuaciones
X(1, 1)	condición inicial de la variable independiente
X(I, J)	condiciones iniciales para cada una de las variables dependientes, $J > 1$
X(I, J)	solución del sistema de ecuaciones
VY(I, J)	valor de las salidas del sistema
SUMA(I, J)	integral del término constante de la ecuación de la recta empleada para aproximar la entrada
RECTA(I, J)	integral del término variable de la ecuación de la recta empleada para aproximar la entrada
SHOM(I, J)	solución del sistema debida a las excitaciones externas
V(I, J)	valor de la entrada en el instante $t_{i-1}$
PEND(I, J)	pendiente de la recta empleada para aproximar la entrada
RE(I, J)	variable de reemplazo
F(I, J)	variable de reemplazo

c) Dimensiones:

La proposición DIMENSION del programa principal y de las subrutinas deberá modificarse cuando:

$N > 100$  y/o  $M > 5$  y/o  $NS > 5$  y/o  $NU > 5$

Si se modifica la extensión de M, deberán modificarse los argumentos de la subrutina EXCITA.

d) Formatos para los datos de entrada:

SEC. TARJETAS	FORMATO	INFORMACION
1	(4I5, F10.0)	M, N, NS, NU, PERIO
2	(8F10.0)	A(I, J), los elementos de la matriz se dan renglón por renglón. Emplear tan-

.		tas tarjetas como sean ne
.		cesarias
.		
3	(8F10.0)	B(I,J), igual que para la
.		matriz <u>A</u>
.		
4	(8F10.0)	C(I,J), igual que para la
.		matriz <u>A</u>
.		
5	(8F10.0)	D(I,J), igual que para la
.		matriz <u>A</u>
.		
6	(8F10.0)	X(I,J), el primer valor de
		bé corresponder a la condi
		ción inicial de la varia-
		ble independiente.

-----  
 otros paquetes de datos (opcional)  
 -----

n

TARJETA EN BLANCO, al finalizar toda la información.

e) Diagrama de bloques:

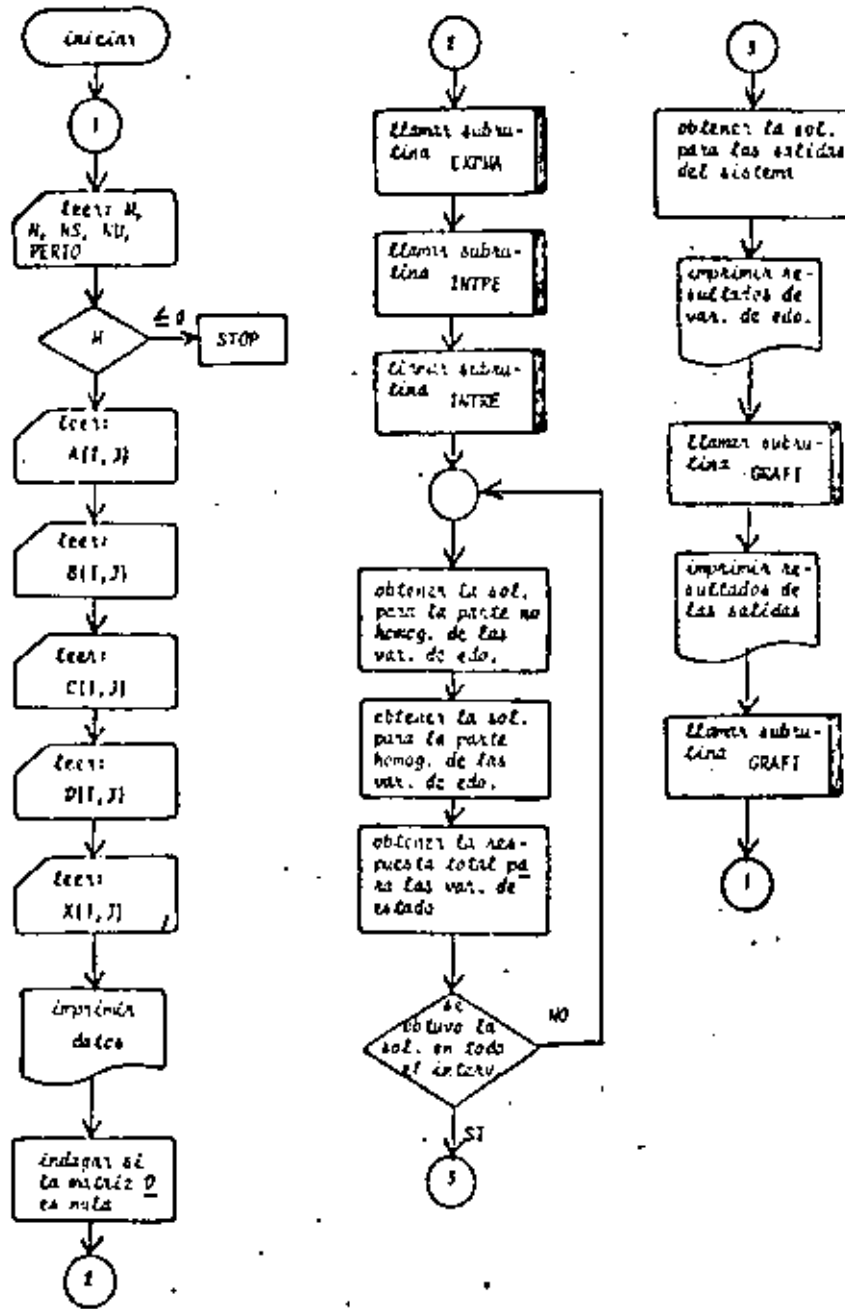


Fig. 10.12 Diagrama de bloques del programa principal



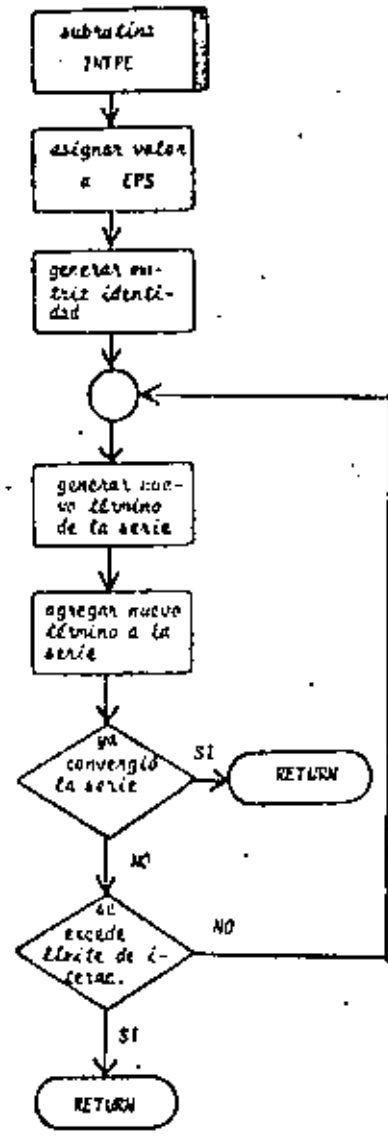


Fig. 10.13 Diagrama de bloques de la subrutina INTPE

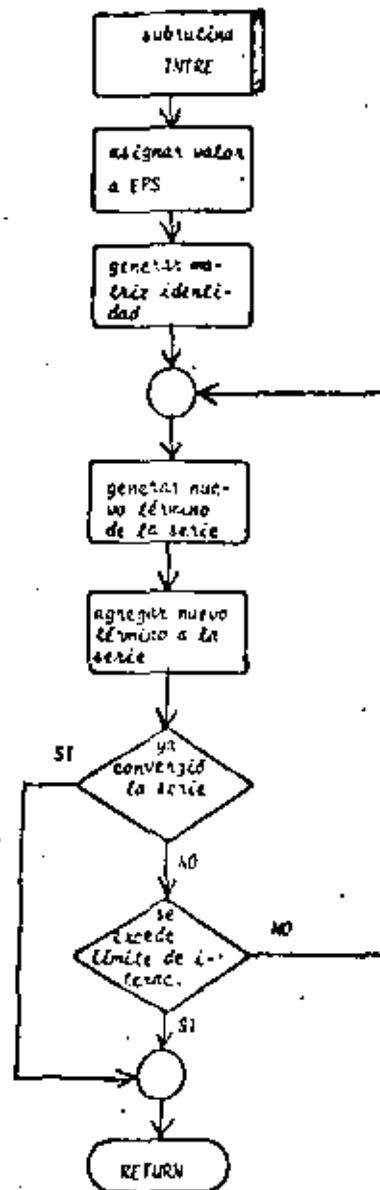


Fig. 10.14 Diagrama de bloques de la subrutina INTRE

6) Listado:

```

C PROGRAM PARA RESOLVER SISTEMAS DE ECUACIONES LINEALES EN UNA COMPUTA-
C DORA DIGITAL MEDIANTE EL METODO DE VARIACION DE PARAMETROS
C SIGNIFICADO DE LAS VARIABLES EMPLEADAS
C RESOLUCION DE ECUACIONES DIFERENCIALES
C RESOLUCION DE PARTES DEL SUR DE SUCCESIVO EL INTERVALO DE INTEGRA-
C CION
C INDEFINICION DE SALIDAS
C INDEFINICION DE ENTRADAS
C PERFORMANCIA DEL INTERVALO DE INTEGRACION
C DELIMITACION DE LOS SUBINTERVALOS
C MATRIZ A DEL SISTEMA DE ECUACIONES
C MATRIZ B DEL SISTEMA DE ECUACIONES
C MATRIZ C DEL SISTEMA DE ECUACIONES
C MATRIZ D DEL SISTEMA DE ECUACIONES
C MATRIZ E DEL SISTEMA DE ECUACIONES
C CONDICION INICIAL DE LA VARIABLE INDEPENDIENTE
C RESOLUCION DE LAS ECUACIONES DIFERENCIALES
C RESOLUCION PARA LAS VARIABLES DE ESTADO
C VALORES DE LAS SALIDAS
C SIMULACION DE LA RESPUESTA A LAS EXCITACIONES EXTERNAS
C EXPONENCIAL DE TRANSICION
C SUMA INTEGRAL DE LA PARTE CONSTANTE DE LA ECUACION DE LA RECTA
C RECTA GENERAL DEL TIPO DE VARIACION DE LA ECUACION DE LA RECTA
C VALOR DE LA ENTRADA EN EL INSTANTE T(1-1)
C VALOR DE LA ENTRADA EN EL INSTANTE T(2)
C PENDIENTE DE LA RECTA
C INDEFINICION DE COLUMNAS DEL ARREGLO MATRICIAL X
C MATRIZ DE REEMPLAZO

```

---

```

DIMENSION A(4,6),B(6,6),C(6,6),D(6,6),E(10,6),EXP(6,6),RECTA(6,6)
1, SUMA(6,6), T(6,6), Y(6,6), P(6,6), P1(6,6), F(6,6), Y1(10,6)
1005
1006
C LECTURA DE DATOS
1 READ(10,100) N,M,N1,M1,PERIO
IF(N) 2,3
2 CALL EXP
3 WRITE(11,200)
DO 4 101,100
4 READ(10,150) (A(I,J),J=1,M)
DO 5 101,100
5 READ(10,150) (B(I,J),J=1,M1)
IF(M1) 6,7
DO 6 101,100
6 READ(10,150) (C(I,J),J=1,M1)
DO 7 101,100
7 READ(10,150) (D(I,J),J=1,M1)
71 READ(10,150) (E(I,J),J=1,M1)
C IMPRESION DE DATOS
WRITE(11,200)
DO 8 101,100
8 WRITE(11,250) (A(I,J),J=1,M)
WRITE(11,300)
DO 9 101,100
9 WRITE(11,250) (B(I,J),J=1,M1)
IF(M1) 10,11
WRITE(11,350)
DO 10 101,100
10 WRITE(11,250) (C(I,J),J=1,M1)
WRITE(11,400)
DO 11 101,100
11 WRITE(11,250) (D(I,J),J=1,M1)
12 WRITE(11,450)
WRITE(11,250) (E(I,J),J=1,M1)
IF(M1) 13,14
13 WRITE(11,500)
DO 12 101,100
12 IF(C(I,J)EQ,0,1) GO TO 12
1001
GO TO 13
12 CONTINUE
73 1000
C CALCULO LA MATRIZ DE TRANSICION
13 CALL EXP(1001,74,EXP)
C CALCULO DE LA RECTA
CALL RECTA(1001,74,RECTA)
CALL REEMPL(1001,74,REEMPL)

```



```

SUBROUTINE INTPECT(A,B,A0001)
C
C SUMATORIA PARA EVALUAR LA INTEGRAL DEL TERMINO CONSTANTE DE LA
C RECTA
C
C SIGNIFICADO DE LAS VARIABLES EMPLEADAS
C DELTERMINACIONTO ENTRE LOS VALORES DE LA VARIABLE INDEPENDIENTE
C PROBABILIDAD DE ECUACIONES DIFERENCIALES
C MATRIZ A DEL SISTEMA DE ECUACIONES
C SUMAMATRIZ RESULTANTE DE EVALUAR LA INTEGRAL
C EPS=CRITERIO DE CONVERGENCIA
C CMAPATRIZ IDENTIDAD
C CMAPCONTADOR DE ITERACIONES
C DIVERGENCIA DIVISOR
C TIEMPORELEVIO DE TIEMPO ELIVADO A LA POTENCIA N
C MATRIZ A ELEVADA A LA POTENCIA N
C MATRIZ RESULTANTE DEL PRODUCTO AN
DIMENSION A(6,6),C*(6,6),R(6,6),I(6,6),SUMA(6,6)
EPS=0.00051
C
C OBTENER MATRIZ IDENTIDAD
DO 3 I=1,6
DO 2 J=1,6
IF(I,6,0) GO TO 1
C*(I,I)=0.0
GO TO 2
1 C*(I,J)=1.0
2 CONTINUE
3 CONTINUE
C OBTENER LOS DOS PRIMEROS TERMINOS DE LA SERIE
DO 4 I=1,M
DO 6 J=1,M
SUMA(I,J)=C*(I,J)*DELT + (A(I,J)*DELT*DELT)/2.0
4 R(I,J)=A(I,J)
TAM=DELT*DELT
C*(I,6)=0
DIV=2.0
C OBTENER LOS TERMINOS RESTANTES DE LA SERIE
5 DIV=DIV*DELT
SUMA(I,J)=R(I,J)*TAM
CALL MULTPLA(A,R,M,M,M,X)
DO 6 I=1,M
DO 6 J=1,M
R(I,J)=X(I,J)
6 SUMA(I,J)=SUMA(I,J)+TAM*R(I,J)
IF(C=0.0) GO TO 9
13 A=IX=C*(I,1)
DO 8 I=1,M
DO 7 J=1,M
IF(C=DELT*A(I,J))=ABS(A(I,J)) 7,7,14
14 A=IX=C*(I,J)
7 CONTINUE
8 CONTINUE
C VERIFICAR LA CONVERGENCIA DE LA SERIE
9 IF(ABS(A(I,J))-EPS) 11,11,9
10 DO 10 I=1,M
DO 10 J=1,M
SUMA(I,J)=SUMA(I,J) + C*(I,J)
IF(C=20.0) 15,15,11
15 C*(I,6) = 1.0
GO TO 5
11 RETURN
END

```

Fig. 10.16 Listado de la subrutinaINTPE

```

SUBROUTINE INTRE (DELTA, N, A, RECTA)
C SUBROUTINA PARA EVALUAR LA INTEGRAL DE LA PARTE VARIABLE DE LA E=
C CUADRA DE LA RECTA
C SIGNIFICADO DE LAS VARIABLES EMPLEADAS
C DELTA: INCREMENTO ENTRE LOS VALORES DE LA VARIABLE INDEPENDIENTE
C RECTA: MATRIZ DE COEFICIENTES DIFERENCIALES
C A: MATRIZ A DEL SISTEMA DE ECUACIONES
C RECTA * DELTA: RESULTANTE DE EVALUAR LA SERIE
C MATRIZ IDENTIDAD
C MATRIZ A ELEVADA A LA POTENCIA N
C RESULTANTE DEL PRODUCTO A *
C RESULTANTE DE CONVERGENCIA
C INCREMENTO DE LA VARIABLE INDEPENDIENTE ELEVADO A LA POTENCIA
C N
C CONTADOR DE ITERACIONES
C DIMENSIONAL A(6,6), RECTA(6,6), CHA(6,6), B(6,6), X(6,6)
C EP=0.00001
C MATRIZ IDENTIDAD
DO 3 J=1,N
DO 2 I=1,N
IF (I, J) GO TO 1
CH(I, J)=0.0
GO TO 3
1 CH(I, J)=1.0
2 CONTINUE
3 CONTINUE
C ESTAR LOS DOS PRIMEROS TERMINOS DE LA SERIE
DO 4 I=1,N
DO 4 J=1,N
RECTA(I, J)=CH(I, J)*DELTA**2/2.0 + (A(I, J)*(DELTA**3))/6.0
4 RT(I, J)=A(I, J)
T(I, J)=DELTA*DELTA*DELTA
C MATRIZ
DO 5 I=1,N
DO 5 J=1,N
CH(I, J)=X(I, J)
5 CH(I, J)=X(I, J)*T(I, J)/DIV
IF (I, LE, 0.0) GO TO 9
MAX=0
DO 6 I=1,N
DO 6 J=1,N
IF (ABS(CH(I, J)), LE, ABS(MAX)) GO TO 7
MAX=ABS(CH(I, J))
6 CONTINUE
7 CONTINUE
8 CONTINUE
C VERIFICAR CONVERGENCIA DE LA SERIE
IF (ABS(MAX), LE, EP) GO TO 11
DO 10 I=1,N
DO 10 J=1,N
10 RECTA(I, J)=RECTA(I, J) + CHA(I, J)
IF (I, GT, 20) GO TO 11
CHC = 1.0
DO 10 5
11 RETURN
END

```

Fig. 10.17 Listado de la subrutina INTRE

```

SUBROUTINE EXCITA (F)
DIMENSION F(6,6)
F(1,1)=5.0*EXP(-0.5*F)
F(2,1)=0.5*EXP(3.0*F)
F(3,1)=0.0
F(4,1)=0.0
F(5,1)=0.0
F(6,1)=0.0
RETURN
END

```

Fig. 10.18 Listado de la subrutina EXCITA

## 10.4.4 Ejemplo

89

Para el siguiente circuito eléctrico:

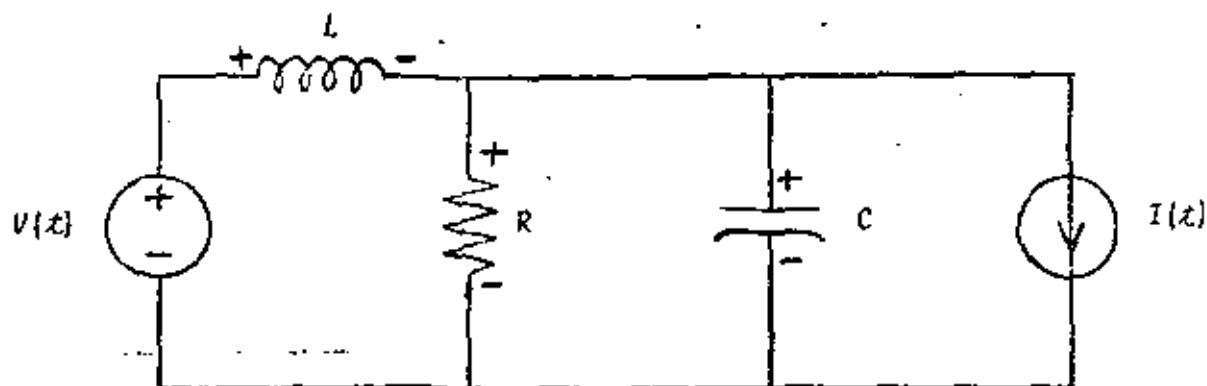


Fig. 10.19 Circuito eléctrico del problema del ejemplo 10.4.4

si se consideran como salidas  $I_c$  y  $V_R$ , su representación mediante variables de estado es:

$$\begin{bmatrix} \frac{dI_L}{dt} \\ \frac{dV_c}{dt} \end{bmatrix} = \begin{bmatrix} 0 & -1/L \\ 1/C & -1/RC \end{bmatrix} \begin{bmatrix} I_L \\ V_c \end{bmatrix} + \begin{bmatrix} 1/L & 0 \\ 0 & -1/C \end{bmatrix} \begin{bmatrix} V(t) \\ I(t) \end{bmatrix}$$

$$\begin{bmatrix} I_c \\ V_R \end{bmatrix} = \begin{bmatrix} 1 & -1/R \\ 0 & 1 \end{bmatrix} \begin{bmatrix} I_L \\ V_c \end{bmatrix} + \begin{bmatrix} 0 & -1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} V(t) \\ I(t) \end{bmatrix}$$

Determine los valores de  $I_L$ ,  $V_c$ ,  $I_c$  y  $V_R$  para  $t \geq 0$ , cuando:

$$\begin{aligned}
 V(t) &= 5e^{-4t}u_{-1}(t) \quad (V) \\
 I(t) &= 0.5\sin(3t)u_{-1}(t) \quad (A) \\
 R &= 100 \text{ ohms} \\
 C &= 0.1 \text{ F} \\
 L &= 1.0 \text{ H} \\
 t_0 &= 0. \\
 V_C(t_0) &= 2 \text{ V} \\
 I_L(t_0) &= 0.3 \text{ A} \\
 t_f &= 10 \text{ s}
 \end{aligned}$$

\* SOLUCION

TABLA 10.5 Datos para el problema del ejemplo 10.4.4

$M = 2$   
 $N = 100$   
 $NS = 2$   
 $NU = 2$   
 $PERIO = 10$

$$A = \begin{bmatrix} 0 & -1 \\ 10 & -0.1 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & 0 \\ 0 & -10 \end{bmatrix}$$

$$C = \begin{bmatrix} 1 & -0.01 \\ 0 & 1 \end{bmatrix}$$

$$D = \begin{bmatrix} 0 & -1 \\ 0 & 0 \end{bmatrix}$$

$$X(1, J) = ( 0 , 0.3 , 2 )$$

---


$$F(1, 1) = 5.*EXP(-4.*T)$$



$$F(2,1) = 0.5 * \text{SIN}(3.0 * T).$$

$$F(3,1) = 0.$$

$$F(4,1) = 0.$$

$$F(5,1) = 0.$$

TABLA 10.6 Resultados del problema del ejemplo 10.4.4

LA SOLUCION PARA LAS VARIABLES DE ESTADO EN  
TIEMPO (11) (12)

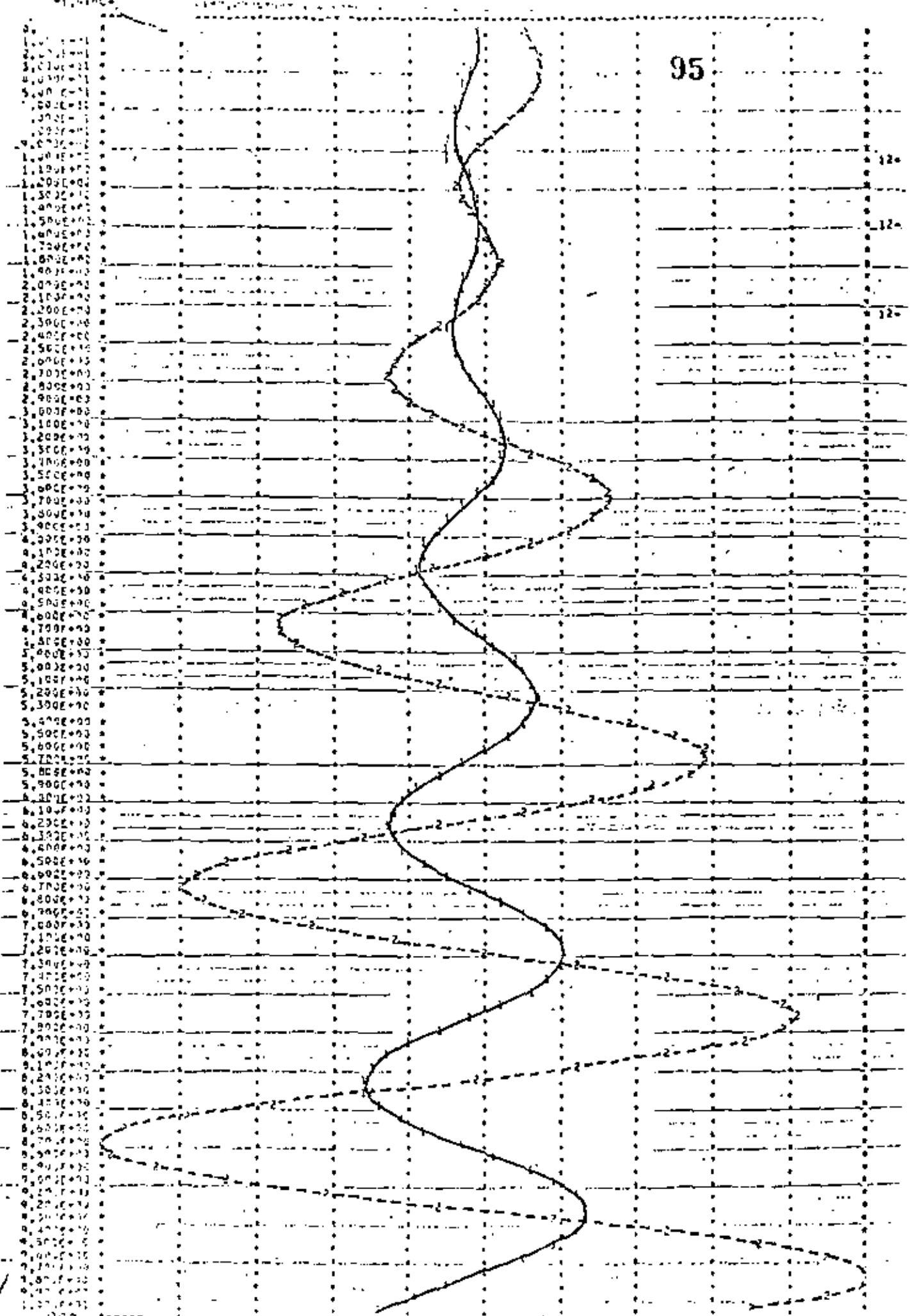
0.	,34000E+00	,20000E+01
,10000E+00	,50141E+00	,23220E+01
,20000E+00	,53427E+00	,26119E+01
,30000E+00	,45229E+00	,27485E+01
,40000E+00	,30803E+00	,26745E+01
,50000E+00	,13400E+00	,23989E+01
,60000E+00	-,25673E+01	,19248E+01
,70000E+00	-,35241E+00	,13500E+01
,80000E+00	-,21201E+00	,76453E+00
,90000E+00	-,26386E+00	,23115E+00
,10000E+01	-,25499E+00	-,17406E+00
,11000E+01	-,21453E+00	-,43483E+00
,12000E+01	-,16776E+00	-,44202E+00
,13000E+01	-,12577E+00	-,36147E+00
,14000E+01	-,10031E+00	-,23598E+01
,15000E+01	-,11965E+00	,32723E+00
,16000E+01	-,10005E+00	,67425E+00
,17000E+01	-,25002E+00	,43023E+00
,18000E+01	-,35072E+00	,10544E+01
,19000E+01	-,45351E+00	,47213E+00
,20000E+01	-,53738E+00	,67331E+00
,21000E+01	-,56102E+00	,17120E+00
,22000E+01	-,56612E+00	-,45849E+00
,23000E+01	-,46037E+00	-,12310E+01
,24000E+01	-,31994E+00	-,19051E+01
,25000E+01	-,01039E+01	-,25654E+01
,26000E+01	,19018E+00	-,29957E+01
,27000E+01	,09818E+00	-,31137E+01
.	.	.
,28000E+01	,13221E+01	-,15828E+02
,29000E+01	,26319E+01	-,12176E+02
,30000E+01	,37213E+01	-,93730E+01
,31000E+01	,44771E+01	-,56132E+01
,32000E+01	,48234E+01	-,12545E+01
,33000E+01	,47215E+01	,32986E+01
,34000E+01	,41721E+01	,76194E+01
,35000E+01	,32206E+01	,11275E+02
,36000E+01	,19834E+01	,13940E+02
,37000E+01	,47349E+01	,16330E+02
,38000E+01	,41497E+01	,15247E+02
,39000E+01	-,75350E+01	,13798E+02
,40000E+02	-,37447E+01	,14944E+02



EL VALOR DE LAS SALIDAS ES  
TIEPO (11) (12)

21	28000E+00	20000E+01
10000E+00	33000E+00	23000E+01
20000E+00	22500E+00	20100E+01
30000E+00	33000E+00	27000E+01
40000E+00	41000E+00	20000E+01
50000E+00	33000E+00	23000E+01
60000E+00	53000E+00	40000E+01
70000E+00	59000E+00	43000E+01
80000E+00	57000E+00	40000E+01
90000E+00	40000E+00	23100E+01
10000E+01	32000E+00	17000E+01
11000E+01	43000E+00	40000E+01
12000E+01	57000E+00	40000E+01
13000E+01	22100E+00	10100E+01
14000E+01	32000E+00	23000E+01
15000E+01	36000E+00	37000E+01
16000E+01	32000E+00	07000E+01
17000E+01	23000E+00	10000E+01
18000E+01	25000E+00	13000E+01
19000E+01	18000E+00	07000E+01
20000E+01	10000E+00	07000E+01
21000E+01	57000E+00	17000E+01
22000E+01	71000E+00	43000E+01
23000E+01	75000E+00	10000E+01
24000E+01	09000E+00	10000E+01
25000E+01	53000E+00	23000E+01
26000E+01	27000E+00	20000E+01
27000E+01	09000E+00	11000E+01
28000E+01	00000E+00	20000E+01
29000E+01	75000E+00	23000E+01
30000E+01	10000E+00	13000E+01
31000E+01	12000E+00	21000E+01
32000E+01	52000E+00	12000E+01
33000E+01	45000E+00	30000E+01
34000E+01	09000E+00	01000E+01
35000E+01	30000E+00	11000E+01
36000E+01	20000E+00	13000E+01
37000E+01	07000E+00	15000E+01
38000E+01	71000E+00	17000E+01
39000E+01	21000E+00	13000E+01
40000E+01	50000E+00	10000E+01

95





**DIVISION DE EDUCACION CONTINUA  
FACULTAD DE INGENIERIA U.N.A.M.**

**INTRODUCCIÓN A LA PROGRAMACION Y COMPUTACION ELECTRONICA**

**CASOS DE APLICACIONES NO MATEMATICAS**

**OCTUBRE, 1981**

A P L I C A C I O N E S

N O - M A T E M A T I C A S .

- 1.- CONCEPTOS BASICOS                   TECNICAS BASICAS
- 2.- ALGUNOS TIPS                           NUMEROS Y CARACTERES
- G R A F I C A C I O N
- 3.- BUSQUEDAS                            BUSQUEDAS EN TABLAS
- C A R A C T E R E S Y P A L A B R A S
- 4.- ACOMODOS.                            S T A C K S Y C O L A S .

R E F E R E N C I A S :

GEREZ, GRIJALVA "EL ENFOQUE DE SISTEMAS" (CAP IV) LIMUSA, MEXICO

PFALTZ "COMPUTER DATA STRUCTURES" MC GRAW HILL

KNUTH "THE ART OF COMPUTER PROG. VOL I y III ADISION WESCEY

FORS THE, ORGANIC.. " TO COMPUTER SCIENCE" JOHN WILEY.

0, 2

VAMOS A VER CASOS CONCRETOS DE APLICACIONES NO - MATEMATICAS,  
 "SUPONEMOS" QUE LOS ASISTENTES YA PROGRAMAN EN FORTRAN MUY  
 BIEN

1.- USO DE BANDERAS ( FLAGS) Y SWITCHES.

SE UTILIZAN BANDERAS O SWITCHES, PARA DETECTAR UN ESTA-  
 DO EN ALGUNA PARTE DEL PROGRAMA, LA BANDERA (FLG) PUEDE  
 TENER DOS ESTADOS FALSO (.FALSE.) Y VERDADERO (.TRUE.),  
 ESE ESTADO PUEDE SER SWICHEADO

FLG = . NOT. FLAG

Y PODEMOS PROBAR EL ESTADO DE LA BANDERA

```
      (TRUE)
      IF ( FLG ) GO TO 111
```

OTRA ALTERNATIVA ES UTILIZAR UNA VARIABLE ENTERA (IFLG).  
 LOS VALORES 1 y 2 SON USADOS Y EL SWITCH PUEDE TOMAR - -  
 CUALQUIERA DE LOS DOS VALORES.

```
      I FLG = 3 - I FLG CON UN GO TO
```

```
      GO TO (10, 20 ), IFLG.
```

SE PUEDE TAMBIEN PROBAR UN LOOP CON UN CONTADOR INICIA-  
 LIZANDO IFLAG, i.e. SUPONGAMOS QUE IFLAG = 1,2,3,4,5,  
 1,2,.....

```
      I FLG = 0
```

```
      I FLAG = IFLG + 1
```

```
      IF ( IFLG. GT. 5) IFLG = 1
```



DO - LOOP'S.

3

LOS LOOP DEL DO, PUEDEN SER IMPLEMENTADOS DE MANERA MUY EFICIENTE EN FORTRAN, SIN EMBARGO LA VARIABLE DEL INDICE -- DEBE DE SER ENTERA Y EL INCREMENTO DEBE DE SER POSITIVO

EJEMPLOS: SE REQUIERE CONSTRUIR UN LOOP EN EL CUAL

J TOMA VALORES DE - 43 a + 43

```
DO 15 I = 1, 87
```

```
J = I - 44
```

SI EN UN LOOP J TOMA VALORES ENTRE 16 Y 2 ( EL INCREMENTO ES - 2) ESTO SE PUEDE HACER.

```
DO 13 I = 2, 16, 2
```

```
J = 18 - I
```

UN LOOP QUE REQUIERE UN INDICE REAL A QUE TOMA VALORES -- 0.1, 0.8, 0.3 .... 1.0 SE PUEDE ESCRIBIR ASI :

```
DO 14 I=1, 10
```

```
A = FLOAT (I)/ 10.0
```

EN ESE CASO A SE INICIALIZA CON 0.0 y 0.1 ES SUMADO CADA VEZ QUE EL CICLO SE EFECTUE.

SI SE QUIERE DOBLAR EL VALOR DE UNA VARIABLE, POR EJEMPLO : 1, 2, 4, 8, 16, 32, 64, 128, 516, ETC EN CADA PASO DEL CICLO.

```
N = 1
```

```
DO 33 I = 1, 10
```

```
.
```

```
.
```

```
33 N = N + N
```

DE OTRA FORMA:

U) 4

DO 33 I = 1, 10

N = 2 \* \* ( I - 1 )

¿ QUE FORMA ES MEJOR ?

EMPACÁNDO NUMEROS.

PARA AHORRAR ESPACIO, ES MUY COMUN GUARDAR VARIOS NUMEROS ENTEROS EN UNA VARIABLE ENTERA, SIEMPRE Y CUANDO ESTOS NUMEROS NO SEA NEGATIVOS.

SI LOS ENTEROS TOMAN VALORES ENTRE 0 Y N EL METODO CONSISTE EN TRATARLOS COMO DIGITOS SUCESIVOS EN LA BASE  $N + 1$ . ESTO SE HACE ASIGNANDO EL PRIMER ENTERO A LA VARIABLE, MULTIPLICANDOLA POR  $N + 1$ , SUMANDO EL SEGUNDO ENTERO.

POR EJ. SI LOS ELEMENTOS 1 a 5 DEL VECTOR I DIG VALEN 6, 8, 0, 3, 1, SE PUEDEN "EMPACAR" EN UNA VARIABLE NUM COMO DIGITOS DE UN NUMERO DECIMAL

NUM = 0

DO 17 I = 2, 5

17 NUM = NUM \* 10 + IDIG (I)

DESPUES DE EJECUTADO EL PROGRAMA NUM = 68031 (NOTA LO ANTERIOR ES VALIDO PARA NUMEROS BINARIOS EN DONDE  $NUM \leq 2$ ). HAY QUE TENER PRECAUCION DE NO EXCEDER EL POSITIVO MAXIMO DE LA COMPUTADORA. PARA DESEMPACAR LOS NUMEROS SE UTILIZA LA FUNCION MOD. EL ULTIMO ENTERO EMPACADO ES EL RESIDUO, CUANDO LA VARIABLE SE DIVIDE ENTRE  $N + 1$

SI NUM = 68031 Y QUEREMOS OBTENER LOS ORIGINALES DE IDIG  
HACEMOS LO SIGUIENTE:

DO 19 I = 1, 5

J = 6 - I

I DIG (J) = MOD (NUM, 10)

19 NUM = NUM/10

NOTESE QUE SE UTILIZO UN INCREMENTO DE - 1, PARA DESEMPACAR  
CORRECTAMENTE ( LIFO )

TRADUCCION DE TABLAS.

MUCHAS VECES SE NECESITA MAPEAR UN CONJUNTO DE NUMEROS A OTROS,  
EN FORMA IRREGULAR, LA CUAL NO PUEDE SER COMPUTADA. SI EL PRI-  
MER CONJUNTO DE NUMEROS CONTIENE ENTEROS, ESTOS SE PUEDEN TOMAR  
COMO INDICES DE UN VECTOR QUE CONTIENE EL SEGUNDO CONJUNTO DE  
NUMEROS.

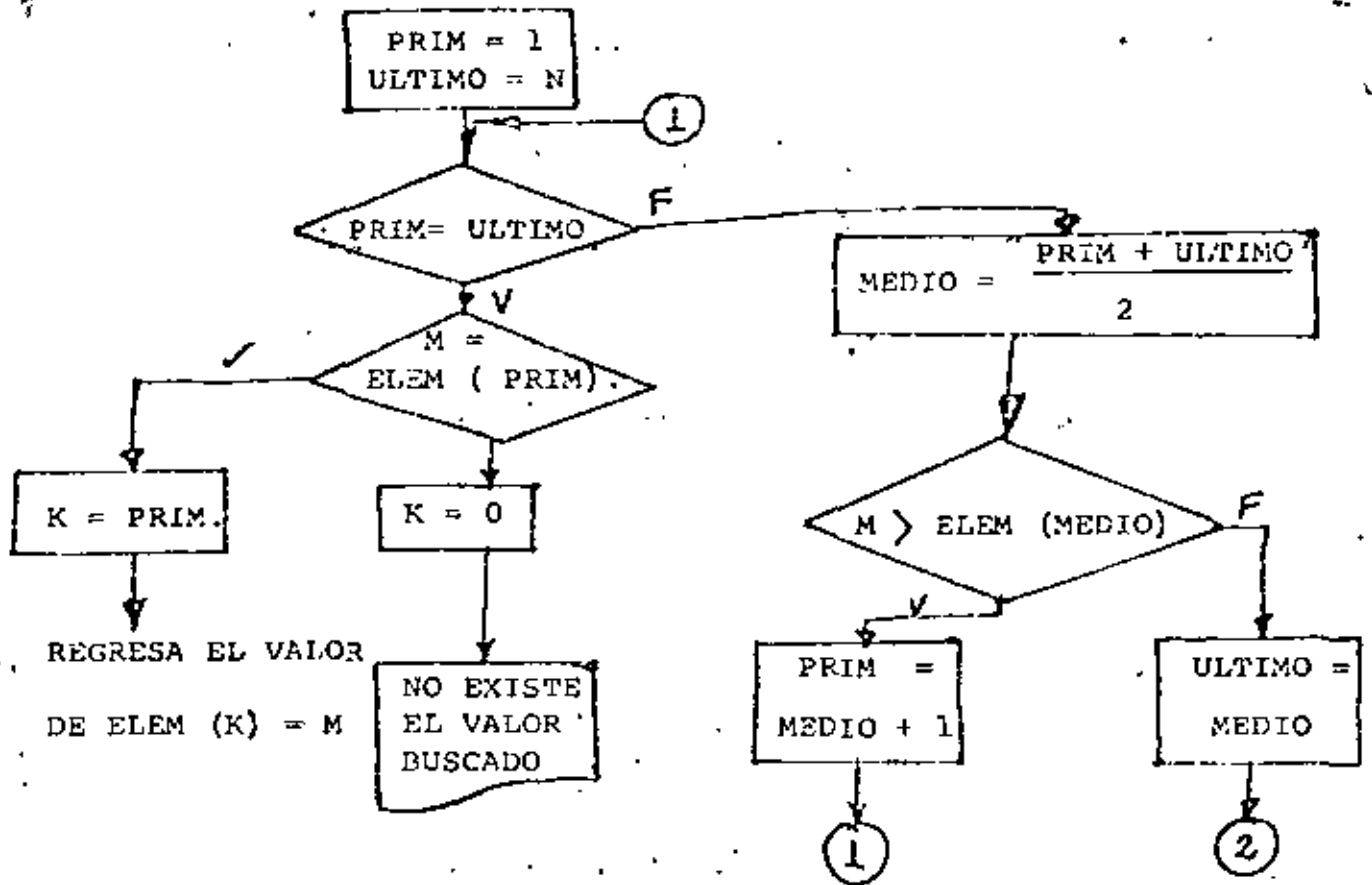
SUPONGA QUE MES CONTIENE ENTEROS ENTRE 1 Y 12 REPRESENTANDO  
CADA MES DEL AÑO, N DIAS CONTIENE EL NUMERO DE DIAS EN EL MES.  
SI SE TIENE UN VECTOR LMES DE LONGITUD 12, SE PUEDE INICIALI-  
ZAR CON EL VERBO

DATA LMES / 31, 28, 31, 30, 31, 30, 31, 31, 30, 31, 30, 31 /

Y EL NUMERO DE DIAS PUEDE SER COLOCADO EN N DIAS

N DIAS = LMES ( MES )

LO CUAL ES MUCHO MAS EFICIENTE QUE IR A TRAVES DE 12 "IFS", O  
UN GO TO COMPUTADO CON 12 RAMAS.



BUSQUEDA BINARIA.

ELEM ( 1 ) = XXX

ELEM ( 2 ) = XXX

SI

ELEM ( K ) = M

M ESTA EN EL ARREGLO.

SUPONGAMOS QUE SE NECESITA UN LOOP EN EL CUAL EL INDICE TOMA VALORES DE 1.5, 2.0, 2.5 .... 4.0 Y LUEGO <sup>5</sup> 7.25, 6.5, 7.75 11.5 Y LUEGO 13.0, 14.5, 16.0 Y POR ULTIMO 20.

6600  
9.00

LO ANTERIOR REQUIERE 5 INCREMENTOS DE 0.5, SEIS DE 1.25 TRES DE 1.5 Y UN INCREMENTO DE 4.0. PARA HACER LO DESCRITO EN FORMA ELEGANTE GUARDEMOS EL INCREMENTO EN UN VECTOR Y EN OTRO EL NUMERO DE VECES QUE HAY QUE HACER EL INCREMENTO.

```

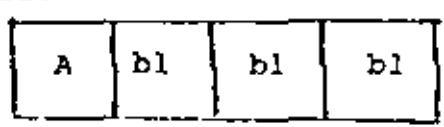
DIMENSION AINC (4), NINC (4)
DATA A INC / 0.5, 1.25, 1.5, 4.0/, NINC
C A / 5, 6, 3, 2/
A = 1.5
DO 1 I = 1, 4
J = NINC (I)
DO 2 K = 1, J
.
.
.
.
2 A = A + ZINC
1 CONTINUE.

```

CARACTERES

EN FORTRAN LOS CARACTERES PUEDEN SER ASIGNADOS A VARIABLES DE CUALQUIER TIPO, (EL NUMERO DE CARACTERES Y EL # DE BITS EN UNA PALABRA VARIAN DE MAQUINA A MAQUINA ) IBM 1130 ES DE 4.

SI UNA PALABRA PUEDE TENER 4 CARACTERES Y SE GUARDA EL CARACTER A ESTO LUCE ASI:



EN FORTRAN SE PUEDE ASIGNAR CARACTERES A VARIABLES DE 3 FORMAS:

- 1.- LOS CARACTERES PUEDEN SER LEIDOS CON FORMATO A d
- 2.- UTILIZANDO EL VERBO DATA CON UNA CONSTANTE HOLLERITH.

```
DATA I / 2 H A B /
```

```
DATA I A ST / 1 H * /
```

- 3.- LOS CARACTERES PUEDEN SER COPIADOS HACIENDO UNA ASIGNACION.

```
DATA PUNTO / I H. /
```

```
DATA BLENCO / 1 H
```

```
L K = PUNTO
```

#### BUSQUEDA LINEAL

( SE VERA MAS TARDE CON DETALLE )

MUCHAS VECES SE DESEA IDENTIFICAR UN VALOR O ELEMENTO DE UNA LISTA.

LA FORMA MAS FACIL ES UTILIZAR UNA BUSQUEDA LINEAL, SE GUARDAN LOS VALORES POSIBLES EN UN VECTOR, SE COMPARA CADA ELEMENTO DEL VECTOR CON EL "IDENTIFICADOR" HASTA QUE SE ENCUENTRE.

EJ. SUPONGA QUE EL VECTOR NUM ES DE LONGITUD 10 Y CONTIENE DIGITOS DECIMAL EN FORMA DE CARACTERES. LO ANTERIOR SE PUEDE HACER CON EL VERBO :

```
DATA NUM / 1 H0, 1 H1, 1 H2, 1 H3, 1 H4, 1 H5, 1 H6,
```

```
c 1 H7, 1 H8, 1 H9/
```

AHORA SUPONEMOS QUE UN CARACTER FUE LEIDO DE UNA TARJETA CON FORMATO A1 Y FUE COLOCADO EN

9

LA VARIABLE KAR, LAS SIGUIENTES INSTRUCCIONES DEBERAN DESCUBRIR QUE DIGITO NUMERICO ESTA EN KAR.

```

DO 15 I = 1, 10
  IF ( KAR. EQ. NUM (I) ) GO TO 24. .
15 CONTINUE
18 .
.
.
.
```

SI EL CONTROL PASA A 24, I CONTIENE EL INDICE DEL DIGITO NUMERICO IGUAL A KAR, SI EL CONTROL PASA A 18 KAR NO CONTIENE UN DIGITO NUMERICO.

## 2.- NUMEROS Y CARACTERES.

VAMOS A VER COMO CAMBIAR UNA CADENA DE CARACTERES A UN NUMERO Y VICEVERSA. ESTAS TECNICAS SON NECESARIAS CUANDO SE LEEN NUMEROS EN FORMATO LIBRE, CUANDO SE MANIPULAN FORMATOS EN LA EJECUCION DE PROGRAMAS O CUANDO SE REQUIEREN -- IMPRIMIR DATOS EN FORMA ESPECIAL PARA LO CUAL FORTRAN NO FUE DISEÑADO.

### 2.1 CONVERSION DE CARACTERES A ENTEROS.

SI UNA CADENA DE CARACTERES REPRESENTA A UN NUMERO ENTERO, SE PUEDE CONVERTIR A UNA FORMA NUMERICA UTILIZANDO ALGUNA TECNICA YA VISTA. SI EL NUM. TIENE SIGNO, SE DEBE HACER UNA PRUEBA PARA EL SIGNO, CADA DIGITO ES IDENTIFICADO, UTILIZANDO UNA BUSQUEDA LINEAL ( LOS 10 DIGITOS) Y EL RESULTADO PUEDE SER EMPACADO EN UNA VARIABLE ENTERA.

UN NUMERO EN FORMATO LIBRE ES LEIDO, UN ESPACIO DEBE DARSE PARA LEER LOS CARACTERES Y LOS DIGITOS DECIMALES EN LA TAJETA, LOS 2 CARACTERES CON SIGNO

## 10

Y EL BLANCO DEBEN PROVEERSE. LO ANTERIOR SE HACE CON LOS SIGUIENTES VERBOS:

DIMENSION NUM. (10), KARD ( 80 )

DATA NUM / 1 H0, 1 H1, 1 H2, 1 H3, 1 H4, 1 H5, 1 H6,

c 1 H7, 1 H8, 1 H9 /

DATA I MAS, I MENO, I BL / 1 H +, 1 H-, 1 H BL /

AHORA LOS CARACTERES SE LEEN EN KARD.

READ ( 5, 2 ) KARD

2 FORMAT ( 80 A1 )

TODOS LOS CARACTERES BLANCOS. DEL INICIO DE LA TARJETA SON IGNORADOS

DO 10 I = 1, 80

IF ( KARD (I). NE. IBL ) GO TO 2 0

10 CONTINUE

SI TERMINA EL LOOP DEL DO QUIERE DECIR QUE LA TARJETA ESTA EN BLANCO, SI EL CONTROL SE VA A 2 0 KARD (I) CONTIENE EL PRIMER CARACTER ( NO BL ) UNA PRUEBA SE DEBE HACER PARA EL SIGNO, PARA LO CUAL SE GUARDA RECORD EN ISGN, SI HAY UN SIGNO, ENTONCES I SE INCREMENTA EN UNO, ANTES DE QUE EL DIGITO PUEDA SER IDENTIFICADO.

```

20  |      ISGN = 1
    |      IF ( KARD (I). EQ. I MAS ) GO TO 30
    |      IF ( KARD (I). EQ. I MEND ) GO TO 40
    |      I SGN = - 1
30  |      I = I + 1
    |      IF ( I. GT. 80 ) GO TO 999

```

EL CONTROL PASA A 999 SI LA TARJETA TENIA UN SIGNO EN LA COLUMNA 80 AHORA EL VALOR NUMERICO (APARTE DEL SIGNO) PUEDE CONSTRUIRSE EN INT



11

```

40      INT = 0
      DO 60 J = 1, 80
      KAR = KARD ( J )
      DO 50 K = 1, 10
      IF ( KAR. NE. NUM ( K ) ) GO TO 50
c      EL CARACTER ES IGUAL AL DIGITO NUMERICO.
      INT = INT * 10 + K - 1
      GO TO 60
) 50   CONTINUE
55   GO TO 20
60   CONTINUE
c      SI SE ENCONTRO UN MENOS CAMBIAR EL SIGNO
70   IF ( ISGN. LT. 0 ) INT = - INT.

```

EL CONTROL PASA A LA ETIQUETA 70, SI EL NUMERO EN LA TARJETA ESTA EN LA COL 80, ( POR LA ETIQUETA 55. ) O SI UN CARACTER NO NUMERICO FUE DETECTADO.

## 2.2.- CONVERSION DE UN ENTERO A UN CARACTER

SE VIERON LAS TECNICAS PARA CONVERTIR UN NUMERO ASIGNADO A UNA VARIABLE ENTERA A UNA CADENA DE CARACTERES. LOS DIGITOS DECIMALES SON DESEMPACADOS DEL ENTERO Y LOS CARACTERES APROPIADOS SON SELECCIONADOS UTILIZANDO UNA TABLA DE TRADUCCION, DE UN VECTOR QUE CONTIENE LOS DIGITOS DECIMALES EN FORMA DE CARACTERES..

EL SIGNO ES VERIFICADO DE ANTEMANO. ( VALOR POSITIVO )

LOS NUMEROS MUY GRANDES SON DIFICILES DE LEER, PARA HACER ESTA LECTURA FACIL, UTILIZAMOS COMAS EJ 1, 3 14, 5 6 2, 1 3 4. LA SIGUIENTE SUBROUTINA CONVIERTE UN NUMERO ENTERO ASIGNADO A IDATUM A UN CONJUNTO DE CARACTERES INCLUYENDO COMAS, EL CUAL ES ASIGNADO A IARRAY, VECTOR DE LONGITUD N. ESTA CADENA DE CARACTERES DEBE DE EMPEZAR EN LA POSICION INIT DEL VECTOR Y SU LONGITUD

12

Y DEBE DE SER LARGO EL # DE CARACTERES.

```
SUBROUTINE COMAS ( IARRAY, N, INIT, LARGO, IDATUM)
```

```
  DIMENSION IARRAY (N), NUM (10)
```

```
  DATA NUM / 1H0, 1H1, 1H2, ..... 1 H9/
```

```
  DATA MENOS, KOMA, IBL, 1AST/ 1H-, 1H., / H, 1 H*/
```

LA POSICION DEL FIN DEL CARACTER DEL VECTOR ES AHORA CALCULADA,

LA APROPIADA SECCION DEL VECTOR ES PUESTA CON BLANCO

```

1  IFIN = INIT + LARGO - 1
   DO 1 I = INIT, IFIN
   IARRAY (I) = IBL
```

c SE GUARDA EL VALOR ABSOLUTO DE DATO CON GUARA.

```
  GUARA = IABS ( I DATO)
```

UN BLOQUE DE 3 DIGITOS ES DESEMPACADO, Y LOS CARACTERES SON GUARDADOS

EN IARRAY. IFIN SE UTILIZA PARA GUARDAR UN RECORD DEL SIG. LUGAR -

DISPONIBLE EN IARRAY, (TRABAJANDO DE DER. A IZQ. SI YA NO HAY DIGI-

TOS A DESEMPACAR IDATUM PASA EL CONTROL A 40, SI NO HAY ESPACIO SU-

FICIENTE EL CONTROL SE VA A 20.

```

5  NO 10 I = 1, 3
   J = MOD (KEEP, 10) + 1
   IARRAY (IFIN) = NUM (J)
   KEEP = KEE0/ 10
   IF (KEEP. EQ. 10 ) GO TO 40
   IFIN = IFIN - 1
   IF (IFIN. LT. INIT) GO TO 40
10 CONTINUE.
```

SI EL LOOP TERMINA NORMALMENTE, 3 DIGITOS SON GUARDADOS EN IARRAY

Y YA NO HAY QUE DESEMPACAR. AHORA HAY QUE AGREGAR UNA KOMA EL CON

TROL REGRESA A 5 PARA COLOCAR MAS (3) DIGITOS

13

```

IARRAY ( IFIN ) = KOMA
IFIN = IFIN - 1
IF ( IFIN. GE. INIT ) GO TO 5

```

SI LA COMA SE COLOCO EN LA ULTIMA POSICION EL CONTROL PASA A LA SIGUIENTE PROPOSICION ( 20 ), SI HAY ERROR IARRAY DEBE CONTENER ASTERISCOS Y REGRESAR EL CONTROL.

```

20 | IFIN = INIT + LENGTH - 1
    | DO 30 I = INIT, IFIN
30 | IARRAY ( I ) = IAST
    | RETURN.

```

EL CONTROL PASA A 40 CUANDO TODOS LOS DIGITOS DECIMALES HAN SIDO DESEMPACADOS, SI EL SIGNO ES POSITIVO EL CONTROL SE REGRESA AL PROGRAMA QUE LLAMO SI ES NEGATIVO, SE DEBE AGREGAR EL SIGNO, SI ES QUE HAY LUGAR.

```

40 | IF ( IDATUM. GE. 0 ) RETURN
    | IF ( IFIN. LE. INIT ) GO TO 20
    | IARRAY ( IFN - 1 ) = MENOS
    | END.

```

### 3.- GRAFICAS.

MUCHAS VECES SE REQUIERE IMPRIMIR GRAFICAS, Y NO SE TIENE UN CRT O UN PLOTTER, A CONTINUACION VAMOS A VER ALGUNAS TECNICAS PARA GRAFICAR, UTILIZANDO UNA IMPRESORA COMUN.

DE ANTEMANO HAY QUE SABER LAS CARACTERISTICAS DE LA IMPRESORA, NUMERO DE COLUMNAS ( 120 o 132 CARACTERES) Y EL NUMERO DE LINEAS ( 66 USUALMENTE). SIN EMBARGO EL TAMAÑO DE GRAFICA PUEDE SER DE CUALQUIER TAMAÑO.

LA TECNICA ESENCIAL A LA GRAFICACION EN UNA IMPRESORA ES LA DE TRANSFORMAR LOS VALORES ( UNIDADES )

## 14

- 1.- MULTIPLIQUE O DIVIDA, EL VALOR POR CUALQUIER CANTIDAD PARA TENER LA ESCALA (DISPERSION) DESEADA.
  - 2.- SUME ( O RESTE) UNA CANTIDAD AL RESULTADO PARA TENER LOS VALORES EN EL RANGO DESEADO.
  - 3.- CONVERTIR LOS RESULTADOS ANTERIORES A UN ENTERO
- HISTOGRAMAS -

LOS HISTOGRAMAS SE PUEDEN CONSTRUIR CON LAS BARRAS HORIZONTALES O VERTICALES.

SUPONGAMOS QUE TENEMOS UN VECTOR MARCA ( 10 ) QUE CONTIENE ENTEROS POSITIVOS Y SE QUIEREN GRAFICAR COMO HISTOGRAMA.

```

DATA IAST / 1 H * /
DO 5 I = 1, 10
N = MARCA ( I )
5 WRITE ( 6, 4 ) ( IAST, J = 1, N )
4 FORMAT ( IX, 50 A 1 )

```

```

***
*****
*****
*****
*****
*****
*****
*****
*****
*****
*****

```

SE OBTENDRA UN RESULTADO ASI

NOTESE QUE  $1 \leq \text{MARCA} \leq 50$   
DE CLASE

SI SE TIENEN RESULTADOS DEMASIADO GRANDES, ESTOS SE PUEDEN ESCALAR DE LA SIGUIENTE FORMA:

- 1.- ESCALAR DEPENDIENDO DEL VALOR MAS GRANDE.
- 2.- SI LA LINEA A IMPRIMIR RESULTO DEMASIADO LARGA, ESCRIBIR UN CARACTER ESPECIAL QUE LO DENOTE.
- 3.- IMPRIMIR ASTERISCOS SI LA IMPRESION NO CABE EN LA HOJA, PARA IDENTIFICACION.

## 15

ES POSIBLE CONSTRUIR HISTOGRAMAS VERTICALES UTILIZANDO UN BUFFER (AMORTIGUADOR) Y LAS BARRAS CUELGAN (COMO ESTALACTITAS) O CRECEN. EL BUFFER ORIGINALMENTE DEBE DE CONTENER BLANCOS, SE UTILIZA UN LOOP CON CUENTA NEGATIVA. CADA CICLO EN ESTE LOOP SE PRUEBAN LOS DATOS, SI UN DATO NO ES MENOR QUE EL INDICE DEL LOOP, EL LUGAR CORRESPONDIENTE EN LA LINEA DEL BUFFER ES ASIGNADO UN ASTERISCO. UNA VEZ QUE FUERON PROBADOS TODOS LOS DATOS, SE PROCEDE A LA IMPRESION.

```

DIMENSION MARCA (10), LINE (10)
.
.
.
DATA LINE (10 * 1 H /, IAST / I H * /
DO 5 I = 1, 25
J = 26 - I
DO 4 K = 1, 10
IF (MARCA (K) .GE. J) LINE (K) = IAST
6 CONTINUE
8 FORMAT ( IX, 10 ( LX, A1) )
5 WRITE (6, 8) LINE

```

SI SE IMPRIMIO UN ASTERISCO, TAMBIEN SE DEBERA DE IMPRIMIR UN ASTERISCO DEBAJO DEL YA IMPRESO, SI SE QUIERE ENSANCHAR LAS BARRAS SE HACE LO SIGUIENTE: (CAMBIAR MODIFICACION ANT).

```

5 | WRITE (6, 8) ( (LINE (K), L = 1, 3), K = 1, 10 )
8 | FORMAT ( IX, 10 ( 2 x, 3A1) )
LO CUAL PRODUCE BARRAS CON 3 ASTERISCOS

```

SI SE QUIERE INCLUIR EJES (Y) EL FORMAT SE DEBERA ESCRIBIR ASI

```

8 | FORMAT ( 4X, 1 HI, 10 ( 2 x, 3A1)

```

AHORA SI CADA 5 LINEAS SE QUIERE ESCRIBIR UN SIMBOLO LA LINEA SE PUEDE DIFERENCIAR DE LA SIG. FORMA:

LA QUINTA LINEA SE IDENTIFICA CON MOD (J, 5) = 0

```

16
9 | WRITE (6, 9) I, ( ( LINE (K), L = 1, 3), K= 1, 10)
  | FORMAT ( 1X, 12, 2 H +, 10 (2X, 3 A1) )

```

NOTESE QUE EL SIGNO + SE ESCRIBE CADA 5 RENGLONES, EL EJE X SE PUEDE ESCRIBIR CON MENOS (SIGNO)

```

11 | WRITE (6, 11) (I, I = 2, 10, 2)
   | FORMAT (4X, 1H +, 10 (JH --- + -, ), 2H ---/ 4X,
   |       5 I 10).

```

EL PROGRAMA ANTERIOR PRODUCE UNA FIGURA COMO LA SIGUIENTE:

```

          ***
        *** ***
       *** ***
      *** ***
     *** ***
    *** ***
   *** ***
  *** ***
 *** ***
*** ***
*** ***
*** ***

```

VEAMOS A CONTINUACION OTRO TIPO DE GRAFICAS.

CONSIDEREMOS UNA GRAFICA PARA DIBUJAR  $\text{SEN}(X)$ ,  $\text{COS}(X)$ ,  $\text{SEN}(X) + \text{COS}(X)$  Y  $\text{SEN}(X) - \text{COS}(X)$ . QUEREMOS GRAFICAR UNOS 120 PUNTOS PARA LO QUE UTILIZAMOS UN AMORTIGUADOR (BUFFER) DE LONGITUD DE 100 ELEMENTOS. LOS VALORES DE  $\text{SEN}(X)$  Y  $\text{COS}(X)$  OSCILARAN ENTRE - 1.0 Y + 1.0 Y LOS VALORES DE  $\text{SEN}(X) \text{COS}(X)$  NO PASARAN LOS VALORES DE  $\pm 2.0$ , POR LO QUE VAMOS A ESCALAR LOS VALORES DE  $\text{SEN}(X)$  Y  $\text{COS}(X)$  MULTIPLICANDOLOS POR 25 Y SUMANDOLE 50.

PARA PODER TENER "BONITA" UNA GRAFICA SE HACE NECESARIO CORRER EL PROGRAMA VARIAS VECES.

**17**

SE VAN A TRAZAR 4 GRAFICAS "1", "2", "3", y "4"

DIMENSION LINE (100), KAR (4), VAL (4)

DATA IBL/ 1H/, KAR/ 1H1, 1H2, 1H3, 1H4/, LINE/ 100\* 1H/

C EMPEZAR EN HOJA NUEVA

```

11  WRITE (6, 11)
    FORMAT (1 H1)
    DO 10 I = 1, 120
    X = FLOAT (I-1) * 0.09
    VAL (1) = SIN (X)
    VAL (2) = COS (X)
    VAL (3) = VAL (1) + VAL (2)
    VAL (4) = VAL (1) - VAL (2)
    DO 5 J = 1, 4
    IND = VAL (J) * 25.0 + 50.

```

5 LINE (IND) = KAR (J)

WRITE (6, 7) LINE

FORMAT (5, X, 100 A1)

DO 10 J = 1, 100

10 LINE (J) = IBL

{ SE HACEN BLANCOS }

C DEJA UNA HOJA AL FIN

WRITE (6, 11)

STOP

END

NOTESE QUE LOS VALORES SE GUARDAN EN UN VECTOR VAL, CON EL FIN DE SER UTILIZADOS POR EL LOOP DEL DO

## " BUSQUEDA BINARIA "

COMO EJEMPLO UTILIZAMOS UNA BUSQUEDA BINARIA PARA OBTENER EL NUMERO DE ELEMENTOS DE CADA INTERVALO DE CLASE PARA CONSTRUIR UN HISTOGRAMA.

LA LONGITUD DE TABLA DEBE DE SER  $2^n - 1$ , POR EJEMPLO SI TENEMOS 32 INTERVALOS, HABRA 31 PUNTOS DE SEPARACION.

```

1 | DIMENSION INTER ( 31)
  | IND X = 0
  | INC = 16
  | IT = INDX + INC
  | IF= (VAL. GT. INTER (IT) )  INDX = 1
  | INC = INC/ 2
  | IF ( INC. GT. 0 ) GO TO 1

```

LOS VALORES DEBEN DE SER ASIGNADOS A INTER QUE MARCA LOS LIMITES DE LOS INTERVALOS, Y ESTOS VALORES DEBEN DE SER ASCENDENTES.

EL VALOR CENTRAL DEL INTERVALO ESTARA EN INTER (16) EL NUEVO

VALOR SERA ASIGNADO A VAL. INC TOMA VALORES 16, 8, 4, 2, 1, Y 0

SI VAL ES MAYOR QUE TODOS LOS VALORES EN INTER, ENTONCES INDX TO-

MA SUCESIVAMENTE LOS VALORES 0, 16, 24, 28, 30, Y 31, PERO SI

VAL < INTER (1), INDX = 0.

EL VALOR FINAL DE INDEX ESTARA ENTRE 0 Y 31, DADO EL LUGAR DEL -

INTERVALO EN EL CUAL CAE VAL



## 6-1 Tree examples

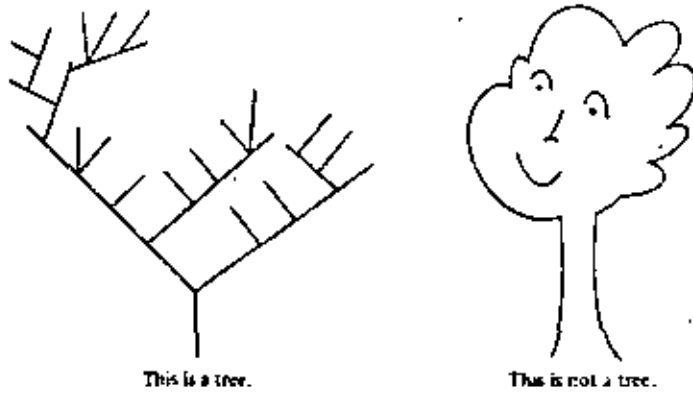
The use of flowcharts to represent algorithms has helped us to recognize their underlying *structure*. Furthermore, attention paid to the structure of an algorithm usually results in a better understanding of the computational process, and often results in our recognizing alternatives and potential improvements to the original design. Similar rewards result from attention paid to the structural relationships among the components of a set of data.

There is, in fact, a close connection between the steps we need to express an algorithm and the way we choose to think about or *represent* the data that are to be transformed by that algorithm. Experience in constructing algorithms fosters an increased appreciation of this interdependence. You will gain some of this experience by studying the next several chapters. Your ability to analyze the structure of a set of data and how alternate representations of it can affect algorithms using such data, undoubtedly will improve. We have already considered two structural forms for data, lists and arrays. Another type of structure is called a *tree* (Figure 6-1). Tree structures are important in representing certain types of data and, oddly enough, the essential steps of a number of algorithms exhibit a treelike structure.

First we will give two simple examples of a process whose strategy of execution (algorithm) can be pictured as a tree and two examples of data that can be pictured as a tree. Later, we will tackle three fascinating problems, the first one at the end of this chapter and the other two in Chapter 7. When we have finished this study, we may claim the title *tree expert*.

Let us agree now, before we get too far along, that trees in this chapter will be drawn upside down (Figure 6-2). We

FIGURE 6-1



do this only because it is convenient. You have to be willing to think of a tree growing toward the earth, its trunk "hanging" from the sky.

Example 1.  
Treelike Algorithms

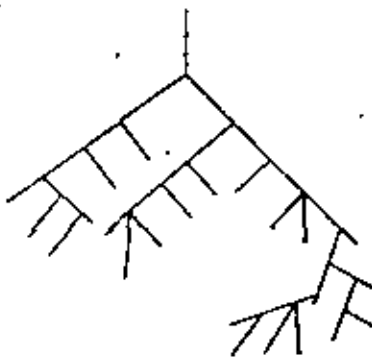


FIGURE 6-2  
This is an upside-down tree.

Our first example shows how we can represent the 16 conclusions to the well-known eight-coin problem as a "decision tree." The problem is this. You are given eight coins, a, b, c, d, e, f, g, and h, and are told that they are all of uniform weight except one, which is either heavier or lighter than the others. You are given an equal arm balance, but you may only use it three times for comparing coins or groups of coins. Your job is to determine the maverick coin and whether it is lighter or heavier than the rest.

Here is a strategy to use (see Figure 6-3) for all possible cases.

1. Compare the weights of two subsets of equal numbers of coins and consider the significance of the *three* possible outcomes. If the weights of the two subsets are equal, the coin in which we are interested cannot belong to either of the compared subsets.
2. Once we have isolated a pair containing the "odd" coin and we want to know whether one of them is heavy or light, we weigh one of the two candidates against any other that is known to be "standard."

There are 16 possible cases, each of which may occur, given the eight labeled coins. The algorithm shown in Figure 6-3 has a treelike structure. Conclusions are reached by follow-

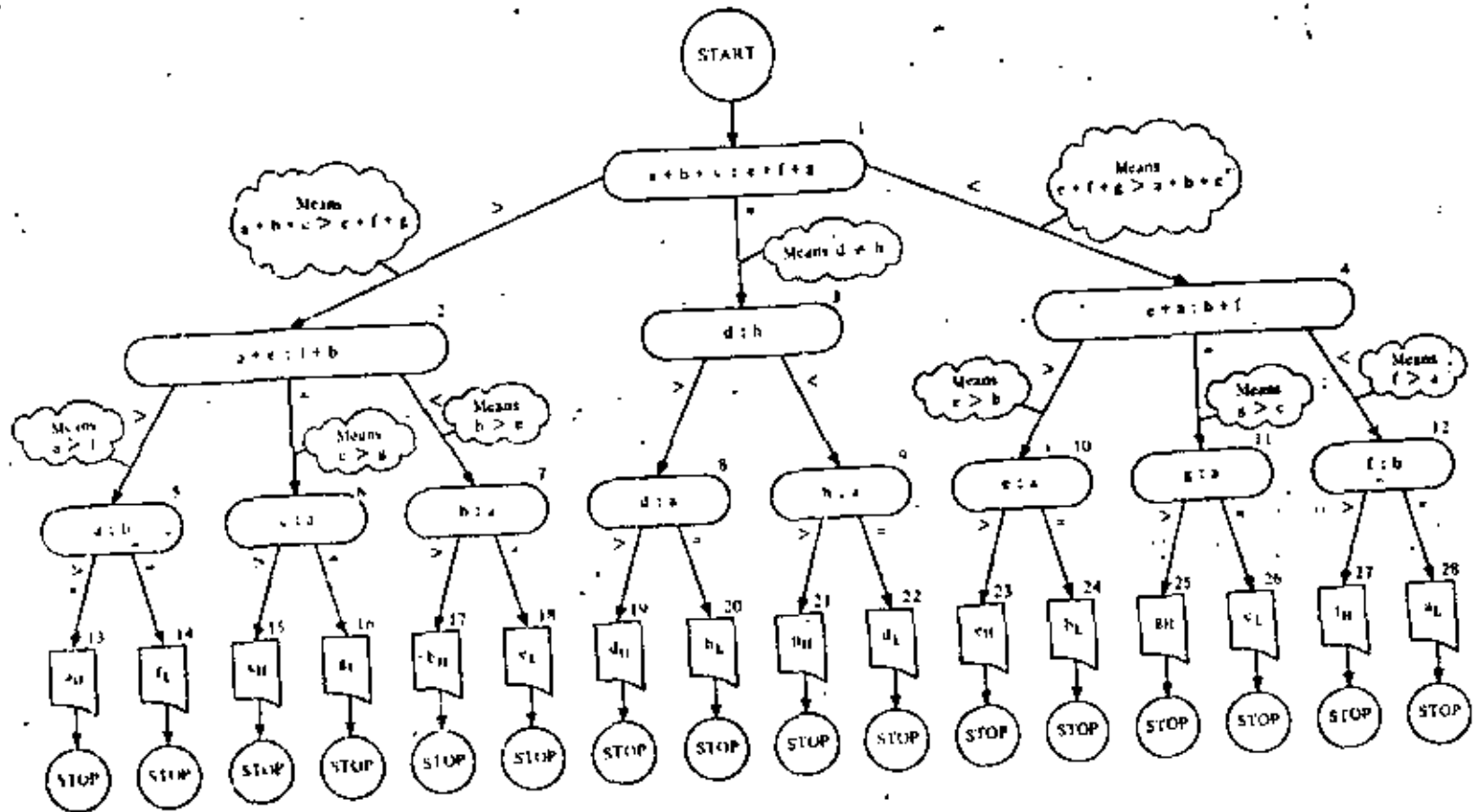
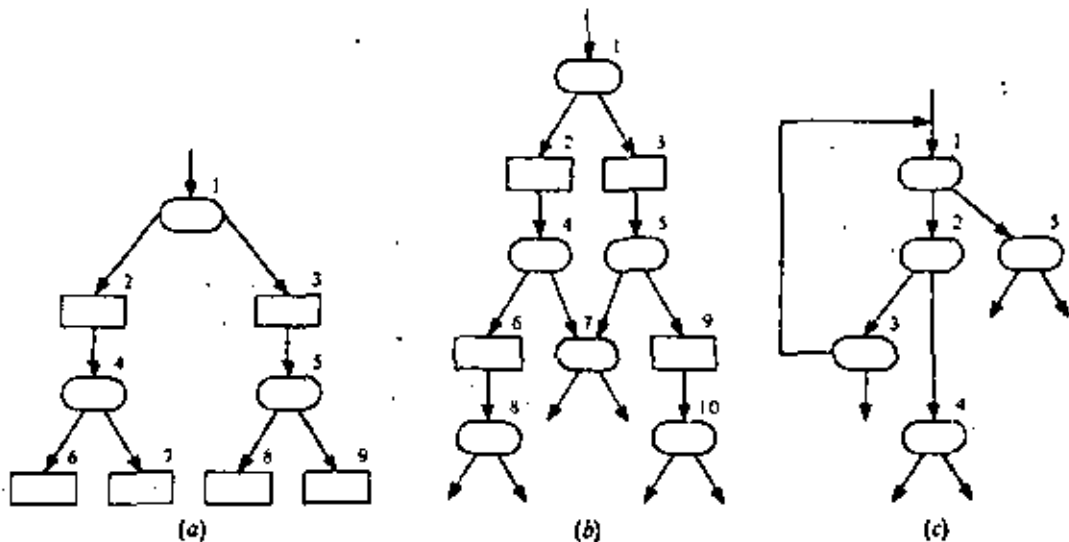


FIGURE 6-3  
 Tree diagram of a strategy to  
 identify the odd coin.  
 Conclusions are subscripted:  
 subscript H means heavy;  
 subscript L means light.

ing a unique path (a sequence of three weighings) from the top or *root* of the tree diagram to one of the terminal boxes or *leaves* at the bottom.

EXERCISES 6-1,  
SET A

1. For decision box 2 in Figure 6-3, explain why:
  - (a) If the relation  $a + e > f + b$  is true, one may conclude that  $a > f$ .
  - (b) If the relation  $a + e = f + b$  is true, one may conclude that  $c > g$ .
  - (c) If the relation  $a + e < f + b$  is true, one may conclude that  $b > e$ .
2. Explain why  $b$  may be regarded as a "standard" coin at decision box 5 but not at decision box 7.
3. Suppose you are given 12 seemingly identical balls and are told that one ball is *heavier* than the others, which are of the same weight. Draw the tree diagram algorithm to identify the heavy ball in three weighings.
4. Suppose you are given 12 seemingly identical balls and are told that one ball is *different* in weight (either heavier or lighter). Draw a tree diagram algorithm to identify the odd ball and to determine whether it is heavier or lighter in three weighings.
5. Are all decision sequences tree structures? Consider the three flowcharts below.



- (a) Which of these are tree structures?
- (b) Consider the following attempt to define a tree structure.

- (1) A node having no segments extending from it is a *terminal node*.
- (2) A node having one or more segments extending from it is a *nonterminal node*.
- (3) A tree structure is a *terminal node* or a *nonterminal node* whose segments consist either of terminal nodes or tree structures.

What corrections or additions, if any, are needed in the above definition so that, when applied to flowcharts *a*, *b*, and *c*, you will reach the same conclusions that you came to in the answer to part *a* of this problem?

### Example 2. Game Trees

A more interesting type of decision tree, frequently referred to as a *game tree*, shows the moves made by the players. Each time a player makes a move, he selects among the available choices of "legal" moves. Each line segment of the tree represents one choice by one player during the playing of one game. Figure 6-4 is a tree for the game of "Eight." This two-player game is so trivial you may not enjoy playing it very long. Its tree is simple enough, however, that we can study it easily, and it serves as a good illustration of similar but far more complicated games.

### The rules of "Eight"

Each player takes a turn at picking a number from one to three, adding this number to a running sum that is initially set at zero. The first player has a free choice of numbers 1, 2, and 3. The choice in each play thereafter is restricted. A player may not choose the opponent's preceding selection. The player who brings the running sum to a total of exactly eight wins the game; a player exceeding eight loses. There is no draw possible.

When we study the game tree, we can observe that a complete game from start to finish is represented by one path (e.g., the colored line) from the beginning or *root* of the tree down to an end or terminal point. Player A always moves first. Thus, on the green line, A chooses 1 from among the three initial choices. Then B chooses 3, then A chooses 1, and so forth, until at the last move for A the running sum is 7, and his choices are 1 and 3. So he chooses 1 to make the sum 8 and wins. Triangular-shaped endpoints denote a win for A. Square-shaped endpoints denote a win for B.

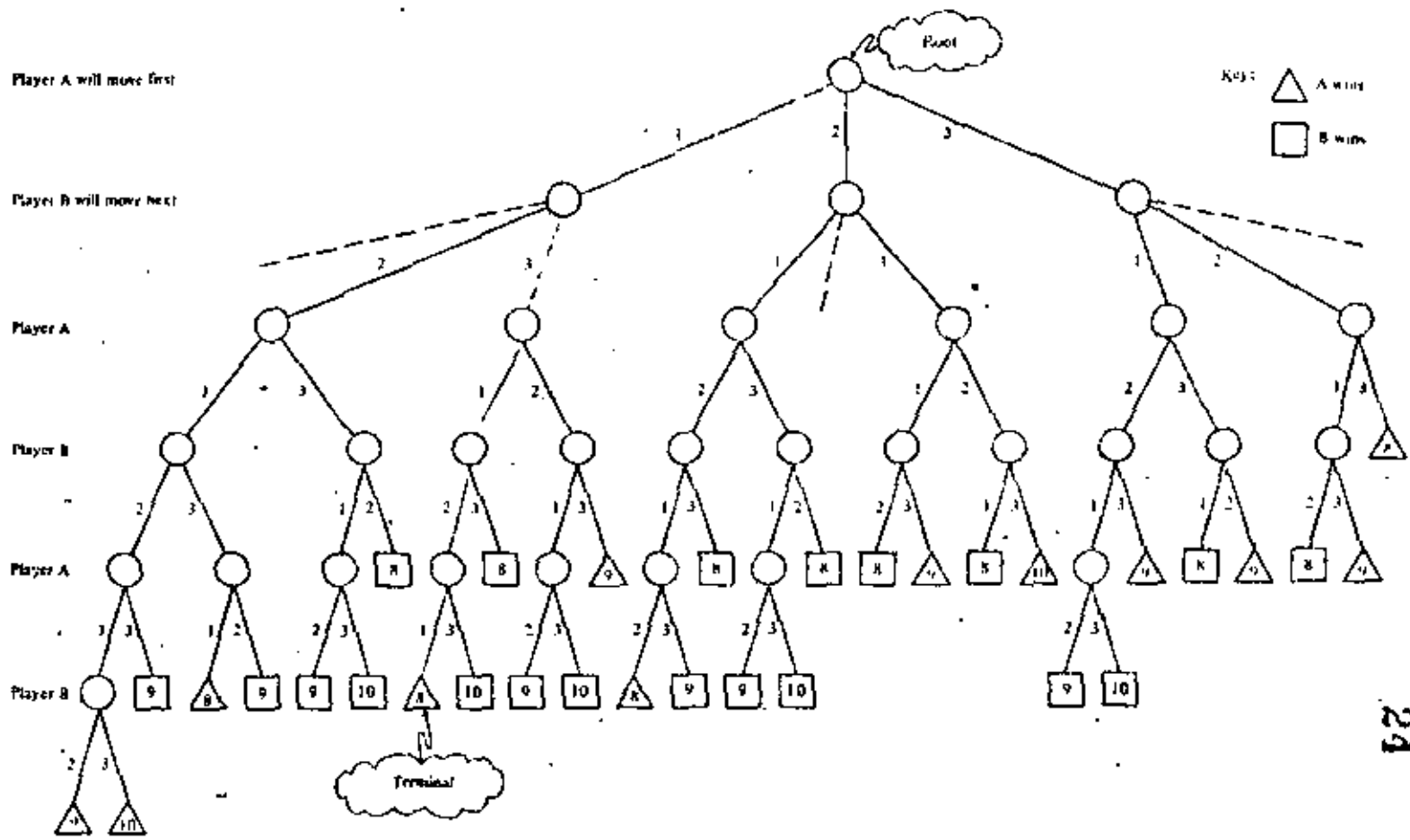


FIGURE 6-4  
 Tree for the game of Eight.

Each time a player makes a move, you can imagine he looks at three choices 1, 2, and 3. After the very first choice he rules out one of these, as the game rules demand. *Inadmissible* moves would not ordinarily appear in the tree because they tend to clutter the diagram. We have shown them as dashed lines for B's first move only as a reminder.

EXERCISES 6-1,  
SET B

1. (a) How many distinct games of "Eight" are there?

Imagine the game of Eight is played by children at the local kindergarten in the following way. Player A twirls the arrow of a

three-part spinner, to select the initial move.



There-

after, each player flips a coin to decide among the two admissible choices. (heads the smaller, tails the larger.)

- (b) What percentage of games played will follow the color line path in Figure 6-4?
- (c) What are A's chances of winning? Express this result as the number of games won for every 100 games played.
- (d) If each player chooses each move as shrewdly as possible, what do you think are A's chances of winning if A plays first? The answer is 0 times out of 100. See if you can develop a proof of this assertion. In Chapter 7 we will take another look at this problem.

In each of the next two exercises, you are given the rules of a simple, two-player game. Your job in each case is to show part or all of the game tree with at least four complete games displayed.

2. The game of *Hex* (or *Hexapawn*) uses a 3 by 3 checkerboard. Each player begins the game with three pieces on his base line, as shown in Figure 6-5. Play alternates between green and gray. The rules of the game are as follows.

		Column		
		1	2	3
Row	1	● 1	● 2	● 3
	2			
	3	○ 7	○ 8	○ 9

FIGURE 6-5  
Board position at the  
beginning of the game of Hex.

- (a) Either green or gray, in his turn, can move forward one space to an unoccupied position.
- (b) Or he can move diagonally one space to capture an opponent. A captured piece is removed from the board.
- (c) The game is won by reaching the opponent's baseline.
- (d) Or by leaving the opponent without a move.
- (e) Or by capturing all opponent pieces.

*Hint* Each segment of the tree should be labeled to indicate the move it represents. One way would be to show the *before* and *after* row,

column values of the piece that is moved. For example, on green's first play he has three choices:  $(3,1) \rightarrow (2,1)$ , or  $(3,2) \rightarrow (2,2)$ , or  $(3,3) \rightarrow (2,3)$ . Each of these moves can be further abbreviated to four-digit numbers without loss of information, that is, 3121, 3222, and 3323, respectively.

Alternatively, if we give the squares of the board the explicit names shown as small digits in the lower right corner of each square in Figure 6-5, then we can use a somewhat more compact representation of a move. Instead of four-digit abbreviations (e.g., 3121, 3222, and 3323), we can use two-digit abbreviations (e.g., 74, 85, and 96, respectively) with no risk of confusion.

3. *The game of "31."* Take a die and roll it. The side that turns up gives the running sum's initial value. Thereafter, each player moves by tilting the die over on its side (one of four possible sides, of course, and remember that opposite faces



always add to seven). The side that turns up after the tilt-over is then added to the running sum. The game proceeds tilt after tilt. A player whose tilt brings the total to exactly 31 wins the game; a player exceeding 31 loses. There are no draws.

## Data Trees

Flowcharts of algorithms often have the characteristic treelike structure, but it is also interesting that *data* can be arranged in a treelike structure. Here are two examples.

### Example 3. Monotone Subsequences

Suppose you are given a sequence (i.e., a list) of  $N$  numbers, all guaranteed to be different. What is the longest *monotone subsequence* in the given sequence?

By a *subsequence* we mean the list that remains after "crossing out" some numbers in the original list. If, for example, the given list is

5 0 9 6 1 12 3 7 2,

then one of the 511 ( $2^9 - 1$ ) possible subsequences of this sequence is:

5 0 9 6 1 12 3 7 2

that is, 9 6 12 3 2.



27

The reason for explaining this idea in terms of "crossing out" is to make it absolutely clear that the order of the *remaining* terms is not altered. By a *monotone* subsequence we mean one in which either the values are increasing from left to right or one in which they are decreasing. Thus the preceding subsequence,

$$9\ 6\ 12\ 3\ 2$$

is not monotone, but the following two are, the first being increasing and the second decreasing.

$$5\ 0\ 9\ 6\ 1\ 12\ 3\ 7\ 2$$

$$5\ 9\ 6\ 1\ 12\ 3\ 7\ 2$$

You can check that the increasing subsequence is the longest possible; that is, there is no increasing subsequence with more than four elements. The decreasing one is not the longest possible, since the subsequence

$$9\ 6\ 3\ 2$$

is longer.

It is possible to develop an algorithm for determining longest monotone subsequences of a given sequence. Our interest here is a bit different. Suppose you are asked to picture *all* the possible monotone decreasing subsequences of our example sequence,

$$5\ 0\ 9\ 6\ 1\ 12\ 3\ 7\ 2$$

A hopeless task? Not if we think in terms of trees! See the answer in Figure 6-6.

A most revealing discovery! We have taken a string of numbers, posed a particular problem concerning that string, and discovered that the problem's answer could lie in inspecting a related tree. Notice that every monotone decreasing subsequence in  $S$  can be represented as a *path* running from the root  $S$  to one of the terminal squares. From now on, we'll call these circles and squares *nodes*.

The longest of such subsequences is easy for the eye to pick out once the tree is drawn. It is the one whose *terminal node* is found at a level of the tree farthest from the root node. In this example, only one path reaches to level 4, so there is only one longest monotone decreasing subsequence.

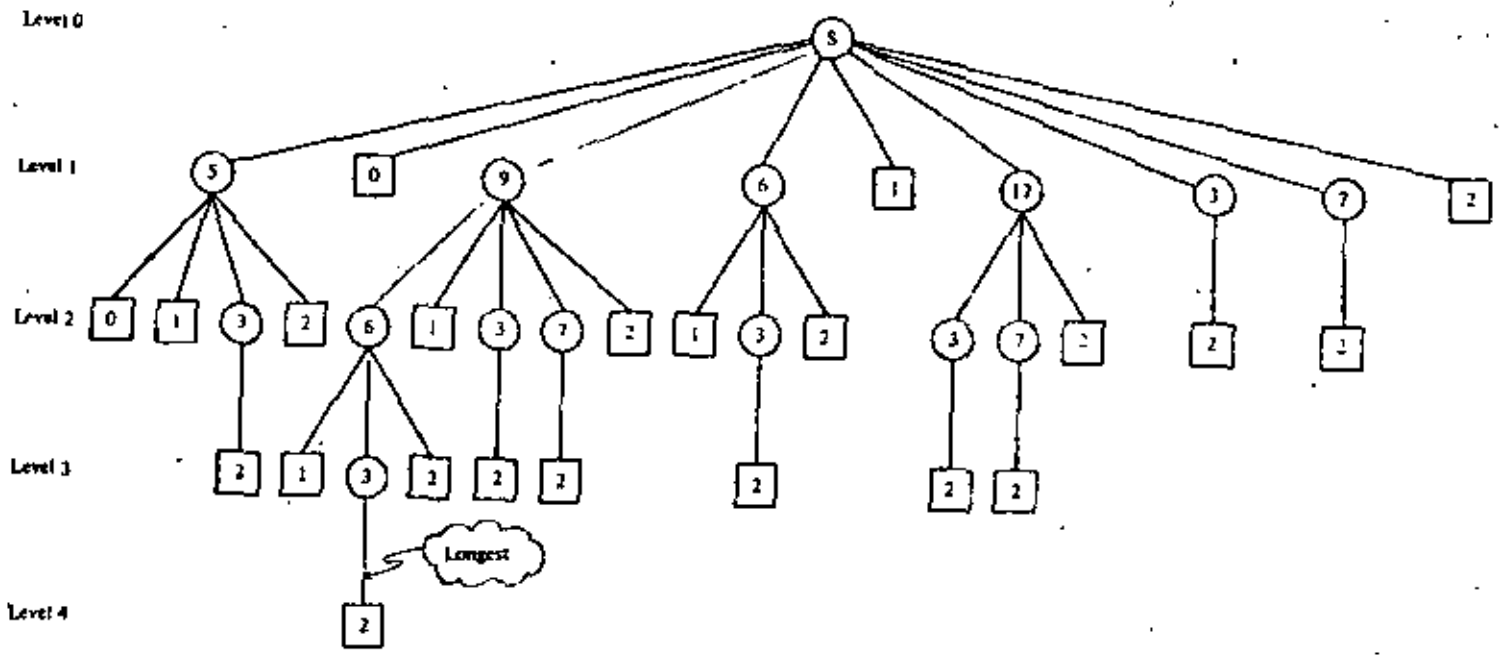


FIGURE 6.6  
 Tree of monotone decreasing  
 subsequences for the list  
 $S = 5, 0, 9, 6, 1, 12, 3, 7, 2$ .

If a computer is to be used for this approach, we must have an algorithm that, in effect, systematically scans the entire tree. This is the interesting part, which will be taken up starting with the next section.

EXERCISES 6-1,  
SET C

1. Construct a tree that displays all monotone *increasing* subsequences of the same sequence given in Figure 6-6.
2. Draw the tree that displays all monotone decreasing subsequences for the sequence  $S$  defined as

$$S = \{3, 2, 1, 0\}$$

3. Imagine you are a student registering at a university and you have decided to enroll in a particular group of five courses. The five courses, together with the available sections and the times each will be taught, are listed in Figure 6-7. We presume these data are extracted from the official class schedule. Notice that the time periods are letter coded for convenience.

Course	Open Sections	
ENG 132	D (9-10	MWF)
	E (10-11	MWF)
	F (11-12	MWF)
FRE 141	F (11-12	MWF)
	H (1-2	MWF)
	Q (10-11:30	TTH)
HIS 231	F (11-12	MWF)
	H (1-2	MWF)
MTH 172	D (9-10	MWF)
	F (11-12	MWF)
	Q (10-11:30	TTH)
CSC 131	F (11-12	MWF)
	H (1-2	MWF)

Timetable

Course	Letter Codes for Possible Sets				
	No. 1	No. 2	No. 3	No. 4	No. 5
ENG 132					
FRE 141					
HIS 231					
MTH 172					
CSC 131					

FIGURE 6-7  
Data taken from the printed  
class schedule.

Does a possible set of nonconflicting sections for the five courses exist? That is, is it possible to select a set with no time conflicts? If so, how many distinct feasible sets can be selected? To be distinct, a set need differ in no more than one section from other possible sets. Complete a column of the timetable shown in Figure 6-7 for each feasible set.

*Hint* This problem and others like it can be solved systematically by constructing a tree of labeled nodes. The structure for the tree could be such that the set of nodes along any path emanating from the root represents a set of nonconflicting course sections. For example, labeled nodes at level 1 could represent the various available sections of ENG 132 (Figure 6-8). Nodes at level 2 could correspond to various sections of FRE 141, and so forth. Any path running from the root to level 5 such that every node has a different label would represent a feasible set of courses.

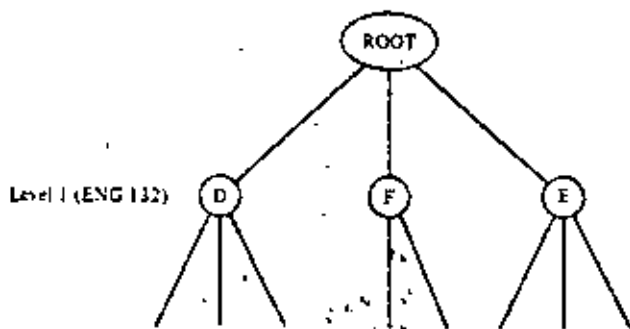


FIGURE 6-8

4. Imagine you are a student registering at a university and assume that you have decided to enroll in the following six courses:

Communications 267	(COM 267)
English 337	(ENG 337)
French 231	(FRE 231)
Geography 233	(GGY 233)
Mathematics 272	(MTH 272)
Music 120A	(MUS 120A)

Below are data taken from the printed class schedule. Imagine that when you reach the registration desk, you find that certain sections of four of the desired courses are closed (as indicated). Prepare a tree diagram that shows whether there are one or more possible programs open to you at this time, permitting you to enroll in all six of the desired courses with no time conflicts. If one (or more) program(s) is (are) available, prepare a filled-out timetable whose format is similar to that given in Figure 6-7.

5. A student who was planning to work every afternoon (1-5 p.m.) for the Athletics Department was also hoping to enroll in all of the following six courses: COM 267, MUS 120A, GGY 233, MTH 272,

COM 267 P601	TV-FILM SCENE AND LIGHT 117-KUHT	9:30-11AM TTH	COLLINS
MUS 120A E601 H602 P603 Q604	MUSICIANSHIP I 129-E 129-E 129-E 101-E	10-11AM WF 1-2PM WF 9-10AM TTH 10-11AM TTH	MILLER MILLER HORVIT BENJAMIN
GGY 233 F601 H602 S603 U604	WORLD REALMS 101-AH 101-AH 210-AH 101-AH	11-12 MWF 1-2PM MWF 1-2:30PM TTH 4-5:30PM TTH	HYER PALMER SHERIDAN COFFMAN
MTH 272 D602 E603 H604 P607 P608 S610	CALCULUS III 204-AH 216-AH 116-T 7-AH 111-Z 211A-SR	9-10AM MWF 10-11AM MWF 1-2PM MWF 8:30-10AM TTH 8:30-10AM TTH 1-2:30PM TTH	RADER RADER
FRE 231 E601 F602 H603 I604 Q605 S606	INTERMEDIATE FRENCH 303-AH 106-Z 105-Z 105-Z 111-Z 112-Z	10-11AM MWF 11-12 MWF 1-2PM MWF 2-3PM MWF 10-11:30AM TTH 1-2:30PM TTH	MCLENDON JANSSENS MCDERMOTT HOWARD
ENG 337 D601 E602 P604 S605	SHAKESPEARE 105-C 110-C 110-C 113-C	9-10AM MWF 10-11AM MWF 8:30-10AM TTH 1-2:30PM TTH	HENDERSON A EAKER EAKER THOMAS

closed sections

FRE 231, and ENG 337. He received special permission to register early (i.e., no closed sections to worry about). How many different feasible programs could he select, given the printed schedule used in Problem 4 (ignoring closed sections), and still take the afternoon job without a time conflict?

Example 4.  
Tree Representation  
of Expressions

Suppose we are given

$$((a \times w + b) \times w)^2 / (d \times y)$$

It seems obvious that whoever first wrote this string of characters intended that it have a mathematical meaning. By now, you are quite expert at interpreting such strings. This interpretation, remember, involved the application of a relatively complicated set of rules (Tables 2-1 and 2-3). Figure 6-9

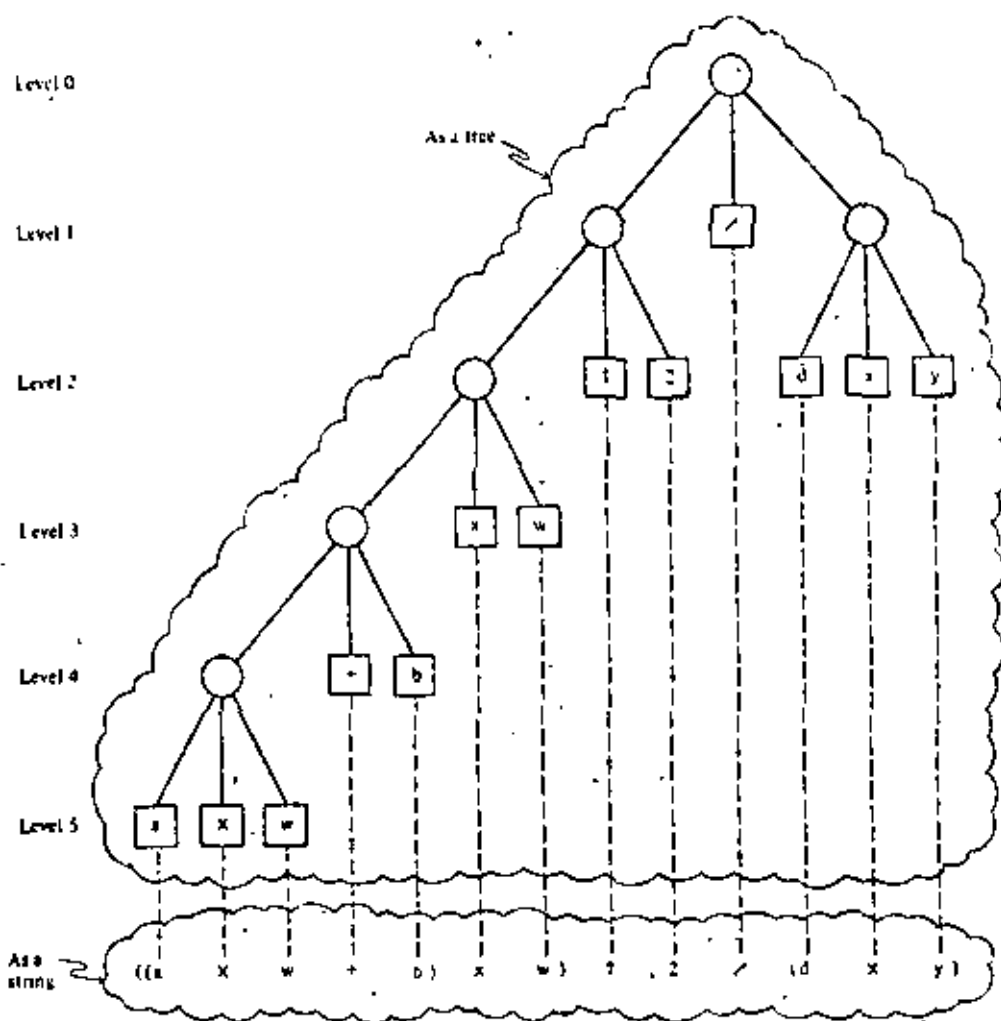


FIGURE 6-9  
A tree representation of an arithmetic expression.

shows how we can represent the same string as a tree and give it the same interpretation. We will quickly discover that the rules for evaluating an expression represented as a tree are much simpler to state because *part of the interpretation is inherent in the structure of the tree.*

Before proceeding with this line of thought, it will be helpful to summarize and supplement the tree terminology developed thus far. This is done with the aid of Figure 6-10a.

We see that every tree has a *root node* from which extend *segments* (one or more) to other nodes, which in turn branch to others, eventually ending in *terminal or leaf nodes*. (Notice that a root node alone is not a tree.) Every segment leads to the root of a subtree, which may be a terminal node. Nodes

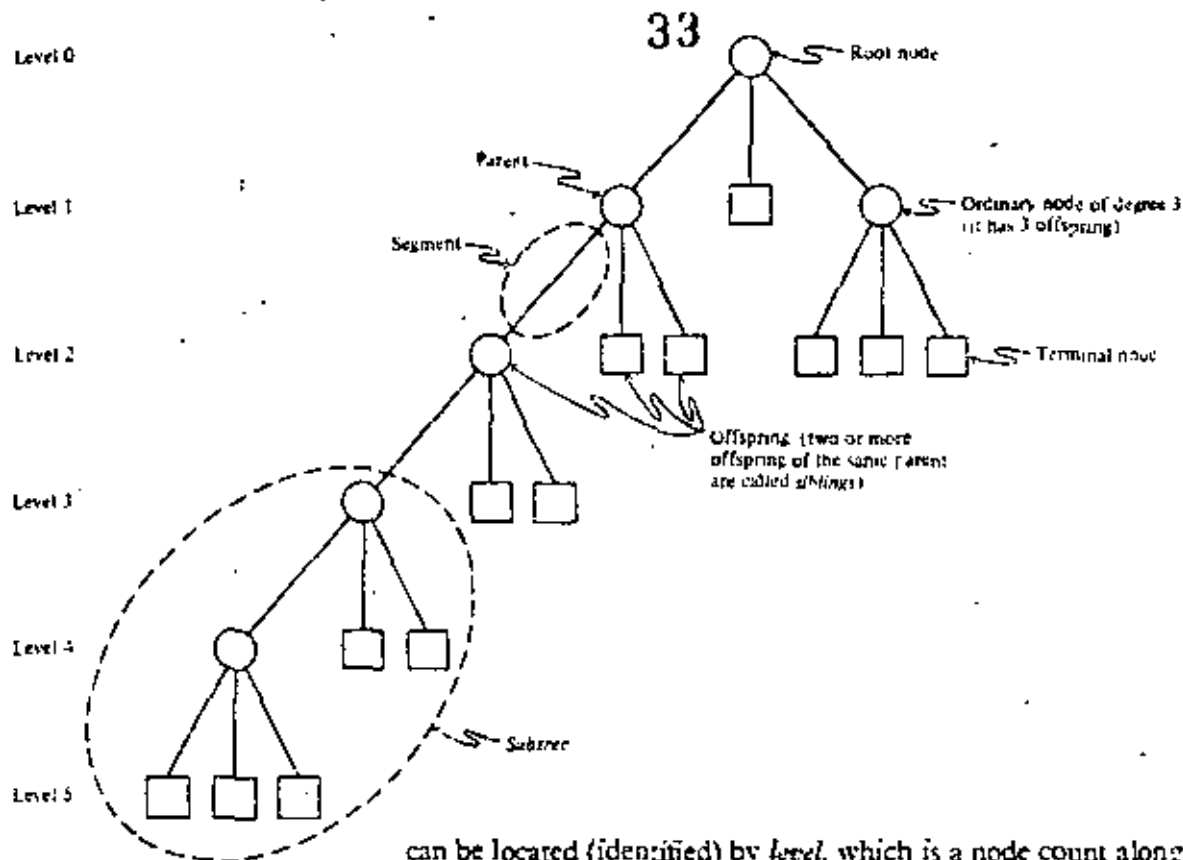


FIGURE 6-10a  
Tree terminology.

can be located (identified) by *level*, which is a node count along a *path* from the root node to a terminal. The level we associate with the root node is purely arbitrary, but we will usually take it to be zero. The nodes along a path are often thought of as having an *ancestral* relationship one to another. By analogy with family trees, moving from a root toward a terminal, each node is the *parent* of its immediate successor nodes (*offspring*). Two or more nodes having a common parent are sometimes called *siblings*. Finally, we can say that the *degree* of a node is the number of its immediate offspring.

A node may also be identified in terms of the *path* that leads from the root to that node. How can we represent that path? An answer comes to mind when we realize that representing a tree in two dimensions imposes an ordering on the segments that emanate from each node. And we might as well recognize this fact of life by numbering the segments in some way, say from left to right or right to left. For simplicity and consistency we will generally number segments from left to right, as suggested in Figure 6-10b. These ordinal numbers amount, in effect, to *names* for the segments.

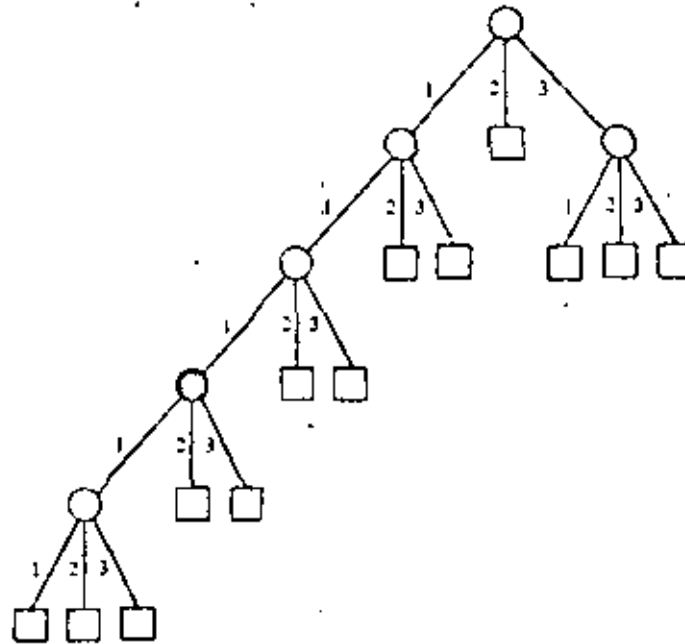


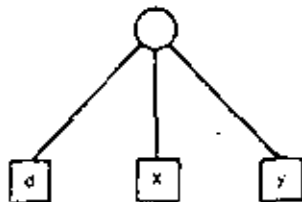
FIGURE 6-10a

Now a node can be designated uniquely by listing the names of all the segments in the path leading to that node. For example, the light green node in Figure 6-10b may be designated by the list (1, 1, 1, 1, 2), the dark green node by the list (3, 1), the gray node by the one-element list (2), and the black node by (1, 1, 1). (How would the root node be designated in this scheme?) Distinct nodes have distinct paths and hence distinct lists.

The *expression tree*, by its very structure, provides the key to evaluating the expression that is represented. For example, suppose values for the variables of our expression are:

a	w	b	d	y
3	2	2	-1	7

A subtree of the form shown in Figure 6-11, together with the above table, can be understood to mean: Look up the values of  $a$  and  $w$ , compute  $a \times w = 3 \times 2 = 6$ , and replace the subtree by the terminal node 6.



Correspondingly, the subtree shown on the left can be interpreted as: Compute  $d \times y = -1 \times 7 = -7$  and replace the subtree by the terminal node  $-7$ .

Figure 6-12 represents a sequence of meaningful substi-



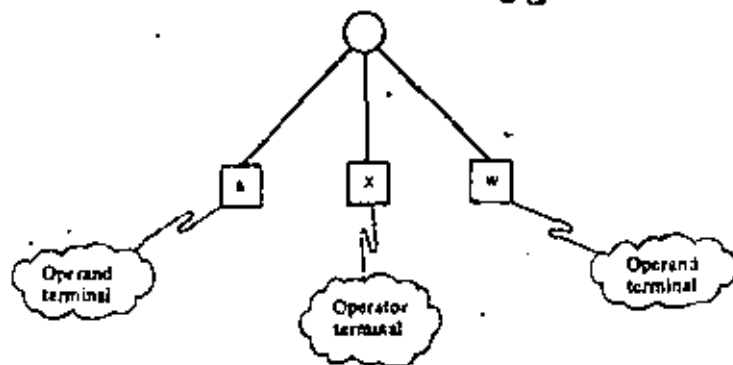


FIGURE 6-11

tutions that, when carried out, will ultimately lead to the replacement of the whole tree, root node and all, by a single terminal, which represents the value of the expression.

Proper evaluation is guaranteed if we follow one simple *replacement rule* that says:

*Whenever you find a subtree consisting of a root node leading to three terminals (an operator and two operands), replace that subtree by a single terminal value.*

Thus the replacement sequence in Figure 6-13, although different from that of Figure 6-12, leads us irrevocably to the

same value,  $\frac{-256}{7}$ . A computer performing either sequence

would evaluate the same indicated quotient  $\frac{-256}{7}$ , notwith-

standing the fact that computer operations on floating-point numbers are nonassociative, a fact explained in Chapter 11. Another point to note from the figures is that the treelike representation of a complicated arithmetic expression allows us to see all the meaningful subexpressions (all the subtrees) at a glance.

Once an expression is represented as a tree, evaluation depends only on repeatedly searching and finding subtrees that are subject to the replacement rule. At any given time, an expression tree, if not already fully evaluated, will exhibit at least one such subtree.

A question that has no doubt been uppermost in the minds of some readers is: How should tree structures be represented in storage? Linked lists, introduced in Chapter 4, suggest one



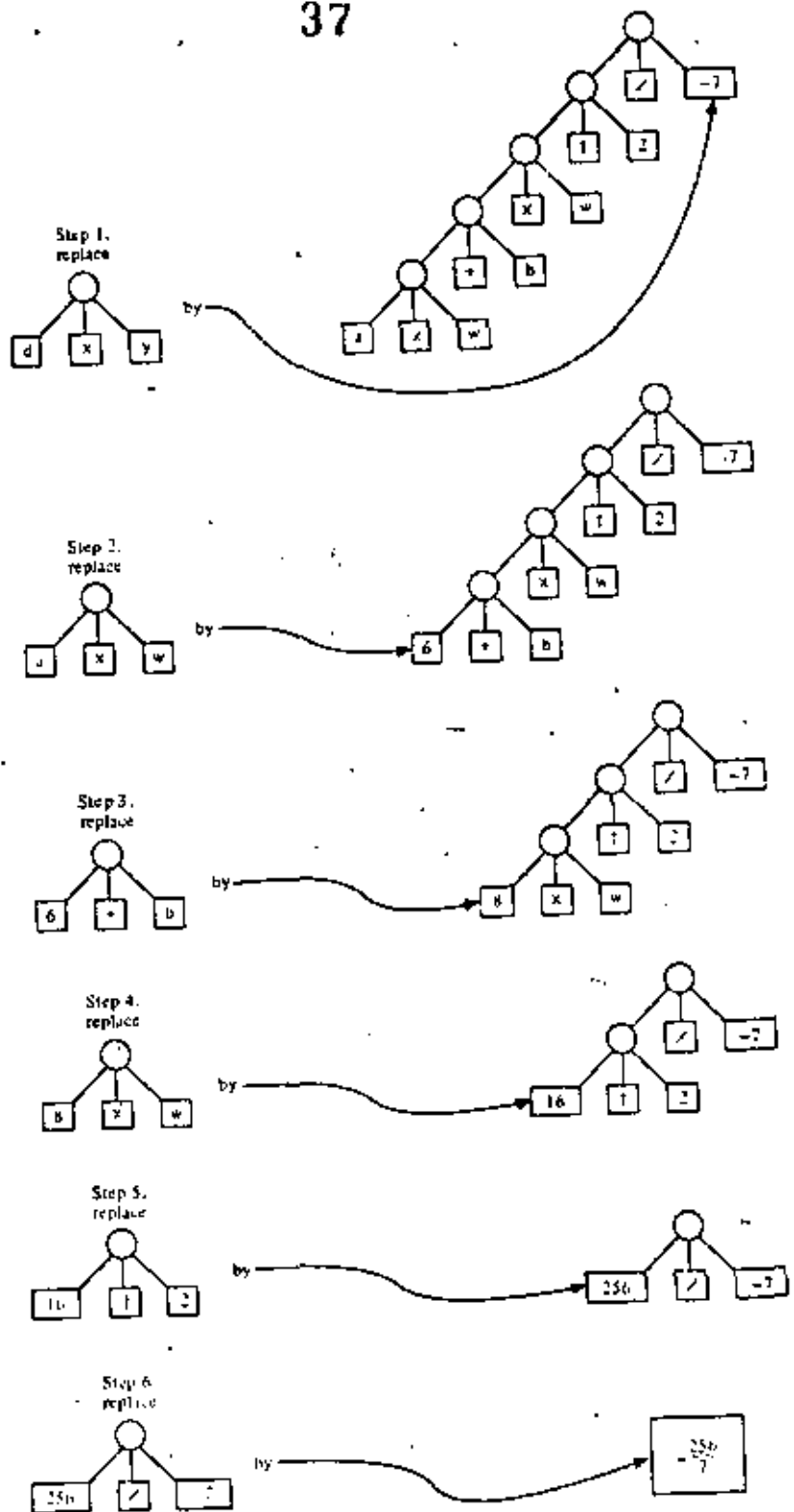


FIGURE 6-13  
Alternative replacement  
sequence for evaluating the  
tree expression.

way. With this approach, one storage representation for the expression

$$((a \times w + b) \times w) \uparrow 2 / (d \times y)$$

is shown in Figure 6-14. A four-column table is used. Each row represents a node with row 1 representing the root node.

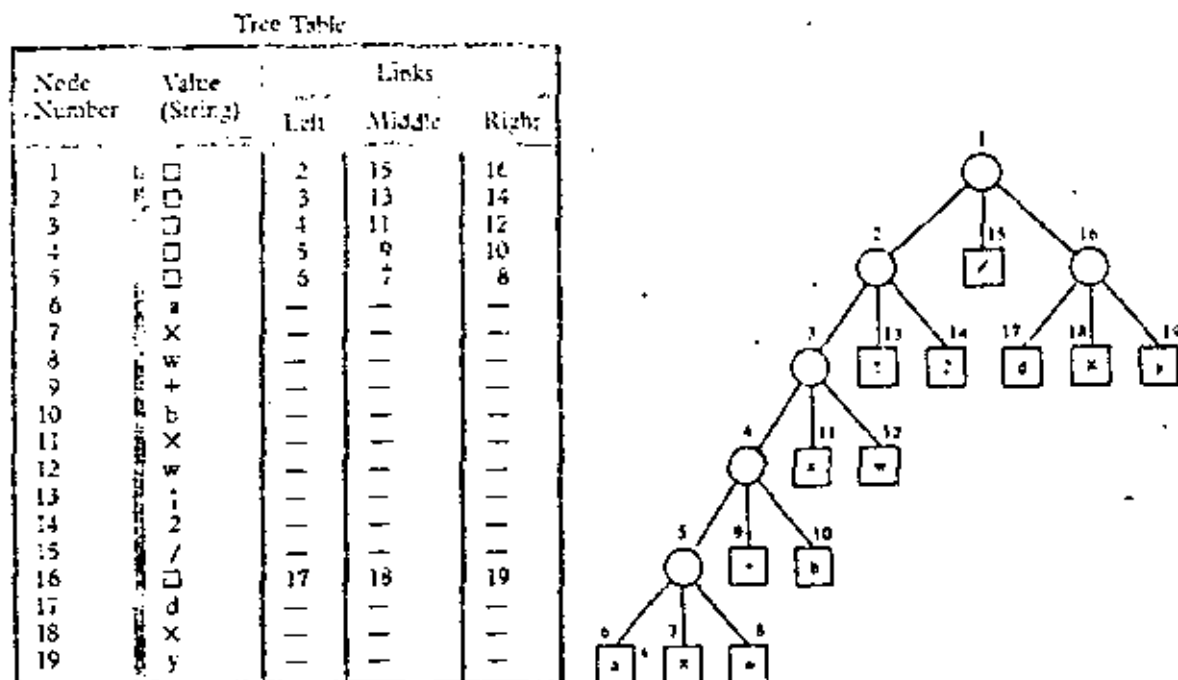
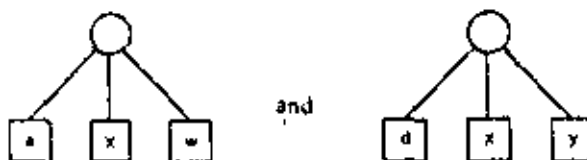


FIGURE 6-14  
Tabular representation of an  
expression tree.

The first column holds the value of the node if it is a terminal or some special mark, for example, □, if the node is nonterminal. The remaining three columns hold node numbers that designate the left, middle, and right offspring. These positions may be left empty (undefined) for terminal nodes. Node numbers in the left, middle, and right columns serve as *links* to other nodes. Other tabular descriptions of tree structure using the linked list approach are discussed in Chapter 7.

#### A Peek at Some Future Models of SIMPLOS

We noticed in the expression tree of Figure 6-12 that two separate subtrees



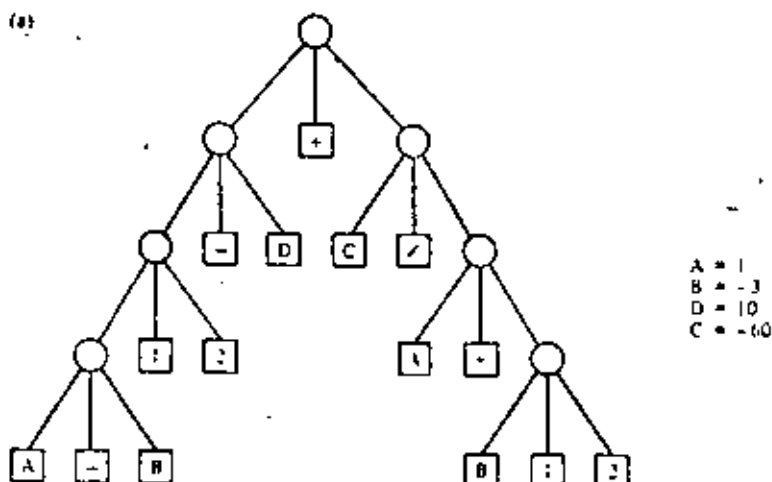
had only terminal nodes as offspring. At the start of evaluation we could invoke the replacement rule on either of these subtrees. It was immaterial which we picked first. This will always be the case for subtrees whose root nodes are siblings or the offspring of sibling nodes (i.e., cousins once or more removed). From the standpoint of expression evaluation, such subtrees are *mutually independent*.

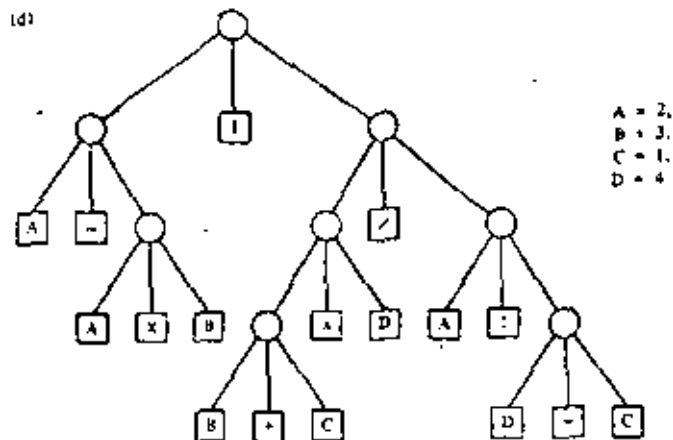
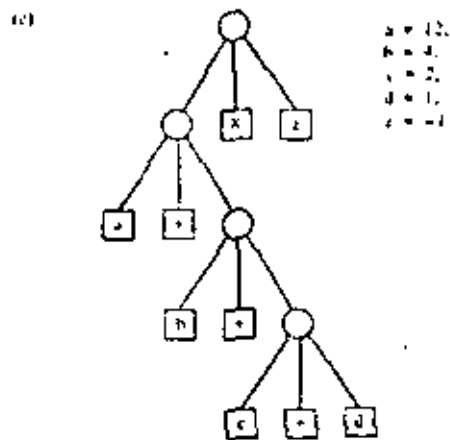
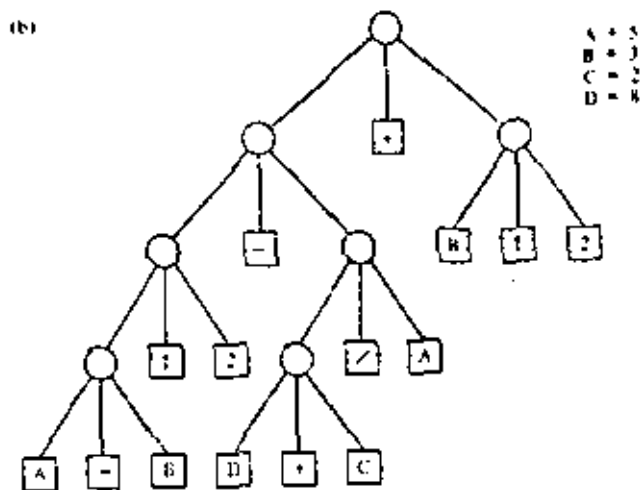
Under what circumstances can a computer work on the evaluation of two or more independent subtrees at the same time? With our present SIMPLoS model the answer is never, because at any one time there is only one team of personnel (Master Computer, Affixer, Reader, and Assigner) available to do work. On the other hand, advanced models of computer systems having several, perhaps many teams of personnel, are quite feasible.

Although it may boggle the mind to think about it, one may anticipate that future computers will evaluate mutually independent subtrees concurrently, that is, *in parallel*, whenever more than one team of personnel is available for the purpose. In cases where speed is essential the capability of concurrent computation offers the opportunity to solve problems that cannot be solved fast enough in any other way. Examples of such problems already abound in our technological society. More can be found on this topic in advanced texts.

EXERCISES 6-1,  
SET D

1. Evaluate the expression trees below, using the given values for the variables.





2. Draw a tree representation for the expression

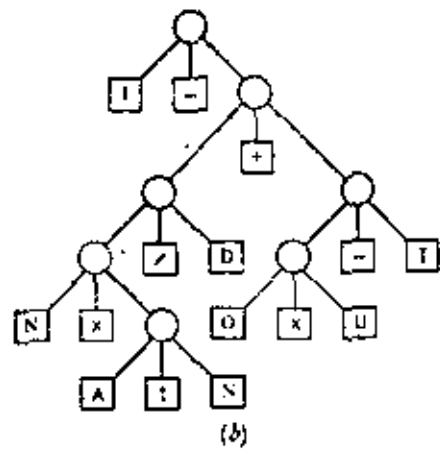
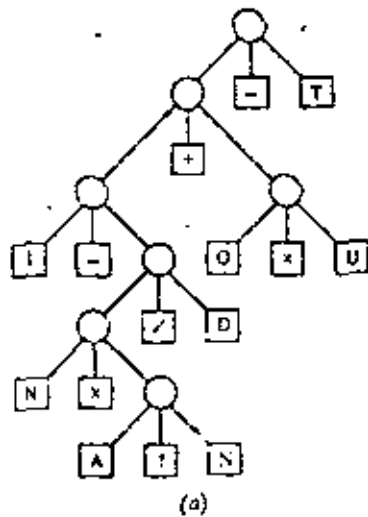
$$B \uparrow 2 - 4 \times A \times C$$

3. The following are two proposed tree representations for the expression

$$I - N \times A \uparrow N / D + O \times U - T$$

Which, if either, of these trees, evaluated by the replacement rule, yields a result computationally equivalent to the result we get by following the evaluation rules laid down in Tables 2-1 and 2-3? If the evaluation of either one of the trees is not compatible with these rules, describe the discrepancy.

41

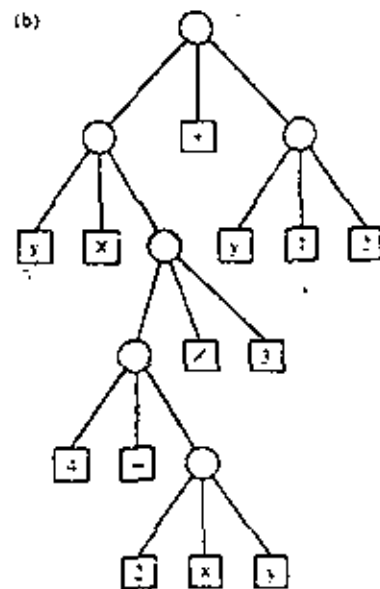
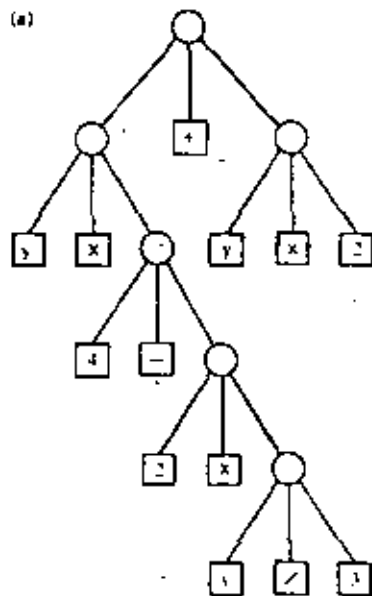


4. Draw a tree representation for the expression

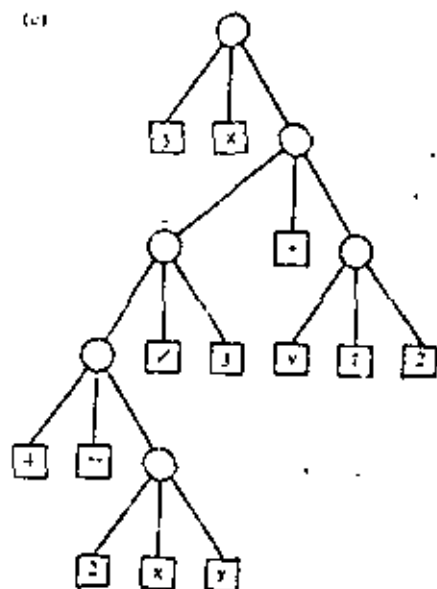
$$(a - b) \times (c - d) / (e \times (f + g))$$

5. Find which of the three trees given below correctly represents the given expression and exhibit the expression represented by each of the other trees.

$$y \left( \frac{4 - 2y}{3} \right) + y^2$$

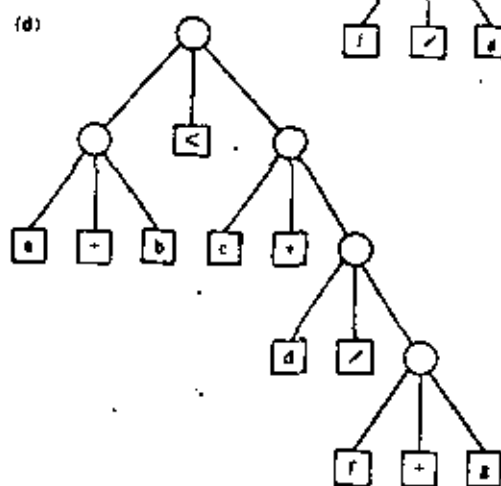
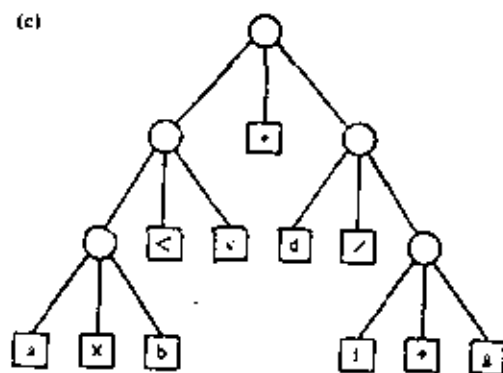
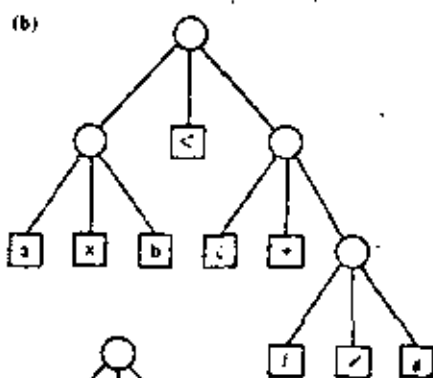
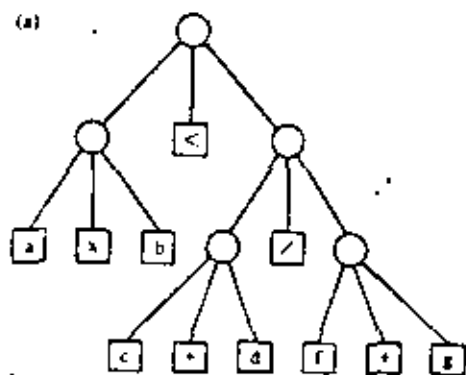


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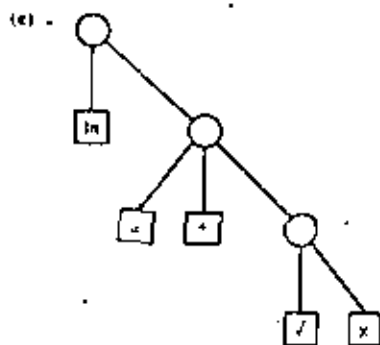
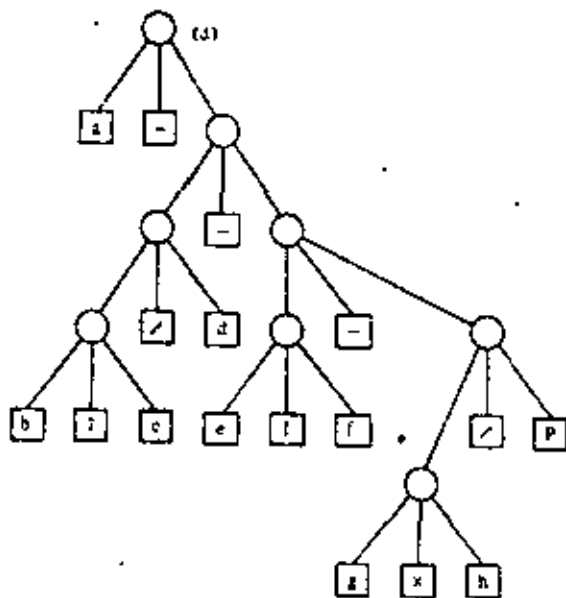
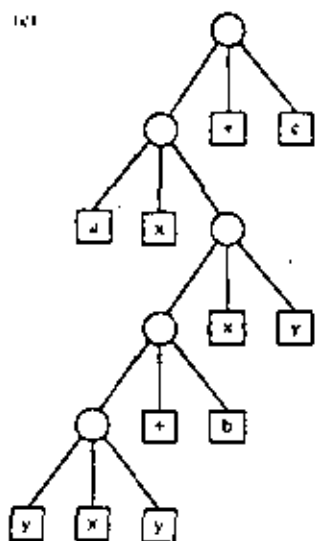
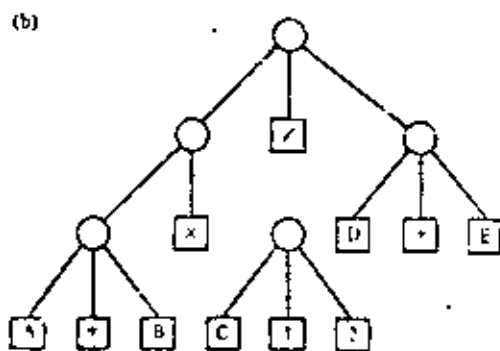
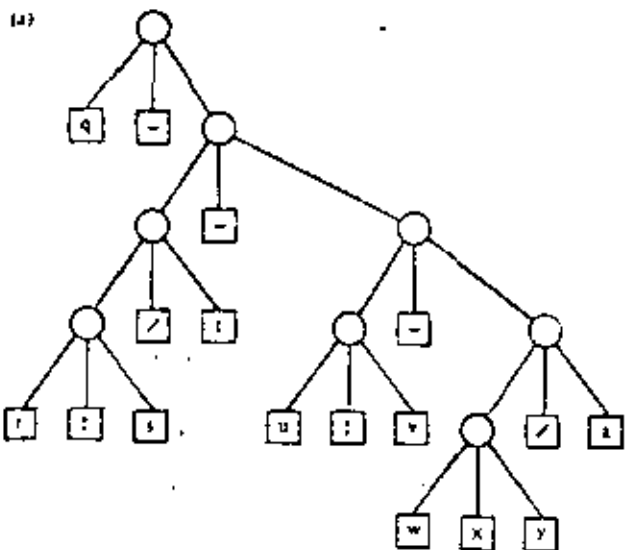
6. Find the tree among the four given below that represents the given expression correctly and exhibit the expressions represented by each of the other trees.

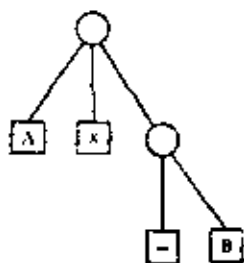
$$a \times b < c + d / (f + g)$$





7. Convert the trees below into the corresponding arithmetic expressions.





8. How would you draw the expression tree for the expression  $A \times (-B)$ ? The problem here is to decide how one should represent a unary operation. One possibility is shown in the tree on the left.

Here the subtree expression  $-B$  is treated as a root node having a unary operator  $-$  and one argument  $B$  as offspring nodes. One can deduce that the operator is unary by the fact that the (left-hand) operand node is missing. Functions such as  $\sqrt{\quad}$ ,  $\cos$ , and so forth, can be thought of as unary operators. Using the above expression scheme, or another of your own choosing, develop expression trees for:

- (a)  $A + \sqrt{x}$   
 (b)  $\cos(x^2 + y^2)$   
 (c)  $\sqrt{\frac{1}{2} \times (1 + q / \sqrt{p^2 + q^2})}$

9. Which of the following statements is false?

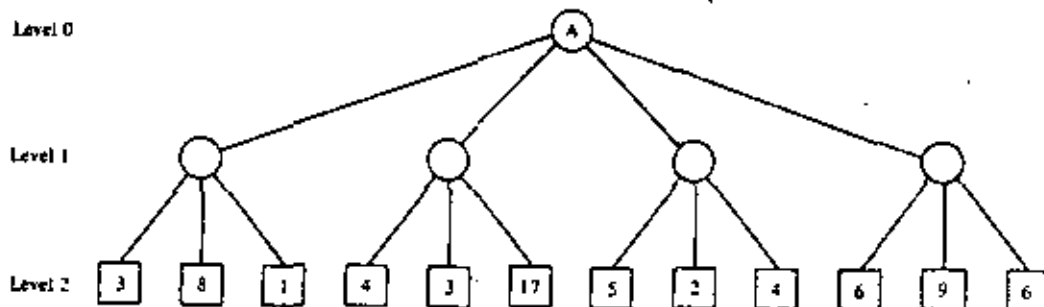
- (a) A terminal node has one ancestor node and no descendant nodes.  
 (b) A root node has no ancestor nodes and may have no descendant.  
 (c) A nonterminal node has no descendant nodes.  
 (d) A nonterminal node may have only one ancestor node.  
 (e) A terminal node can be connected to an ancestor.

*Hint* If you have any question as to the meaning of "ancestor" and "descendant" just think of a family tree.

10. Any given two-dimensional matrix can be represented as a tree. For example, the matrix

$$A = \begin{bmatrix} 3 & 4 & 5 & 6 \\ 8 & 3 & 2 & 9 \\ 1 & 17 & 4 & 6 \end{bmatrix}$$

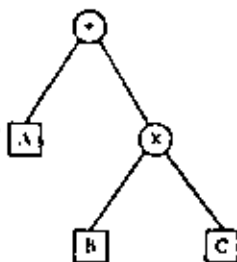
can be expressed as the tree:



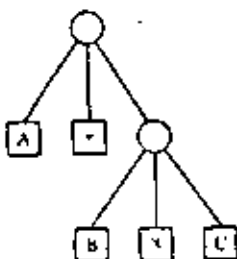
- (a) Given the representation above, the four nodes at Level 1 correspond to (choose one):  
 (1) The four elements of the main diagonal of the given matrix.  
 (2) The four elements of row 1 of the given matrix.

- (3) The four columns of the given matrix.  
 (4) The sums of the elements in each of the columns of the given matrix.  
 (5) None of the above.
- (b) Show at least one other way to represent the matrix  $A$  as a tree structure.
11. Using list notation, give the paths for the nodes labeled  $\square D$ ,  $\square U$ , and  $\square \cdot$ , in the second of the two trees referred to in Problem 3 of this exercise set.
12. Develop a scheme to denote the saving in time that, in principle, is possible in a computer having multiple processing units that can execute concurrently in the same expression. Show how your scheme would work on the following expressions.
- (a)  $a^2 + b^2 + c^2$   
 (b)  $(a - b) \times (c - d) / (e \times (f \div g))$   
 (c)  $(\sqrt{x} + \cos y) / z$
13. In the text we have always shown the operator symbol of an expression tree as a terminal node, so each nonterminal node of the tree has three offspring if the operator has two operands, and two offspring if the operator has one operand. Another way to draw the tree is to place each operator symbol *at* its parent (nonterminal) node. For example, the tree for the expression  

$$A + B \times C$$
 may be drawn as



instead of as



The new form, which we shall call a *binary expression tree*, has fewer nodes but the same amount of information. Refer to Figure 6-14 and:

- (a) Produce the binary expression tree equivalent to the expression tree given in the figure.
- (b) Show how the tree table in that figure can be changed in structure and in content to represent the binary tree you developed in part a.
- (c) Which tree table would require less storage in a computer representation?

## 6-2 Tree searches

We have now seen enough of trees to have observed their main structural characteristics; segments of a subtree always connect to new nodes that form a continuation of the same subtree; there is no looping back to nodes closer to the root; and there is no crossing or crisscrossing between subtrees.

There are many ways one can construct and store a tree structure. Depending on what use is to be made of the tree, some representations (we will call these *storage structures*) are better than others. Trees are searched for one reason or another, either to gain specific information, to reach a conclusion, or to modify the tree in a certain way. A tree search lies at the heart of a number of mathematical problems and a great number of games.

### Natural-order Tree Search

There is a systematic way to scan all the nodes of a tree that is used frequently in solving problems. We call it *natural-order searching*. Although a squirrel may have better ways of finding nuts in a tree, it will help us to understand natural-order search if we imagine a nut-seeking squirrel willing to follow these rules.

1. Start at the trunk (root) and don't stop trying segments until you reach a leaf (terminal node) unless you find a nut and choose to stop at that point.
2. Upon reaching a terminal without finding a nut, back up to the node you just passed, that is, to the *parent* node of this terminal.
3. Now, choose the next untried segment, if any, and move forward along it toward another leaf node.

4. If there are no untried segments, crawl backward to the predecessor (parent) node and repeat the process of trying to reach another leaf node.

5. If you ever find yourself back at the root having already tried all segments from the root without finding a nut, you have finished searching the entire tree in natural order and can report a failure to find a nut.

Figure 6-15 shows a natural-order search of a tree. The numbers beside the nodes indicate the sequence in which they

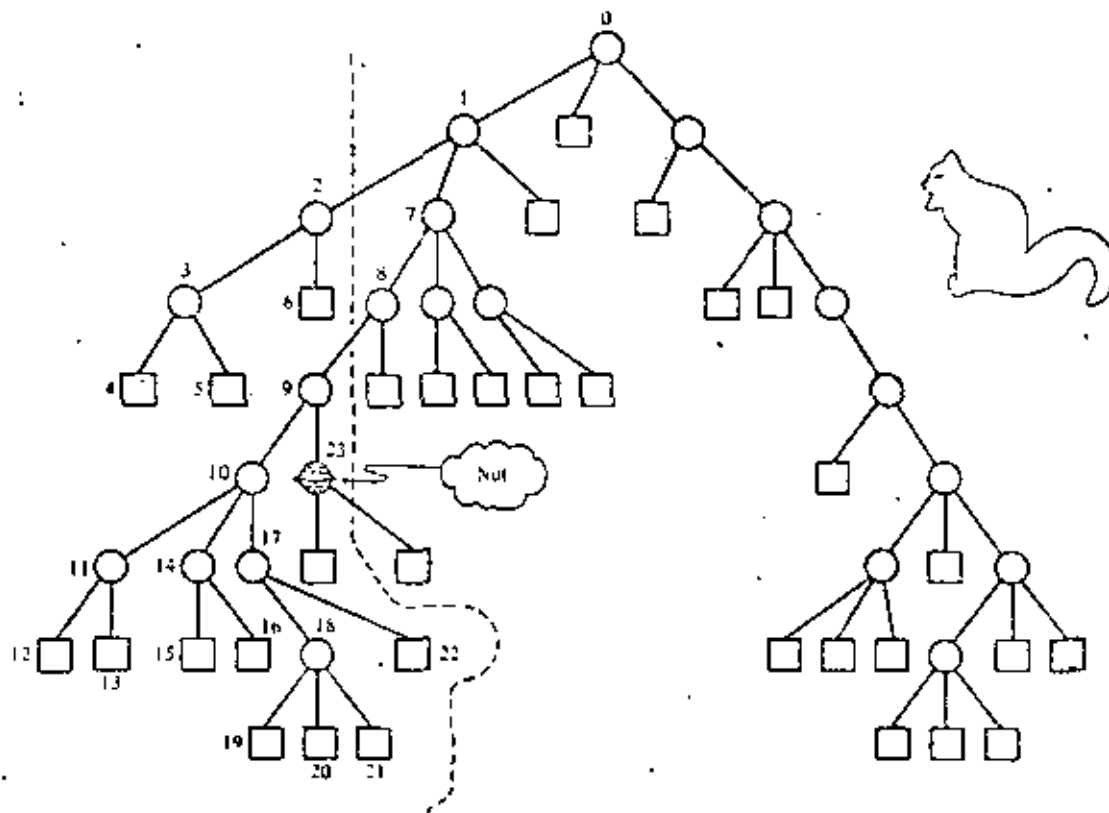


FIGURE 6-15  
Systematic (natural-order)  
search for a nut.

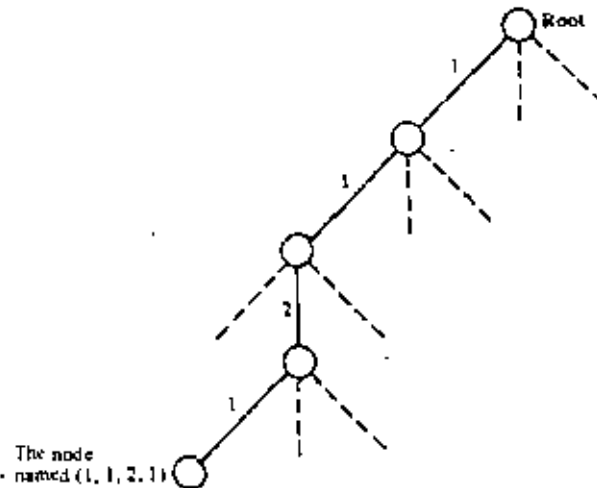
are first encountered (i.e., as the squirrel sees them in its forward progress). We picture one of these nodes as a nut. It is the 23rd node encountered. Notice the systematic, left-to-right selection of segments at each node.

#### Algorithm for Natural-Order Tree Search

Now suppose we wish to construct a tree search algorithm that generally follows the stated set of rules. One of our problems is how to interpret rule 3, that is, how to choose among the

remaining untried segments. If we recall, however, that the segments emanating from each node are, or always can be, *ordered*, then a simple interpretation comes quickly to mind: choose the segment, if any, whose ordinal number name is one higher than that of the segment previously tried.

To make this choice implies that the algorithm can always identify the ancestor or parent node from which the "previously tried" segment emanated. That is, the algorithm can only identify additional segments in terms of the common parent. This *backup* capability is assured if the algorithm at all times has an up-to-date record of where it is in the tree search and can represent this data in the form of a path list. For example, suppose it has been discovered that the segments from the node whose path designation is  $(1, 1, 2, 1)$  need be examined no further (Picture 1).

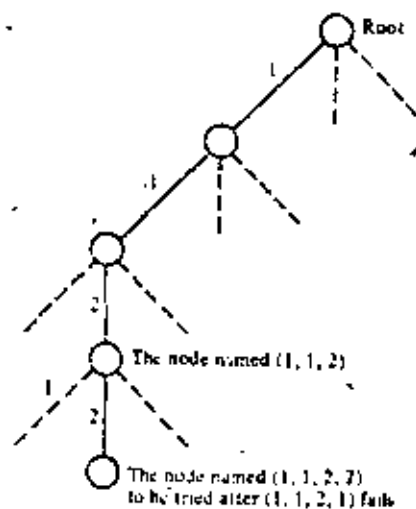


PICTURE 1

What is the path name for the parent of that node? The answer is  $(1, 1, 2)$ .

How do we apply rule 3 to this parent  $(1, 1, 2)$ ? (Rule 3: choose the next untried segment, if any, and move forward along it toward another leaf node.) The answer is, if there is a node whose path is  $(1, 1, 2, 1 + 1)$ , try it (Picture 2).

In general, suppose we have tried the segment leading from node  $(1, 1, 2)$  to node  $(1, 1, 2, i)$  and the subtree whose root is  $(1, 1, 2, i)$  has failed to contain the nut we are looking for. To select the next untried segment, if any, of node  $(1, 1, 2)$ , we have only to check whether there exists a valid node



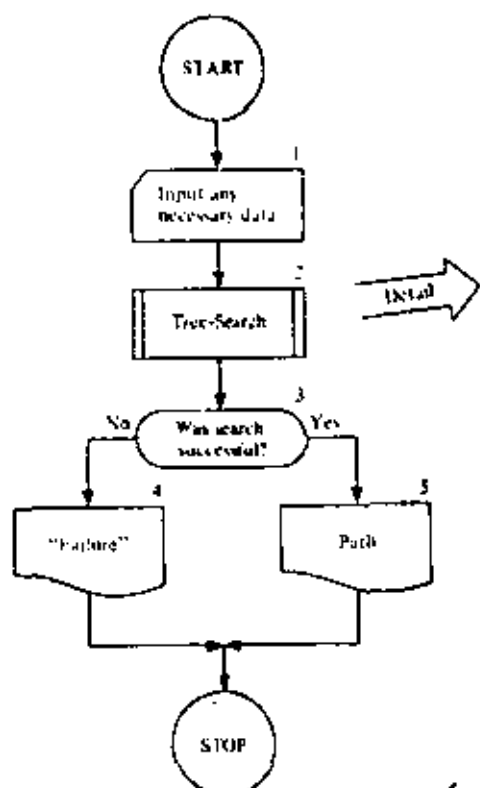
PICTURE 2

whose path is  $(1, 1, 2, i + 1)$ . If so, select the segment leading to this node and if not, back up, and check whether there is a valid node  $(1, 1, 2 + 1)$ . If so, select the segment leading to this node, but if not, back up again and see whether  $(1, 1 + 1)$  is valid, and so on.

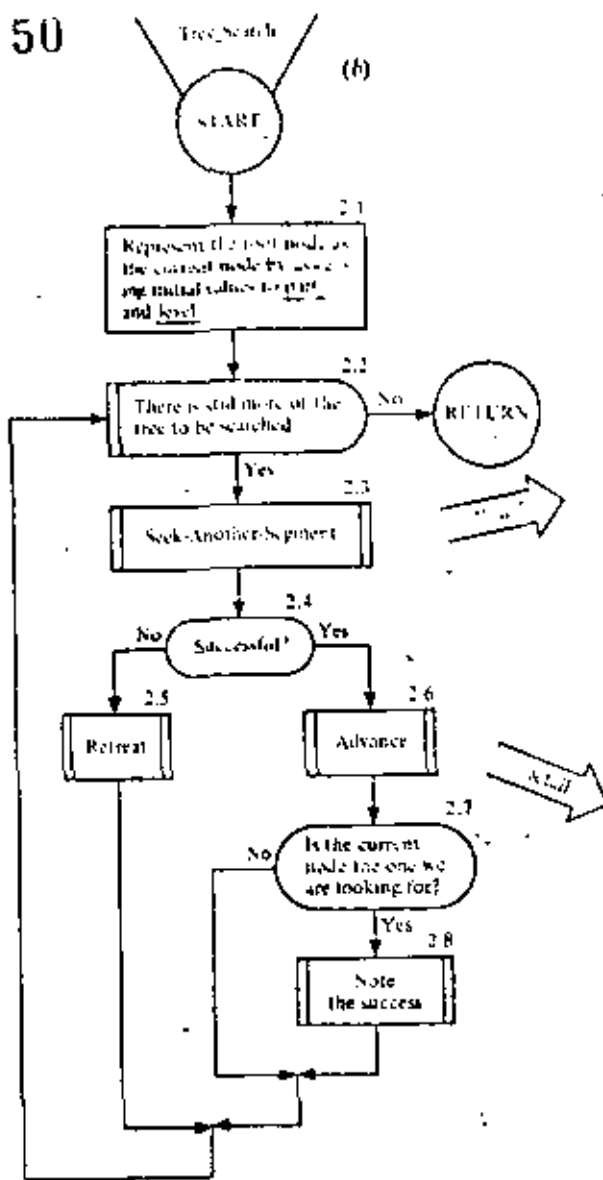
We now sense that by starting out with a path list that represents the root node (an empty list of segments), and by continuing to update that list as we move through the tree to reflect where we are in the search, then simple adjustments to the path allow us to determine each new direction of search.

Figure 6-16 shows a systematic procedure, that is, an algorithm for conducting natural-order tree search. The algorithm is represented in top-down style, with Figure 6-16a giving the topmost view. Any necessary data are input in box 1 and the tree search begins at box 2. In `Tree_Search`, whose details are given in Figure 6-16b, there are two key variables: *level* and *path*. The value of *level* tells us the number of elements in *path*. Values of these two variables determine the *current node* of the search. In a sense the current node is the one we are standing on while we try to find the next node to move to. These variables are initialized in box 1 of Figure 6-16b. `Tree_Search` sets some sort of switch to indicate success or failure. (Recall that a root node by itself does not constitute a tree. There must be at least one subtree. For this reason the first time box 2.2 is executed the Yes outlet will be taken.) Upon exit from `Tree_Search`, the main program, in effect, tests

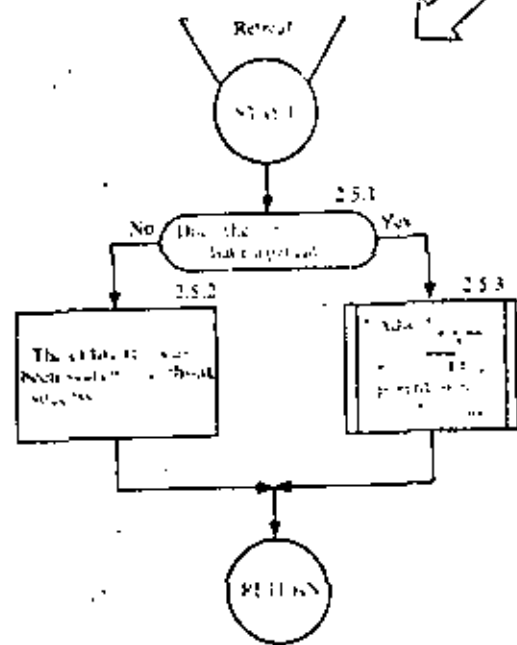
50



(a) Main flowchart



(b)

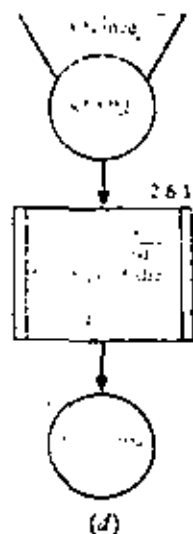
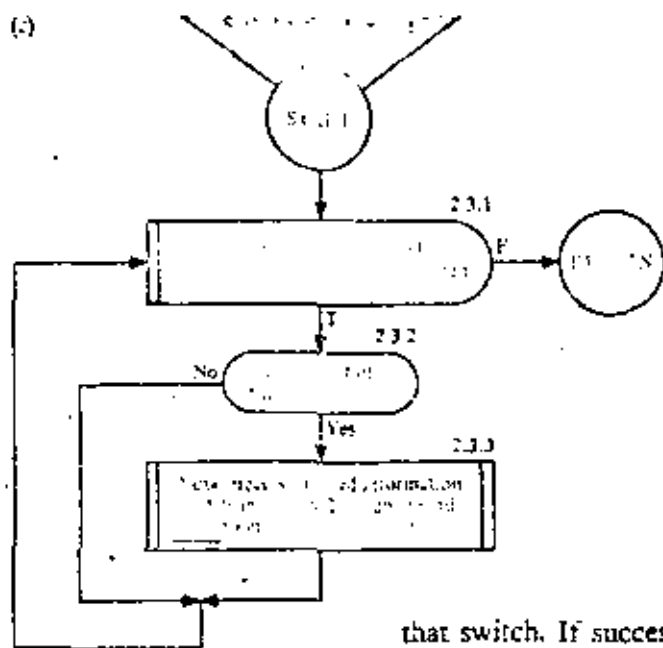


(c)

FIGURE 6-16 Top-down development of an algorithm for natural-order tree search.



51



that switch. If success is indicated, the path list is displayed, identifying the location in the tree where the nut was found; otherwise a failure message is displayed.

To simplify the details of *Tree\_Search*, three of its boxes are given in more detail in Figure 6-16c, 6-16d, and 6-16e. Notice that rule 3 is implemented in box 2.3 as a call to a procedure, "Seek\_Another\_Segment," whose details (Figure 6-16c) include a test for admissibility of untried segments. Although not shown in the level of detail given in Figure 6-16c, we imagine that some sort of switch is set by *Seek\_Another\_Segment*, which can be tested upon return to *Tree\_Search* so that the former's success or failure can be determined at box 2.4. If successful, there is a new node to which the search may *advance* (details in Figure 6-16d). If unsuccessful, it is necessary to *retreat* to the parent node, if any (Figure 6-16c). (Remember that *Seek\_Another\_Segment* reports failure only after *all* segments have been tested.)

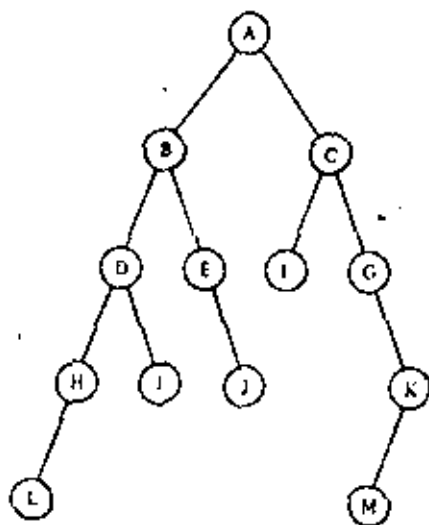
The bookkeeping of the *retreat* operation (box 2.5.3) is a two-step process.

1. Detach the last element of *path*, which is a segment number, and save it to use the next time *Seek\_Another\_Segment* is called at box 2.3.
2. Decrement *level* by one to reflect the shortened length of *path*.

The segment number saved in step 1 is needed in boxes 2.3.1 and 2.3.3. When a new segment number is selected in box 2.3.3, it in turn is saved for use by Advance, the next time that procedure is called at box 2.6. Advance increments *level* by one and appends the new segment number on to the end of *path*. We leave to the reader the pleasure of reviewing these details and convincing himself of their correctness. As a parting remark, it is worth observing that the nature of the admissibility check hinted at in box 2.3.2 may be crucial to the success of the search. As many inadmissible structures as possible must be ruled out at each stage. For example, the squirrel should recognize each dead limb and not search it. Otherwise, the proportion of useless paths may grow rapidly, meaning that the efficiency of the search method can plummet toward zero. Next we examine several interesting problems that employ this type of search in their algorithmic solution.

## EXERCISE 6.2

1. List the nodes of the tree below in the order in which they would be encountered in a natural-order search.



### 6.3 The four-color problem

Maps are colored to make it easy to see at a glance the extent of each country. It is necessary that neighboring countries (i.e. countries with a common boundary line) be assigned different colors. Does the mapmaker then need more than four colors to do his job? He doesn't care, but we do.

This problem was one of the most celebrated challenges in mathematics. It is of great intellectual interest and has intrigued many people from all paths of life. Actually, its solution has little or nothing whatsoever to do with making maps. A mapmaker is and always will be able to print maps using as many different colors as he needs.

A checkerboard is an example of a map that can be colored with only *two* colors. The four-country map shown in Figure 6-17 requires *four* colors. Because each pair of countries is adjacent, no two can have the same color.

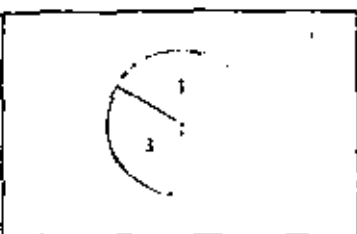


FIGURE 6-17

It didn't take us long to find a map requiring four colors. Yet, in over 100 years of searching, no one has succeeded in finding a map requiring five! It is natural to conjecture that every map can be colored with four colors, and many mathematicians have racked their brains trying to prove this conjecture. The best they have been able to do so far is to show that every map can be colored using no more than five colors.\*

We are about to see how computer methods can be applied to the four-color problem. We will not use the computer to show that the four-color conjecture is *true*. Indeed, it is entirely possible that no computer can ever prove this. However, true or false, we can use the computer to determine whether a *particular map* can be colored in only four colors. This is the task for which we want to construct an algorithm.

Before starting on this algorithm, a few remarks concerning the coloring of maps may be helpful.

A *minimal five-color map* is a map requiring five colors, so that every other map requiring five colors has at least as many countries. Of course, no minimal five-color map has ever been found. But mathematicians have shown that if such maps exist at all, then some of them satisfy these two conditions.

1. No point is a boundary point of more than three countries.
2. Each country is a neighbor of at least five others.

Moreover, it can be shown that every minimal map, if any exist, must satisfy the second condition.

It is therefore customary to consider as candidates for counterexamples to the four-color conjecture only maps fulfilling these conditions.

\*A simple proof of the five-color theorem exists. It may be found, for example, in *What is Math, math?* (Oxford University Press (1941), by Courant and Robbins.

Four-Coloring as a  
Tree Search

We can model the problem of four-coloring a given map, say, the one pictured in Figure 6-18, as one of traveling along a path through a tree such as that shown in Figure 6-19. Each segment represents a decision to color a country, with colors 1, 2, 3, or 4. The  $i$ th segment in a path from the root corresponds to the coloring of the  $i$ th country of the map.

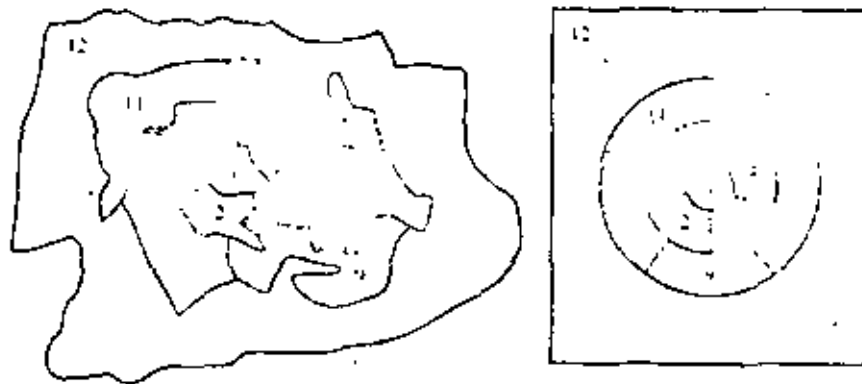


FIGURE 6-18

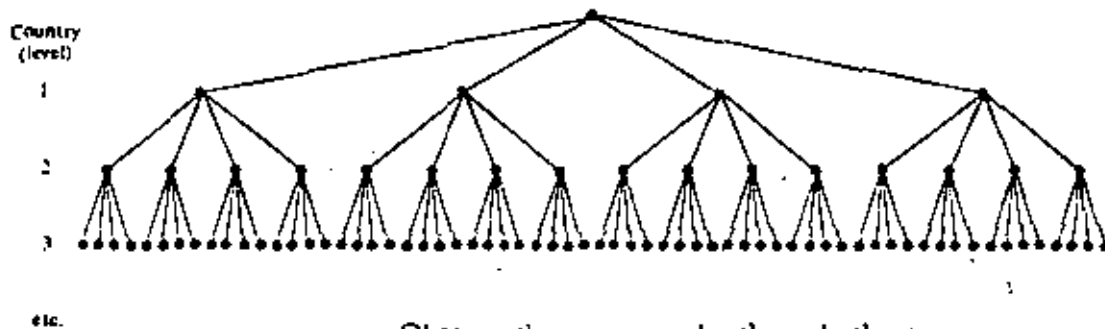


FIGURE 6-19

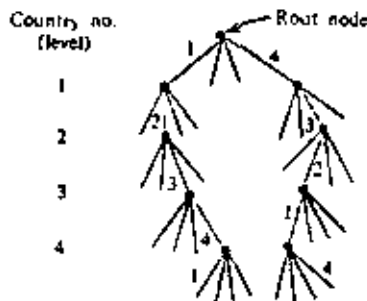
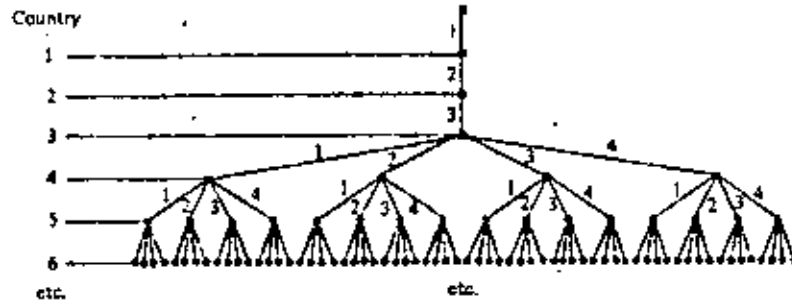


FIGURE 6-20

Observe that many paths through the tree turn out to represent identical colorings of the map except for renaming of the colors, and it is desirable to avoid searching through such duplicate patterns. (E.g., the two heavy-line paths in Figure 6-20 represent the same coloring patterns with different names used for the colors.) One way to avoid the unnecessary search is to fix at the outset in a quite arbitrary way the colors for neighboring countries 1, 2, and 3 and to begin the real search with the coloring of country 4.

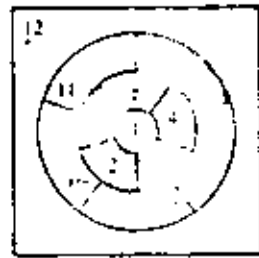
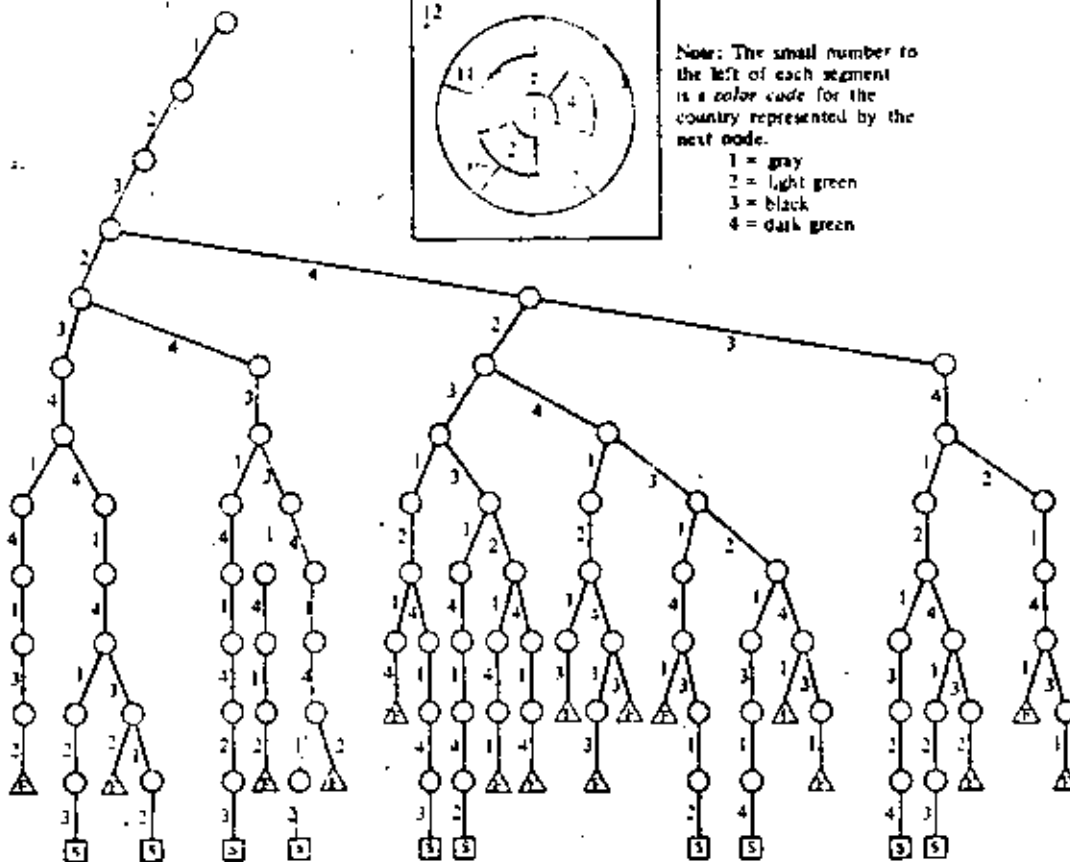
In coloring all countries, from the fourth country on, as seen in Figure 6-21, we assume that all four choices are possible. Most of the time, however, as can be seen in Figure 6-22, only one, two, or three of these choices will be admissible. Sometimes even all four choices will be inadmissible, as ex-

FIGURE 6-21  
Showing coloring tree and one path representing the coloring of the first six countries (colored line).



Country no. (level)

1  
2  
3  
4  
5  
6  
7  
8  
9  
10  
11  
12



Note: The small number to the left of each segment is a color code for the country represented by the next node.  
1 = gray  
2 = light green  
3 = black  
4 = dark green

FIGURE 6-22  
An entire coloring tree showing how to four-color the map of Figure 6-18.

10 Successes, marked by terminal nodes of the form **S**  
16 Failures, marked by terminal nodes of the form **F**

emphified by terminal nodes marked **F** in Figure 6-22. Only 10 paths lead to **S** (success) terminals.

EXERCISES 6-3  
SET A

1. Compute the theoretical maximum number of possible terminal nodes for the coloring tree of the 12-country map in Figure 6-18.

*Hint* Use Figure 6-21 as a guide.

## 336 COMPUTER SCIENCE: A FIRST COURSE

2. Assume that it takes only 1 microsecond to check another path to a terminal, and that the search of half of these paths is required before the desired terminal is reached. How long would the computer chug away before it found what it was looking for in a 39-country map? Assume all segments to be admissible. Express your answer in units of years.
3. By renumbering the countries on the map of Figure 6-18, show that a coloring tree can have nodes with three and even four permissible segments emanating from them.
4. Using a form similar to that of Figure 6-22, draw a "coloring tree" for the map shown below.



### A Four-Coloring Algorithm

Let us see how to apply what we have just learned about tree search to an actual problem. It is one thing to discuss a tree in the abstract and another to start with a problem, define in some detail the tree search that is involved, and then develop a detailed flowchart algorithm. In this case, we will take as our problem statement: Develop a detailed flowchart algorithm for four-coloring any  $n$ -country map.

The first step toward this objective might be to devise a method to represent any  $n$ -country map. To do this we need a sample map for study as, for example, in Figure 6-23. The

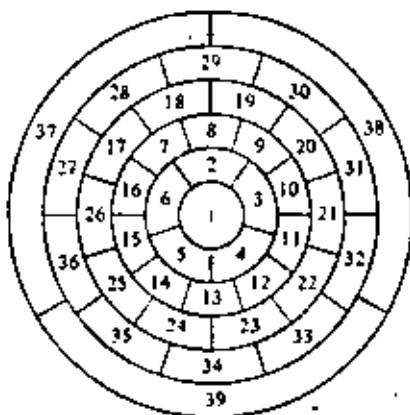


FIGURE 6-23  
Example of map to be four-colored by a computer algorithm.

map consists of 39 countries, and the countries have been numbered or indexed in the order that the algorithm will attempt to "color" them.

The efficiency of the algorithm will be greatly improved if each country borders on as many lower-numbered countries as possible. We do not absolutely insist on this but, if you have done Problem 3 of Exercise 6-3, you will appreciate why we recommend this approach. We do, however, require that the first three countries all be neighbors of each other.

How do we represent the map in computer storage? One way is to construct a "connection table," listing after each country all of its neighbors in increasing order. This is shown for our example in Table 6-1.

Our algorithm should consult this table when deciding how to color a particular country. For example, if we were coloring country 15, we could see in row 15 that countries 5, 6, and 14 are neighbors already colored. Our choice of color for 15, then, depends solely on the currently chosen colors for 5, 6, and 14.

Knowing that country 15 also has neighbors numbered 16, 25, and 26 appears to be superfluous. This leads us to the idea of a shaved-down table, which we will call the "reduced connec-

TABLE 6-1  
The Connection Table for the Map in Figure 6-23

Country	Neighbors	Country	Neighbors
1.	2 3 4 5 6	21.	10 11 20 22 31 32
2.	1 3 6 7 8 9	22.	11 12 21 23 32 33
3.	1 2 4 9 10 11	23.	12 13 22 24 33 34
4.	1 3 5 11 12 13	24.	13 14 23 25 34 35
5.	1 4 6 13 14 15	25.	14 15 24 26 35 36
6.	1 2 5 7 15 16	26.	15 16 17 25 27 36
7.	2 6 8 16 17 18	27.	17 26 28 36 37
8.	2 7 9 18 19	28.	17 18 27 29 37
9.	2 3 8 10 19 20	29.	18 19 28 30 37 38
10.	3 9 11 20 21	30.	19 20 29 31 38
11.	3 4 10 12 21 22	31.	20 21 30 32 38
12.	4 11 13 22 23	32.	21 22 31 33 38 39
13.	4 5 12 14 23 24	33.	22 23 32 34 39
14.	5 13 15 24 25	34.	23 24 33 35 39
15.	5 6 14 16 25 26	35.	24 25 34 36 39
16.	6 7 15 17 26	36.	25 26 27 35 37 39
17.	7 16 18 26 27 28	37.	27 28 29 36 38 39
18.	7 8 17 19 28 29	38.	29 30 31 32 37 39
19.	8 9 18 20 29 30	39.	32 33 34 35 36 37 38
20.	9 10 19 21 30 31		

TABLE 6-2  
Reduced Connection Table for the Map in Figure 6-23

58

Country $i$	Neighbors $\text{CONN}_i$	Width $w_i$	Country $j$	Neighbors $\text{CONN}_j$	Width $w_j$
1		0	21	10 11 20	3
2	1	1	22	11 12 21	3
3	1 2	2	23	12 13 22	3
4	1 3	2	24	13 14 23	3
5	1 4	2	25	14 15 24	3
6	1 2 5	3	26	15 16 17 25	4
7	2 6	2	27	17 26	2
8	2 7	2	28	17 18 27	3
9	2 3 8	3	29	18 19 28	3
10	3 9	2	30	19 20 29	3
11	3 4 10	3	31	20 21 30	3
12	4 11	2	32	21 22 31	3
13	4 5 12	3	33	22 23 32	3
14	5 13	2	34	23 24 33	3
15	5 6 14	3	35	24 25 34	3
16	6 7 15	3	36	25 26 27 35	4
17	7 16	2	37	27 28 29 36	4
18	7 8 17	3	38	29 30 31 32 37	5
19	8 9 18	3	39	32 33 34 35 36 37 38	7
20	9 10 19	3			

tion table." It is constructed by striking out of each row in the table all numbers greater than the number of the row itself. The reduced connection table for our example is seen in Table 6-2 and can be thought of in this case as a 39-row by 7-column array called CONN. The number of nonnull elements in each row is given by elements of an associated list  $w$ . Thus the algorithm can search the first  $w_i$  elements in the  $i$ th row of CONN to determine which neighbors have already been colored.

If we are to apply our generalized tree search algorithm (Figure 6-16) to the map-coloring problem, we must also decide how to represent the *current node* (i.e., how to represent the variables *path* and *level*). The variable *path* is a list of elements, each of which designates a segment choice. Our decision to use color codes 1, 2, 3, and 4 for the four possible color choices leads us directly to the decision that a search from a node may be accomplished by selecting (trying) the segments in the same order, 1, 2, 3, and 4. The decision to make this correspondence between the color codes and the segment order imposes the required ordering on the segments from each node of our coloring tree. Moreover, the  $i$ th element



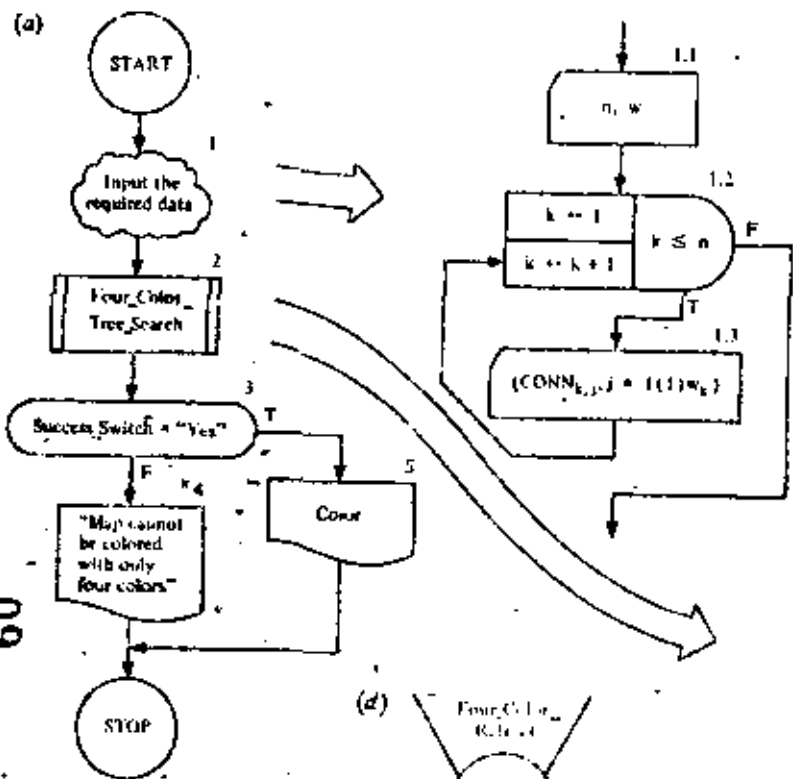
of *path* automatically identifies the color chosen for the *i*th country! This means that whenever we have been able to choose a valid color for the *n*th country, the current contents of the path is the desired list of colors for the *n* countries of the map. Nothing could be simpler. For this problem, let us call the path list COLOR, since it is more suggestive of our desired objective.

Figure 6·24 shows a flowchart algorithm incorporating the foregoing concepts and details and following the identical top-down structure given in the generalized search (Figure 6·16). It will be easy to verify the claimed similarity. If you have any difficulty in following Figure 6·24, remember that boxes with corresponding numbers in the generalized flowchart have similar meanings. Only Figure 6·24f, the detail of the admissibility test in box 2.3.2, is really new.

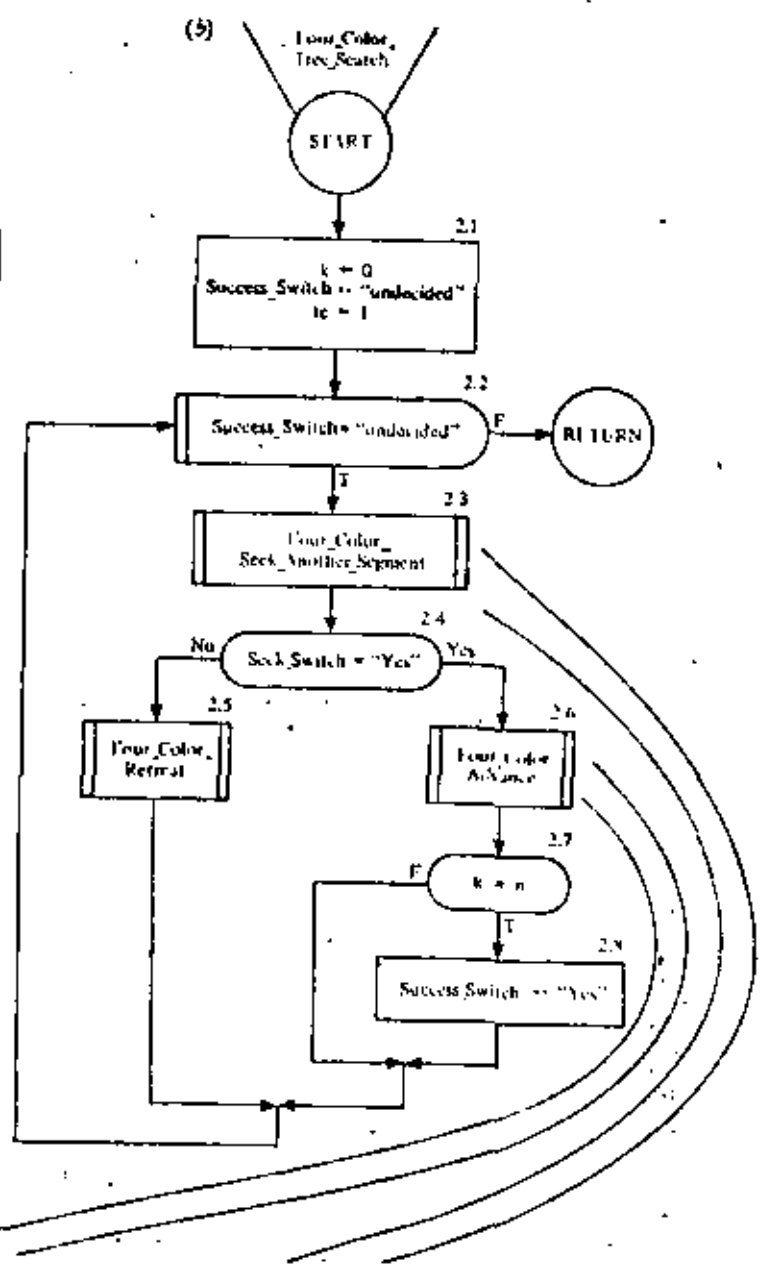
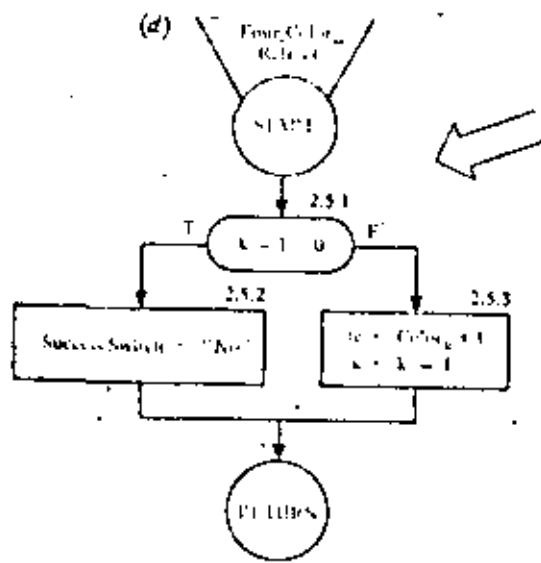
### Discussion

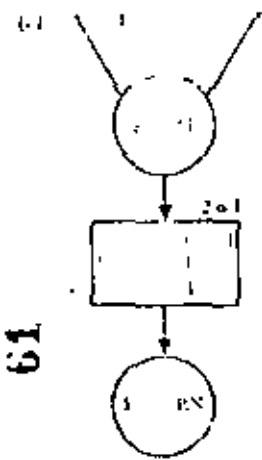
Box 1 of Figure 6·24 is a counterpart to box 1 of Figure 6·16. In the detailed algorithm we must input the data explicitly to represent the map if we are going to deduce the actual structure of the tree. In Figure 6·24b, to keep track of what tree level has been reached, a level or path length counter *k* is needed. This counter is initially set to 0 in box 2.1 to reflect the start of the search at the root node. [The algorithm could be made more efficient by initializing the level counter to 3 and path to (1, 2, 3) to reflect coloring the first three countries with the first three colors, as suggested in Figure 6·21.]

Success\_Switch is a three-valued switch variable that is initially set to "undecided" (at box 2.1), and then is set to either "Yes" if the tree search succeeds or to "No" if the search fails. To see why or where this switch is set to either "Yes" or to "No," you may have to descend to the next levels of detail. Thus, whenever we discover that the search is about to backtrack to level zero, the search has failed (boxes 2.5.1 and 2.5.2 of Retreat). If  $k - 1 = 0$  in box 2.5.1, the current node is at level 1. In other words we have backtracked to the first country. The first country was colored with color 1 at the beginning of the search. We have not tested colors 2, 3, or 4 on country 1. Should we? Not really, because we know that any coloring we find will simply be a renaming of a previous coloring (if any) when country 1 had color 1. We won't find



60





6.1

Legend

Variable	Description
$n$	Number of countries
$w$	A list of $n$ integers
CONN	An $n$ row reduced connection matrix (The $k$ th row of CONN has $w_k$ elements)
Color	The path list of the current node
$k$	Level counter, i.e., number of elements in path list
$tc$	Tentative color for the next country

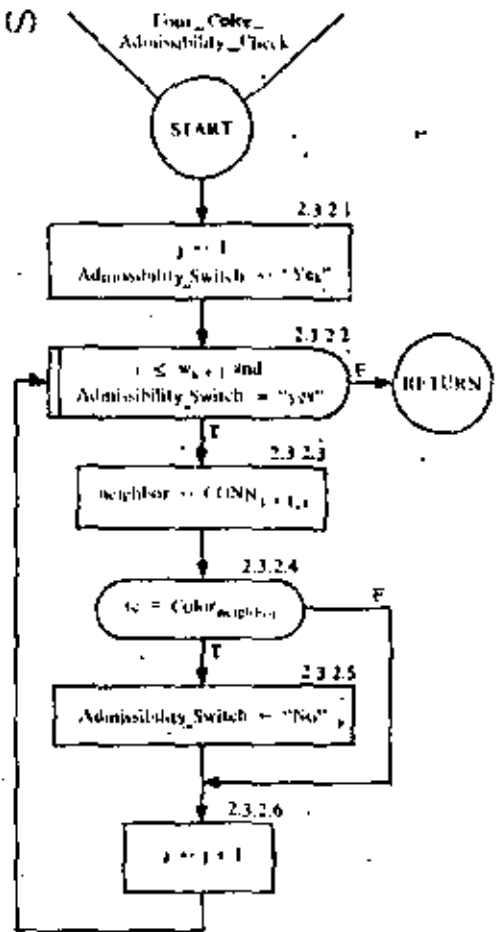
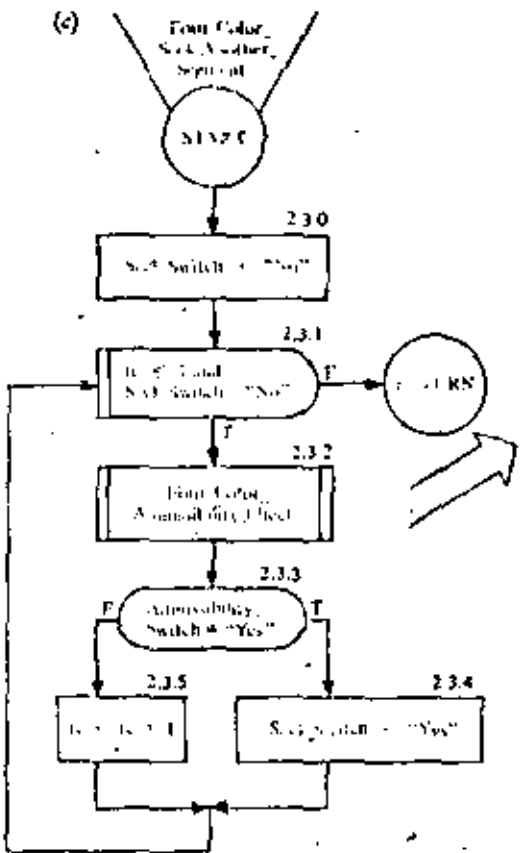
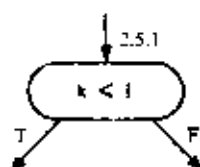


FIGURE 6.24  
Four-coloring algorithm.  
Top-down approach.

any new patterns. If we want to search the complete tree, however, including the four possible colors for the first country, we have only to change the test in box 2.5.1 to read



Whenever the level counter  $k$  is found to equal  $n$  (boxes 2.7 and 2.8 of *Tree\_Search*), *Success\_Switch* is set to "Yes." The variable *Seek\_Switch* tested by *Tree\_Search* in box 2.4 is set to either "Yes" or "No" by *Seek\_Another\_Segment* (Figure 6-24c). This procedure in turn reports success if and only if the subprocedure *Admissibility\_Check* reports success. This latter procedure (Figure 6-24f) determines whether any of the previously colored neighbors (there are  $w_{k+1}$  of them) have the same color as the tentative color,  $tc$ , that is being considered for the  $k + 1$ st country. If so, *Admissibility\_Switch* is set to "No" so that, after the RETURN to *Seek\_Another\_Segment*, another (the next) color may be tried. Notice that only in *Admissibility\_Check* is there any reference to the map's representation. This suggests that detailed flowcharts for different natural-order tree search problems will differ mainly in the details of this particular part of the search algorithm.

The bookkeeping of *Retreat* and *Advance* in Figure 6-24 uses auxiliary variable,  $tc$ , tentative color. This variable is also used in *Seek\_Another\_Segment* during the search for an admissible segment and, in box 2.3.5,  $tc$  is incremented whenever an inadmissible segment is found. In *Advance*,  $k$  is incremented to represent the longer successful coloring path. The successful tentative color is stowed away in  $Color_k$ , and the auxiliary variable  $tc$  is reset to 1. (See box 2.6.1.) During *Retreat* the current color choice for country  $k$  must be remembered so that the search for another segment of country  $k$ 's parent can resume at a value of  $tc$  that is one greater than the last one tried. The saving of this information is accomplished by the assignment step,

$$tc \leftarrow Color_k + 1$$

as seen in box 2.5.3. Then the path length  $k$  is shortened by 1.



**DIVISION DE EDUCACION CONTINUA  
FACULTAD DE INGENIERIA U.N.A.M.**

INTRODUCCION A LA PROGRAMACION Y COMPUTACION ELECTRONICA

M A T R I C E S

APLICACIONES NO MATEMATICAS

OCTUBRE, 1981

## INVERSO DE UNA MATRIZ.

NUM. REALES:  $a \neq 0$      $a \cdot b = b \cdot a = 1$      $b = a^{-1} = \frac{1}{a}$   
 $8 \cdot b = b \cdot 8 = 1 \Rightarrow b = \frac{1}{8} = .125$

MATRICES:  $A \cdot B = I$ ,  $B \cdot A = I$   
 $A \cdot B = B \cdot A = I \Rightarrow A$  cuadrada.

$$B = A^{-1}$$

INVERSA MULTIPLICATIVA

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$

$$B = \begin{bmatrix} -2 & 1 \\ 3/2 & -1/2 \end{bmatrix}$$

$$A \cdot B = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} -2 & 1 \\ 3/2 & -1/2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I_2 = B^{-1} \cdot A$$

$$A = B^{-1}$$

$$B = A^{-1}$$

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$

$$B = ? = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$AB = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a+2c & b+2d \\ a+4c & 3b+4d \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\left\{ \begin{array}{l} a+2c=1 \\ 3a+4c=0 \\ b+2d=0 \\ 3b+4d=1 \end{array} \right\} \rightarrow \begin{array}{l} a = 1-2c \\ 3(1-2c)+4c=0, -2c=-3 \\ c = \\ a = 1-2 \cdot \frac{3}{2} \end{array}$$

$$A = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}; A^{-1} = ?$$

$$AA^{-1} = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} c & d \\ c & d \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$c=1, c=0 \quad d=0, d=1$$

$\therefore A^{-1}$  no existe

MATRICES CUADRADAS SIN INVERSO: SINGULARES.

MATRICES CUADRADAS CON INVERSO: NO SINGULARES.  
O' REGULARES.

PROPIEDADES:

1) CONMUTATIVIDAD:  $A \cdot A^{-1} = A^{-1} \cdot A = I$

2) UNICIDAD

3)  $(A^{-1})^{-1} = A$

4)  $(A \cdot B)^{-1} = B^{-1} \cdot A^{-1}$  (ANALOGA  $(AB)' = B' \cdot A'$ )

DEM.  $(B^{-1} \cdot A^{-1})(AB) = B^{-1} \underbrace{A^{-1} \cdot A}_I \cdot B = B^{-1} \underbrace{B}_I = I$

$\therefore (AB)^{-1} = B^{-1} \cdot A^{-1}$

5)  $(A')^{-1} = (A^{-1})'$

UTILIDAD DEL INVERSO:  $A \underline{x} = \underline{b}$   
 $\underline{x} = A^{-1} \underline{b}$

$$\begin{cases} x_1 + 2x_2 = 4 \\ 3x_1 + 4x_2 = -2 \end{cases}$$

$$\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 4 \\ -2 \end{pmatrix}$$

$$\boxed{A \underline{x} = \underline{b}}$$

?

$$\underline{x} = A^{-1} \underline{b}$$

$$A^{-1} = \begin{pmatrix} -2 & 1 \\ 3/2 & -1/2 \end{pmatrix}, \quad \underline{x} = \begin{pmatrix} -2 & 1 \\ 3/2 & -1/2 \end{pmatrix} \begin{pmatrix} 4 \\ -2 \end{pmatrix} = \begin{pmatrix} -10 \\ 7 \end{pmatrix}$$

$\begin{matrix} \nearrow x_1 \\ \searrow x_2 \end{matrix}$

---


$$\underline{Ax} = \underline{b}$$

varias diferentes, invertir A

---

A VECES, LAS COMPONENTES DE  $A^{-1}$  TIENEN INTERPRETACION ESPECIAL.

AJUSTE POR MINIMOS CUADRADOS:

$A^{-1}$ : COMPONENTES  $\rightarrow$  CLASE Y MAGNITUD DE ERRORES, EN LOS DATOS.



MÉTODOS:  $\left\{ \begin{array}{l} \text{ALGEBRAICOS (EXACTOS)} \\ \text{NUMÉRICOS (APROXIMACIONES} \\ \text{SUCCESIVAS)} \end{array} \right.$

ALGEBRAICOSADJUNTA

$$A^{-1} = \frac{ac - b \Delta}{|\Delta|}$$

$$A = \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$$

$$\begin{pmatrix} + \begin{vmatrix} e & f \\ h & i \end{vmatrix} & - \begin{vmatrix} d & f \\ g & i \end{vmatrix} & + \begin{vmatrix} d & e \\ g & i \end{vmatrix} \\ - \begin{vmatrix} b & c \\ h & i \end{vmatrix} & + \begin{vmatrix} a & c \\ g & i \end{vmatrix} & - \begin{vmatrix} a & b \\ g & h \end{vmatrix} \\ + \begin{vmatrix} b & c \\ e & f \end{vmatrix} & - \begin{vmatrix} a & d \\ d & f \end{vmatrix} & + \begin{vmatrix} a & b \\ d & e \end{vmatrix} \end{pmatrix}^T$$

$$|A| = \begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = a \begin{vmatrix} e & f \\ h & i \end{vmatrix} - b \begin{vmatrix} d & f \\ g & i \end{vmatrix} + c \begin{vmatrix} d & e \\ g & h \end{vmatrix}$$

$$= a(ei - fh) - b(di - fg) + c(dh - eg)$$

## INVERSION POR PARTICIPACION

$$A = \left( \begin{array}{c|c} \Delta_1 & \Delta_2 \\ \hline \Delta_3 & \Delta_4 \end{array} \right) \quad A^{-1} = B = \left( \begin{array}{c|c} B_1 & B_2 \\ \hline B_3 & B_4 \end{array} \right)$$

$$A A^{-1} = A B = \left( \begin{array}{c|c} \Delta_1 & \Delta_2 \\ \hline \Delta_3 & \Delta_4 \end{array} \right) \left( \begin{array}{c|c} B_1 & B_2 \\ \hline B_3 & B_4 \end{array} \right) = I = \left( \begin{array}{c|c} I & O \\ \hline O & I \end{array} \right)$$

$$\left( \begin{array}{cc|cc} \Delta_1 B_1 + \Delta_2 B_3 & \Delta_1 B_2 + \Delta_2 B_4 & & \\ \Delta_3 B_1 + \Delta_4 B_3 & \Delta_3 B_2 + \Delta_4 B_4 & & \\ \hline & & I & O \\ & & O & I \end{array} \right)$$

$$A^{-1} = B = \left( \begin{array}{c|c} \Delta^{-1} (I - \Delta_3 B_3) & -\Delta_1^{-1} \Delta_2 B_4 \\ \hline -B_4 \Delta_3 \Delta^{-1} & (\Delta_4 - \Delta_3 \Delta_1^{-1} \Delta_2)^{-1} \end{array} \right)$$

INVERTIR,  $\Delta^{-1}$  Y  $(\Delta_4 - \Delta_3 \Delta_1^{-1} \Delta_2)^{-1}$

DE ORDENES MENORES QUE  $\Delta$

SOL. NUMERICA  
SIST. ECS

- SOL. NUM. ECS. DIFS. OR. DINARIAS Y PARCIALES.
- ANALISIS ESTRUCTURAL.
- ANALISIS DE REDES
- OPTIMIZACION.
- ANALISIS DE DATOS

$$A\bar{x} = \bar{b}$$

POR REGLA DE CRAMER:

NUMERO OPERACIONES  $\sim n^4$   
IMPRACTICO

POR INVERSION DE MATRICES:

CUANDO HAY MUCHAS  $\bar{b}$  DIFERENTES.

MATRIZ SIST. ECS.  $\left\{ \begin{array}{l} \text{LLENA} \\ \text{MUCHOS CEROS} \end{array} \right.$

METODOS DE SOL:  $\left\{ \begin{array}{l} \text{DIRECTOS} \\ \text{ITERATIVOS.} \end{array} \right.$

# SOLUCION SISTEMA DE ECUACIONES 16

$$A = \begin{pmatrix} 6 & 2 \\ 2 & 1 \end{pmatrix}$$

$$AB = I$$

$$\begin{pmatrix} 6 & 2 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\begin{cases} 6a + 2c = 1 \\ 2a + c = 0 \\ 6b + 2d = 0 \\ 2b + d = 1 \end{cases}$$

$$a = 0.5$$

$$c = -1$$

$$b = -1$$

$$d = 3$$

$$\begin{pmatrix} 6 & 2 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} a \\ c \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 6 & 2 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} b \\ d \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

A DE  $3 \times 3$

$$A^{-1} = B = \begin{pmatrix} b_{11} & b_{12} & b_{13} \\ b_{21} & b_{22} & b_{23} \\ b_{31} & b_{32} & b_{33} \end{pmatrix}$$

HAY QUE RESOLVER

$$A \begin{pmatrix} b_{11} \\ b_{21} \\ b_{31} \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad A \begin{pmatrix} b_{12} \\ b_{22} \\ b_{32} \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \quad A \begin{pmatrix} b_{13} \\ b_{23} \\ b_{33} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

# DIAGONALIZACION (GAUSS-JORDAN)

70

$$[A \mid I]$$

$$\downarrow$$
$$[I \mid A^{-1}]$$

$$\left[ \begin{array}{cccc|cccc} a_{11} & a_{12} & \dots & a_{1n} & 1 & 0 & \dots & 0 \\ a_{21} & a_{22} & \dots & a_{2n} & 0 & 1 & \dots & 0 \\ \vdots & \vdots & & \vdots & \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} & 0 & 0 & \dots & 1 \end{array} \right]$$

$$\downarrow$$
$$\left[ \begin{array}{cccc|cccc} 1 & 0 & \dots & 0 & b_{11} & b_{12} & \dots & b_{1n} \\ 0 & 1 & \dots & 0 & b_{21} & b_{22} & \dots & b_{2n} \\ \vdots & \vdots & & \vdots & \vdots & \vdots & & \vdots \\ 0 & 0 & \dots & 1 & b_{n1} & b_{n2} & \dots & b_{nn} \end{array} \right]$$

POR OPERACIONES ELEMENTALES DE  
RENGLON:

- 1) INTERCAMBIO DE RENGLONES.
- 2) MULTIPLICAR UN RENGLON POR UN ESCALAR.
- 3) MULTIPLICAR UN RENGLON POR UN ESCALAR Y SUMARLO A OTRO RENGLON.

ESCOGER PIVOTE :



PIVOTEO PARCIAL.



PIVOTEO TOTAL.

# OPERACIONES GAUSS - JORDAN :  $O(n^3)$   
CRAMER :  $O(n^4)$

MATRICES DE BANDA :



$O(n)$

ALMACENAMIENTO MAT. LENA :  $n^2 + 2n$   
MAT. BANDA :  $5n$

GAUSS - SEIDEL

$|x_i^{(k-1)} - x_i^{(k)}| \leq \epsilon$  : CRITERIO ABSOLUTO CONVER.

$\left| \frac{x_i^{(k-1)} - x_i^{(k)}}{x_i^{(k)}} \right| \leq \epsilon$  : CRITERIO RELATIVO CONVER.

CONV. GARANTIZADA SOLO SI :  $|c_{ii}| > \sum_{j=1, j \neq i}^n |c_{ij}|$   
(DIAGONALMENTE DOMINANTE)

## POTENCIAS DE UNA MATRIZ

$$A^n = A \cdot A \cdots A$$

(n FACTORES)

$$A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}, \quad A^2 = A \cdot A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} = \begin{pmatrix} 7 & 10 \\ 15 & 22 \end{pmatrix}$$

$$A^0 = I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad (a^0 = 1)$$

$$A^{-1} = \begin{pmatrix} -2 & 1 \\ 3/2 & -1/2 \end{pmatrix}$$

$$A^{-2} = (A^{-1})^2 = \begin{pmatrix} -2 & 1 \\ 3/2 & -1/2 \end{pmatrix} \begin{pmatrix} -2 & 1 \\ 3/2 & -1/2 \end{pmatrix} =$$

## PROPIEDADES DE MATRICES

1) NUMEROS REALES...:  $ab = 0 \Rightarrow \begin{cases} a = 0 \\ b = 0 \end{cases}$

MATRICES:  $AB = 0 \Rightarrow \begin{cases} A = 0 \\ B = 0 \end{cases}$

$$\begin{pmatrix} 1 & -1 \\ 7 & -7 \end{pmatrix} \begin{pmatrix} 2 & 2 \\ 2 & 2 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\neq 0 \quad \neq 0$$

$$2) \quad ab = ac \quad \Rightarrow \quad b = c$$

$$AB = AC \quad \not\Rightarrow \quad B = C$$

$$\begin{pmatrix} 1 & 2 \\ 2 & 4 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} = \begin{pmatrix} 7 & 10 \\ 14 & 20 \end{pmatrix}$$

$$\parallel \quad \# \quad \parallel$$

$$\begin{pmatrix} 1 & 2 \\ 2 & 4 \end{pmatrix} \begin{pmatrix} -3 & -2 \\ 5 & 6 \end{pmatrix} = \begin{pmatrix} 7 & 10 \\ 14 & 20 \end{pmatrix}$$

$$3) \quad ab = ba$$

$$AB \neq BA \quad \text{EN GENERAL}$$

$$4) \quad ab = 1 \quad \Rightarrow \quad b = \frac{1}{a} = a^{-1}$$

$$AB = I \quad B = A^{-1} \quad \text{NO SIEMPRE EXISTE}$$

$$5) \quad \text{NO EXISTE TRANSPUESTO DE NUMERO REAL}$$

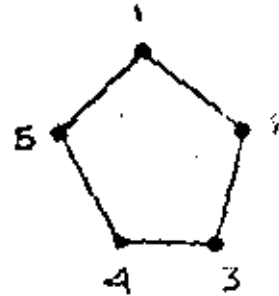
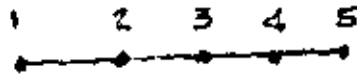
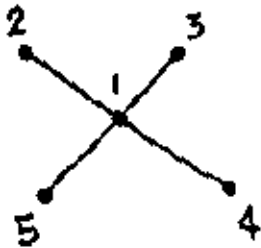
$$A \quad A' \quad (A')' = A$$



# APLICACIONES DE MATRICES

1-) TEORIA DE REDES.

GRAFICAS QUIMICAS O ESTRUCTURALES.



ENLACE : 1  
NO ENLACE : 0

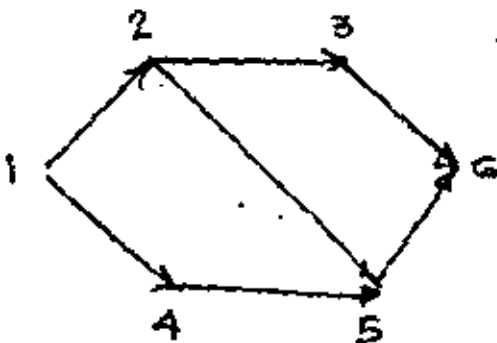
MATRIZ DE INCIDENCIA.

$$\begin{bmatrix} 0 & 1 & 1 & 1 & 1 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$

RUTA CRITICA.



$$\begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \end{bmatrix}$$



$$P_x n_{xk} = n_{x+1, k+1} \quad x = 0, 1, \dots, m-1$$

TRANSICION DE LA POBLACION DE  $t=0$  A  $t = \Delta t$

$$\begin{pmatrix} F_0 & F_1 & \dots & F_{m-1} & F_m \\ P_0 & 0 & \dots & 0 & 0 \\ 0 & P_1 & \dots & 0 & 0 \\ \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & P_{m-1} & 0 \end{pmatrix} \begin{pmatrix} n_{00} \\ n_{10} \\ n_{20} \\ \dots \\ n_{m0} \end{pmatrix} = \begin{pmatrix} n_{01} \\ n_{11} \\ n_{21} \\ \dots \\ n_{m1} \end{pmatrix}$$

o SEA :

$$\boxed{M \underline{n}_0 = \underline{n}_1}$$

$$M \underline{n}_1 = \underline{n}_2, \quad \underline{n}_2 = M \underline{n}_1 = M(M \underline{n}_0) = M^2 \underline{n}_0$$

$$M \underline{n}_2 = \underline{n}_3, \quad \underline{n}_3 = M \underline{n}_2 = M(M \underline{n}_0) = M^3 \underline{n}_0$$

$$\boxed{M \underline{n}_{k-1} = \underline{n}_k}$$

$$\boxed{\underline{n}_k = M^k \underline{n}_0}$$

$M =$  MATRIZ DE PROYECCION.

$$\underline{n}_k = M \underline{n}_{k-1} \quad \underline{n}_{-k} = M^k \underline{n}_0$$

- 1) DADA UNA POBLACION INICIAL Y SU DISTRIBUCION ( $\underline{n}_0$ ), Y DADA M:

SE PUEDE CALCULAR POBLACION FUTURA Y SU DISTRIBUCION.

- 2) DADA UNA POBLACION INICIAL Y SU DISTRIBUCION, ¿QUE PROPIEDAD DEBE TENER M PARA TENER POBLACION ESTABLE ( $\underline{n}_0 = \underline{n}_1 = \underline{n}_2 \dots$ )?

$$\underline{n}_k = M \underline{n}_{k-1}$$

$$\underline{0} = (M - I) \underline{n}_k$$

$$\Rightarrow |M - I| = 0$$

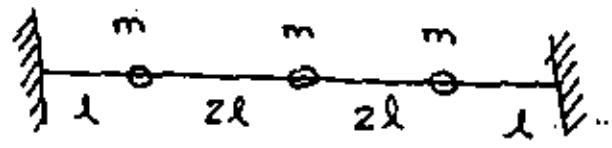
$$F_0 + F_1 P_0 + F_2 P_0 P_1 + \dots + F_m P_0 P_1 \dots P_{m-1} = 1$$

- 3) DADA UNA POBLACION INICIAL Y SU DISTRIBUCION DE EDADES ESTABLE, ¿CUAL ES LA POBLACION?

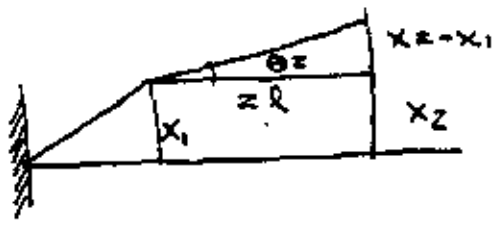
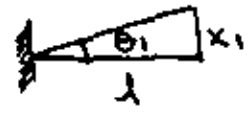
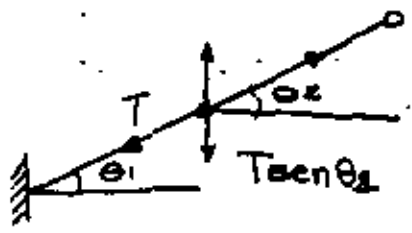
$$\underline{n}_{k+1} = \lambda \underline{n}_k$$

$$M \underline{n}_k = \lambda \underline{n}_k$$

VALORES Y VECTORES CARACTERISTICOS.



$T \text{ sen } \theta_2$



$$T \text{ sen } \theta_1 \approx T \frac{x_1}{l}$$

$$T \text{ sen } \theta_2 \approx T \frac{x_2 - x_1}{2l}$$

$$F = m a = m \frac{d^2 x}{dt^2}$$

$$m \frac{d^2 x_1}{dt^2} = T \frac{(x_2 - x_1)}{2l} - T \frac{x_1}{l}$$

$$m \frac{d^2 x_2}{dt^2} = -T \frac{(x_2 - x_1)}{2l} + T \frac{(x_3 - x_2)}{2l}$$

$$m \frac{d^2 x_3}{dt^2} = -T \frac{(x_3 - x_2)}{2l} - T \frac{x_3}{l}$$

(15)

$$\boxed{X_i = X_i e^{i\omega t}}$$

$$\lambda = \omega^2 ml/T$$

$$\begin{cases} (3-\lambda)x_1 - x_2 = 0 \\ -x_1 + (2-\lambda)x_2 - x_3 = 0 \\ -x_3 + (3-\lambda)x_3 = 0 \end{cases}$$

$$\begin{pmatrix} 3 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \lambda \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

$$\underline{A} \underline{x} = \lambda \underline{x}$$

$$(A - \lambda I) \underline{x} = 0$$

$$\exists \underline{x} \Rightarrow |A - \lambda I| = 0$$

$$\begin{vmatrix} 3-\lambda & -1 & 0 \\ -1 & 2-\lambda & -1 \\ 0 & -1 & 3-\lambda \end{vmatrix} = 0$$

$$(1-\lambda)(3-\lambda)(4-\lambda) = 0$$

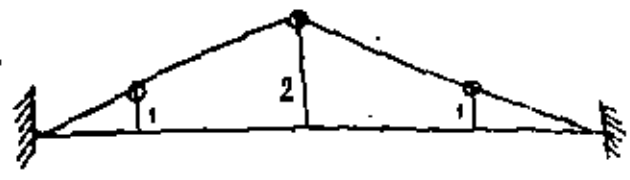
1)  $\lambda_1 = 1$

$$\begin{cases} 2X_1 - X_2 = 0 \\ -X_1 - X_2 - X_3 = 0 \\ -X_2 + 2X_3 = 0 \end{cases}$$

$X_1 = \frac{X_2}{2} = X_3$

$\underline{x} = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$

MODO DE VIBRACION.

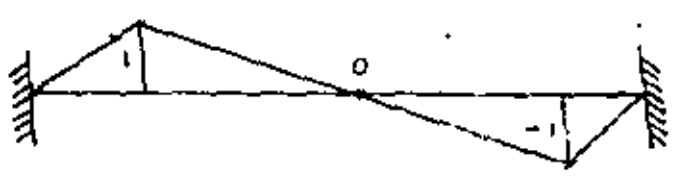


$$W^2 = \frac{\lambda T}{2ml} = \frac{T}{2ml}$$

FRECUENCIA ANGULAR DE VIBRACION.

2:)  $\lambda_2 = 3$

$\underline{x} = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$



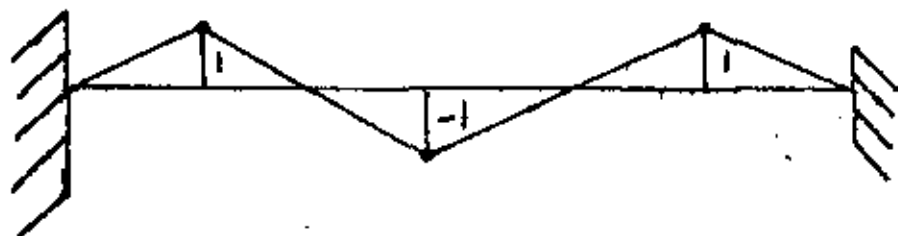
$$W^2 = \frac{3T}{2ml}$$

$$3) \lambda = 4,$$

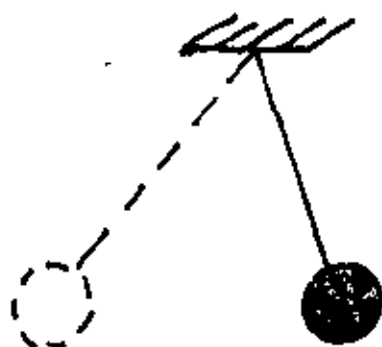
$$\underline{x} = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

$$\omega^2 = \frac{4T}{2m}$$

(17)



## RESONANCIA



## FUENTE DE TACOMA



7 NOV 1940, 4 MESES DE INKUGUREDO

VIENTO 67 Km/h

12 m x 853 m.

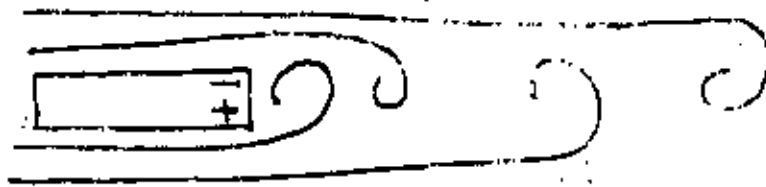
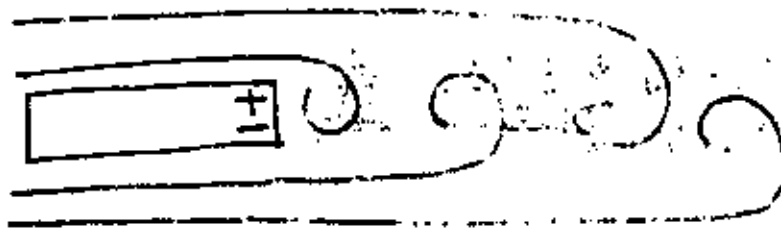
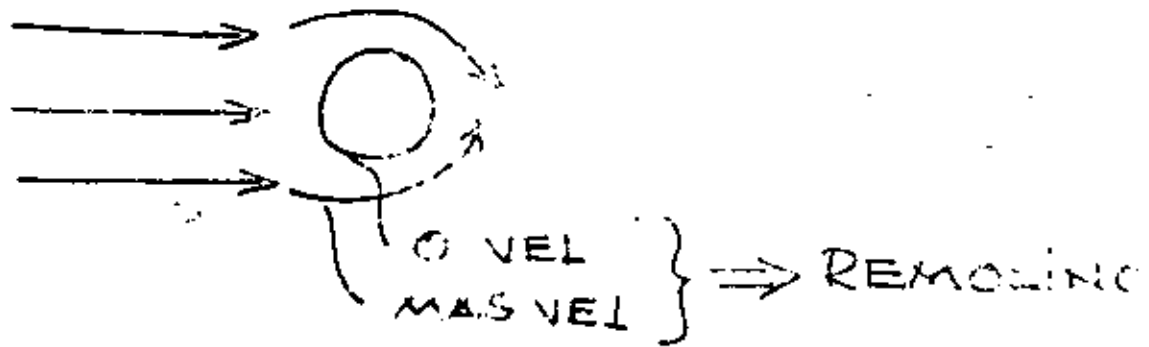
OSCILACIONES TORSIONALES

IMPULSO INVESTIGACION AERODINAMICA



# FLUIDO CON OBSTÁCULO: VORTICES DE VON KÁRMÁN 18

## DE VON KÁRMÁN



VORTICES DE VON KÁRMÁN:  
ALTERNADOS EN TIEMPO Y ESPACIO.

- RUGOSIDAD MEDIO
- FORMA
- VELOCIDAD FLUIDO

PROBLEMA: SI LA FRECUENCIA DE LOS VORTICES DE VON KÁRMÁN COINCIDE CON FRECUENCIA NATURAL DE OSCILACION TORSIONAL DEL PUENTE.

# THEODORE VON KÁRMÁN (1881-1963) (13)

PIONERO, USO MATEMÁTICAS EN CIENCIAS BÁSICAS (AERONÁUTICA, ASTRONÁUTICA)

1911: ANÁLISIS DE LOS VORTICES.

---

$$A\underline{x} = \lambda\underline{x}$$

SOLUCION  $\left\{ \begin{array}{l} \underline{x} = 0 \quad \text{TRIVIAL} \\ \underline{x} \neq 0 \iff |A - \lambda I| = 0 \end{array} \right.$

---

$$A\underline{x} = \lambda\underline{x}$$

$A; n \times n$

$$A\underline{x} = \lambda I \underline{x}$$

$$(A - \lambda I)\underline{x} = \underline{0}$$

$$\implies |A - \lambda I| = 0 \quad \text{ECUACION CARACTERISTICA}$$

$$P(\lambda) = |A - \lambda I| = \text{POLINOMIO CARACTERISTICO}$$

POLINOMIO EN  $\lambda$  DE GRADO  $n$

RAICES:  $\lambda_1, \lambda_2, \dots, \lambda_n$  EIGEN VALORES

$$|A - \lambda I| = 0$$

VALORES PROPIOS

VALORES CARACTERISTICOS

$$\lambda_i \longrightarrow c \underline{x}_i$$

$x_i$  : EIGENVECTOR  
VECTOR CARACTERISTICO  
VECTOR PROPIO

CORRESPONDIENTE A  $\lambda_i$

$x_i$  SE OBTIENE SUSTITUYENDO EN

$$(A - \lambda I) \underline{x} = 0$$

CON:  $\lambda = \lambda_i$

**EJEMPLO**

$$A = \begin{pmatrix} 3 & -1 \\ 4 & -2 \end{pmatrix}$$

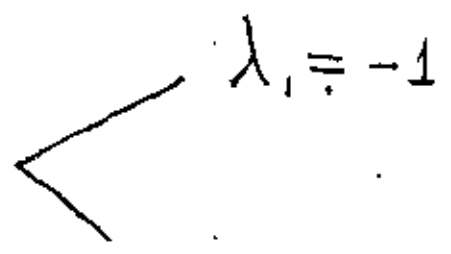
$$|A - \lambda I| = 0$$

$$\begin{vmatrix} 3-\lambda & -1 \\ 4 & -2-\lambda \end{vmatrix} = 0$$

$$(3-\lambda)(-2-\lambda) + 4 = 0$$

$$\lambda^2 - \lambda - 2 = 0$$

$$\lambda = \frac{+1 \pm \sqrt{1 - 4(-2)}}{2} = \frac{+1 \pm 3}{2}$$



$$\lambda_1 = -1$$

$$(A - \lambda I) \underline{x} = \underline{0}$$

$$\begin{cases} (3 - \lambda)x_1 - x_2 = 0 \\ 4x_1 - (2 + \lambda)x_2 = 0 \end{cases}$$

$$1) \lambda_1 = -1$$

$$\begin{cases} 4x_1 - x_2 = 0 \\ 4x_1 - x_2 = 0 \end{cases}$$

$$\therefore x_2 = 4x_1$$

$$\underline{x}_1 = \begin{pmatrix} x_1 \\ 4x_1 \end{pmatrix} = x_1 \begin{pmatrix} 1 \\ 4 \end{pmatrix}$$

$$\underline{x}_1 = \begin{pmatrix} 1 \\ 4 \end{pmatrix}$$

$$2) \lambda_2 = 2$$

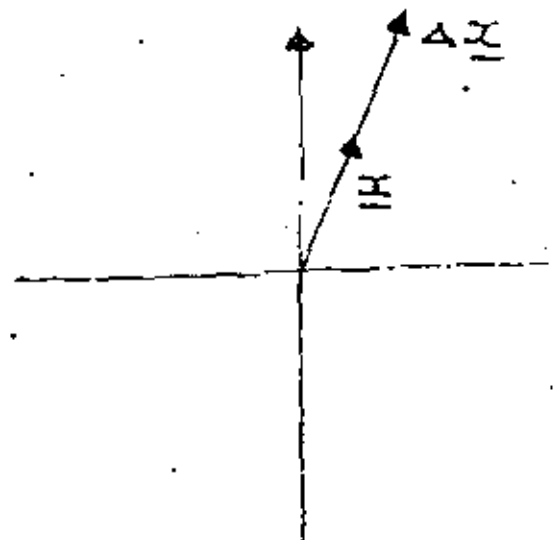
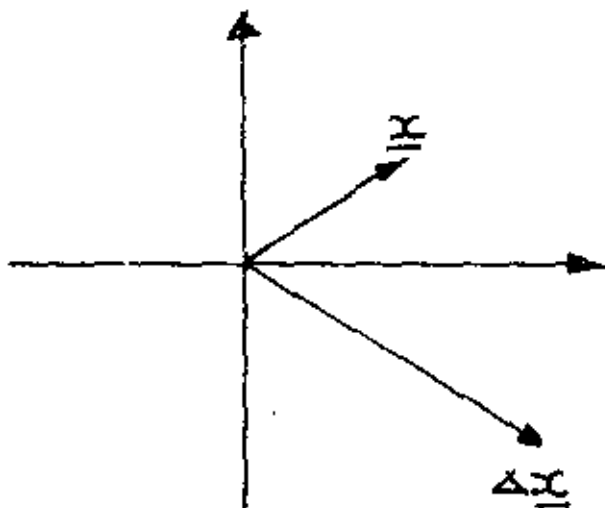
$$\begin{cases} x_1 - x_2 = 0 \\ 4x_1 - 4x_2 = 0 \end{cases}$$

$$\therefore x_2 = x_1$$

$$\underline{x}_2 = \begin{pmatrix} x_1 \\ x_1 \end{pmatrix} = x_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\underline{x}_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

## INTERPRETACION GEOMETRICA



$$\Delta x = \lambda x$$

# OBTENCION DE LOS VALORES CARACTERISTICOS

## METODO DE KRYLOV

$$\left. \begin{array}{l} |A - \lambda I| = 0 \\ P(\lambda) = 0 \end{array} \right\} \text{ ECUACION CARACTERISTICA}$$

1° OBTENER NUMERICAMENTE LOS COEFICIENTES  $C_i$  DEL POLINOMIO CARACTERISTICO.

$$P(\lambda) = \lambda^n + C_{n-1}\lambda^{n-1} + \dots + C_1\lambda + C_0$$

2° OBTENER NUMERICAMENTE LOS VALORES CARACTERISTICOS  $\lambda_i$ , QUE SON LAS RAICES DE LA ECUACION CARACTERISTICA

$$P(\lambda) = 0$$

$$\lambda^n + C_{n-1}\lambda^{n-1} + \dots + C_1\lambda + C_0 = 0$$

1° OBTENER COEFICIENTES  $C_i$

TEOREMA DE CAYLEY - HAMILTON:

$$\text{SI } P(\lambda) = 0 \Rightarrow P(A) = 0$$

$$P(A) = 0$$

$$A^n + C_{n-1}A^{n-1} + \dots + C_1A + C_0 = 0$$

POSTMULTIPLICANDO POR UN VECTOR ARBITRARIO  $\underline{y}$  CONOCIDO,  $\underline{y} \neq \underline{0}$ :

$$A^n \underline{y} + C_{n-1}A^{n-1} \underline{y} + \dots + C_1A \underline{y} + C_0 \underline{y} = \underline{0}$$

REPRESENTA UN SISTEMA DE ECUACIONES CON INCOGNITAS  $C_{n-1}, \dots, C_1, C_0$

SE RESUELVE EL SISTEMA DE ECS. Y SE DETERMINAN LAS  $C_i$

EJEMPLO:

$$A = \begin{pmatrix} 3 & -1 \\ 4 & -2 \end{pmatrix}$$

EC. CARACT:  $\lambda^2 + C_1\lambda + C_0 = 0$

CAYLEY-HAMILTON:  $A^2 + C_1A + C_0I = 0$

POR  $\underline{y}$ :  $A^2 \underline{y} + C_1A \underline{y} + C_0 \underline{y} = \underline{0}$

$$A^2 = \begin{pmatrix} 3 & -1 \\ 4 & -2 \end{pmatrix} \begin{pmatrix} 3 & -1 \\ 4 & -2 \end{pmatrix} = \begin{pmatrix} 5 & -1 \\ 4 & 0 \end{pmatrix}; \text{ SEA } \underline{y} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

SUST :

$$\begin{pmatrix} 5 & -1 \\ 4 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} + c_1 \begin{pmatrix} 3 & -1 \\ 4 & -3 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} + c_0 \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 3 \\ 4 \end{pmatrix} + c_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_0 \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$c_1 + c_0 = -3$$

$$2c_0 = -4$$

$$c_0 = -2 \quad c_1 = -1$$

ECUACION CARACTERISTICA:

$$\lambda^2 + (-1)\lambda + (-2) = 0$$

SE DEBEN OBTENER NUMERICAMENTE LAS RAICES DE LA ECUACION CARACTERISTICA.

METODO DE APROXIMACIONES SUCESIVAS

MAYOR O MENOR EIGENVALOR Y EIGENVECTOR CORRESPONDIENTE.

$$A \underline{x}_1 = \lambda_1 \underline{x}_1$$

NUEVA APROXIMACION A EIGENVECTOR.

1ª APROXIMACION A

APROXIMADO:

$$\underline{x}_0 \approx \underline{x}$$

$$A \underline{x}_0 = \lambda_1 \underline{x}_1$$

$$A \underline{x}_1 = \lambda_2 \underline{x}_2$$

⋮

$$A \underline{x}_n = \lambda_{n+1} \underline{x}_{n+1}$$

ALTO: SI  $|\lambda_{n+1} - \lambda_n| < \epsilon$

---

MENOR EIGENVALOR.

$$A \underline{x} = \lambda \underline{x}$$

$A^{-1}$

$$A^{-1} A \underline{x} = A^{-1} \lambda \underline{x}$$

$$\underline{x} = \lambda A^{-1} \underline{x}$$

$$A^{-1} \underline{x} = \frac{1}{\lambda} \underline{x}$$

$$A^{-1} \underline{x} = \lambda^* \underline{x}$$

MAYOR  $\lambda \longrightarrow$  MENOR  $\lambda$

$$\lambda^* = \frac{1}{\lambda}$$





**DIVISION DE EDUCACION CONTINUA  
FACULTAD DE INGENIERIA U.N.A.M.**

**INTRODUCCION A LA PROGRAMACION Y COMPUTACION ELECTRONICA**

**PROGRAMACION LINEAL SIMPLEX, EL PROBLEMA DE TRANSPORTE  
UN CASO DE APLICACION**

**OCTUBRE, 1981**

## 14. PROGRAMACION LINEAL

## 1

## 14.1.-Introducción

En diversas situaciones para la toma de decisiones relacionadas con el uso eficiente de una serie de recursos o asignación óptima de recursos limitados, es necesario construir un modelo matemático. Si dicho modelo matemático se puede expresar como un sistema de desigualdades lineales, dadas por las restricciones en la disponibilidad de los recursos, y una función que representa la meta u objetivo a alcanzar, también de tipo lineal, se dice que se trata de un problema de programación lineal. La función objetivo generalmente representa costos o utilidades.

En términos generales el sistema de desigualdades lineales tendrá más variables o incógnitas que desigualdades, para su solución se requerirá convertir el sistema de desigualdades en ecuaciones pero el sistema será de tipo indeterminado, sin embargo, la combinación de las restricciones con la función objetivo transforma el sistema determinado en un sistema determinado que tendrá solución única y además dicha solución optimizará la función objetivo.

El propósito de la programación lineal es encontrar dicha solución óptima. De los métodos existentes probablemente el más empleado sea el método Simplex de Dantzig.

La estructura general de un problema de programación lineal es:

$$\begin{array}{l} \max \\ \delta \\ \min \end{array} z = \sum_{i=1}^n c_i x_i \quad (14.1)$$

sujeta a:

$$x_i \geq 0, \quad i=1, \dots, n$$

$$\sum_{i=1}^n A_{ki} x_i \leq B_k, \quad k=1, \dots, b$$

(14.2)

$$\begin{array}{l}
 2 \\
 \left. \begin{array}{l}
 \sum_{i=1}^n A_{ki} X_i \geq B_k, \quad k=g+1, \dots, g \\
 \sum_{i=1}^n A_{ki} X_i = B_k, \quad k=g+1, \dots, m
 \end{array} \right\} \quad (14.2)
 \end{array}$$

donde  $m < n$ ,  $Z$  es la función objetivo a optimizar, a los valores  $C_i$  se les denomina coeficientes de costos, las variables  $X_i$  son las incógnitas del problema, a los coeficientes  $A_{ki}$  se les denomina coeficientes estructurales y a las constantes  $B_k$  se les denomina estipulaciones. Las restricciones del problema están dadas por el sistema de desigualdades (14.2)

Las características que debe reunir un problema de programación lineal son:

- 1) que el modelo sea determinístico,
- 2) variables positivas,
- 3) que el único objetivo sea maximizar o minimizar
- 4) divisibilidad de las variables, es decir, que puedan adquirir valores fraccionarios.

Se denomina solución básica factible del sistema:

$$\sum_{i=1}^l A_{ki} X_i = B_k \quad \dots k=1, \dots, m \quad (14.3)$$

a un conjunto de "m" valores  $X_i$  tal que satisfaga el sistema de ecuaciones (14.3) y que no necesariamente optimiza la función objetivo. A cada una de las "m" variables  $X_i$  se les denomina variables básicas y deberán ser positivas para garantizar una posible solución y evitar que degenera el método a emplear.

Para convertir las desigualdades en igualdades es necesario agregar ciertas variables al sistema como se muestra a continuación.

Sea el sistema de desigualdades:

$$\begin{aligned}
 x_1 + x_2 + 2x_3 &\leq 10 \\
 x_1 - 2x_2 + x_3 &= 5 \\
 x_1 - 3x_3 &\geq 12
 \end{aligned}
 \tag{14.4}$$

considerando que toda  $x_i$  es positiva, la conversión de las desigualdades en igualdades se logrará agregando o restando cantidades positivas como se muestra a continuación:

$$\begin{aligned}
 x_1 + x_2 + 2x_3 + x_4 &= 10 \\
 x_1 - 2x_2 + x_3 + x_6 &= 5 \\
 x_1 - 3x_3 - x_5 + x_7 &= 12
 \end{aligned}
 \tag{14.5}$$

Las variables  $x_1, x_2, x_3$  se conocen como variables estructurales y tienen significado físico; las variables  $x_4$  y  $x_5$  se conocen como variables de holgura, tienen significado físico y sus coeficientes en la función objetivo son nulos; a las variables  $x_6$  y  $x_7$  se les denomina variables artificiales, no tienen significado físico alguno y se agregan para poder formar la primera solución básica del sistema, pero se debe garantizar su exclusión de la solución óptima del sistema. Esto último se logra asignándoles coeficientes de costos  $C_i$  muy negativos cuando se desee maximizar o mucho mayores que cero cuando se desee minimizar.

## 14.2 Método Simplex

### 14.2.1 Objeto

Dado el modelo de programación lineal para un sistema, en la forma:

$$\begin{aligned}
 \max & \\
 \delta & \\
 \min & \\
 s/a &
 \end{aligned}
 \quad
 \begin{aligned}
 z &= \sum_{i=1}^n C_i x_i \\
 \sum_{i=1}^n A_{ki} x_i &\geq B_k, \quad k=1, \dots, m
 \end{aligned}
 \tag{14.6}$$

obtener los valores  $X_i$  que optimizan la función  $Z$  mediante el método Simplex en forma computacional.

#### 14.2.2 Método

Para obtener la solución del modelo (14.6) es necesario convertir las desigualdades en igualdades, o sea, llegar al siguiente sistema de ecuaciones:

$$\begin{array}{l} \max \\ \text{ó} \\ \min \end{array} Z = \sum_{i=1}^l C_i X_i \quad (14.7)$$

s/a

$$\sum_{i=1}^l A_{ki} X_i = B_k, \quad k=1, \dots, m$$

donde las variables  $X_i$  para  $i=n+1, \dots, l$  son variables de holgura y/o artificiales y los coeficientes  $C_i$  desde  $i=n+1, \dots, l$  tienen el siguiente valor:

$$C_i = \begin{cases} 0 & \text{si corresponde a una variable de} \\ & \text{holgura} \\ \gg 0 & \text{si corresponde a una variable arti-} \\ & \text{ficial y se está minimizando } Z \\ \ll 0 & \text{si corresponde a una variable arti-} \\ & \text{ficial y se está maximizando } Z \end{cases}$$

$i=n+1, \dots, l$

A continuación se forma la siguiente tabla, que suele denominarse como TABLEAU:

I		II					
Base C de la base		Sol. básica	$C_1$	$C_2 \dots C_i \dots C_n \dots C_\ell$	$P_1$	$P_2 \dots P_i \dots P_n \dots P_\ell$	
$x_1^*$	$C_1^*$	$B_1^*$	$A_{11}^*$	$A_{12}^* \dots A_{1i}^* \dots A_{1n}^* \dots A_{1\ell}^*$	.	.	
.	.	.	.	.	.	.	
.	.	.	.	.	.	.	
$x_k^*$	$C_k^*$	$B_k^*$	$A_{k1}^*$	$A_{k2}^* \dots A_{ki}^* \dots A_{kn}^* \dots A_{k\ell}^*$	.	.	
..	..	.	.	.	.	.	
.	.	.	.	.	.	.	
$x_m^*$	$C_m^*$	$B_m^*$	$A_{m1}^*$	$A_{m2}^* \dots A_{mi}^* \dots A_{mn}^* \dots A_{m\ell}^*$	.	.	
valor de Z	$Z_0$	$Z_1 - C_1$	$Z_2 - C_2$	$Z_i - C_i$	$Z_n - C_n$	$Z_\ell - C_\ell$	

Fig. 14.1 Tableau para aplicar el Método Simplex computacional

La primera solución básica estará formada por las variables de holgura y variables artificiales que tengan coeficiente unitario positivo, habrá "m" variables que cumplan lo anterior; las variables que no forman parte de la base tienen valor nulo.

El proceso del método Simplex consiste en ir cambiando las variables que pertenecen a la base en forma sistemática hasta optimizar la función objetivo. Para describir el proceso se considerará que se desea  $\min Z$ , lo anterior no origina ninguna restricción puesto que  $\min Z$  equivale a  $\max\{-Z\}$ .

Al seleccionar la primera base o solución factible inicial del sistema, los elementos del Tableau de la fig. 14.1 tendrán el siguiente valor:

$$\begin{aligned} A_{ki}^* &= A_{ki} \\ B_k^* &= B_k \\ Z_i - C_i &= C_i \end{aligned}$$

$$Z_0 = C_1^* B_1^* + \dots + C_m^* B_m^*$$

$x_1^*, \dots, x_m^*$  : variables que forman la primera solución básica

$C_1^*, \dots, C_m^*$  = coeficientes de costos correspondientes a las variables de la solución básica

Para resolver el sistema de ecuaciones representado por el Tableau se aplica el método de Gauss-Jordan a la sección II del Tableau, la selección del elemento pivote para efectos de minimización se describe a continuación:

- ① Analizar los elementos  $Z_i - C_i$  para toda "i" a fin de determinar si ya se optimizó la función objetivo. El mínimo se obtiene cuando  $(Z_i - C_i) \leq 0$  para toda "i", si se cumple lo anterior se detiene el proceso y el valor de las incógnitas que forman la base es la solución óptima. En caso contrario continuar.
- ② Buscar todos los  $(Z_i - C_i) > 0$  y seleccionar como columna del elemento pivote aquella columna "i" para la que se cumpla que  $(Z_i - C_i) > 0$  es el máximo.
- ③ Para asegurar la factibilidad de la nueva solución, el renglón "k" del elemento pivote será aquel para el cual se tenga el  $\min_k (B_k^* / A_{ki}^*)$  tal que  $A_{ki}^* > 0$ , "i" corresponde a la columna seleccionada en el paso ②. La solución será no acotada cuando  $A_{ki}^* \leq 0$  para toda "k".
- ④ Introducir en la base la nueva variable básica  $x_i$ , es decir, hacer  $x_k^* = x_i$  y  $C_k^* = C_i$ .
- ⑤ Aplicar el método de eliminación de Gauss-Jordan a la sección II del Tableau pivotando sobre el elemento  $A_{ki}^*$ . Al efectuar esta eliminación, los nuevos valores  $B^*$  corresponderán a los valores de las variables que forman la base  $X^*$ .
- ⑥ Regresar al paso ①.

Se puede presentar el caso de que el problema sea cíclico o degenerativo, lo cual es una posibilidad muy remota en

problemas reales. En previsión a lo anterior, se debe establecer un máximo número de iteraciones al implementar el algoritmo en una computadora. Si se tiene un sistema con "m" restricciones se requerirán aproximadamente " $2m$ " cambios de base para llegar a la solución óptima, en base a esto se puede establecer el máximo número de iteraciones a efectuar.

En el caso de que aparezcan variables artificiales, si es que se emplearon, en la solución óptima será necesario modificar sus coeficientes de costos y volver a aplicar el método Simplex al sistema de ecuaciones.

Las variables que no formen parte de la base correspondiente a la solución óptima tienen valor nulo.

#### 14.2.3 Descripción del Programa

##### a) Subrutinas requeridas:

Ninguna

##### b) Descripción de las variables:

M	cantidad de renglones de la matriz de coeficientes del sistema de ecuaciones
N	cantidad de columnas de la matriz de coeficientes = variables estructurales + variables de holgura + variables artificiales
B(I, J)	matriz de coeficientes que contiene los elementos $A_{ki}$
PO(I, 1)	vector de términos independientes del sistema de ecuaciones o estipulaciones $B_k$
C(I, J)	coeficientes de costos de la función objetivo
ASK	variable que indica el tipo de optimización a efectuar, puede ser MAX o MIN
LA(I, 1)	incógnitas que forman parte de la base
COI(I, 1)	coeficientes de costos de las incógnitas que forman parte de la base
D(I, J)	índices que indican cuando detener el proceso, son los valores $Z_i - C_i$



VALZ	valor de la función objetivo
X(I)	caracteres alfanuméricos que se utilizan en la impresión para representar las variables $x_i$
L	contador
K	identificador de las variables que formarán la primera base
ITERA	contador de iteraciones
LLL	variable de reemplazo
LIM	límite de iteraciones
AMAX	valor del máximo índice $Z_i - C_i > 0$
AMIN	valor del mínimo cociente $B_k^*/A_{ki}^*$
LR	identificador de la variable que saldrá de la base
LC	identificador de la variable que entrará a la base
ATEMP	variable de reemplazo

## c) Dimensiones:

Las proposiciones DIMENSION y DATA deberán modificarse cuando:

$$M > 30 \quad \text{y/o} \quad N > 30$$

## d) Formatos para los datos de entrada:

SEC.	TARJETAS	FORMATO	INFORMACION
1		(2I2)	M, N
2		(8F10.0)	B(I, J), los elementos de la matriz se dan renglón por renglón. Emplear las tarjetas que sean necesarias.
3		(8F10.0)	PO(I, 1), los términos independientes se dan uno a continuación del otro en una o más tarjetas según se requiera.
4		(8F10.0)	C(I, J), los coeficientes de costos se dan uno a conti--

.  
 .  
 .  
 ----- 5 (A3) nuación del otro. Emplear  
 las tarjetas que sean nece-  
 sarias.  
 ASK puede adoptar dos va-  
 lores:  
 MIN cuando se desea minimi-  
 zar  
 MAX cuando se desea maximiz-  
 ar

-----  
 otros paquetes de datos (opcional)  
 -----

n

TARJETA EN BLANCO, al fina-  
 lizar toda la información

e) Diagrama de bloques:

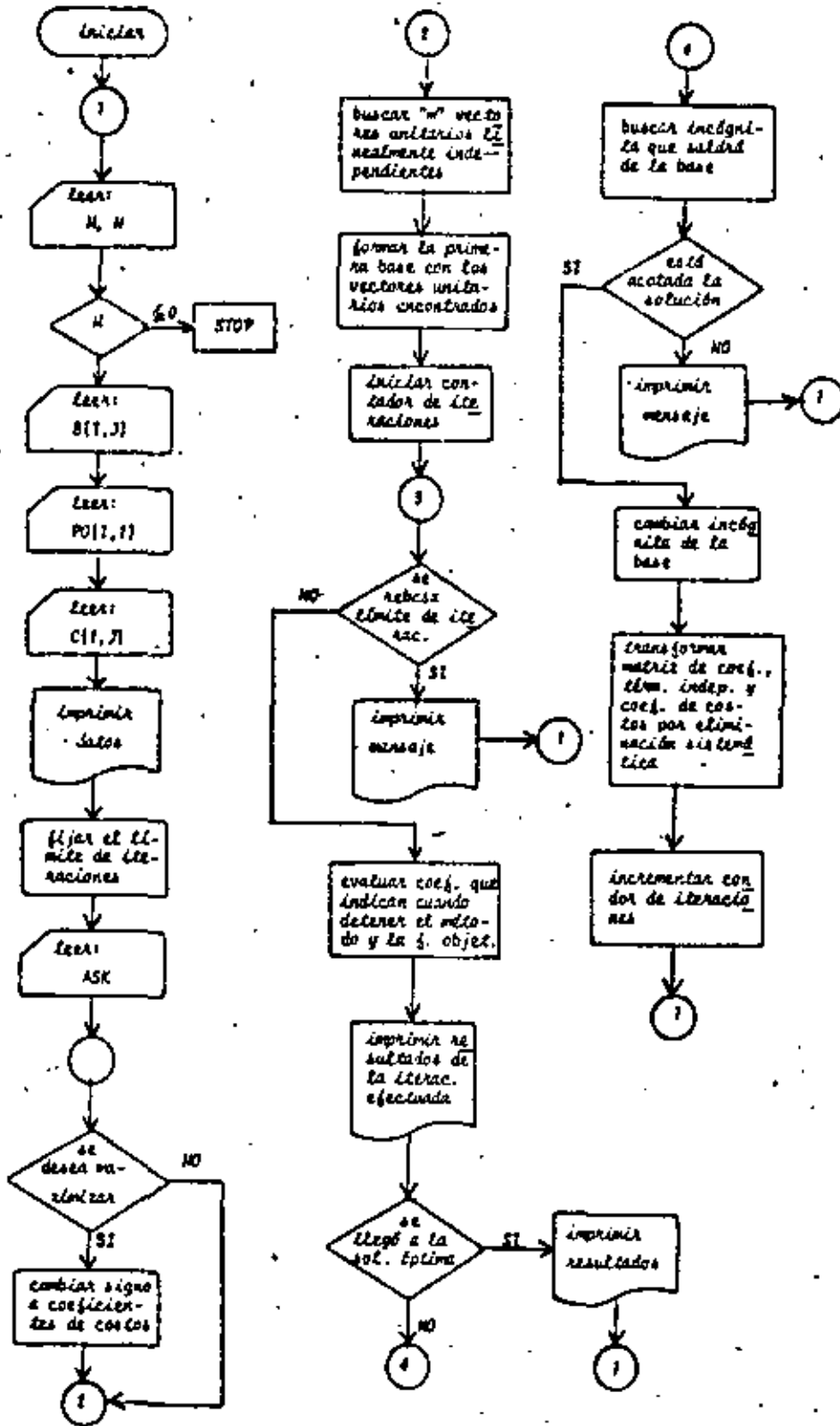


Fig. 14.2 Diagrama de bloques del programa principal

## 6) Listado:

```

C PROGRAMA PARA APLICAR EL METODO SIMPLEX EN UN SISTEMA DE ECUACIONES
C LINEALMENTE INDEPENDIENTES DE GRADO MxN QUE CONTIENE M VECTORES
C UNITARIOS LINEALMENTE INDEPENDIENTES
C EL SIGNIFICADO DE LAS VARIABLES EMPLEADAS ES
C MNUMERO DE REAGENTES DE LA MATRIZ DE COEFICIENTES
C NNUMERO DE COLUMNAS DE LA MATRIZ DE COEFICIENTES
C MMATRIZ DE COEFICIENTES
C PVECTOR DE CONSTANTES INDEPENDIENTES
C CCOEFICIENTES DE LA FUNCION A OPTIMIZAR
C ASK-VARIABLE CON LA QUE SE INDICA EL TIPO DE OPTIMIZACION(MAX,MIN)
C LA Y COEFICIENTES Y SUS COEFICIENTES EN LA FUNCION A OPTIMIZAR
C QUE FORMAN LA BASE
C UNINDICE QUE INDICAN CUANDO DETENER EL METODO
C VALORVALOR DE LA FUNCION A OPTIMIZAR
C LIMITE DE ITERACIONES

```

```

DIMENSION B(30,30),P(30,1),C(1,30),L(30,1),CO(10,1),Y(30),O(1,3
10)
DATA X(1),X(2),X(3),X(4),X(5),X(6),X(7),X(8),X(9),X(10),Y(1),Y(2
1),Y(3),Y(4),Y(5),Y(6),Y(7),Y(8),Y(9),Y(10),X(11),X(12),X(13),X(14),X(15),X(16),X(17),X(18),X(19),X(20),X(21),X(22),X(23
2),X(24),X(25),X(26),Y(27),Y(28),Y(29),X(30),ZHX1,ZHX2,ZHX3,ZHX4,ZH
3),ZHX5,ZHX6,ZHX7,ZHX8,ZHX9,ZHX10,ZHX11,ZHX12,ZHX13,ZHX14,ZHX15,ZHX16,Z
4),ZHX17,ZHX18,ZHX19,ZHX20,ZHX21,ZHX22,ZHX23,ZHX24,ZHX25,ZHX26,ZHX27,Z
5),ZHX28,ZHX29,ZHX30/
DATA ALF/1000/
C LECTURA DEL GRADO DE LA MATRIZ DE COEFICIENTES
I=0
I=0
1 READ(I,100) M,N
IF(I) 2,3
2 CALL CRT
C LECTURA DE LA MATRIZ DE COEFICIENTES
3 DO 4 I=1,M
4 READ(I,150) (C(I,J),J=1,N)
C LECTURA DEL VECTOR DE CONSTANTES INDEPENDIENTES
READ(I,150) (P(I),I=1,M)
C LECTURA DE LOS COEFICIENTES DE LA FUNCION A OPTIMIZAR
READ(I,150) (CO(I),I=1,N)
C IMPRESION DE DATOS
WRITE(I,150) M,N
WRITE(I,200)
DO 5 I=1,M
5 WRITE(I,250) (C(I,J),J=1,N)
WRITE(I,300)
DO 6 I=1,M
6 WRITE(I,350) P(I)
WRITE(I,400)
WRITE(I,250) (CO(I),I=1,N)
C LECTURA DEL TIPO DE OPTIMIZACION DESEADO
LIM=0
READ(I,450) ASK
IF(ALF=0,ASK) GO TO 8
DO 7 J=1,N
7 C(I,J)=C(I,J)
C BUSQUEDA DE LOS N VECTORES UNITARIOS LINEALMENTE INDEPENDIENTES
8 LC 10 J=1,N
L=0
K=0
DO 9 I=1,M
IF(P(I)=0,0,0) GO TO 9
K=I
CONTINUE
IF(L=K) GO TO 10
IF(C(K,J)=C(I,J)) GO TO 10
L=K+1
CO(I)=C(K,I)
10 CONTINUE
ITER=1
11 IF(ITER=LY-LIM) GO TO 12
WRITE(I,500)
GO TO 1
12 LC 13 I=1,M
L(I)=C(I)
VALZ=C(I)
C IMPRESION DEL VALOR DE LA FUNCION QUE SE ESTA OPTIMIZANDO
14 VALZ=VALZ + P(I)*CO(I)

```

```

C   CALCULO DE LOS COEFICIENTES QUE INDICAN CUANDO DETENER EL METODO
16 DO 17 J=1,N
   DO 16 I=1,N
16 UC(I,J)=DC(I,J) + B(I,J)*CC(I,J)
   UC(I,J)=UC(I,J) + CC(I,J)
17 CONTINUE
C   IMPRESION DE LOS VALORES OBTENIDOS EN LA ITERACION EFECTUADA
WRITE(IW,750) ITERA
WRITE(IW,800)
DO 18 J=1,N
  LLL=LA(I,J)
18 WRITE(IW,850) X(LLL),PC(I,J)
WRITE(IW,850) X(LLL),PC(I,J)
  WRITE(IW,750)
  WRITE(IW,850) (DC(I,J),J=1,N)
  APAY=PC(I,J)
  LC=J
C   SE INDAGA SI YA TERMINO EL PROCESO EN CASO CONTRARIO SE BUSCA LA
C   INCOGNITA QUE ENTRA EN LA BASE
DO 19 J=1,N
  IF(AMAX.DC(DC(I,J))) GO TO 19
  APAY=DC(I,J)
  LC=J
19 CONTINUE
  IF(AMAX.DC(DC(I,J)) GO TO 21
C   IMPRESION DE LOS VALORES QUE OPTIMIZAN LA FUNCION
WRITE(IW,800)
DO 20 I=1,N
  LLL=LA(I,J)
20 WRITE(IW,850) X(LLL),PC(I,J)
  WRITE(IW,850) VALZ
  GO TO 1
21 L=0
  K=0
C   BUSQUEDA DE LA INCOGNITA QUE SALORA DE LA BASE
DO 22 I=1,N
  IF(B(I,LC).LE.0.0) GO TO 22
  GO TO 23
22 L=L+1
  GO TO 24
23 K=K+1
  IF(K=NE-1) GO TO 24
  AMIN=PC(I,1)/B(I,LC)
  LR=I
  GO TO 25
24 ATEMP=PC(LR,1)/B(LR,LC)
  IF(AMIN.LE.ATEMP) GO TO 25
  AMIN=ATEMP
  LR=L
25 CONTINUE
C   INVESTIGANDO SI LA SOLUCION ESTA ACOTADA
IF(L=NE,N) GO TO 26
WRITE(IW,900)
GO TO 1
C   INSERCIÓN DE LA INCOGNITA EN LA BASE
26 LA(LR,1)=LC
  CC(LR,1)=CC(L,LC)
C   TRANSFORMACION DE LA MATRIZ DE COEFICIENTES Y DEL VECTOR DE CONSTANTES INDEPENDIENTES
ATEMP=9(L,LC)
DO 27 J=1,N
  B(LR,J)=B(LR,J)/ATEMP
  PC(LR,1)=PC(LR,1)/ATEMP
DO 28 I=1,N
  IF(I.EQ.LR) GO TO 29
  ATEMP=9(I,LC)
DO 28 J=1,N
  UC(I,J)=B(I,J) + ATEMP*B(LR,J)
  PC(I,1)=PC(I,1) + ATEMP*PC(LR,1)
29 CONTINUE
  ITERA=ITERA + 1
  GO TO 11

```

IF (ASK, EQ, ALF) WRITE (IW, 700) VALZ  
 IF (ASK, NE, ALF) WRITE (IW, 700) VALZ

```

6   FORMATEO DE LECTURA E IMPRESION
100 FORMAT (2I2)
150 FORMAT (8F10.0)
200 FORMAT (3I7,45A, 'LA MATRIZ DE COEFICIENTES DEL SISTEMA ES',/)
250 FORMAT (7A5,4E (13,5,2F))
300 FORMAT (3I7,45A, 'EL VECTOR DE CONSTANTES INDEPENDIENTES ES',/)
350 FORMAT (7A50,4E13.5)
400 FORMAT (3I7,42A, 'LOS COEFICIENTES DE LA FUNCION A OPTIMIZAR SON
1',/)
450 FORMATEO(1)
500 FORMAT(3I7,5A, 'EL PROBLEMA ES CICLICO')
550 FORMAT(5I7,53A, '*** ITERACION NUMERO ',I2)
600 FORMAT(3E7,1E5, 'INCÓGNITAS QUE FORMAN LA BASE',I2, 'VALOR DE LA
16 INCÓGNITAS',/)
650 FORMAT(7A5,17,43,50A,4E13.0)
700 FORMAT(3I7,42A, 'VALOR DE LA FUNCION QUE SE ESTA OPTIMIZANDO ',E
13,0)
750 FORMAT(3I7,43A, 'VALOR DE LOS COEFICIENTES QUE INDICAN CUANDO DE
1TENER EL PROCESO',/)
800 FORMAT(5I7,43A, '*** LOS VALORES QUE OPTIMIZAN LA FUNCION SON',/
1,70A, 'INCÓGNITA',49A, 'VALOR',/)
850 FORMAT(3E7,43A, 'EL VALOR OPTIMO DE LA FUNCION ES ',E13,0)
900 FORMAT(9I7,53A, 'LA SOLUCION NO ESTA ACOTADA')
950 FORMAT(4I10,5E7,42A, 'EL ORDEN DE LA MATRIZ DE COEFICIENTES ES ',
112, 'N',I2)
END

```

Fig. 14.3 Listado del programa principal

14.2.4 Ejemplo

En un taller se cuenta con tres tipos de máquinas: cortadora (A), torno (B) y taladro (C). En dicho taller se fabrican cuatro productos: 1, 2, 3, 4. Cada producto debe de pasar por cada máquina con la secuencia ABC. El tiempo (horas) empleado por cada máquina para el acabado del producto, la cantidad de horas efectivas de trabajo de cada máquina y la utilidad neta obtenida por la venta de cada producto terminado son:

Tipo de Máq.	Tiempo útil de trabajo	Productos			
		1	2	3	4
A	3,500	2	1.5	3.0	1.5
B	8,000	1.5	5.5	1.5	4.0
C	4,500	2	3.5	4.0	1.5
utilidad unitaria (\$)		70	90	100	60

Para que la producción sea rentable se requiere que la cantidad de artículos elaborados sea mayor de 500.

Determine la cantidad de artículos de cada tipo que se deben producir en el año para que la ganancia obtenida sea máxima. Considere que todos los productos elaborados son vendidos.

\* SOLUCION

El modelo matemático del problema planteado es:

$$\begin{aligned}
 \max Z &= 70X_1 + 90X_2 + 100X_3 + 60X_4 \\
 \text{s/a} \quad &2X_1 + 1.5X_2 + 3.0X_3 + 1.5X_4 \leq 3500 \\
 &1.5X_1 + 5.5X_2 + 1.5X_3 + 4.0X_4 \leq 8000 \\
 &2X_1 + 3.5X_2 + 4.0X_3 + 1.5X_4 \leq 4500 \\
 &X_1 + X_2 + X_3 + X_4 \geq 500
 \end{aligned}$$

Eliminando desigualdades:

$$\max Z = 70X_1 + 90X_2 + 100X_3 + 60X_4 + 0X_5 + 0X_6 + 0X_7 + 0X_8 - 10,000X_9$$

s/a

$$\begin{aligned} 2X_1 + 1.5X_2 + 3X_3 + 1.5X_4 + X_5 &= 3500 \\ 1.5X_1 + 5.5X_2 + 1.5X_3 + 4.0X_4 + X_6 &= 8000 \\ 2.0X_1 + 3.5X_2 + 4.0X_3 + 1.5X_4 + X_7 &= 4500 \\ X_1 + X_2 + X_3 + X_4 - X_8 + X_9 &= 500 \end{aligned}$$

TABLA 14.1 Datos para el problema del ejemplo 14.2.4

$$M = 4$$

$$N = 9$$

$$\underline{B} = \begin{bmatrix} 2.0 & 1.5 & 3.0 & 1.5 & 1.0 & 0.0 & 0.0 & 0.0 & 0.0 \\ 1.5 & 5.5 & 1.5 & 4.0 & 0.0 & 1.0 & 0.0 & 0.0 & 0.0 \\ 2.0 & 3.5 & 4.0 & 1.5 & 0.0 & 0.0 & 1.0 & 0.0 & 0.0 \\ 1.0 & 1.0 & 1.0 & 1.0 & 0.0 & 0.0 & 0.0 & -1.0 & 1.0 \end{bmatrix}$$

$$\underline{P0} = \begin{bmatrix} 3500 \\ 8000 \\ 4500 \\ 500 \end{bmatrix}$$

$$\underline{C} = (70, 90, 100, 60, 0, 0, 0, 0, -10000)$$

$$ASK = \text{MAX}$$

TABLA 14.2 Resultados del problema del ejemplo 14.2.4



EL ORDEN DE LA MATRIZ DE COEFICIENTES ES DE 9

LA MATRIZ DE COEFICIENTES DEL SISTEMA ES

0.	+20000E+01	+15000E+01	+30000E+01	+15000E+01	+10000E+01	0.	0.	0.
0.	+15000E+01	+55000E+01	+15000E+01	+60000E+01	0.	+10000E+01	0.	0.
0.	+30000E+01	+35000E+01	+80000E+01	+15000E+01	0.	0.	+10000E+01	0.
0.	+15000E+01	+15000E+01	+10000E+01	+10000E+01	0.	0.	0.	+10000E+01

EL VECTOR DE CONSTANTES INDEPENDIENTES ES

- +15000E+04
- +40000E+04
- +45000E+04
- +50000E+04

LOS COEFICIENTES DE LA FUNCION A OPTIMIZAR SON

+70000E+02	+80000E+02	+10000E+03	+40000E+02	0.	0.	0.	0.
------------	------------	------------	------------	----	----	----	----

\*\*\* ITERACION NUMERO 1

INCOGNITAS QUE FORMAN LA BASE

VALOR DE LAS INCOGNITAS

X3	+13000000E+04
X8	+80000000E+04
X7	+45000000E+04
X6	+50000000E+03

VALOR DE LA FUNCION QUE SE ESTA OPTIMIZANDO +50000000E+07

VALOR DE LOS COEFICIENTES QUE INDICAN CUANDO DETENER EL PROCESO

+10070E+03	+10000E+03	+10100E+03	+10000E+03	0.	0.	0.	+10000E+03
------------	------------	------------	------------	----	----	----	------------

INCOGNITAS QUE FORMAN LA BASE

17

VALOR DE LAS INCOGNITAS

X3	.2880000E+04
X4	.7230000E+04
X7	.8100000E+04
X1	.3800000E+03

VALOR DE LA FUNCION QUE SE ESTA OPTIMIZANDO .3680000E+03

VALOR DE LOS COEFICIENTES QUE INDICAN CUANDO DETENER EL PROCESO

.30000E+02	.10000E+02	0.	.40000E+02	0.	0.	0.	.10000E-02
+.10100E+05							

\*\*\* ITERACION NUMERO 3

INCOGNITAS QUE FORMAN LA BASE

VALOR DE LAS INCOGNITAS

X3	.12500000E+03
X4	.41120000E+04
X8	.42300000E+03
X3	.81250000E+04

VALOR DE LA FUNCION QUE SE ESTA OPTIMIZANDO .11250000E+04

VALOR DE LOS COEFICIENTES QUE INDICAN CUANDO DETENER EL PROCESO

.20000E+02	.25000E+01	0.	.25000E+02	0.	0.	.25000E+02	0.
+.10000E+05							

\*\*\* ITERACION NUMERO 4

INCOGNITAS QUE FORMAN LA BASE

VALOR DE LAS INCOGNITAS

X4	.3333333E+03
X4	.51666667E+04
X8	.8333333E+03
X3	.16000000E+04

VALOR DE LA FUNCION QUE SE ESTA OPTIMIZANDO .12000000E+04

VALOR DE LOS COEFICIENTES QUE INDICAN CUANDO DETENER EL PROCESO

.10000E+02	.70000E+02	0.	0.	.40000E+02	0.	.20000E+02	0.
+.10000E+05							

\*\*\* ITERACION NUMERO 5

INCÓGNITAS QUE FORMAN LA BASE

VALOR DE LAS INCÓGNITAS

X4	.14323949E+04
X3	-.39832144E+03
X2	.13439774E+04
X1	.28735632E+03

VALOR DE LA FUNCION QUE SE ESTA OPTIMIZANDO .14494233E+04

VALOR DE LOS COEFICIENTES QUE INDICAN CUANDO DETENER EL PROCESO

0.	0.	0.	0.	0.	0.	0.
-.09057E+01	0.	0.	0.	-.15747E+02	-.48274E+01	-.11379E+02
-.10000E+05						

\*\*\* ITERACION NUMERO 6

INCÓGNITAS QUE FORMAN LA BASE

VALOR DE LAS INCÓGNITAS

X4	.11884957E+04
X3	-.38800800E+03
X2	.14921739E+04
X1	.54247426E+03

VALOR DE LA FUNCION QUE SE ESTA OPTIMIZANDO .14954522E+04

VALOR DE LOS COEFICIENTES QUE INDICAN CUANDO DETENER EL PROCESO

0.	0.	0.	0.	0.	0.	0.
0.	0.	0.	0.	0.	0.	0.
-.10000E+05						

\*\*\* LOS VALORES QUE OPTIMIZAN LA FUNCION SON

INCÓGNITA

VALOR

X4	.11884957E+04
X3	-.38800800E+03
X2	.14921739E+04
X1	.54247426E+03

EL VALOR OPTIMO DE LA FUNCION ES .14954522E+04

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## 16. RUTA CRITICA

### 16.1 Introducción

Todo sistema o proyecto complejo se encuentra formado por gran cantidad de actividades, las cuales pueden o no estar interrelacionadas. Mediante el proceso de jerarquización es posible determinar cuáles de esas actividades deben realizarse antes de poder efectuar algunas otras.

Cada actividad generalmente tendrá asociado un tiempo de duración y la subordinación entre actividades puede ser representada mediante una red gráfica de flujo.

Para poder lograr el correcto avance del proyecto o desarrollo del sistema así como para establecer el control y plan de avance es necesario contar con la información de los tiempos que emplea cada actividad. Por otro lado, el conocimiento acerca de las actividades a las que no se puede modificar su tiempo de inicio o de terminación, así como de las actividades que pueden ser modificadas en su tiempo de inicio o duración - permite una asignación más eficiente de recursos, la reasignación de tiempos de duración y la redefinición de relaciones en forma tal que el sistema o proyecto cumpla su objetivo en el tiempo que se le había asignado y en la forma más económica posible.

Un método para efectuar el control antes mencionado es el método de Ruta Crítica (CPM), este método fue desarrollado en 1956 en U.S.A. y es una de las herramientas básicas en la planeación y dirección de proyectos.

### 16.2 Método de la Ruta Crítica

#### 16.2.1 Objeto

Dada una serie de actividades que forman parte de un proyecto, las cuales pueden ser simultáneas o secuenciales así como sus tiempos de ejecución, determinar:

a) actividades que forman parte de la ruta crítica, son aquellas que no pueden adelantarse ni retrasarse y que por lo tanto con

- trolan el tiempo total de duración del proyecto,
- b) los tiempos de holgura existentes entre actividades secuenciales que no pertenecen a la ruta crítica y,
- c) tiempo total necesario para llevar a cabo el proyecto.

### 16.2.2 Método

Para la representación gráfica de la secuencia de actividades se utilizan nodos (círculos) y ramas (segmentos dirigidos). Los nodos representan eventos o actividades y los segmentos dirigidos la relación entre actividades. A toda red se le asignan dos nodos o actividades ficticias de duración nula: el nodo inicial y el nodo terminal.

Como ejemplo de una red de secuencia de actividades se tiene:

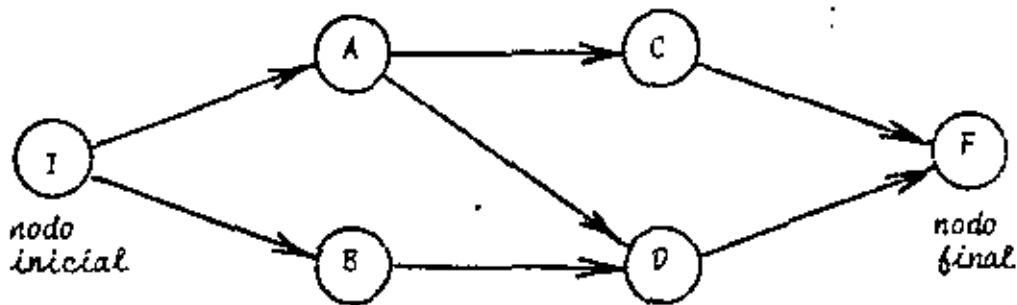


Fig. 16.1 Red gráfica de la secuencia de actividades

La duración de una actividad es el tiempo necesario para llevarla a cabo, dicho tiempo se determina en base al conocimiento que tenga del proyecto el encargado del mismo. Como se mencionó con anterioridad, la duración del evento inicial y del evento final es nula.

Para la descripción del método es necesario definir algunos conceptos:

- 1) Tiempo más próximo de inicio (EST) de una actividad, es lo más pronto que puede comenzarse su ejecución.
- 2) Tiempo más próximo de terminación (EFT), de una actividad, es igual al EST de la actividad más su duración.
- 3) Tiempo más lejano de terminación (LFT) de una actividad, es

## 22

el tiempo más remoto en que se puede terminar dicha actividad sin retrasar el inicio de cualquier actividad subordinada.

- 4) Tiempo más lejano de inicio (LST) de una actividad, es igual al LFT de la actividad menos su duración.
- 5) Tiempo de Holgura Total de una actividad, es la cantidad total de tiempo que se puede retrasar la actividad sin retrasar el tiempo de terminación del proyecto.
- 6) Tiempo de Holgura Libre de una actividad, es la cantidad de tiempo que se puede retrasar la actividad sin retrasar cualquier otra actividad.

Los primeros cuatro conceptos se representan en la gráfica de la red en la siguiente forma:

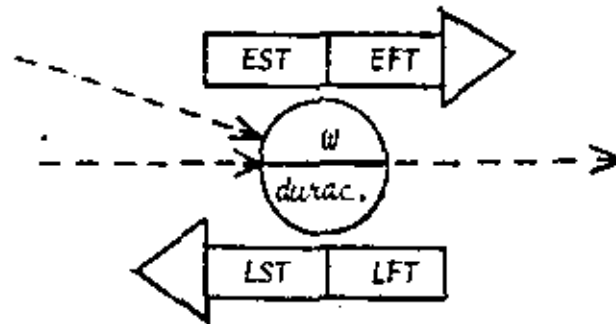


Fig. 16.2 Representación gráfica de una actividad con su duración, EST, EFT, LST, LFT.

Para obtener los valores EST y EFT se recorre la red en sentido directo desde el nodo inicial hasta el nodo final a través de todas sus ramas y para la "i-ésima" actividad de la red se tendrá:

$$EST_i = \max \text{ EFT de todas las actividades precedentes inmediatas de la actividad "i" } \quad (16.1)$$

$$EFT_i = EST_i + \text{ Duración de la actividad } \quad (16.2)$$

Los valores LST y LFT se obtienen recorriendo la red en sentido inverso desde el nodo final hasta el nodo inicial a través de todas las ramas y para la "i-ésima" actividad se tendrá:

$$LFT_i = \min \text{ LST de todas las actividades de las cuales} \\ \text{la actividad "i" es precedente inmediato} \quad (16.3)$$

$$LST_i = LFT_i - \text{Duración} \quad (16.4)$$

Los tiempos de holgura para una actividad "i" se evalúan como a continuación se indica:

$$(\text{HOLGURA TOTAL})_i = LST_i - EST_i = LFT_i - EFT_i \quad (16.5)$$

$$(\text{HOLGURA LIBRE})_i = \{ \min \text{ EST de todas las actividades} \\ \text{de las cuales la actividad "i" es} \\ \text{precedente inmediato} \} - EFT_i \quad (16.6)$$

Siempre se cumple que:

$$\text{HOLGURA LIBRE} \leq \text{HOLGURA TOTAL} \quad (16.7)$$

La ruta crítica está formada por todas las actividades que tienen holgura total nula.

Para desarrollar el proceso en una computadora digital es necesario proporcionar las conexiones existentes entre las actividades mediante una matriz binaria  $G$ . Si existen "n" actividades, incluyendo las ficticias, la matriz será de orden (nxn) y sus elementos estarán dados en la siguiente forma:

$$g_{ij} = \begin{cases} 0 & , \text{ si } i = j \\ 1 & , \text{ si la actividad "j" es prece-} \\ & \text{dente inmediato de la activi-} \\ & \text{dad "i"} \\ 0 & , \text{ si la actividad "j" no es pre-} \\ & \text{cedente inmediato de la activi-} \\ & \text{dad "i"} \end{cases}$$

### 16.2.3 Descripción del Programa

a) Subrutinas requeridas:

Ninguna.



## b) Descripción de las variables:

N	cantidad de actividades incluyendo las dos actividades ficticias
G(I, J)	matriz binaria <u>G</u> que indica cuáles actividades se encuentran directamente interconectadas
D(I)	vector con la duración de todas las actividades
GB(I, J)	matriz binaria que da las relaciones directas entre actividades al efectuar el recorrido de la red en sentido inverso
CS(I)	contador
EST(I)	fecha más próxima de inicio
EFT(I)	fecha más próxima de terminación
LST(I)	fecha más lejana de inicio
LFT(I)	fecha más lejana de terminación
NCON	contador
FF(I)	holgura libre
TF(I)	holgura total
RC(I)	variable en la que se archivan las actividades que forman parte de la ruta crítica
L(I)	identificador de todas las actividades precedentes o consecuentes en forma inmediata a una actividad
IDASH(I)	guión [-] se emplea para impresión

## c) Dimensiones:

La proposición INTEGER deberá modificarse cuando:

$$N > 100$$

## d) Formatos para los datos de entrada:

SEC. TARJETAS	FORMATO	INFORMACION
1	{I3}	N
2	{40I2}	G(I, J) Los elementos de la matriz binaria se dan renglón por renglón empleando la cantidad de -
.		
.		
.		

3  
 :  
 :  
 :  
 :

(1615)

tarjetas que sea necesaria D[1], las duraciones de -- las actividades se proporcionan una a continuación de la otra y deben ser valores enteros. Emplear tan tarjetas como sean necesarias.

-----  
 otros paquetes de datos (opcional)  
 -----

n

TARJETA EN BLANCO, al finalizar toda la información.

e) Diagrama de bloques:

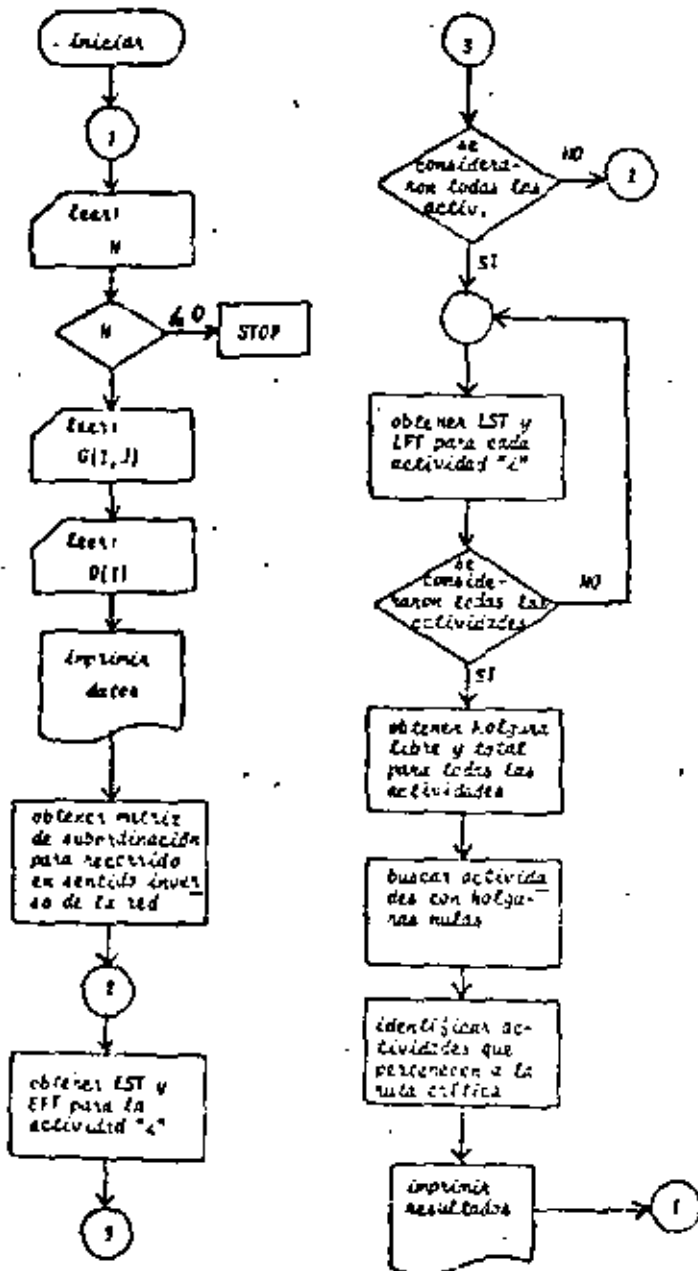


Fig. 16.3 Diagrama d



```

SUBROUTINE RUCUI
COMMON I,S,D,EST,LST,L,T,FF,TF,CS,L,RC,RCH,FLAM
DIMENSION F(30),L(30),S(30),L(30),RC(30),C(30),EST(30),EFT(30),
1 EFT(30),L(30),FF(30),TF(30)
REAL MAX,MIN
C
DETERMINED EST Y LFT
DO 1 I=1,N
1 CSC(I)=0
NM1=N-1
EST(I)=0.0
EFT(I)=0.0
LST(I)=0.0
L(I)=0.0
RC(I)=RC
CSC(I)=1
10 NCON=C
DO 14 J=2,N
IF (CSC(J).EQ.1) GO TO 14
NUM=0
DO 12 T=1,N
IF (L(FD,J)) GO TO 12
IF (C(C,J).EQ.0) GO TO 12
IF (CSC(T).EQ.1) GO TO 11
NUM=NCON + 1
GO TO 14
11 NCON=NUM + 1
L(NUM)=T
12 CONTINUE
MAX=EFT(L(I))
DO 13 T=1,N
IF (MAX.GT.EFT(L(T))) GO TO 13
MAX=EFT(L(T))
13 CONTINUE
EST(J)=MAX
EFT(J)=MAX + L(J)
CSC(J)=1
14 CONTINUE
C
C L(I)=L(I)+L(S+0) EFT
L(I)=L(I)+L(S)
LST(I)=LST(I)
FF(I)=0
TF(I)=0
RC(I)=RC
DO 15 T=2,N-1
15 CSC(I)=0
16 NCON=C
DO 20 T=2,N-1
I1=N+1-T
IF (LST(I1).EQ.1) GO TO 20
NUM=0
DO 18 J=1,N-1
IF (L(FD,J)) GO TO 18
IF (C(C,J).EQ.0) GO TO 18
IF (LST(I1).EQ.1) GO TO 17
NUM=NCON + 1
GO TO 20
17 NCON=NUM + 1
L(NUM)=J
18 CONTINUE

```

```

MIN=LST(L(I))
DL 19 J=1+1
IF (FIN.LE.FST(L(J))) GO TO 19
MIN=LST(L(J))
19 CONTINUE
LFT(I)=MIN
LST(I)=FIN-L(I)
CS(I)=1
20 CONTINUE
IF (NCON.NE.0) GO TO 16
OBTENER HORAS Y ACTIVIDADES DE LA RUTA CRITICA
DL 25 J=1+1
NUM=0
DL 21 I=1+
IF (I.FE.J) GO TO 21
IF (G(I+J).FE.G) GO TO 21
NUM=NUM+1
L(NUM)=I
21 CONTINUE
MIN=EST(L(I))
DL 22 I=1+1
IF (FIN.LE.FST(L(I))) GO TO 22
MIN=EST(L(I))
22 CONTINUE
FT(J)=MIN-FT(J)
IF (J)=LST(J)-LST(J)
IF (TF(J).EQ.0) GO TO 23
RL(J)=PLAN
DL TO 25
23 RL(J)=FT
25 CONTINUE
RETURN
END

```

## 16.2.4 Ejemplo

Obtener para la jerarquía no trivial del ejemplo 15.2.4 - la ruta crítica de las actividades si la duración de las mismas es como se muestra a continuación:

<u>Actividad</u>	<u>Duración (segundos)</u>
A) Detener el coche	8
B) Poner freno de mano	2
C) Bajar del vehículo y checar llanta mala	30
D) Abrir cajuela	30
E) Sacar llanta buena	30
F) Sacar gato y ponerlo	40
G) Sacar llave de cruz	15
H) Quitar tapón	20
I) Aflojar y quitar tuercas	60
J) Subir coche	35
K) Desmontar llanta mala	15
L) Montar llanta buena	25
M) Apretar tuercas y poner tapón	70
N) Bajar el coche y guardar gato	20
O) Guardar llanta mala	20
P) Guardar llave de cruz	15
Q) Cerrar cajuela	5
R) Subirse al coche y quitar freno de mano	15
S) Arrancar	10

## \* SOLUCION

La red de actividades aparece en la Fig. 16.5

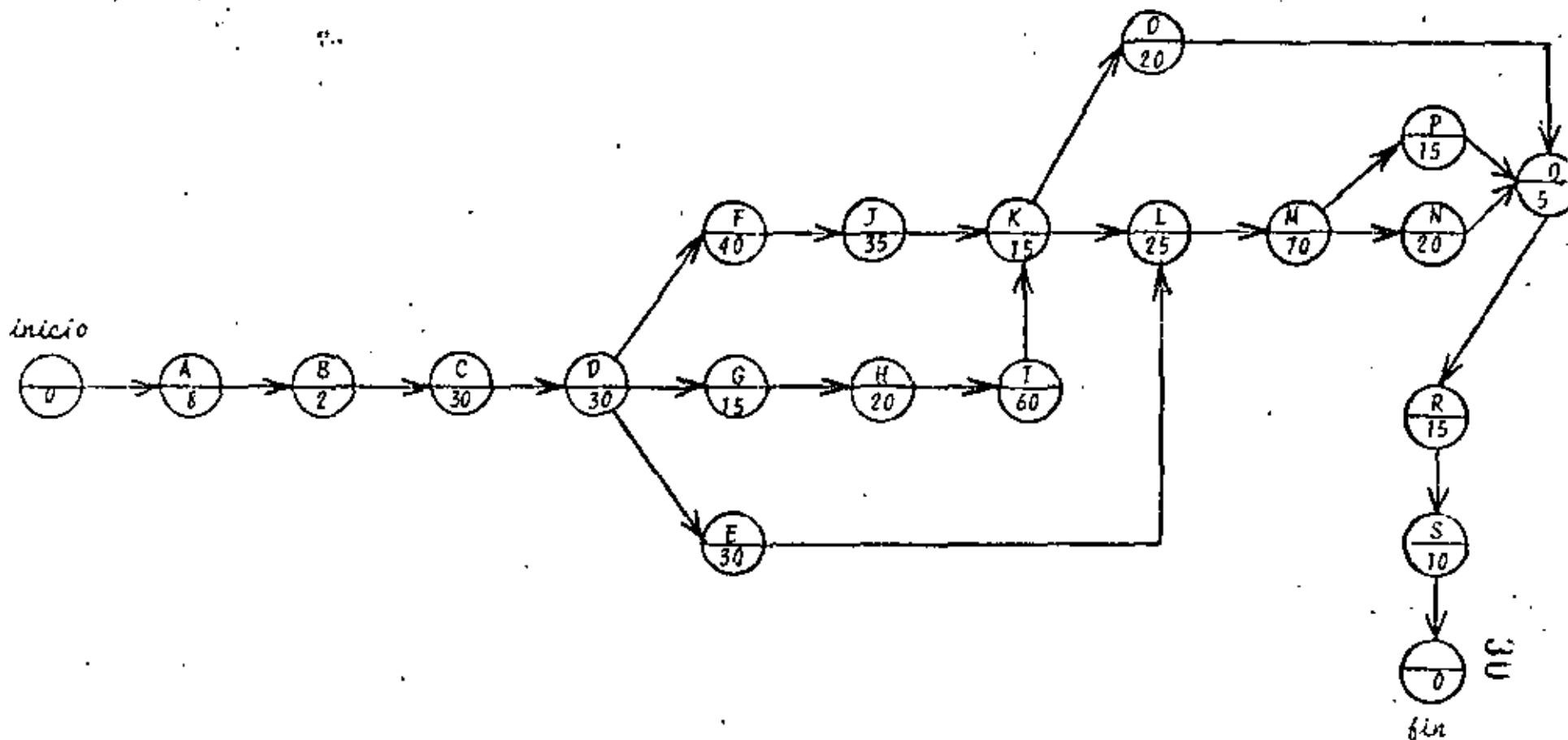


Fig. 16.5 Red de la secuencia de actividades del problema del ejemplo 16.2.4

TABLA 16.1 Datos para el problema del ejemplo 16.2.4

<u>Actividad</u>	<u>Indice asociado</u>
inicio	1
A	2
B	3
C	4
D	5
E	6
F	7
G	8
H	9
I	10
J	11
K	12
L	13
M	14
N	15
O	16
P	17
Q	18
R	19
S	20
F $\bar{c}_n$	21

$D = (0, 8, 2, 30, 30, 30, 40, 15, 20, 60, 35, 15, 25, 70, 20, 20, 15, 5, 15, 10, 0)$

$N = 21$



	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21
1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
2	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
3	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
4	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
5	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
6	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
7	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
8	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
9	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0
10	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0
G = 11	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0
12	0	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0
13	0	0	0	0	0	1	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0
14	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0
15	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0
16	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0
17	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0
18	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1	1	0	0	0	0
19	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0
20	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0
21	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0

TABLA 16.2 Resultados del ejemplo 16.2.4

## MATRIZ DE SUBORDINACION DE ACTIVIDADES

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21
G. 1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
G. 2	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
G. 3	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
G. 4	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
G. 5	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
G. 6	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
G. 7	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
G. 8	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
G. 9	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0
G. 10	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0
G. 11	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
G. 12	0	0	0	0	0	0	0	0	1	1	0	0	0	0	0	0	0	0	0	0	0
G. 13	0	0	0	0	1	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0
G. 14	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0
G. 15	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0
G. 16	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0
G. 17	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0
G. 18	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1	1	0	0	0	0	0
G. 19	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0
G. 20	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0
G. 21	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0

LOS RESULTADOS OBTENIDOS SON

ACTIVIDAD	DURACION	EST	EFT	LST	LFT	FF	TF	
1	0.00	0.00	0.00	0.00	0.00	0.00	0.00	R.C.
2	5.00	0.00	5.00	0.00	5.00	0.00	0.00	R.C.
3	2.00	5.00	7.00	5.00	7.00	0.00	0.00	R.C.
4	30.00	10.00	40.00	10.00	40.00	0.00	0.00	R.C.
5	30.00	40.00	70.00	40.00	70.00	0.00	0.00	R.C.
6	30.00	70.00	100.00	150.00	120.00	80.00	80.00	
7	40.00	70.00	110.00	90.00	130.00	0.00	20.00	
8	15.00	70.00	85.00	70.00	85.00	0.00	0.00	R.C.
9	20.00	85.00	105.00	85.00	105.00	0.00	0.00	R.C.
10	60.00	105.00	165.00	105.00	165.00	0.00	0.00	R.C.
11	35.00	110.00	145.00	130.00	165.00	20.00	20.00	
12	15.00	165.00	180.00	165.00	180.00	0.00	0.00	R.C.
13	25.00	180.00	205.00	180.00	205.00	0.00	0.00	R.C.
14	70.00	205.00	275.00	205.00	275.00	0.00	0.00	R.C.
15	20.00	275.00	295.00	275.00	295.00	0.00	0.00	R.C.
16	20.00	180.00	200.00	275.00	295.00	95.00	95.00	
17	15.00	275.00	290.00	280.00	295.00	5.00	5.00	
18	5.00	295.00	300.00	295.00	300.00	0.00	0.00	R.C.
19	15.00	300.00	315.00	300.00	315.00	0.00	0.00	R.C.
20	10.00	315.00	325.00	315.00	325.00	0.00	0.00	R.C.
21	0.00	325.00	325.00	325.00	325.00	0.00	0.00	R.C.

34

16.3 Bibliografía

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EL PROBLEMA DE LA DIETA Y SU DUAL

DEFINICION DEL PROBLEMA DE LA DIETA.

Suponga que un dietista está tratando de seleccionar una combinación de cinco tipos de alimentos (naranja, manzana, lechuga, chicharo y zanahoria) de manera que el alimento resultante de esta combinación reúna ciertas requerimientos nutricionales y tenga un costo mínimo. Los requerimientos nutricionales que debe tener el alimento resultante es de al menos 21 unidades de vitamina A y al menos 12 unidades de vitamina B. Las propiedades de los cinco elementos disponibles son:

ALIMENTO	CONTENIDO DE VITAMINA A POR UNIDAD DE ALIMENTO.	CONTENIDO DE VITAMINA B POR UNIDAD DE ALIMENTO.	COSTO POR UNIDAD DE ALIMENTO
1 (Naranja)	1	0	20
2 (Manzana)	0	1	20
3 (Lechuga)	1	2	31
4 (Chicharo)	1	1	11
5 (Zanahoria)	2	1	12

El problema a que se enfrenta el dietista se puede modelar como un problema de programación lineal (o programa lineal), de la siguiente manera.

Sea  $x_i$  la cantidad de alimento  $i$  ( $i=1, 2, \dots, 5$ ) que debe estar en el alimento resultante de la combinación de los cinco alimentos. Por lo tanto, el costo de introducir el alimento  $i$  en la mezcla será su costo unitario por la cantidad  $x_i$  que esta presente en la mezcla. El costo total de la combinación de los cinco alimentos será la suma de los costos al combinar  $x_1, x_2, \dots$  y  $x_5$  unidades de cada alimento, i.e. si  $z$  es el costo total entonces

$$z = 20x_1 + 20x_2 + 31x_3 + 11x_4 + 12x_5$$

Ya que el objetivo del dietista es minimizar este costo total, entonces este objetivo se puede representar a través de la siguiente función objetivo

$$\min z = 20x_1 + 20x_2 + 31x_3 + 11x_4 + 12x_5 \tag{1}$$

Los requerimientos nutricionales de vitamina A se pueden representar en la siguiente forma. Si el alimento  $i$  está presente en una cantidad  $x_i$  entonces proporciona una cantidad de vitamina A igual al producto de vitamina A que contiene una unidad de alimento por la cantidad  $x_i$ . La cantidad total proporcionada por los cinco alimentos será la suma de vitamina A con que contribuye cada alimento y esta deberá ser mayor que el contenido mínimo requerido que es de 21 unidades, i.e.

$$x_1 + x_3 + x_4 + 2x_5 \geq 21 \tag{2}$$

Similarmente, los requerimientos de vitamina B se pueden representar por

$$x_2 + 2x_3 + x_4 + x_5 \geq 12 \quad (3) \quad 37$$

Por último, otra restricción que debe estar presente en el problema del dietista es que la cantidad  $x_i$  que interviene en la mezcla debe ser mayor o igual a cero, i.e.

$$x_i \geq 0 \quad i = 1, 2, \dots, 5 \quad (4)$$

Esta restricción es impuesto ya que no tiene sentido hablar de que una cantidad negativa  $x_i$  esté formando parte de la combinación de alimentos.

En resumen el problema del dietista es encontrar valores  $x_1, x_2, \dots, x_5$  para los cuales la función objetivo (i) alcance su mínimo y satisfagan las restricciones (2), (3) y (4). Reescribiendo las ecuaciones del (1) al (4), el problema del dietista está simbólicamente dado por

$$\min z = 20x_1 + 20x_2 + 31x_3 + 11x_4 + 12x_5 \quad (*)$$

$$\left. \begin{aligned} x_1 + x_3 + x_4 + 2x_5 &\geq 21 \\ x_2 + 2x_3 + x_4 + x_5 &\geq 12 \\ x_i &\geq 0 \end{aligned} \right\} \quad (**)$$

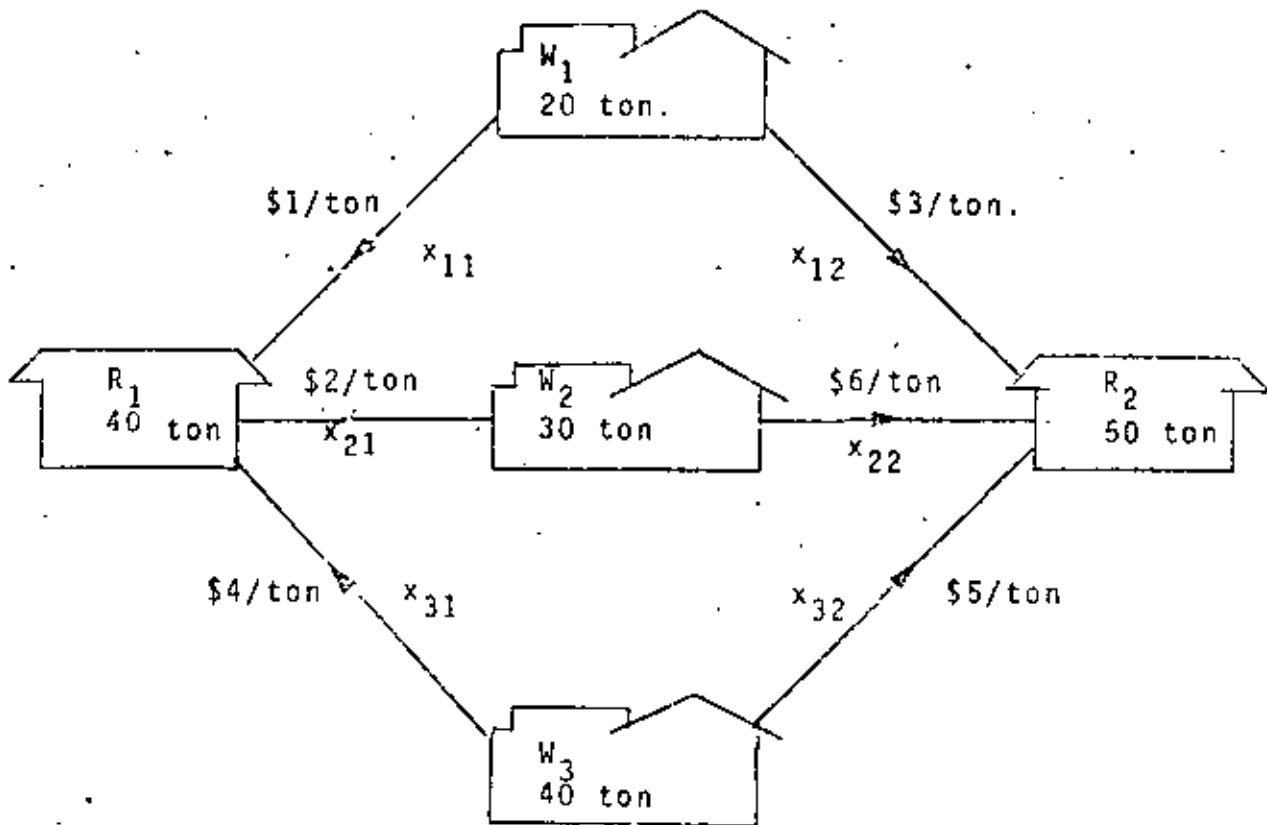
La formulación anterior, (\*) y (\*\*), se acostumbra representar en un tablero (llamado también tableau) que aparecerá abajo. Esta representación es solo una abreviación de escritura (a manera de una taquígrafa de programación lineal) que es útil en el algoritmo de solución, en el proceso convencional al procesar el problema por computadora y por una gran claridad en la formulación del problema dual que se presentará después. La representación de un programa lineal en forma de tablero consiste representar cada ecuación o desigualdad únicamente por los coeficientes de las variables omitiendo la escritura de sus correspondientes variables. Para conocer a que variable pertenece un coeficiente que aparece en este esquema se da la posición del coeficiente, escribiéndolo en la columna encabezada por la variable que le corresponde.

Para nuestro problema (\*) y (\*\*), la representación a través de un tablero está dada por

$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	
20	20	31	11	12	$z$ (min)
1	0	1	1	2	$\geq 21$
0	1	2	1	1	$\geq 12$

$$x_i \geq 0$$

Una compañía tiene tres almacenes  $W_1$ ,  $W_2$ , y  $W_3$ , y dos tiendas de ventas al por menor,  $R_1$ ,  $R_2$ . Las demandas en las tiendas al por menor y el inventario en los almacenes, se muestra en las respectivas cajas de la siguiente figura. Los costos de envío por tonelada también se muestran en la figura. La compañía desea determinar la manera de realizar los envíos en forma tal que minimice los costos totales de envíos, satisfaga las demandas de las tiendas de menudeo, y no excedan los inventarios en los almacenes.



Sea  $x_{ij}$  las toneladas del almacén  $W_i$  a la tienda de menudeo  $R_j$ . Entonces  $x_{32}$  representa el tonelaje enviado del almacén  $W_3$  a la tienda de menudeo  $R_2$ .

Si  $z$  representa el costo total de envíos, entonces nuestro problema se puede formular por:

$$\min z = 1x_{11} + 3x_{12} + 2x_{21} + 6x_{22} + 4x_{31} + 5x_{32} \quad (*)$$

sujeta a

$$\begin{aligned} \text{Restricciones sobre} & & x_{11} + x_{12} & \leq 20 \\ \text{disponibilidad de} & & & \\ \text{almacenes} & & x_{21} + x_{22} & \leq 30 \\ & & x_{31} + x_{32} & \leq 40 \end{aligned}$$

(\*\*)

$$\begin{aligned} \text{Restricciones sobre} & & x_{11} + x_{21} + x_{31} & \geq 40 \\ \text{la demanda en tiendas} & & & \\ \text{de de menudeo} & & x_{12} + x_{22} + x_{32} & \geq 50 \end{aligned}$$

La formulación anterior, (\*) y (\*\*), se acostumbra representar (por conveniencia del algoritmo de solución y del proceso convencional en el procesamiento en computadora) en la siguiente tabla:

$x_{11}$	$x_{12}$	$x_{21}$	$x_{22}$	$x_{31}$	$x_{32}$	
1	3	2	6	4	5	= z
1	1	0	0	0	0	$\leq 20$
0	0	1	1	0	0	$\leq 30$
0	0	0	0	1	1	$\leq 40$
1	0	1	0	1	0	$\geq 40$
0	1	0	1	0	1	$\geq 50$



REPRESENTACION MATRICIAL. La formulación (\*) y (\*\*), se puede representar matricialmente como sigue:

$$\min z = \begin{bmatrix} 1 & 3 & 2 & 6 & 4 & 5 \end{bmatrix} \begin{bmatrix} x_{11} \\ x_{12} \\ x_{21} \\ x_{22} \\ x_{31} \\ x_{32} \end{bmatrix}$$

sujeta a

$$\begin{bmatrix} 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_{11} \\ x_{12} \\ x_{21} \\ x_{22} \\ x_{31} \\ x_{32} \end{bmatrix} \begin{matrix} \\ \\ \\ \\ \\ \\ \end{matrix} \begin{bmatrix} 20 \\ 30 \\ 40 \\ 40 \\ 50 \end{bmatrix}$$

COMENTARIOS. El problema de programación lineal anterior ocurre tan frecuentemente en la práctica, que se le ha dado un nombre especial: el problema de transporte. Los problemas de transporte en general, tienen tablas ralas (o matrices ralas), lo cual significa que la tabla tiene muchos ceros o sea pocos elementos distintos de cero. Dantzig y otros han desarrollado métodos especiales para la solución rápida de estos problemas.

Otro comentario importante, es la característica que presentan cada una de las columnas de la matriz de restricciones: observe que cada una tiene dos unos y los demás elementos son todos ceros.

Un inversionista tiene disponibles las actividades financieras A y B, al comienzo de cada uno de los siguientes cinco años. Cada peso invertido en A, al comienzo de un año, le regresa \$ 1.40 (una ganancia de \$ 0.40) dos años más tarde (en el momento preciso para una reinversión inmediata). Cada peso invertido en B al comienzo de un año, le regresa \$ 1.70 tres años después.

Además existen dos actividades financieras C y D que estarán disponibles solamente una vez en el futuro. Cada peso invertido en C en el comienzo del segundo año le regresa \$ 2.00 cuatro años más tarde. Cada peso invertido en D, en el comienzo del quinto año le regresa \$ 1.30 un año más tarde.

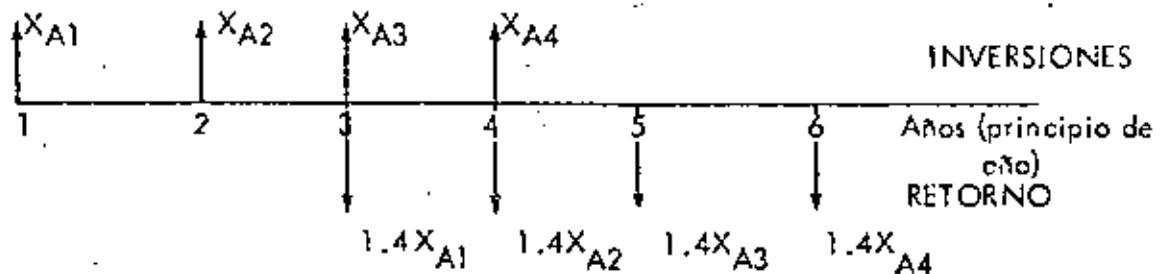
El inversionista comienza con \$ 10,000.00. El desea conocer que plan de inversión maximiza la cantidad de dinero que el puede acumular al comienzo del sexto año. Formule un modelo de programación lineal para este problema y también expréselo en forma tabular.

SOLUCION.

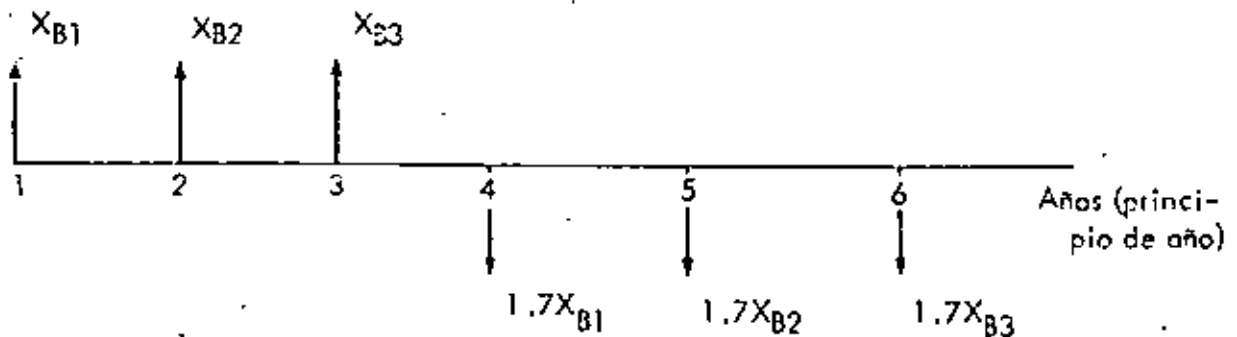
Sea  $X_{ij}$  la cantidad de dinero invertida en la actividad  $i$  ( $i = A, B, C, D$ ) en el año  $j$  ( $j = 1, 2, 3, 4, 5$ ).

Las características dadas sobre las formas de inversión de cada una de las actividades -- A, B, C y D pueden mostrarse esquemáticamente como sigue.

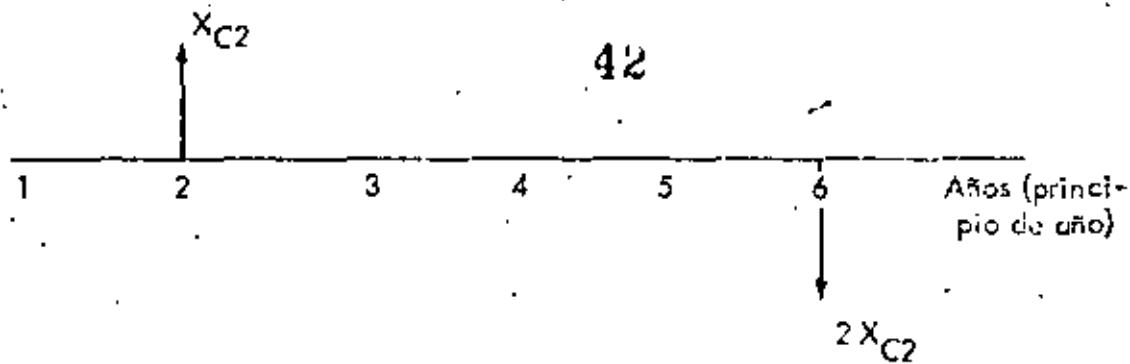
CONDICIONES DE INVERSION EN LA ACTIVIDAD A.



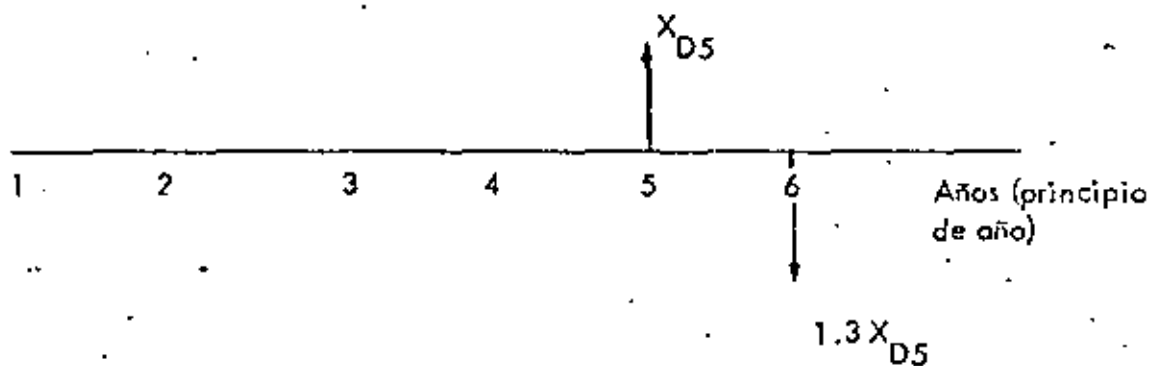
CONDICIONES DE INVERSION EN LA ACTIVIDAD B



CONDICIONES DE INVERSION EN LA ACTIVIDAD C:



CONDICIONES DE INVERSION EN LA ACTIVIDAD D:



La cantidad acumulada en el comienzo del sexto año es la cantidad original (10000) más la ganancia obtenida hasta esta fecha. Por lo tanto, el problema de maximizar la cantidad acumulada de dinero es equivalente a minimizar la ganancia, ya que la cantidad original disponible es una constante que no afecta el valor del dinero acumulado a través de cualquier plan de inversión que se siga.

Si  $Z$  es la ganancia total obtenida hasta el comienzo del sexto año, entonces la función objetivo será:

$$\max Z = 0.4 X_{A1} + 0.4 X_{A2} + 0.4 X_{A3} + 0.4 X_{A4} + 0.70 X_{B1} + 0.70 X_{B2} + X_{C2} + 0.3 X_{D5}$$

Del enunciado del problema, se observa que las restricciones al problema están dadas por la cantidad disponible para invertir en cada año, y por las características de las actividades A, B, C y D. Estas restricciones sobre las inversiones anuales se determinan como sigue:

PRIMER AÑO: La cantidad de dinero invertida en el primer año debe satisfacer:

$$X_{A1} + X_{B1} \leq 10000$$

Si  $U_1$  es una variable positiva o cero, que se adiciona a la desigualdad anterior, para que

esta desigualdad llegue a ser una igualdad, entonces

$$x_{A1} + x_{B1} + u_1 = 10000 \quad (1)$$

$$u_1 \geq 0$$

**NOTAS:**

1. A la variable que se adiciona a una desigualdad para convertirla en igualdad se le llama una variable de holgura. Entonces  $u_1$  es una variable de holgura.
2. Observe que  $u_1$  representa la cantidad de dinero no invertido en el primer año, y por lo tanto también representa la cantidad disponible para invertir en el segundo año.

**SEGUNDO AÑO:** Las inversiones en este año deben satisfacer (observe en las figuras anteriores en que actividades financieras podemos invertir para el segundo año):

$$x_{A2} + x_{B2} + x_{C2} \leq u_1$$

Si introducimos una variable positiva  $u_2$  para pasar la desigualdad anterior a igualdad, entonces

$$x_{A2} + x_{B2} + x_{C2} + u_2 = u_1 \quad (2)$$

$$u_2 \geq 0$$

Observese que la variable  $u_2$  es una variable de holgura que representa la cantidad no invertida en el segundo año.

**TERCER AÑO:** En este año la cantidad de dinero disponible para inversiones proviene de tres fuentes:

- i) cantidad no invertida en el segundo año:  $u_2$
- ii) ganancia obtenida de inversiones anteriores:  $0.4x_{A1}$
- iii) cantidad recuperada de inversiones anteriores:  $\frac{x_{A1}}{u_2 + 1.4x_{A1}}$

Observando cada uno de los cuatro diagramas mostrados anteriormente, se tiene que para el tercer año las inversiones deben satisfacer

$$x_{A3} + x_{B3} \leq u_2 + 1.4x_{A1}$$

Introduciendo una variable de holgura  $u_3$  ( $u_3 \geq 0$ ), se tiene que

$$x_{A3} + x_{B3} + u_3 = u_2 + 1.4x_{A1} \quad (3)$$

$$u_3 \geq 0$$

Otra vez notese que  $u_3$  representa la cantidad no invertida en el tercer año.

**CUARTO AÑO:** En forma similar al análisis del tercer año, se tienen tres fuentes de dinero disponibles:

- i) cantidad no invertida en el tercer año:  $u_3$
- ii) ganancia obtenida entre el tercer y cuarto periodo:  $0.4x_{A2} + 0.7x_{B2}$
- iii) cantidad recuperada de inversiones anteriores:  $\frac{x_{A2} + x_{B1}}{u_3 + 1.4x_{A2} + 1.7x_{B1}}$

Por lo tanto, las inversiones en el cuarto periodo deben satisfacer

$$x_{A4} \leq u_3 + 1.4 x_{A2} + 1.7 x_{B1}$$

Introduciendo la variable de holgura positiva  $u_4$ , se tiene:

$$x_{A4} + u_4 = u_3 + 1.4 x_{A2} + 1.7 x_{B1} \quad (4)$$

$$u_4 \geq 0$$

QUINTO AÑO: La cantidad disponible en este periodo proviene de:

- i) cantidad no invertida en el cuarto año:  $u_4$
- ii) ganancia entre el tercero y el cuarto periodo:  $0.4x_{A3} + 0.7x_{B2}$
- iii) cantidad recuperada entre el periodo 3 y 4to.:  $\frac{x_{A3} + x_{B2}}{u_4 + 1.4x_{A3} + 1.7x_{B2}}$

Por lo tanto,

$$x_{D5} \leq u_4 + 1.4 x_{A3} + 1.7 x_{B2}$$

Si  $u_5$  es una variable de holgura, entonces

$$x_{D5} + u_5 = u_4 + 1.4 x_{A3} + 1.7 x_{B2} \quad (5)$$

$$u_4, u_5 \geq 0$$

Por lo tanto, nuestro modelo de programación lineal quedaría definido por la función objetivo, dada anteriormente y el conjunto de restricciones definidas por la ecuación del (1) a la (5).

Reescribiendo las ecuaciones anteriores, nuestro modelo de programación lineal queda expresado por:

$$\max z = 0.4x_{A1} + 0.4x_{A2} + 0.4x_{A3} + 0.4x_{A4} + 0.7x_{B1} + 0.7x_{B2} + 0.7x_{B3} + x_{C2} + 0.3x_{D5} \quad (0)$$

sujeto a (s.a.)

$$x_{A1} + x_{B1} + u_1 = 10\ 000 \quad (1)$$

$$x_{A2} + x_{B2} + x_{C2} + u_2 = u_1 \quad (2)$$

$$x_{A3} + x_{B3} = u_2 + 1.4x_{A1} \quad (3)$$

$$x_{A4} + u_4 = u_3 + 1.4x_{A2} + 1.7x_{B1} \quad (4)$$

$$x_{D5} + u_5 = u_4 + 1.4x_{A3} + 1.7x_{B2} \quad (5)$$

$$x_{Aj} \geq 0 \quad (j = 1, 2, 3, 4)$$

$$x_{Bj} \geq 0 \quad (j = 1, 2, 3, )$$

$$x_{C2} \geq 0$$

$$x_{D5} \geq 0$$

$$u_i \geq 0 \quad (i = 1, 2, \dots, 5)$$

Este problema expresado en la forma particionada

$$\begin{array}{|c|c|} \hline x & \\ \hline c & z \\ \hline A & b \\ \hline \end{array} \quad x \geq 0$$

Se presenta a continuación:

La Compañía aérea Aeronaves del Pacífico, necesita decidir cuántas aeromozas contratan y adiestran en los próximos 6 meses. Los requerimientos expresados como horas-vuelo-aeromozas son:

8000 en Enero; 9000 en Febrero; 7000 en Marzo, 10 000 en Abril, 9000 en Mayo; y 11 000 en Junio.

El entrenamiento para que una aeromoza dé servicio en un vuelo dura un mes, por tanto cada muchacha debe contratarse por lo menos un mes antes de ser necesitada.

El entrenamiento requiere de 100 horas de supervisión de aeromozas ya -- entrenadas por lo tanto disponemos de 100 horas-vuelo-aeromozo menos, durante un mes por cada aeromoza en entrenamiento.

Cada aeromoza entrenada puede trabajar hasta 150 horas en un mes y la compañía tiene 60 aeromozas entrenadas al principio de enero.

Si el máximo tiempo disponible de las aeromozas excede al requerido en el mes (horas vuelo + supervisión) trabajarán menos de 150 horas y no es despedida ninguna. Pero en cada mes, aproximadamente el 10% de las -- aeromozas con experiencia dejan el trabajo por matrimonio u otras razones.

Cada aeromoza entrenada cuesta a la compañía \$ 8000.00 al mes y cada -- aeromoza en entrenamiento \$ 4000.00; tomando en cuenta salarios y otros -- beneficios.

- a) Formule el problema de contratar y entrenar como un modelo de programación lineal haciendo  $x_t$  el número de aeromozas que principian su -- entrenamiento en el mes  $t$ , donde  $x_0 = 60$  representa las aeromozas -- disponibles al principio de enero. Defina cualquier símbolo adicional -- que necesite para expresar las variables de decisión .
- b) El inciso anterior supone un horizonte de 6 meses. Suponga que se -- agregan requerimientos de julio al modelo, por ejemplo 10 000 horas. (Cambiaría necesariamente la solución para los meses anteriores encontrada anteriormente? Explíquelo.

Solución :

47

Sea  $x_t$  el número de personas contratadas que principian su entrenamiento al inicio del mes  $t$  ( $t = 1, 2, \dots, 6$ ).

Sea  $y_t$  el número de aeromozas experimentadas al final del mes  $t$  ( $t = 1, 2, \dots, 6$ ). Nótese que  $y_t$  también representa la cantidad de aeromozas experimentadas al inicio del mes  $t + 1$ .

#### DISPONIBILIDAD DE AEROMOZAS EXPERIMENTADAS.

Observe que el número de aeromozas experimentadas  $y_t$  al final del mes  $t$ , está formado por las personas contratadas al inicio de este mes (las cuales fueron entrenadas en el transcurso del mes) más el 90% de las aeromozas experimentadas que había al final del mes anterior  $t - 1$  (o sea al inicio del mes  $t$ ), i.e.:

$$y_t = x_t + .9 y_{t-1} \quad (t = 1, 2, \dots, 6)$$

con

$$y_0 = x_0 = 60$$

(\*)

ó sea

$$y_1 = x_1 + .9y_0 = x_1 + .9x_0 \quad (1)$$

$$y_2 = x_2 + .9y_1 \quad (2)$$

$$y_3 = x_3 + .9y_2 \quad (3)$$

$$y_4 = x_4 + .9y_3 \quad (4)$$

$$y_5 = x_5 + .9y_4 \quad (5)$$

$$y_6 = x_6 + .9y_5 \quad (6)$$

#### DEMANDAS DE HORAS DE TRABAJO (VUELOS COMERCIALES Y ENTRENAMIENTO):

La demanda total de horas de vuelo por mes corresponde a la demanda de vuelos comerciales más la demanda de horas para entrenar a las nuevas personas contratadas en el inicio del mes. Para satisfacer esta demanda total en el mes  $t$  (inicio del mes  $t$ ); se dispone de  $y_{t-1}$  aeromozas con experiencia, las cuales pueden proporcionar 150 horas cada una de ellas. Por lo tanto, si  $D_t$  es la demanda de vuelos comerciales en el mes  $t$ , entonces:

$$\text{Demanda en el mes } t : \quad 150y_{t-1} \geq D_t + 100x_t \quad (t=1, 2, \dots, 6)$$

$$\text{con } y_0 = x_0$$

Introduciendo una variable de holgura a cada ecuación, entonces

$$150y_{t-1} = D_t + 100x_t + u_t \quad (t = 1, 2, \dots, 6)$$

$$y_0 = x_0$$

$$u_t \geq 0$$

(\*\*)



Observe que  $u_t$  es una variable de holgura que representa el número de horas disponible no usadas al final del período  $t$ . Expresando esta restricción para cada  $t$  se tiene que:

Demanda en el mes 1 :  $150y_0 = 8000 + 100x_1 + u_1$   
 Demanda en el mes 2 :  $150y_1 = 9000 + 100x_2 + u_2$   
 Demanda en el mes 3 :  $150y_2 = 8000 + 100x_3 + u_3$   
 Demanda en el mes 4 :  $150y_3 = 10000 + 100x_4 + u_4$   
 Demanda en el mes 5 :  $150y_4 = 9000 + 100x_5 + u_5$   
 Demanda en el mes 6 :  $150y_5 = 12000 + 100x_6 + u_6$

48

**FUNCION OBJETIVO:**

Ya que el objetivo de la compañía es determinar cuantas aeromozas contratar en los próximos meses, entonces la función objetivo es minimizar los costos involucrados. Estos costos son los costos de las aeromozas experimentadas más los costos de las aeromozas que están siendo entrenadas. Por lo tanto, la función objetivo está dada por

$$\min Z = 8000 [x_0 + y_1 + \dots + y_6] + 4000 [x_1 + x_2 + \dots + x_6]$$

ya que  $x_0 = y_0$ ,

$$\min Z = 8000 [y_0 + y_1 + \dots + y_6] + 4000 [x_1 + x_2 + \dots + x_6] \quad (***)$$

Por lo tanto nuestro modelo de programación lineal para el problema dado, está definido por (\*), (\*\*), y (\*\*\*) . La representación de este problema de programación lineal en forma particionada (ó tableau ó tablero) es la siguiente.

$y_0$	$y_1$	$y_2$	$y_3$	$y_4$	$y_5$	$y_6$	$x_0$	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$x_6$	$u_1$	$u_2$	$u_3$	$u_4$	$u_5$	$u_6$	$Z'$ (min)	
800	800	800	800	800	800	800		400	400	400	400	400	400								60
								1													0
								-1													0
									-1												0
										-1											0
											1										0
												-1									0
													-1								0
														-1							0
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																				-1	0
																					8000
																					9000
																					8000
																					10000
																					9000
																					12000

$$x = [y_0 \ y_1 \ y_2 \ y_3 \ y_4 \ y_5 \ y_6 \ x_0 \ x_1 \ x_2 \ x_3 \ x_4 \ x_5 \ x_6 \ u_1 \ u_2 \ u_3 \ u_4 \ u_5 \ u_6] \geq 0$$

$x_{A1}$	$x_{B1}$	$u_1$	$x_{A2}$	$x_{B2}$	$x_{C2}$	$u_2$	$x_{A3}$	$x_{B3}$	$u_3$	$x_{A4}$	$u_4$	$x_{O5}$	$u_5$	
.4	.7		.4	.7	1		.4	.7		.4		.3		= z (max)
1	1	1												= 10 000
		-1	1	1	1	1								= 0
-1.4						-1	1	1	1					= 0
	-1.7		-1.4					-1	1	1				= 0
				-1.7			-1.4			-1	1	1		= 0

$$x = [x_{A1} \ x_{B1} \ u_1 \ x_{A2} \ x_{B2} \ x_{C2} \ u_2 \ x_{A3} \ x_{B3} \ u_3 \ x_{A4} \ u_4 \ x_{D5} \ u_5] \geq 0$$

NOTA: Las restricciones del ( 1 ) al ( 5 ) pueden expresarse sin variables de holgura, con objeto de expresar estas restricciones como desigualdades en lugar de igualdades. El procedimiento para obtener estas igualdades es el siguiente:

Obviamente de la ecuación ( 1 ) se tiene

$$x_{A1} + x_{B1} \leq 10\ 000 \quad (1^1)$$

Sumando ( 1 ) y ( 2 ):

$$x_{A1} + x_{B1} + x_{A2} + x_{B2} + x_{C2} + u_2 = 10\ 000$$

$$x_{A1} + x_{B1} + x_{A2} + x_{B2} + x_{C2} \leq 10\ 000 \quad (2^1)$$

Sumando ( 1 ), ( 2 ) y ( 3 ):

$$x_{A1} + x_{B1} + x_{A2} + x_{B2} + x_{C2} + x_{A3} + x_{B3} + u_3 = 10\ 000 + 1.4x_{A1}$$

$$x_{A1} + x_{B1} + x_{A2} + x_{B2} + x_{C2} + x_{A3} + x_{B3} \leq 10\ 000 + 1.4x_{A1} \quad (3^1)$$

Sumando (1), (2), (3) y (4) :

$$x_{A1} + x_{B1} + x_{A2} + x_{B2} + x_{C2} + x_{A3} + x_{B3} + x_{A4} + u_4 = 10\ 000 + 1.4x_{A1} + 1.4x_{A2} + 1.7x_{B1}$$

$$x_{A1} + x_{B1} + x_{A2} + x_{B2} + x_{C2} + x_{A3} + x_{B3} + x_{A4} \leq 10\ 000 + 1.4x_{A1} + 1.4x_{A2} + 1.7x_{B1} + 1.4x_{A3} + 1.7x_{B2} \quad (4^1)$$

Sumando (1), (2), (3), (4) y (5):

$$x_{A1} + x_{B1} + x_{A2} + x_{B2} + x_{C2} + x_{A3} + x_{B3} + x_{A4} + x_{D5} + u_5 = 10\,000 + 1.4x_{A1} + 1.4x_{A2} + 1.7x_{B1} + 1.4x_{A3} + 1.7x_{B2}$$

$$x_{A1} + x_{B1} + x_{A2} + x_{B2} + x_{C2} + x_{A3} + x_{B3} + x_{A4} + x_{D5} \leq 10\,000 + 1.4x_{A1} + 1.4x_{A2} + 1.7x_{B1} + 1.4x_{A3} + 1.7x_{B2} \quad (5^1)$$

Por lo tanto, las desigualdades del (1<sup>1</sup>) al (5<sup>1</sup>) son las restricciones a nuestro problema estas restricciones pueden obtenerse directamente del contexto del problema sin la introducción de variables de holgura, nuestro problema expresado a través de las restricciones de la (1<sup>1</sup>) a la (5<sup>1</sup>), queda representado en forma particionada como sigue:

$$x_{A1} \quad x_{B1} \quad x_{A2} \quad x_{B2} \quad x_{C2} \quad x_{A3} \quad x_{B3} \quad x_{A4} \quad x_{D5}$$

.4	.7	.4	.7	1	.4	.7	.4	.3	= z (max)
1	1								≤ 10 000
1	1	1	1	1					≤ 10 000
-.4	1	1	1	1	1	1			≤ 10 000
-.4	-.7	-.4	1	1	1	1	1		≤ 10 000
-.4	-.7	-.4	-.7	1	-.4	1	1	1	≤ 10 000

$$x = [x_{A1} \quad x_{B1} \quad x_{A2} \quad x_{B2} \quad x_{C2} \quad x_{A3} \quad x_{B3} \quad x_{A4} \quad x_{D5}] \geq 0$$



**DIVISION DE EDUCACION CONTINUA  
FACULTAD DE INGENIERIA U.N.A.M.**

**INTRODUCCION A LA PROGRAMACION Y COMPUTACION ELECTRONICA**

**PROBELMA DE INVENTARIOS, APLICACIONES**

**OCTUBRE, 1981**

# INSYS

## **an inventory system model**

*computes inventory levels and factory output for a factory-wholesaler-retailer inventory system. Inventory replenishment and lead time policies may be changed in order to test the effect of these policies on the performance of the overall system.*

The purpose of an inventory is to provide a separation in time or location between the production of goods and the consumption of goods. In our specialized economy a man is no longer his own butcher, baker, and candlestick-maker. Rather, we have production centers (factories) which are specialized, centrally located, and have high production rates. There is a great gain in production efficiency from this specialization, but it also requires a large increase in inventories to separate the centralized factory from the ultimate consumer. No longer do we follow the example of the little red hen who planted, reaped, milled, baked, and ate (without the help of the pig, cow, rabbit, or duck) her own loaf of bread.

The most common inventory system in our economy is the factory-wholesaler-retailer system. The wholesaler provides a time decoupling service between the factory and the retailer, in that he holds the factory output until ordered by the retailer. The wholesaler also provides a location decoupling, in that he generally ships goods over a wide geographic area. Similarly, the retailer provides a decoupling service between the wholesaler and the consumer, in that he maintains an inventory of goods on display for sale to customers.

The purpose of this exercise is to provide an illustration of the dynamic nature of the factory-wholesaler-retailer inventory system. A computer model is used to calculate week by week how the retail inventory, the wholesale inventory, and the factory output rate change in response to retail sales. The model user may make changes in retail and wholesale inventory policy in an attempt to control the overall inventory system.

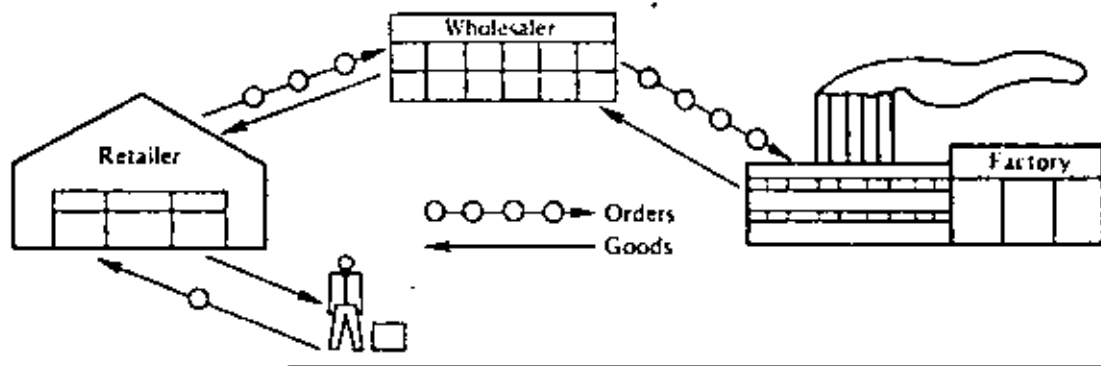


Figure 2-1 The factory-wholesaler-retailer system.

Section 2.1 explains the normal inventory systems and the rules for maintaining inventory levels. The following sections present three illustrated computer problems for maintaining and controlling the inventory system.

## 2.1 FACTORY-WHOLESALER-RETAILER MODEL

The normal system for the production and distribution of goods in our economy is through the factory-wholesaler-retailer system. A visual conceptualization of this system is shown in Figure 2-1. The function of the retailer in this system is to

- take orders from customers
- deliver goods to customers from on-the-shelf inventory
- reorder goods from the wholesaler
- receive shipments from the wholesaler

The function of the wholesaler is similar to the retailer except that the wholesaler's customer is the retailer and there is a time lag between the ordering and the delivery of goods. The wholesaler must

- receive orders from the retailer
- ship goods from the warehouse inventory
- reorder goods from the factory
- receive shipments from the factory.

Finally, the factory must produce the goods which are ultimately sold to the customers. The factory may or may not hold inventories. In the current model the factory does not maintain any inventory so that its only functions are to

- produce goods at some rate
- change production rate as requested by wholesaler

The model just described is a simple abstraction of that which is found in the industrial system. Durable goods, such as appliances, more or less follow the system described. There are variations in that some large retailers order directly from the factory, or the factory may maintain a

showroom and make direct retail sales. In other cases, the factory maintains large inventories and performs the function of the wholesaler. In all of these modifications, however, there is a dynamic interplay of sales with the inventories maintained and the factory rate as illustrated in this model.

**Retail  
Model  
Formulas**

The parameters and formulas for the actual computer model of the retailer are presented in this section. These formulas are a mathematical statement of the verbal model description above. We also present some sample computations using the retail formulas.

*Retail sales* are controlled by the customer. They are part of the input to the program by the reader. Retail sales in the past have been about 100 units per week.

*Retail receipts* are the units received from the wholesaler each Monday morning that were ordered Friday one week (10 days) prior.

*Retail inventory level* is the number of units on hand Friday afternoon at the close of business. The inventory level varies through the week as shown in Figure 2-2. The formula for determining the inventory level is

$$\text{Inventory level} = \text{prior inventory level} + \text{retail receipts} - \text{retail sales}$$

*Retail orders* are placed with the wholesaler each Friday afternoon after determining the inventory level. The order policy is to order the retail sales for the week plus or minus enough units to return the base stock level to 100 units. Thus

$$\text{Retail order} = \text{retail sales} + (100 - \text{inventory level})$$

The effects of these formulas on inventory level and the retail order can be seen in the following sample computation.

In a normal week

$$\text{Retail sales} = 100$$

$$\text{Retail receipts} = 100$$

$$\begin{aligned} \text{Retail inventory level} &= 100 + 100 - 100 \\ &= 100 \end{aligned}$$

$$\begin{aligned} \text{Retail order} &= 100 + (100 - 100) \\ &= 100 \end{aligned}$$

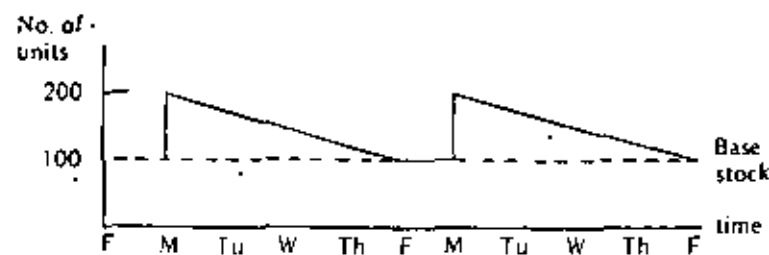


Figure 2-2 Retail inventory level.

In a week in which sales increase

$$\begin{aligned} \text{Retail sales} &= 110 \\ \text{Retail receipts} &= 100 \\ \text{Retail inventory level} &= 100 + 100 - 110 \\ &= 90 \\ \text{Retail order} &= 110 + (100 - 90) \\ &= 120 \end{aligned}$$

In a week in which sales decrease

$$\begin{aligned} \text{Retail sales} &= 90 \\ \text{Retail receipts} &= 100 \\ \text{Retail inventory level} &= 100 + 100 - 90 \\ &= 110 \\ \text{Retail order} &= 90 + (100 - 110) \\ &= 80 \end{aligned}$$

**Wholesaler  
Model  
Formulas**

The wholesaler's policies for maintaining inventory and reordering from the factory are similar to the retailer's policies. The formulas for the wholesaler and sample computations are now presented.

*Wholesale shipments* are dispatched each Wednesday from orders submitted by the retailer on the prior Friday. These orders arrive at the retailer's on the following Monday.

$$\text{Wholesale shipments} = \text{retail order (prior week)}$$

*Wholesale receipts* is the factory production of the previous week which is received each Monday morning.

$$\text{Wholesale receipts} = \text{factory production (prior week)}$$

*Wholesale inventory level* is the number of units on hand Friday afternoon at the close of business. The inventory level actually varies through the week as shown in Figure 2-3.

The formula for determining the Friday afternoon inventory level is as follows:

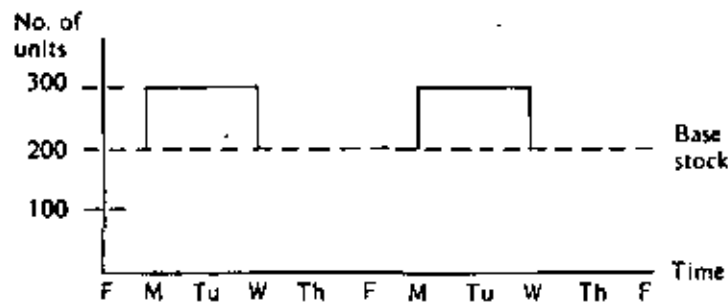


Figure 2-3 Wholesale inventory.



$$\text{Wholesale inventory level} = \text{prior inventory level} + \text{wholesale receipts} \\ - \text{wholesale shipments}$$

*Wholesale orders* are placed with the factory each Friday afternoon after taking inventory. The factory, however, requires a week to change the production rate, so two weeks pass before the wholesaler receives the actual order. The policy is to order the current week's shipments plus enough units to return the base stock to a normal level of 200 units. The formula is

$$\text{Wholesale order} = \text{wholesale shipments} \\ + (200 - \text{inventory level})$$

The effects of the wholesaler's policies can be seen in the following sample computation.

In a normal week:

$$\begin{aligned} \text{Wholesale shipments} &= 100 \\ \text{Wholesale receipts} &= 100 \\ \text{Wholesale inventory level} &= 200 + 100 - 100 \\ &= 200 \\ \text{Wholesale order} &= 100 + (200 - 200) \\ &= 100 \end{aligned}$$

In a week in which shipments increase

$$\begin{aligned} \text{Wholesale shipments} &= 110 \\ \text{Wholesale receipts} &= 100 \\ \text{Wholesale inventory level} &= 200 + 100 - 110 \\ &= 190 \\ \text{Wholesale order} &= 110 + (200 - 190) \\ &= 120 \end{aligned}$$

In a week in which shipments decrease

$$\begin{aligned} \text{Wholesale shipments} &= 90 \\ \text{Wholesale receipts} &= 100 \\ \text{Wholesale inventory level} &= 200 + 100 - 90 \\ &= 210 \\ \text{Wholesale order} &= 90 + (200 - 210) \\ &= 80 \end{aligned}$$

It should be noted that in the present simplified model, the wholesaler only services one retailer. This is an obvious oversimplification from the real world and allows the analysis to isolate the effect of a single retailer in the entire system.

Factory  
Production  
Rate

In this model, the factory maintains no inventory. The factory produces at the rate specified by the wholesale order. There is, however, a one-week delay when changing the production rate and a one-week delay for shipping. The net effect is that the wholesaler receives the actual order two weeks after it is placed with the factory. Thus, for example, one might have the situation shown in Figure 2-4.

Week number	Wholesale order	Factory rate	Wholesale receipts
1	100	100	100
2	120	100	100
3	80	100	100
4	100	120	100
5	100	80	120
6	100	100	80

Figure 2-4 Changing factory production rate.

## 2.2 NORMAL INVENTORY POLICY

This section presents the results of following a normal inventory policy. By "normal" we mean that the retailer and wholesaler follow the rules described in the preceding sections. The most significant rule, which will be analyzed in detail later, is the reorder rule. The normal reorder rule which is followed in the current problem is

*Order the current week's sales plus or minus enough to bring the base stock back to its normal level.*

Following this reorder rule and the other inventory policies outlined in Section 2.1, one can compute over a number of weeks the inventory level and orders in response to retail sales. For example, if retail sales are 100 in weeks 1 and 2, then increase to 110 in weeks 4, 5, 6, and 7, results will occur as shown in Figure 2-5.

These results are arrived at by following the computation formulas given in the preceding section. For example, the formula for the retail order each week is as follows:

$$\text{Retail order} = \text{weekly sales} + (100 - \text{inventory level})$$

The retail order in week 5 is 120 units, derived from the above formula as follows:

$$\begin{aligned} \text{Retail order} &= 110 + (100 - 90) \\ &= 120 \end{aligned}$$

Week No.	Retail					Wholesale			Factory Rate
	Sales	Rec	Inv	Order	Ship	Rec	Inv	Order	
1	100	100	100	100	100	100	200	100	100
2	100	100	100	100	100	100	200	100	100
3	110	100	90	120	100	100	200	100	100
4	110	100	80	130	120	100	180	140	100
5	110	120	90	120	130	100	150	180	100
6	110	130	110	100	120	100	130	190	140
7	110	120	120	90	100	140	170	130	180

Figure 2-5 "Normal" inventory policy.

It is quite possible to compute the results by hand for as many weeks of operation as desired. Fortunately, the computer program will do the tedious calculations. We next consider briefly the data cards required to run the computer program and then we will analyze twenty-five weeks of operation by using the computer model.

**Computer Input** This section presents the data cards required as input to the computer program. The program listing is found in Section 2.6.

*User name card* is the first card in the data deck. It is used to identify who is making the analysis and any other identification desired. This card is *free field*, in that any information may be keypunched in columns 1 to 40.

```

EXERCISE ONE BY HOY HARRIS
XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
  
```

*Control card* is the second card in the data deck. This card contains the number of weeks to be analyzed, which is punched in columns 1 and 2.

```

25
XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
  
```

*Weekly sales cards* contain the week number and the retail sales for that week. There is one card per week and the total number of cards must be exactly the number specified by the control card. The week number is keypunched in columns 1 and 2. The retail sales for the week are in columns 11, 12, and 13, *right justified* (that is, the last digit is always in column 13).

```

01      100
XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
  
```

The complete data deck setup for problem one is shown in Figure 2-6. Each typewritten line in the figure corresponds to one keypunched data card.

**Computer Output** The computer printout resulting from the normal reorder policy is depicted in Figure 2-7. The first line in the computer output is a reproduction of the information keypunched on the first data card. The last line of the computer output is information from the second data card, the control card. The notation 25 WEEKS RUN is a reminder that the control card specified that 25 weeks of data were to be run. If there is too little weekly sales data or if the weekly sales data is out of order the computer will print the message SOMETHING WRONG WITH YOUR DATA and stop processing the program.

EXERCISE ONE BY ROY HARRIS

25	
01	100
02	100
03	110
04	110
05	110
06	110
07	110
08	110
09	110
10	110
11	110
12	110
13	110
14	110
15	110
16	110
17	110
18	110
19	110
20	110
21	110
22	110
23	110
24	110
25	110

Figure 2-6 Computer input-normal policy.

PROGRAM MNSYS FOR EXERCISE ONE BY ROY HARRIS

WEEK	-----RETAIL-----				*****WHOLESALE*****				FACTORY
NO.	SALES	REC	INV	ORDER	SHIP	REC	INV	ORDER	WATE
1	100	100	100	100	100	100	200	100	100
2	100	100	100	100	100	100	200	100	100
3	110	100	90	120	100	100	200	100	100
4	110	100	80	130	120	100	180	140	100
5	110	120	90	120	130	100	150	180	100
6	110	130	110	100	120	100	130	190	100
7	110	120	120	90	100	140	170	130	100
8	110	100	110	100	90	180	260	30	100
9	110	90	90	120	100	190	350	0	130
10	110	100	80	130	120	130	360	0	30
11	110	120	90	120	130	30	260	70	0
12	110	130	110	100	120	0	140	180	0
13	110	120	120	90	100	0	40	260	70
14	110	100	110	100	90	70	20	270	100
15	110	90	90	120	100	180	100	200	260
16	110	100	80	130	120	260	240	80	270
17	110	120	90	120	130	270	380	0	200
18	110	130	110	100	120	200	460	0	80
19	110	120	120	90	100	80	440	0	0
20	110	100	110	100	90	0	350	0	0
21	110	90	90	120	100	0	250	50	0
22	110	100	80	130	120	0	130	190	0
23	110	120	90	120	130	0	0	330	50
24	110	130	110	100	120	50	0	320	140
25	110	120	120	90	100	190	90	210	300

25 WEEKS RUN 0 0 0 0

Figure 2-7 Computer output-normal policy.

**Analysis  
of the  
Normal  
Inventory  
Policy**

It is quite evident that the so-called normal inventory policy is not a very smart policy. A simple increase in retail sales to a new level 10 percent higher than before has set off uncontrollable fluctuations in the wholesale inventory and in the factory rate. Even though the factory services only one wholesaler and one retailer these uncontrollable swings cause the factory to completely shut down by week 11. Negative inventories, orders, or factory rates are not allowed.

By week 25 the situation is still not in control. The retailer has not stabilized his inventory level back to 100 units, the wholesaler has not stabilized, and the factory is going from boom to bust. This cyclic behavior in the system is the result of the lead times in the system and the "blind" ordering policies of the retailer and the wholesaler. The next two sections consider some methods for bringing this situation under control.

### 2.3 CONTROLLING THE REPLENISHMENT RATE

This section considers the problem of controlling fluctuation in the inventory system through a change in the reorder policies of the retailer and the wholesaler. The basic concept applied is that of *dampening* the amplitude of change. This concept is implemented by changing the reorder policy to decrease the amount of replenishment of the base stock. The new policy, the computer output, and an analysis of the results are presented here.

**The  
Replenishment  
Concept**

According to the old policy, the reorder formula for the retailer is

$$\text{Retail order} = \text{retail sales} + (100 - \text{inventory level})$$

This policy says in effect that the retailer wants to replenish the stock he has actually sold during the week. In addition, if sales are above or below the base stock level of 100 units he wants to maintain, he will order enough to bring the base stock to 100.

This policy appears reasonable enough but it is based on the rather nearsighted assumptions that

- future sales will be the same as this week's
- stock replenishment is instantaneous

The first assumption is obviously risky for almost any retail operation. The second assumption is obviously not fulfilled in the present system. The retailer orders on Friday, the goods are shipped on the next Wednesday and received the following Monday. Each Friday, the retailer orders enough "to bring the base stock back to normal" even though the goods he ordered the prior Friday to bring the base stock back to normal still have not arrived. When the order does arrive the retailer overreacts by ordering too little the next time. The net result, as seen in Section 2.2, is that the retailer is never able to stabilize his order or inventory level. Business cycles may be caused by just this kind of behavior.

One way to dampen the swings is to change the replenishment policy to specify that only a percentage of the base stock difference is to be ordered. Thus we change the formula to

$$\text{Retail order} = \text{retail sales} + (100 - \text{inventory level}) (4\%)$$

If we set *A* at 50 percent and thus try to make up only one-half the difference, then we can compare the retail order when sales are up to 110 units.

<i>Old Policy</i>	<i>New Policy</i>
Retail order = 110 + (100 - 90)	Retail order = 110 + [(100 - 90) × 0.5]
= 110 + 10	= 110 + 5
= 120	= 115

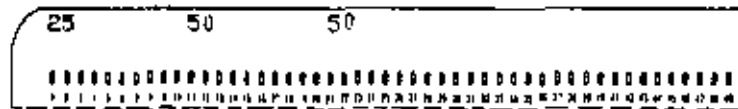
When sales are down to 90 units the result is

<i>Old Policy</i>	<i>New Policy</i>
Retail order = 90 + (100 - 110)	Retail order = 90 + [(100 - 110) × 0.5]
= 90 - 10	= 90 - 5
= 80	= 85

The overall effect of the new policy is that the retailer only partly reacts to increases or decreases in the base stock and allows some time for inventories to return to normal. The wholesaler may follow a similar policy in ordering from the factory by including *B* percent in the wholesale order formula.

Computer  
Input  
- Replenishment  
Rate

*User name card* remains unchanged. The new reorder policy is implemented by specifying on the *control card* the percentage value for *A* (retailer) in columns 11 and 12, and *B* (wholesaler) in columns 21 and 22.



If the field is left blank, the value for *A* or *B* is set to 100 percent. Otherwise, *A* or *B* may be set from 01 to 99 by the user.

*Weekly sales cards* are keypunched as in Section 2.2.

A complete data deck listing for the new policy is shown in Figure 2-8. The retailer and the wholesaler only try to make up 50 percent of the difference in base stock under the new policy.

Computer  
Output  
- Replenishment  
Rate

The computer printout for the new 50 percent reordering level policy which is generated from these data cards is shown in Figure 2-9. Note that the last line of the printout includes the input values for *A* and *B* specified in the control card.

Analysis  
of the  
Replenishment  
Rate  
Control.

The overall result of the new reordering policy is a dramatic improvement in the performance of the inventory system.

- Retail reorders match the new sales level within eleven weeks.
- Wholesale reorders match the new sales level within twelve weeks.
- Factory rate is not yet stable, but appears to be dampening out.

Most significantly, the system is no longer out of control, i.e., caught up in uncontrollable fluctuation. The fluctuations have been dampened out and the system stabilizes itself to the new sales level.

EXERCISE	IND BY ROY HARRIS
25	50
01	100
02	100
03	110
04	110
05	110
06	110
07	110
08	110
09	110
10	110
11	110
12	110
13	110
14	110
15	110
16	110
17	110
18	110
19	110
20	110
21	110
22	110
23	110
24	110
25	110

Figure 2-8 Computer input—replenishment rate.

PROGRAM INSYS FOR EXERCISE IND BY ROY HARRIS

WEEK	RETAIL				HOLESAL			FACTORY	
NO.	SALES	REC	INV	ORDER	SHIP	REC	INV	ORDER	RATE
1	100	100	100	100	100	100	200	100	100
2	100	100	100	100	100	100	200	100	100
3	110	100	90	115	100	100	200	100	100
4	110	100	80	120	115	100	185	123	100
5	110	115	85	118	120	100	165	134	100
6	110	120	95	113	110	100	148	144	123
7	110	118	103	109	110	123	158	134	130
8	110	113	105	108	109	120	180	116	144
9	110	109	104	108	108	144	223	96	134
10	110	108	101	109	108	134	248	84	116
11	110	108	99	110	109	116	254	82	96
12	110	109	94	111	110	96	240	91	84
13	110	110	99	110	111	84	214	104	82
14	110	111	100	110	110	82	185	114	90
15	110	110	100	110	110	90	165	127	104
16	110	110	100	110	110	104	159	130	118
17	110	110	100	110	110	118	167	120	127
18	110	110	100	110	110	127	185	118	130
19	110	110	100	110	110	130	205	107	126
20	110	110	100	110	110	126	221	94	118
21	110	110	100	110	110	114	229	96	107
22	110	110	100	110	110	107	226	97	94
23	110	110	100	110	110	90	216	107	96
24	110	110	100	110	110	96	201	104	97
25	110	110	100	110	110	97	188	116	102

25 WEEKS RUN 53 50 0 0

Figure 2-9 Computer output—replenishment rate.

However, all is still not perfect. There is still a long time lag before the factory "catches on" to the new rate. Moreover, a simple 10 percent increase in sales still causes a 20 percent change in the wholesale shipments and a 44 percent change in the factory rate. Section 2.4 considers additional control measures for bringing the inventory system under even tighter control.

## 2.4 CONTROL OF LEAD TIME

This section considers the problem of controlling fluctuations in the inventory system through a decrease in the lead time between the order and the receipt of goods. The basic concept is to change the lead time required to respond to changes in the system. This concept is implemented by testing the effect of faster delivery from the wholesaler and faster changeover to a new production rate by the factory.

### Lead Time Concept

Under the "normal" system setup the two basic lead times in the system were (1) between the order and receipt of goods by the retailer, and (2) between the order and receipt of goods from the factory. These were as follows:

#### *Retailer normal lead time*

Order on	Delivered on
Friday week 1	Monday week 3

#### *Wholesaler normal lead time*

Order on	Change rate	Deliver goods
Friday week 1	Week 3	Monday week 4

The effects of these lead times are clearly seen in Section 2.2 when the retailer reorders every Friday to make up goods that have previously been ordered. In effect, he makes a double reorder for the same goods. In addition, the factory takes seven weeks to begin to respond to a change in retail sales.

In the current example we will consider the effects of decreasing this lead time. The new policy is to work the wholesaler on Saturday in order to deliver Friday-afternoon orders the very next Monday. Thus

#### *Retailer decreased lead time*

Order on	Delivered on
Friday week 1	Monday week 2

Similarly the lead time for the wholesaler may be changed if the factory can shift to a new production rate without a week lag and if the factory ships over the weekend.

#### *Wholesaler decreased lead time*

Order on	Change rate	Delivered in
Friday week 1	week 2	week 3



Computer  
Input  
-Lead  
Times

The *user name card* is the same as that in Section 2.2. The change in the lead times is implemented in the computer model by two fields in the *control card*. A speedup of one week in the wholesaler deliveries is accomplished by placing a 1 in column 31 of the control card. A speedup of one week in the changeover of the factory is accomplished by placing a 1 in column 41 of the control card.

The control card now reads

25	50	50	1	1
.....				
.....				

The *weekly sales cards* retain the same format.

The complete data deck setup to test the effects of the decreased lead time is shown in Figure 2-10.

Computer  
Output

The computer printout with lead time decreased is shown in Figure 2-11.

Analysis of  
Lead  
Time  
Control

The result of the new lead time policy is a further improvement in the overall performance of the inventory system.

Retail orders match the new sales rate within five weeks.

---

EXERCISE	THREE	BY	ROT	MARSH
25	50	50	1	1
01	100			
02	100			
03	114			
04	110			
05	110			
06	110			
07	110			
08	110			
09	110			
10	110			
11	110			
12	110			
13	110			
14	110			
15	110			
16	110			
17	110			
18	110			
19	110			
20	110			
21	110			
22	110			
23	110			
24	110			
25	110			

---

Figure 2-10 Computer input-lead times.

PROGRAM INVENTORY FOR EXERCISE THREE BY ROY HARRIS

WEEK NO.	RETAIL				WHOLESALE				FACTORY
	SALES	REC	INV	ORDER	SHIP	REC	INV	ORDER	RATE
1	100	100	100	100	100	100	200	100	100
2	100	100	100	100	100	100	200	100	100
3	110	100	90	115	115	100	185	123	100
4	110	115	95	113	113	100	173	126	123
5	110	113	98	111	111	123	184	119	126
6	110	111	99	111	111	126	199	111	119
7	110	111	99	110	110	119	208	106	111
8	110	110	100	110	110	111	209	106	106
9	110	110	100	110	110	106	205	107	106
10	110	110	100	110	110	106	201	110	107
11	110	110	100	110	110	107	148	111	110
12	110	110	100	110	110	110	198	111	111
13	110	110	100	110	110	111	199	111	111
14	110	110	100	110	110	111	200	111	111
15	110	110	100	110	110	111	200	111	110
16	110	110	100	110	110	110	201	119	110
17	110	110	100	110	110	110	200	110	110
18	110	110	100	110	110	110	200	110	110
19	110	110	100	110	110	110	200	110	110
20	110	110	100	110	110	110	200	110	110
21	110	110	100	110	110	110	200	110	110
22	110	110	100	110	110	110	200	110	110
23	110	110	100	110	110	110	200	110	110
24	110	110	100	110	110	110	200	110	110
25	110	110	100	110	110	110	200	110	110

25 WEEKS RUN 50 50 1 1

Figure 2-11 Computer output—lead times.

Wholesaler orders match the new sales rate within eight weeks.  
Factory rate is set to the new sales level in nine weeks.

In addition to cutting response lags down, there is less fluctuation in the inventory levels.

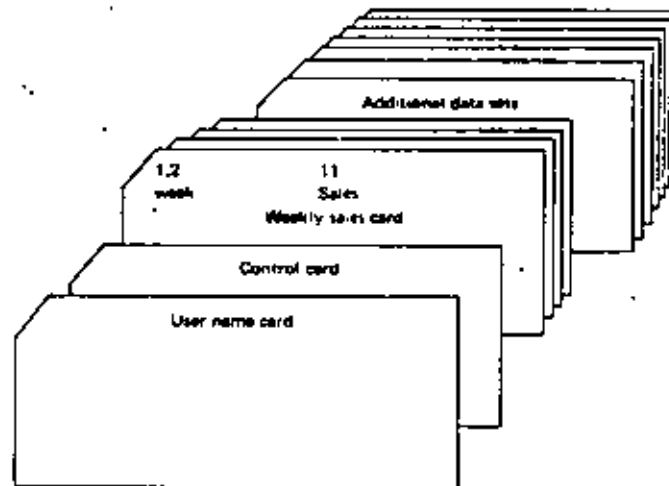
A simple increase in sales of 10 percent causes a 15 percent change in wholesale shipments, down from the prior 20 percent change. Also, the factory rate changes 20 percent, down from the prior 44 percent. Thus, in general, it may be said that the inventory system is now in better control.

There are, however, many complications one could add to the model before it would approximate the real world. For example, customers are never so kind as to provide such nice uniform retail sales. Hence, the user might want to try his hand at controlling the inventory system if retail sales were to randomly fluctuate between, say, 80 units and 120 units in any given week.

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## 2.5 INSYS DATA DECK STRUCTURE



Control Card	Card columns	Format	Item
	1, 2	12	No. of weeks
	11; 12	12	Percentage value for retailer
	21, 22	12	Percentage value for wholesaler
	31	11	Wholesaler lead time
	41	11	Factory lead time

16

2.6 INSYS PROGRAM LISTING

C	PROGRAM INSYS	IBM	1
C	INVENTORY SYSTEM CONTROL MODEL	A	2
C	COPYRIGHT 1969 BY ROY D HARRIS	A	3
C	THIS VERSION FOR IBM 360	IBM	4
	DIMENSION ALPHA(10)	A	5
C		A	6
C	READ AND PRINT STUDENTS NAME CARD	A	7
	NI = 5	IBM	8
	NO = 6	IBM	9
1	HEAD (MI+26) ALPHA	A	10
	WRITE (MO+27) ALPHA	A	11
C		A	12
C	HEAD CONTROL CARD AND INITIALIZE	A	13
	HEAD (MI,28) N, IN, IM, LN, LF	A	14
	IF (IN) 2,2+3	A	15
2	A = 1.0	A	16
	GO TO 4	A	17
3	A = IM/100.	A	18
4	IF (LN) 5,5+6	A	19
5	B = 1.1	A	20
	GO TO 7	A	21
6	B = IM/100.	A	22
7	M1 = 100.	A	23
	MU = 100.	A	24
	MS = 100.	A	25
	M1 = 200.	A	26
	M02 = 100.	A	27
	M01 = 100.	A	28
	FR = 100.	A	29
C		A	30
C	PRINT HEADINGS FOR WEEKLY OUTPUT	A	31
	WRITE (MO+29)	A	32
	WRITE (MO+30)	A	33
C		A	34
C	START OF DO LOOP THROUGH WEEKLY COMPUTATIONS	A	35
	DO 24 I = 1, N	A	36
C		A	37
C	READ AND CHECK DATA CARD CONTAINING WEEKLY SALES	A	38
	READ (MI+31) KWEEK, SALES	A	39
	IF (I-KWEEK) 4,4+8	A	40
8	WRITE (MO+32)	A	41
	GO TO 25	A	42
C		A	43
C	COMPUTE RETAIL INVENTORY LEVEL AND ORDER	A	44
9	MREC = MS	A	45
	MINV = RI+MREC-SALES	A	46
	IF (MINV) 10,10+11	A	47
10	MINV = 0.0	A	48
11	MORD = SALES+((10)-MINV)*A1	A	49
	IF (MORD) 12,12+13	A	50
12	MORD = 0.0	A	51
C		A	52
C	SET WHOLESALE DELIVERY RATE FROM CONTROL CARD	A	53
13	IF (LW=1) 15,14+15	A	54
14	MSHIP = MORD	A	55
	GO TO 16	A	56
15	MSHIP = RU	A	57
C		A	58
C	COMPUTE WHOLESALE INVENTORY LEVEL AND ORDER	A	59
16	MREC = MW	A	60
	MINV = M1+MREC-MSHIP	A	61
	IF (MINV) 17,17+18	A	62

17	WINV = 0.0	A	63
18	WORD = W5MIP*((200.-WINV)*6)	A	64
	IF (WORD) 19,19,20	A	65
19	WORD = 0.0	A	66
C		A	67
C	SET FACTORY RATE FROM CONTROL CARD	A	68
20	IF 1LF-11 22,21,22	A	69
21	FRATE = W01	A	70
	GO TO 23	A	71
22	FRATE = W02	A	72
C		A	73
C	PRINT OUT CURRENT WEEK RESULTS	A	74
23	WRITE (M0,33) I, SALES, RREC, RINV, RORD, WSHIP, WREC, WINV, WORD,	A	75
	FRATE	A	76
C	UPDATE ORDERING AND FACTORY RATE FOR NEXT WEEK	A	77
	W1 = WINV	A	78
	W0 = RORD	A	79
	W5 = WSHIP	A	80
	W1 = WINV	A	81
	W02 = W01	A	82
	W01 = W0WU	A	83
	FR = FRATE	A	84
24	CONTINUE	A	85
C		A	86
C	PRINT CONTROL CARD VALUES	A	87
	WRITE (M0,34) N, IR, IX, LX, LF	A	88
25	CONTINUE	A	89
	GO TO 1	A	90
C		A	91
C		A	92
C		A	93
26	FORMAT (10A)	A	94
27	FORMAT (1M,18MPROGRAM INSYS FOR ,10A)	A	95
28	FORMAT (12,4A,12,8X,12,8A,11,9X,11)	A	96
29	FORMAT (13M0WEEK -----RETAIL-----	A	97
	1 JUM*****WOLESALE*****FACTORY)	A	98
30	FORMAT (1M ,136ND, SALES REC INV ORDER SHIP ,	A	99
	1 23MREC INV ORDER RATE)	A	100
31	FORMAT (12,8X,F3,1	A	101
32	FORMAT (3;M SOMETHING WRONG WITH YOUR DATA)	A	102
33	FORMAT (1M ,12,4F6,0,F7,0,3F6,0,F7,0)	A	103
34	FORMAT (1M,12,10M WEEKS RUN,413)	A	104
	END	A	105

# EOQ

**a model for inventory ordering policy**  
*computes the most economical inventory order quantity under a variety of conditions, including price discounts, shortage cost, and storage limitations.*

A primary purpose of inventories is to decouple production from consumption. Inventories are goods which may be used as a hedge against uncertainty in demand or as a buffer for production fluctuations.

The *replenishment* of inventories is the topic of this exercise. We describe an elementary, but fundamental, inventory replenishment model: the Economic Order Quantity (EOQ) model. In Section 3.1, the development of the basic EOQ model is given. In Section 3.2, the basic EOQ model is extended to include a real world phenomenon: quantity price discounts. In Section 3.3, the basic model is modified to incorporate shortage costs. Consideration of storage limitations and their effects upon the order quantity decision are the subject of Section 3.4.

The rational basis for deciding how much, if any, inventory to hold, and to order, is an economic basis. There are costs associated with holding inventory in stock, e.g., insurance, taxes, interest on capital, and so on. Conversely, there are costs related to not holding inventory, e.g., lost sales, frequent purchase orders, production delays, etc. There is also the cost of purchasing the replenishment for inventories, e.g., paperwork and material handling.

The intent of this exercise is to allow the user an opportunity to get a feel for the *effects* of changing parametric values in the basic economic order quantity formulas. Hence, the reader is encouraged to conduct *sensitivity analysis* on each parameter in the EOQ formula.

## 3.1 ECONOMIC ORDER QUANTITY

This section introduces the basic Economic Order Quantity (EOQ) model. It also describes in detail the data cards required for the accompanying computer program, and the computer output.

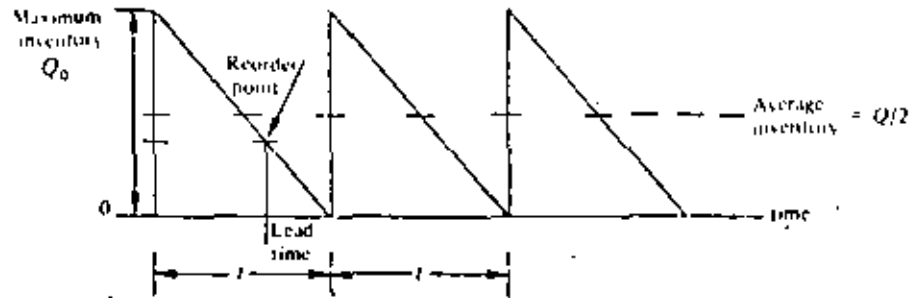


Figure 3-1 Inventory level and usage pattern for EOQ model.

#### The Economic Order Quantity Inventory Model

A basic assumption of the EOQ model is that the consumption of the inventory is constant over time and that it is possible to replenish the inventory on very short notice. The quantity in inventory at any point in time, for this circumstance, is shown in Figure 3-1. The basic EOQ model also assumes no quantity price discounts and no backorders.

In this "sawtooth" usage pattern the inventory is consumed over time until it is depleted. It is then instantly replenished (straight vertical line), and the usage continued.

#### Inventory Cost

The rational basis for determining inventory levels is to balance the cost of holding inventory against the cost of not holding inventory. In the consumption situation described above, the types of cost for holding the inventory are fairly obvious. Storage must be provided for the inventory and the inventory must be financed.

The cost of not holding inventory may not be so obvious. Since it was assumed that the inventory was easily and instantaneously obtainable, then there is no cost attached to being caught short. However, like a housewife who goes to the grocery store three times each day to purchase a single meal, there is a cost attached to procurement of the inventory. Not holding inventory may lead to very high procurement cost.

The issue in the economic order quantity model is to determine how much inventory to order each time. The cost of procurement per unit goes down if more is ordered each time, but the cost of holding inventory goes up. Figure 3-2 shows a graphic representation of these costs as they vary with the size of the order. The total incremental cost of inventory is shown as the top curve on the graph in the figure.

$$\text{Total incremental cost} = \text{holding cost} + \text{ordering cost}$$

The best inventory policy is to order the amount of inventory each time which yields the minimum total cost. This "correct quantity" to order is called the economic order quantity (EOQ).

The following definitions and variables will be used in deriving a mathematical expression for the EOQ.

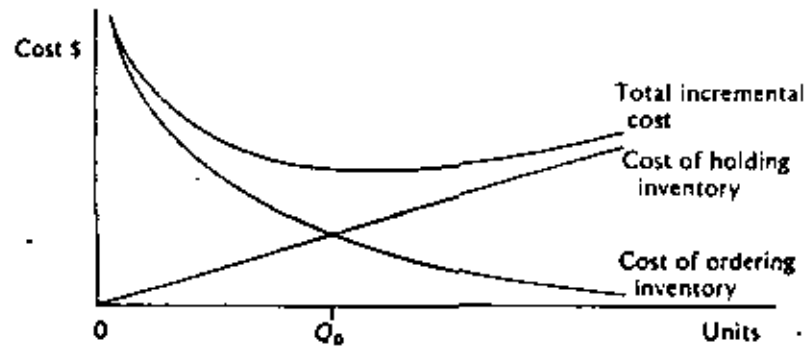


Figure 3-2 Costs of holding and ordering inventory.

$$\begin{aligned} \text{Holding cost} &= (\text{average inventory}) \times (\text{unit inventory holding cost per year}) \\ &= (Q/2) \times (P \times FH) \end{aligned}$$

where  $Q$  = quantity ordered

$P$  = price per unit

$FH$  = annual unit holding cost as percentage of the unit price

$$\text{Order cost} = (\text{number of orders per year}) \times (\text{cost per order})$$

$$= \left(\frac{R}{Q}\right) \times (C_p)$$

where  $R$  = annual requirements in units, level demand

$C_p$  = procurement cost (includes costs of paperwork, handling, etc.)

$$\begin{aligned} \text{Cost of inventory} &= (\text{unit price}) \times (\text{annual requirements}) \\ &= (P) \times (R) \end{aligned}$$

$$\text{Total cost} = \text{holding cost} + \text{order cost} + \text{cost of inventory}$$

$$\text{Total cost} = \frac{Q \times P \times FH}{2} + \frac{R \times C_p}{Q} + P \times R$$

$$\text{Total incremental cost} = \frac{Q \times P \times FH}{2} + \frac{R \times C_p}{Q}$$

Solving for the economic order quantity  $Q_0$  by algebra: the minimum point on the total incremental cost curve is where the inventory holding cost and the procurement cost curves intersect. Where they intersect they must be equal. Therefore, at  $Q_0$ :

$$\frac{Q}{2} (P \times FH) = \left(\frac{R}{Q}\right) C_p$$

Clearing denominators:

$$Q(Q)(P \times FH) = 2(R)C_p$$

$$Q^2 = \frac{2RC_p}{P \times FH}$$

$$Q = \sqrt{\frac{2RC_p}{P \times FH}}$$



Solving for  $Q$  by calculus: the minimum point on the total incremental cost curve is where the first derivative equals zero. Taking the first derivative with respect to  $Q$  and setting it equal to zero:

$$0 = (P \times FH)/2 - (R/Q^2)Cp$$

$$\frac{(P \times FH)}{2} = \frac{RCp}{Q^2}$$

$$Q^2 = \frac{2RCp}{P \times FH}$$

$$Q = \sqrt{\frac{2RCp}{P \times FH}}$$

Sample  
Problem  
One

It is a straightforward matter to find the economic order quantity (EOQ) and the total inventory cost (TC), when the values for  $R$ ,  $Cp$ ,  $P$ , and  $FH$  are known. For example, if

$R = 1600$  units (total annual usage)

$Cp = \$5.00$  (cost of one procurement)

$P = \$1.00$  (unit price of product)

$FH = 0.10$  (unit holding cost per year as percentage of price), then

$$Q = \sqrt{\frac{2 \times 1600 \times 5.00}{1.00 \times 0.1}}$$

$Q = 400$  units

$$\text{Total cost (TC)} = \frac{400 \times 1.00 \times 0.1}{2} + \frac{1600 \times 5.00}{400} + 1.00 \times 1600$$

$$TC = 20.00 + 20.00 + 1600.00$$

$$TC = \$1640.00$$

This computation is not too tedious to do, if there is only one. However, when there are many alternatives to test and when more complicated formulas are required, then a computer program is a great computational aid. The next section introduces the data input and computer output for the simple example shown above. In following sections more complicated problems illustrating the use of the computer program will be presented.

Computer  
Input  
-Problem  
One

Before describing the data cards, several comments will be made pertaining to the program itself. The user should keep these comments in mind when using the program.

The program is applicable only to a fixed-order-quantity inventory system, and all quantities in the program are expressed in annual amounts or rates. In the case of  $R$  (annual inventory requirement), a level usage rate is assumed throughout the year. In order to convert the program for monthly or seasonal calculations one would have to adjust the inputs to the same time scale.

Although the figure available for inventory holding costs is often stated as an annual cost per unit, this program requires that holding costs be expressed as a percentage of the unit value of inventory.

To run the economic order quantity computer model, only two cards



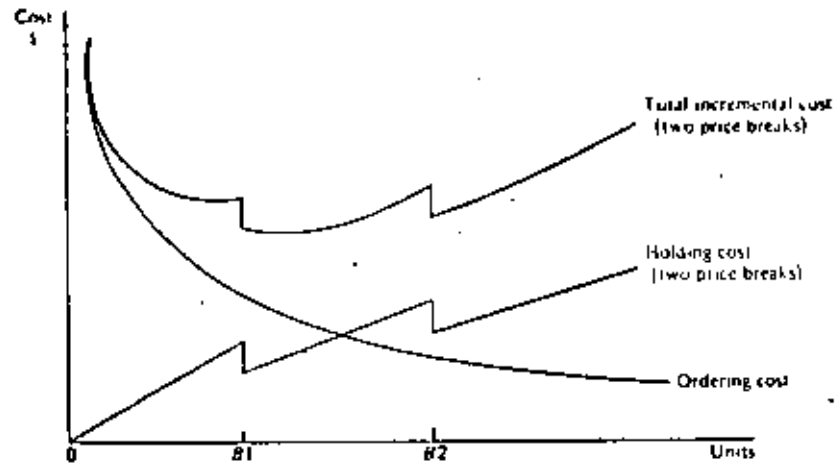


Figure 3-5 The effects of price discounts on the economic order quantity.

as input variables. Inasmuch as price discounts do happen in reality, the extension of the EOQ model to include price discounts will be the subject of this section.

The  
EOQ Model  
—With  
Price  
Discounts

Referring to Section 3.1, the user should note that in the derivation of the EOQ model the price per unit ( $P$ ) affects the holding cost  $(Q/2) \times (P \times FH)$ , but not the ordering costs. Nevertheless, if price discounts are introduced as variables, they will influence the total incremental costs ( $TIC$ ). The effects of price discounts are graphically illustrated in Figure 3-5.

The addition of the quantity discounts to the economic order quantity model makes it somewhat more difficult to obtain a solution. It is not possible to find directly the lowest point on the Total Incremental Cost ( $TIC$ ) curve shown in Figure 3-4. The general approach used is to investigate the  $TIC$  curve at each price break. In addition, the curve must be analyzed at different points near the price break giving the lowest  $TIC$  to see if an even better solution can be found. Problem Two illustrates this general search solution when price discounts are to be considered.

Sample  
Problem  
Two

The supplier has recently revised his pricing policies and now offers the following price discounts: If one orders in lot sizes of  $B1$  ( $Q_{B1} = 300$ ), the price will be \$0.90/unit ( $P_2$ ); if one orders quantity  $B2$  ( $Q_{B2} = 2000$ ), the price will be \$0.80/unit ( $P_3$ ).

Solution  
for EOQ  
with Two  
Price  
Breaks

First calculate  $Q_3$  using  $P_3$ ; if it is greater than  $Q_B$ , then order  $Q_3$ . If it is less than  $Q_B$ , then (using  $P_3$ ) it is infeasible.

Next, calculate  $Q_2$  using  $P_2$ . If  $Q_2 > Q_{B2}$ , then order  $Q_{B2}$ .

If  $Q_2$  is less than  $Q_{B2}$  but greater than  $Q_{B1}$ , i.e.,  $Q_{B1} < Q_2 < Q_{B2}$ , then compare  $TC_2$  with  $TC_{B2}$ .

If  $TC_2 > TC_{B2}$ , then order  $Q_{B2}$ .



```

PROGRAM EQ FOR HAGGARD EQ PROBLEM TWO. PRICE DISCOUNTS
INPUT DATA IS *****
      R   CP   FM   P1   CS   H1   P2   H2   P3   M
      1600 5.00 .10 1.00  0   300  .90 2000 .80  0

ANALYSIS RESULTS ARE ****
OPTIMUM ORDER QUANTITY IS                2000.00
AT A PRICE PER ITEM OF                    .80
YIELDING A TOTAL INVENTORY COST OF        1364.00
WHERE THE NUMBER OF ORDER CYCLES PER YEAR IS  .00
    
```

Figure 3-7 Computer output—Problem Two.

Computer Output  
—Problem Two

The computer printout resulting from the above data is shown in Figure 3-7.

3.3 SHORTAGE COSTS

Just as it is true that in the real world quantity price discounts exist, it is also true that *backorders* are a reality. By allowing backorders we are saying that if an order cannot be filled at this time due to stock shortages, then as soon as inventory is available previously unfilled orders, i.e., backorders, will be the first orders to be filled. However, in an inventory system allowing for backorders (see Figure 3-8) a *shortage cost* is usually input relating to the backorder quantities. Generally, this shortage cost consists of costs due to (1) possible lost sales due to stockouts, (2) decreased customer satisfaction, (3) additional costs associated with rush shipments, and so on.

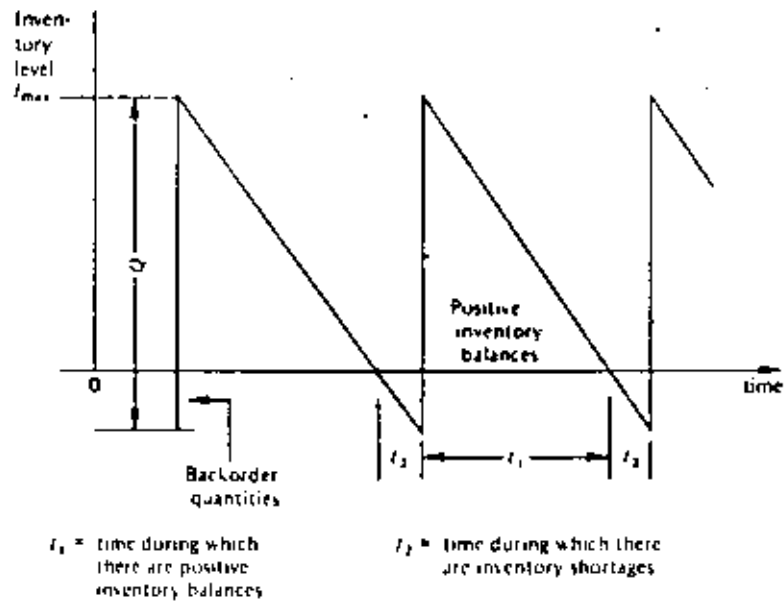


Figure 3-8 An inventory system with  $(Q - I_{max})$  backorders allowed.

The basic EOQ formula may be modified to incorporate shortage costs as follows:

1.  $C_p$  = procurement cost per order (unchanged)

2.  $\frac{(P \times FH)(I_{max})}{2} t_1$  = the holding cost of the *positive inventory balance* during time  $t_1$  ( $t$  is on an annual basis, i.e.,  $t$  = a fraction of a year).  
Since  $t_1 = I_{max}/R$ , this becomes:

$$\frac{(P \times FH)I_{max}^2}{2R}$$

3.  $C_s \frac{(Q - I_{max})}{2} t_2$  = the shortage cost of the backorders during time  $t_2$ .  
Since  $t_2 = \frac{Q - I_{max}}{R}$ , this becomes:

$$C_s \frac{(Q - I_{max})^2}{2R}$$

where  $I_{max}$  = maximum level of inventory and  
 $C_s$  = shortage cost.

Hence, the total incremental cost for one cycle,  $t_1 + t_2$ , of an inventory system which allows backorders is

$$C_p + (P \times FH) \frac{(I_{max}^2)}{2R} + C_s \frac{(Q - I_{max})^2}{2R}$$

The annual total incremental cost is now obtained by multiplying the above equation through by the number of orders placed per year,  $R/Q$ :

$$TIC = \frac{R \times C_p}{Q} + (P \times FH) \frac{(I_{max}^2)}{2Q} + C_s \frac{(Q - I_{max})^2}{2Q}$$

To determine optimal values for  $Q$  and  $I_{max}$ , take the partial derivatives of the above equations with respect to  $Q$  and  $I_{max}$ , equate to zero and obtain

$$Q = \sqrt{\frac{2RC_p}{P \times FH}} \times \sqrt{\frac{P \times FH + C_s}{C_s}}$$

$$I_{max} = \sqrt{\frac{2RC_p}{P \times FH}} \times \sqrt{\frac{C_s}{P \times FH + C_s}}$$

$$TIC = \sqrt{2(P \times FH)RC_p} \times \sqrt{\frac{C_s}{P \times FH + C_s}}$$

However, if either  $Q$  or  $I_{max}$  is constrained, their respective values are obtained as follows:

1. When  $Q$  is constrained, for example, fixed at price discount quantities, then  $I_{max}$  is calculated as

$$I_{max} = \frac{C_s Q}{C_H + C_s}$$



3.4 STORAGE LIMITATIONS

In this section, an additional constraint of maximum storage limitations, either in terms of available warehouse space or available capital, will be placed upon the basic EOQ model. This is intended to be an illustrative example of an additional type of constraint which may be (and in the real world is) imposed upon the basic EOQ model. By incorporating this added constraint the reader should get some additional insight into the problems that face management when determining what quantities to purchase from suppliers.

Sample Problem Four

This problem is basically the same as Sample Problem One except that the additional constraint of maximum warehouse space available ( $W$ ) has been imposed.

In this problem,  $W = 100$  units. From Sample Problem One,  $Q = 400$  units, but since  $W < Q$ , the order quantity must be  $Q = W = 100$  units.

In this problem, the cost of the limited storage constraint is  $TC_{prob1} - TC_w$ .

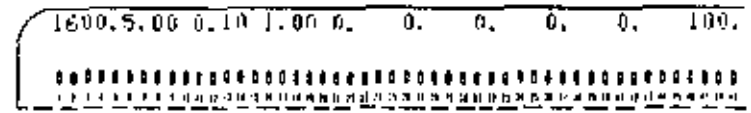
$$TC_w = \frac{100(1.00)(0.10)}{2} + \frac{1600(5.00)}{100} + 1600(1.00)$$

$$= 5 + 80 + 1600 = \$1685.00$$

$$Cost_w = TC_1 - TC_w = \$1640.00 - \$1685.00 = \$45.00$$

Computer Input - Problem Four

The data card of the above example problem follows the same form as outlined previously, with one addition. The maximum warehouse space available, expressed in units, is keypunched in columns 46-50. The data card looks like this:



The computer input for this example problem is shown in Figure 3-11.

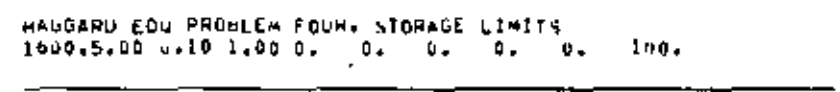


Figure 3-11 Computer input-Problem Four.

Computer Output - Problem Four

The computer output will indicate whether or not the warehouse constraint has had an effect on the economic order quantity. If an economic order quantity has been determined which exceeds  $W$ , the output will indicate that this has happened.

Furthermore, on the output will be a statement to the effect that, if the warehouse restrictions are operative, the order quantity determined may not be optimal. Suggestions are made for a method to determine the optimal quantity if this restraint is present. The computer output is shown in Figure 3-12.



```

PROGRAM EOQ FOR MAGGARD EOQ PROBLEM FOUR, STORAGE LIMITS
INPUT DATA IS *****
      R      CP      FH      P1      CS      R1      P2      B2      P3      W
      1600   5.00   .10   1.00      0      0      0      0      0   100

ANALYSIS RESULTS ARE ****
BEFORE THE WAREHOUSE STORAGE LIMITATION IS APPLIED
OPTIMUM ORDER QUANTITY IS                400.00
AT A PRICE PER ITEM OF                    1.00
YIELDING A TOTAL INVENTORY COST OF        1600.00
WHERE THE NUMBER OF ORDER CYCLES PER YEAR IS  4.00

THE ORDER QUANTITY IS LIMITED BY THE WAREHOUSE SPACE
RESTRICTION AND IS NOT AT AN OPTIMUM. LOOSEN THE
RESTRICTION AND RUN AGAIN OBSERVING THE EFFECT.

ANALYSIS RESULTS ARE ****
AFTER THE WAREHOUSE STORAGE LIMITATION IS APPLIED
OPTIMUM ORDER QUANTITY IS                100.00
AT A PRICE PER ITEM OF                    1.00
YIELDING A TOTAL INVENTORY COST OF        1685.00
WHERE THE NUMBER OF ORDER CYCLES PER YEAR IS  16.00
THIS ORDER QUANTITY IS AT THE MAXIMUM WAREHOUSE CAPACITY

```

Figure 3-12 Computer output-Problem Four.

To conclude our discussion of economic order quantity models and, in particular this computer model, we would point out:

1. that the model is, in its present form, limited to only two price breaks.
2. the inclusion of shortage costs certainly complicates the storage limitation problem. In this model, when backorders and storage limitations are included in the same problem, the assumption is made that the backorders are instantaneously filled and that the storage limitation  $W$  is a constraint upon  $I_{max}$  and not upon  $Q$ . The user must remember that if  $I_{max}$  is constrained by  $W$  then neither  $Q$  nor  $I_{max}$  will be optimal.
3. this model will solve problems including one or all of the constraints previously described in a single problem. To appreciate this fact the reader may wish to solve the following problem manually and then by the use of the herein described EOQ model.

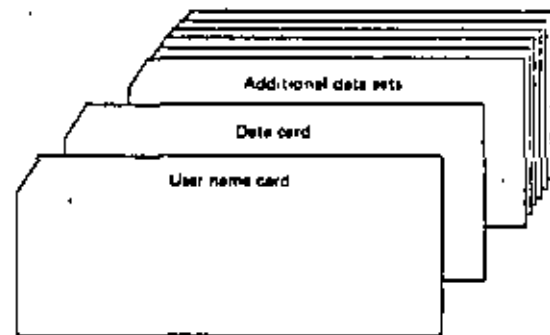
*Data*

$R$	$C_p$	$FH$	$P_1$	$C_s$	$B1$	$P_2$	$B2$	$P_3$	$W$
1600	5.00	0.10	1.00	0.30	300	0.90	500	0.80	350

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### 3.5 EOQ DATA DECK STRUCTURE



Data Card	Card column	Format	Item
	1-5	F5.0	annual usage requirement
	6-10	F5.0	ordering cost
	11-15	F5.0	holding cost
	16-20	F5.0	unit price
	21-25	F5.0	shortage cost
	26-30	F5.0	minimum order quantity—first price discount
	31-35	F5.0	unit price—first price discount
	36-40	F5.0	minimum order quantity—second price discount
	41-45	F5.0	unit price—second price discount
	46-50	F5.0	maximum warehouse space available

3.6 EOQ PROGRAM LISTING

```

C      PROGRAM EOQ
C* ECONOMIC ORDER QUANTITY MODEL
C* COPYRIGHT ROY D HARRIS OCTOBER 1970
C* THIS VERSION FOR THE IBM 360
C*
C* R = ANNUAL USAGE REQUIREMENT, LEVEL DEMAND
C* CP = COST OF ONE PURCHASE ORDER
C* FM = HOLDING COST AS A PERCENTAGE OF UNIT PRICE
C* P(1) = PRICE OF EACH UNIT BEFORE DISCOUNT P(1)=P1
C* P(2) = PRICE OF EACH UNIT AT FIRST DISCOUNT BREAK POINT
C* P(3) = PRICE OF EACH UNIT AFTER FIRST DISCOUNT P(3) = P2
C* P(4) = PRICE OF EACH UNIT AT SECOND DISCOUNT BREAK POINT
C* P(5) = PRICE OF EACH UNIT AFTER SECOND DISCOUNT P(5) = P3
C* P(6) = PRICE OF EACH UNIT AT WAREHOUSE CAPACITY RESTRAINT
C* EOQ = ECONOMIC ORDER QUANTITY
C* B(1) = FIRST DISCOUNT BREAK POINT B(1) = B1
C* B(2) = SECOND DISCOUNT BREAK POINT B(2) = B2
C* CS = SHORTAGE COST
C* W = MAXIMUM WAREHOUSE SPACE AVAILABLE
C* TCST = TOTAL COST AT EOQ
C* ON = NUMBER OF ORDERS PER YEAR AT EOQ
C* Q(1) = EOQ AT P(1)
C* Q(3) = EOQ AT P(3)
C* Q(5) = EOQ AT P(5)
C* Q(2) = B(1)
C* Q(4) = B(2)
C* Q(6) = FOR CS=0 Q(6)=OPTIMUM ORDER AT ENV(6) = W FOR CS NOT 0
C* TC(1) = TOTAL COST
C* TC(I) = TOTAL COST AT Q(I) AND ENV(I) FOR I = 1 TO 6
C* ENV(I) = MOST ECONOMICAL INVENTORY LEVEL AT EOQ =Q(I) I=1 TO 5
C* ENV(6) = W
C* ENV = OPTIMAL INVENTORY WHEN CS NOT 0
C*
C*****
C      DIMENSION P(6), Q(6), ENV(6), TC(6), B(3), ALPHA(10)
C      M1 = 5
C      M0 = 6
C      READ AND PRINT NAME CARD - - - - -
C      1 READ (M1,7) ALPHA
C      WRITE (M0,72) ALPHA
C      READ AND PRINT DATA CARD - - - - -
C      READ (M1,73) R, CP, FM, P(1), CS, B(1), P(3), B(2), P(5), W
C      WRITE (M0,74)
C      WRITE (M0,75)
C      WRITE (M0,76) R, CP, FM, P(1), CS, B(1), P(3), B(2), P(5), W
C      CHECK OUT THE DATA - - - - -
C      2 IF (M1 19,19,2)
C      3 IF (CP 19,19,3)
C      4 IF (FM 19,19,4)
C      5 IF (P(1) 19,19,5)
C      6 IF (B(1) 19,14,6)
C      7 IF (P(3) 19,19,7)
C      8 IF (B(2) 19,16,8)
C      9 IF (B(2)-B(1) 19,9,9)
C      TWO PRICE BREAKS - - - - -
C      4 NSEG = 3
C      10 IF (P(5) 19,19,11)
C      11 IF (W 19,12,13)
C      12 W = 1.E25
C      13 B(3) = W
C      IF (CS 19,20,20)
C      NO PRICE BREAKS - - - - -

```

10M 1  
 A 2  
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 10M 4  
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 A 62

14	NSEG = 1	A	63
	W(1) = 1.E25	A	64
	IF (P(3)) 19,15,19	A	65
15	P(3) = P(1)	A	66
	IF W(2) 19,17,19	A	67
C	ONE PRICE BREAK - - - - -	A	68
16	NSEG = 2	A	69
17	W(2) = 1.E25	A	70
	IF (P(5)) 19,18,19	A	71
18	P(5) = P(3)	A	72
	GO TO 10	A	73
C	ERROR IN DATA - - - - -	A	74
19	WRITE (NO,77)	A	75
	GO TO 1	A	76
20	P(4) = P(5)	A	77
	P(2) = P(3)	A	78
	IF (W(5)-P(3)) 22,22,21	A	79
21	P(4) = P(3)	A	80
22	IF (W(3)-P(1)) 24,24,23	A	81
23	P(2) = P(1)	A	82
24	P(6) = P(2)	A	83
	IF (W(1)) 28,30,25	A	84
25	IF (W(2)) 27,29,26	A	85
26	P(6) = P(5)	A	86
	GO TO 30	A	87
27	P(6) = P(3)	A	88
	GO TO 30	A	89
28	P(6) = P(1)	A	90
	GO TO 30	A	91
29	P(6) = P(4)	A	92
30	Q(2) = B(1)	A	93
	Q(4) = B(2)	A	94
	Q(6) = B(3)	A	95
	IF (CS) 31,31,61	A	96
C	SHORTAGES NOT ALLOWED - - - - -	A	97
31	DO 32 I = 1, 3	A	98
	J = 2*I-1	A	99
C	CALCULATE W(I) I=1,3,5 - - - - -	A	100
32	W(I) = SORT(.0CP+P/(FH*W(J)))	A	101
	DO 35 I = 1, 6	A	102
	IF (W(I)-1.E25) 33,34,33	A	103
C	CALCULATE TC(I) I=1 TO 6 - - - - -	A	104
33	TC(I) = (CP*W(I)) + P(I)*W(I)*FH*(I/2.)	A	105
	GO TO 35	A	106
34	TC(1) = 1.E25	A	107
35	CONTINUE	A	108
	DO 36 I = 1, 6	A	109
36	ENV(I) = W(I)	A	110
C	TEST FOR FEASIBILITY WITH RESPECT TO THE PRICE BREAKS - - - - -	A	111
37	IF (Q(1)-Q(2)) 39,39,38	A	112
38	TC(1) = 1.E25	A	113
39	IF (W(2)-Q(3)) 41,40,41	A	114
40	IF (W(3)-Q(4)) 42,42,41	A	115
41	TC(3) = 1.E25	A	116
42	IF (W(4)-Q(5)) 44,44,43	A	117
43	TC(5) = 1.E25	A	118
C	FIND EQQ WITH OUT STORAGE LIMITATIONS - - - - -	A	119
44	KFLB = 1	A	120
	TCST = TC(1)	A	121
	EQQ = W(1)	A	122
	ENV = ENV(1)	A	123
	DO 46 I = 1, 5	A	124

```

      IF (TCST-TC(I)) 46,46,45          A 125
45  TCST = TC(I)                        A 126
      KFLB = 1                          A 127
      ECOQ = Q(I)                       A 128
      ENVT = ENV(I)                     A 129
46  CONTINUE                            A 130
      ON = R/ECOQ                       A 131
C   PRINT RESULTS BEFORE STORAGE RESTRICTIONS - - - - - A 132
      WRITE (MO,78)                     A 133
      IF (W-1.E25) 47,48,47            A 134
47  WRITE (MO,79)                       A 135
48  WRITE (MO,80) ECOQ                  A 136
      IF (CS) 49,5,49                  A 137
49  WRITE (MO,90) ENVT                  A 138
50  WRITE (MO,81) P(KFLB)               A 139
      WRITE (MO,82) TCST                A 140
      WRITE (MO,83) ON                  A 141
      IF (W-1.E25) 91,1,51             A 142
C   TEST FOR FEASIBILITY WITH RESPECT TO THE STORAGE REQUIREMENT - - - - A 143
51  DO 53 I = 1, 5                     A 144
      IF (ENV(I)-W) 53,53,52           A 145
52  TC(I) = 1.E25                      A 146
53  CONTINUE                            A 147
      IF (TC(KFLB)-1.E25) 54,55,54    A 148
54  WRITE (MO,84)                       A 149
      GO TO 1                          A 150
C   FIND EQD WITH STORAGE LIMITATIONS - - - - - A 151
55  KFLB = 1                            A 152
      TCST = TC(I)                     A 153
      ECOQ = Q(I)                      A 154
      ENVT = ENV(I)                    A 155
      DO 57 I = 1, 6                   A 156
      IF (TCST-TC(I)) 57,57,56        A 157
56  TCST = TC(I)                       A 158
      ECOQ = Q(I)                      A 159
      KFLB = I                         A 160
      ENVT = ENV(I)                   A 161
57  CONTINUE                            A 162
      ON = R/ECOQ                      A 163
C   PRINT RESULTS AFTER STORAGE LIMITATIONS - - - - - A 164
      WRITE (MO,85)                     A 165
      WRITE (MO,86)                     A 166
      WRITE (MO,87)                     A 167
      WRITE (MO,78)                     A 168
      WRITE (MO,88)                     A 169
      WRITE (MO,80) ECOQ                A 170
      IF (CS) 58,59,58                 A 171
58  WRITE (MO,90) ENVT                 A 172
59  CONTINUE                            A 173
      WRITE (MO,81) P(KFLB)            A 174
      WRITE (MO,82) TCST                A 175
      WRITE (MO,83) ON                  A 176
      IF (KFLB=6) 1,60,1               A 177
60  WRITE (MO,89)                       A 178
      GO TO 1                          A 179
C   SHORTAGES ALLOWED - - - - - A 180
61  ENV(6) = Q(6)                      A 181
      DO 62 I = 1, 5, 2                A 182
      ENV(I) = SQRT(2.*CP*R*CS/(FH*P(I)*(FH*P(I)+CS))) A 183
62  Q(I) = SQRT(12.*CP*R*(FH*P(I)+CS)/(FH*P(I)*CS)) A 184
      DO 65 I = 1, 2                   A 185
      J = 2*I                          A 186

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```

IF (W(I)-1.E25) 64,63,66
83 ENV(I) = 1.E25
GO TO 65
84 ENV(I) = (W(I)*CS)/(P(I)*FM+CS)
85 CONTINUE
IF (ENV(1)-1.E25) 66,67,66
86 U(6) = SQRT((2.*CP*R+ENV(6)**2*(CS*P(6)*FM))/CS)
87 DO TO I = 1, 6
IF (U(I)-1.E25) 68,69,68
88 TC(I) = (CP*R/Q(I)+FM*P(I)*ENV(I)**2/(2.*Q(I))+R*P(I)-(CS*(Q(I)-EN
IV(I)**2)/(2.*Q(I)))
GO TO 70
89 TC(I) = 1.E25
70 CONTINUE
GO TO 37

```

C  
C  
C

TABLE OF FORMATS

71	FORMAT (10A4)	A 204
72	FORMAT (17M)PROGRAM EOG FOR (10A4)	A 205
73	FORMAT (11F5.0)	A 206
74	FORMAT (26M)INPUT DATA IS ***** )	A 207
75	FORMAT (60M R CP FM P1 CS B1 P2 B2 P3 )	A 208
76	FORMAT (11X,F6.0,F6.2,F6.0,F6.2,F6.0,F5.2,F6.0)	A 209
77	FORMAT (64M)ERROR IN INPUT DATA, CHECK AND RUN AGAIN )	A 210
78	FORMAT (26M)ANALYSIS RESULTS ARE ****)	A 211
79	FORMAT (56M)BEFORE THE WAREHOUSE STORAGE LIMITATION IS APPLIED )	A 212
80	FORMAT ( 27M)OPTIMUM ORDER QUANTITY IS(20A,F10.2)	A 213
81	FORMAT (25M)AT A PRICE PER ITEM OF .22X(F10.2)	A 214
82	FORMAT (37M)YIELDING A TOTAL INVENTORY COST OF (11X,F10.2)	A 215
83	FORMAT (47M)WHERE THE NUMBER OF ORDER CYCLES PER YEAR IS (F10.2)	A 216
84	FORMAT (51M)THE WAREHOUSE LIMITATION HAD NO EFFECT ON THE EOG )	A 217
85	FORMAT (54M)THE ORDER QUANTITY IS LIMITED BY THE WAREHOUSE SPACE )	A 218
86	FORMAT (54M)RESTRICTION AND IS NOT AT AN OPTIMUM, LOOSEN THE )	A 219
87	FORMAT (54M)RESTRICTION AND RUN AGAIN OBSERVING THE EFFECT. )	A 220
88	FORMAT (60M)AFTER THE WAREHOUSE STORAGE LIMITATION IS APPLIED )	A 221
89	FORMAT (60M)THIS ORDER QUANTITY IS AT THE MAXIMUM WAREHOUSE CAPAC )	A 222
90	FORMAT (28M)WITH OPTIMUM INVENTORY OF (19X,F11.2)	A 223

END



**DIVISION DE EDUCACION CONTINUA  
FACULTAD DE INGENIERIA U.N.A.M.**

INTRODUCCION A LA PROGRAMACION Y COMPUTACION ELECTRONICA

PROBLEMA DE COLAS

OCTUBRE, 1981

# QUESIM

## a model for queueing systems

*is a simulation model for single-phase, multiple-channel queueing systems. The performance of one to nine channels may be investigated under a variety of arrival and service parameters and for a variety of associated costs.*

Queues (waiting lines) are common, everyday occurrences. Queues occur in grocery stores, in banks, in front of movie theaters, during university registration, and so on. Queues build up as a result of an interaction between customers arriving for service and a service facility. Almost everyone has experienced being frustrated by waiting in a line. The purpose of this computer exercise is to allow the user to experiment with situations in which queues occur. The model is concerned with more than waiting time in the queues, however. It allows one to look at the entire system from the operation manager's viewpoint, i.e., not only worrying about the customer but also being concerned about the utilization of facilities and the total cost of operation.

The first section provides background information on queueing concepts and how these concepts may be used by the operations manager as an aid for decision making.

The following sections present a situation in which the computer model may be used as a tool for analysis of some possible alternative management decisions. These illustrative problems include complete instructions on how to use the computer program QUESIM.

### 9.1 THE QUEUEING PROCESS

This section contains an introduction to some queueing concepts. No mathematical formulas are presented, although references are given for those readers interested in a detailed presentation of queueing theory.



Definition  
of  
Queuing  
Terms

The queuing process is centered around a *service system* which has one or more *service channels*. Customers (*arrivals*) are drawn from an *input source*, or population. In queuing models, the customer arrivals from the input source are generally characterized by a probability distribution. The symbol commonly used to represent the mean arrival rate of customers is the Greek letter *lambda* ( $\lambda$ ). Any arrival entering the system joins a *queue*, or waiting line (a queue may be of zero length). The customer is selected from the queue for service according to a *queue discipline* or a *priority rule*. Usually, service times follow some probability distribution and the average service rate is commonly represented by the Greek letter *mu* ( $\mu$ ). In order to have a stable queuing process the average service rate ( $\mu$ ) must be greater than the mean arrival rate ( $\lambda$ ). After service is completed the customer exits the system. See Figure 9-1.

Generally, a queuing system is characterized by the following properties:

1. Its arrival pattern.
2. Its service time distribution.
3. Its queue discipline.
4. Its layout, or customer-flow pattern.

Arrival  
Patterns

The feature that makes some situations into queuing situations and other situations non-queuing is the nature of the arrivals to the system. Arrivals are the customers to the service facility, since they are the people or things that need to be processed.

In the situation where all arrivals are on hand, such as a large stock of raw materials, the service center may process arrivals at will, and there is no real queuing problem as such. In other situations where appointments are made ahead of time, there is also no real, or at least visible, queuing problem.

The really interesting problems, those worthy of being studied as queuing systems, exist when arrivals are not controlled or controllable by the service center. The most common assumption made in these cases is that the time intervals between consecutive arrivals are independent random variables. Each arrival is considered to be unaffected by the time at which

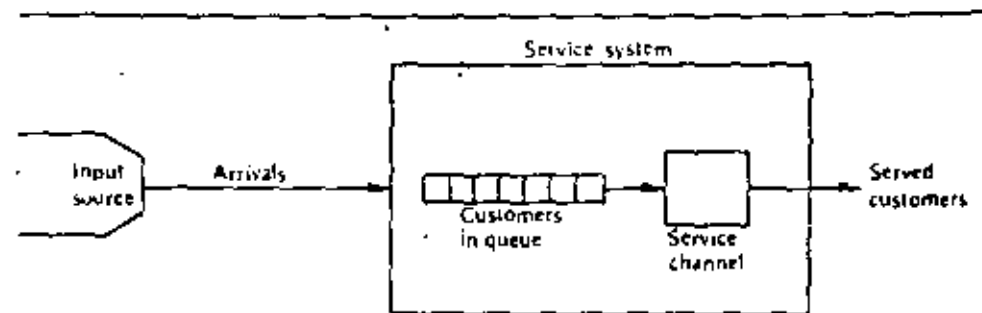


Figure 9-1 Single queue—single channel, single-phase queuing process.

any other arrival occurs or by the number of arrivals which have already taken place. A good example is the placing of telephone calls when each customer does not really know, or care, who else is placing a call.

Studies of queueing systems have revealed that the time intervals between consecutive arrivals are often distributed according to the negative-exponential distribution. (Longer time intervals have a lower probability of occurrence.) In this case the number of arrivals expected forms a Poisson distribution. Other arrival distributions are possible, but the Poisson distribution is the most frequently occurring distribution.

#### Service Time Distributions

The simplest situation is that in which each arrival requires the same time for service as every other arrival. A vending machine, for example, is usually assumed to have a constant service time. The most commonly assumed service time density distribution, however, is the negative-exponential distribution. The service process may be further characterized as being single-phase (one operation) or multiple-phase (a series of operations).

#### Queue Disciplines

The queue discipline is the priority rule by which waiting jobs are selected from the queue for service. Because this represents a directly controllable decision variable, an extensive amount of research has been done in this area of queueing theory.

The most common priority rule is the first-come-first-served rule (FCFS). According to this rule, the first job to arrive in the queue will be the first job to be serviced. In addition, the following priority rules have received much attention: (1) the random rule selects the job which has the smallest value of a random priority assigned at the time of its arrival, and (2) the shortest operation time rule (SOT) selects from the queue the job which requires the least processing time at that service center.

#### Layout or Customer-Flow Patterns

The layout or flow pattern of a queueing system is largely determined by the specific servicing requirements of the arriving population, and by the physical limitations of the service facility.

This factor of specific servicing requirements is important when the job *must* be processed through a specific service channel or through a particular sequence of operations. If the job has no specific routing requirements, however, this factor becomes negligible. If the job requires several operations, for example, it is possible that the sequencing of these operations is of no consequence.

The physical limitations of the service facility are important, as they affect the facility layout. These physical limitations impose an additional constraint when they tend to limit waiting areas for jobs. As an example, one may prefer to have a single-queue, multiple-channel service facility, but adequate waiting space may not be available. The following arrangements are some examples of system geometry or job-flow patterns: single queue—single channel (Figure 9-1), single queue—multiple channels in parallel (Figure 9-2), multiple queue—multiple channels (Figure 9-3), service centers in tandem (Figure 9-4), and service centers in a network.

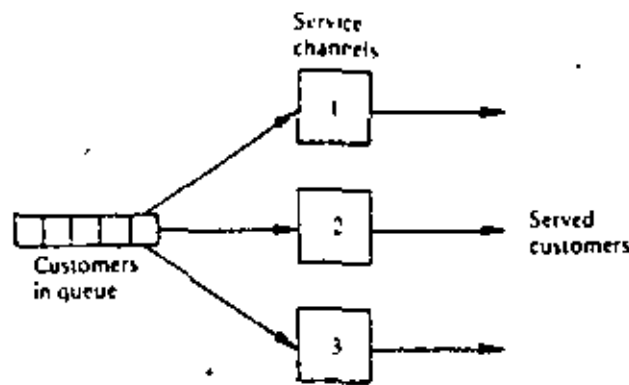


Figure 9-2 Single queue—multiple channel, single-phase.

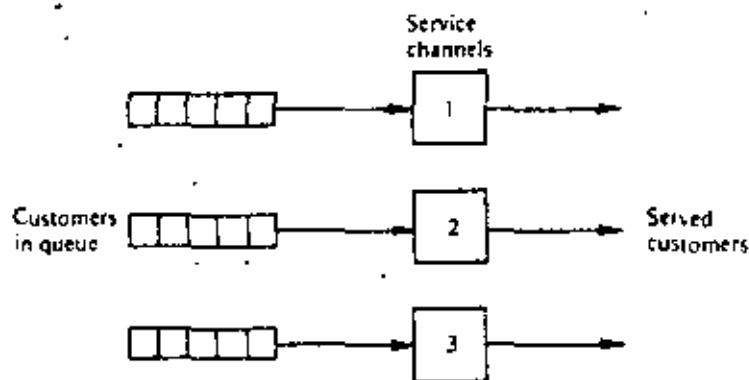


Figure 9-3 Multiple queue—multiple channel, single phase.

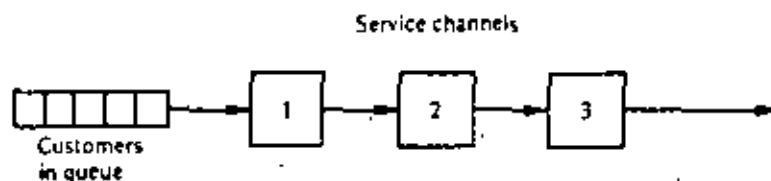


Figure 9-4 Single queue—single channel, multiple-phase.

**Analysis  
for  
Management  
Decision**

One of the primary purposes for studying queueing theory is its predictive capabilities. In turn, this predictive capability is relevant to the design and control of operation systems. Some of the operational characteristics of a queueing system which may be of interest to a manager are the distributions of:

1. Queue length.
2. Customer waiting time (in queue and/or in the system).
3. Idle time of service facilities.
4. Number of customers in the service system.

These distributions may be described by their mean value, standard deviation, and the probability that the variable exceeds a specific value. With

information of this nature the queueing system could then be designed (or altered) so that

1. The resulting operational characteristics are within acceptable limits.
2. An economic criterion such as cost (or profit) may be minimized (or maximized).

An economic criterion may be established if one can associate dollar values with arrivals and service. For example, if one knew the revenues per arrival and the cost of service, it would be possible to set up a profit-maximization objective. Or, if the cost of an arrival waiting in line (or in the system) and the cost of service are known, the measure of effectiveness could be a cost-minimization function.

For solving operational problems which may be characterized as a queueing process there are two methods available. First, if the arrival and service time distributions are well-known mathematical distributions, it is possible to derive formulas for describing the operational characteristics. Secondly, even if the queueing process does not possess properties of well-known distributions, one can still attempt to solve the problem by means of Monte Carlo simulation. In this approach, empirical or assumed data for arrival and service time distributions are used as bases for generating a large number of arrivals and services, on paper. This may be done by hand, but for a large simulation it is most often done on a computer.

Since QUESIM is a computer simulation model for waiting lines, the development of the analytical formulas for solving these problems will not be presented here. For readers interested in the mathematical development of these formulas see Hillier and Lieberman, Morse, and Saaty, in the references for this exercise.

## 9.2 JOHN'S ICE CREAM SHOPPE

In this section, a sample problem suitable for the application of the computer model QUESIM will be presented. The QUESIM model itself will then be described. This description will point out to the user the types of systems for which QUESIM is applicable and the control options available to the user. Following the above, detailed descriptions of both the computer input and the computer output for the sample problem will be given.

### Problem Statement

John Entrepreneur, who is a senior at the local college of business administration, is going to open a campus ice cream shoppe. The store features seventy-eight varieties of ice cream (more than double the number of his competitor), and pretty coed's to serve them. Even though John's store will have more to offer than his competitor's store, called The Establishment, it is hypothesized that in the first few months local business will be roughly divided between both stores.

John also feels that the confection industry has a high index of substitutability and the improved availability of ice cream due to the opening of his shoppe in the near future will marginally increase the gross sales of both stores, rather than merely dividing the present sales market. John's marketing research efforts have turned up the following information:

the distribution of customer arrivals into his shoppe will most likely follow a Poisson distribution, with a mean arrival rate of 60 people per hour. John has planned that upon arrival in his shoppe each customer will take a sequential number and await his turn for service. This will facilitate his servicing of customers on a first-come-first-served basis.

John's preliminary analyses also show that one server (whose wages are \$1.80 per hour) can be expected to service about 30 customers per hour, following a negative-exponential distribution. Moreover, John's marketing research shows that when the service rate is slower than the arrival rate, customers will leave rather than wait in a long line. John estimates that his cost (possible opportunity cost) will be \$0.05 for every minute that a customer must wait.

Thus far, however, John has not been able to ascertain from his research data the optimum number of servers to have on duty. Logically, he knows that more than one server is required, because the mean arrival rate is twice the mean service rate. Furthermore, he realizes that these rates are mean rates of probability distributions, not constant rates.

John recognizes that his problem is one of design, i.e., how many service channels to provide in the above queueing system in order to minimize total costs. He could, in fact, actually operate his shoppe with one server, two servers, three servers, etc., each for a period of time, and calculate his total costs. However, John has an alternative, and that is to simulate his ice cream shoppe operations in a compressed time period with QUESIM. Using QUESIM, John could experiment with using one, two, three servers, and so on, until the model indicates to John the optimum number of service channels to have in his service facility. Moreover, the simulation can be done in a short period of time, as opposed to waiting for weeks of empirical data from actual operations.

#### The Quesim Model

QUESIM is a computer model developed for simulating single-queue, single-phase, parallel queueing systems, that is, the type of system proposed by John Entrepreneur. The model determines, through an iterative process, the optimal number of service channels to allocate to a service facility. The configuration, or design, of the service facility is under the control of the user; hence, the user must specify the following characteristics of the queueing system to be studied:

1. The arrival distribution, the mean arrival rate, and the costs associated with arrivals waiting in line.
2. The service time distribution, the mean service time, and the costs of idle servers.
3. The simulation control limits, or the initial and maximum number of service channels (up to nine) which may be considered available to the service facility during a simulation run, and the maximum length of time for the simulation to run.

The above information on arrivals, services, and simulation control limits comprises the input for the computer program, QUESIM.

The computer output includes, at the top of the page, the user's

input data as a means of identifying the user's (problem) output. Following this identification information, the first twenty simulated arrivals and services are printed in a tabular form. The program then prints out statistics for the number arrived, number serviced, actual simulation-run time, maximum length of queue, mean length of queue, mean waiting time in queue, percent utilization of service facilities, waiting time (in queue) costs, idle service time costs, and total costs of operations. This data is printed out for each iterative number of service channels and the simulation is terminated when either the number of service channels has reached the maximum allowed or the total cost of the system with  $N$  servers (channels) exceeds the total cost with  $N - 1$  servers.

An example of the application of program QUESIM to John Entrepreneur's problem is given next.

Computer  
Input  
- John's  
Ice Cream  
Shoppe

Shown below are the input data cards required by QUESIM for solving John's Ice Cream Shoppe Problem. In all, four data cards are required to run program QUESIM; they are the user name card, the arrival data card, the service data card, and the simulation control card. Each card will be described in turn.

*User name card* is the first card. This card may contain any identifying information (such as the user's name) which is desired. The identifying information is keypunched in the first forty card columns.

```

MARGARET QUERTIN PROBLEM ONE
  1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40
  
```

*Arrival data card* is the second data card. This card contains the arrival type (the arrival pattern) in column 1, the mean arrival rate in columns 11-15, and the cost per unit of waiting time in columns 21-25. On this and all data cards, the user *must* keypunch all decimal points. For John Entrepreneur's problem, this card is illustrated below.

```

1      1.0      .05
  1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40
  
```

The 1 in card column one is for arrival type code 1, which specifies the Poisson arrival distribution. The 1.0 in column 11 specifies a mean arrival rate of 1.0 customers per time unit, and the .05 in column 21 represents the cost per unit of waiting time per arrival in John's Ice Cream Shoppe.

*Service data card* is the third data card. This card contains the service type (the service time distribution) in column 1, the mean service time in columns 11-15, and the cost per unit of idle service time in columns 21-25. For John Entrepreneur's problem, this data is shown below.

```

2      2.0      .03
  1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40
  
```



PROGRAM QUESIM FOR MAGGARD QUESIM PROBLEM ONE  
 ARRIVAL TYPE 1 RATE = 1.00 COST = .05  
 SERVICE TYPE 2 TIME = 2.00 COST = .03  
 NO. CHANNELS START 1 MAX 9  
 MAX TIME 60

FIRST TWENTY OCCURRENCES FOR \*\*1\*\*SERVICE CHANNELS

ARRIVAL TIME---	-----DEPARTURE TIME AT CHANNEL NUMBER----- ONE TWO THREE FOUR FIVE SIX SEVEN EIGHT NINE
0	2.6
.0	3.3
.7	4.6
5.1	5.1
6.9	8.5
8.0	8.6
8.1	8.8
9.1	9.4
11.2	12.7
11.4	12.8
14.6	15.2
15.1	17.8
17.0	18.2
17.4	21.0
19.3	24.6
19.5	26.0
20.1	26.0
20.2	27.3
20.8	28.3
21.4	29.4

AFTER	54 ARRIVED	36 SERVED	60 TIME UNITS
QUEUE-MAXIMUM LENGTH =	14		
-MEAN LENGTH =	5.5		
-MEAN WAIT TIME =	6.4		
SERVICE UTILIZATION =	89.6 PERCENT		
COSTS-WAIT IN QUEUE	331.1 UNITS AT \$	.05 = \$	16.55
IDLE SERVICE	6.2 UNITS AT \$	.03 = \$	.19
TOTAL COST OF OPERATIONS		\$	16.74

Figure 9-6 Computer output—John's Ice Cream Shoppe.

length of the queue, the mean number of customers in queue, and the mean waiting time in the queue are printed out. Then, the percent utilization of the service facilities is printed out. This is followed by the cost calculations. First, the total waiting time cost, which is the total waiting time of all customers in the system multiplied by the cost per unit waiting time, is given. The next line gives idle time cost, calculated as units of idle time (in the service facility) multiplied by the cost per unit of idle time.

The last line printed out is the total cost of operations, which is the idle time cost and the waiting time cost added together. It is this value that the simulator uses as a basis for comparing each iteration to the previous iteration for the purpose of determining when to terminate the simulation.

In the sample problem, the basic issue facing John Entrepreneur is the number of service channels (servers) he should have in his ice cream shoppe. The summary statistics for one channel (Figure 9-6) indicate that he



should at least have more than one server. The average length of the waiting line is greater than five customers, so any as fourteen at one time, and all customers must wait, on the average, more than 6 time units (minutes). In real life, one would not expect ice cream shoppe customers to be so patient! Moreover, as one would expect with so many customers waiting, the server is busy almost 90 percent of the time.

For the cost structure given in the problem, the waiting time cost for the customers far exceeds the idle time cost of the single server. The total cost of \$16.74 consists almost entirely of waiting time costs.

The *simulation control card* for this problem requested that program QUESIM initially simulate John Entrepreneur's system with one service channel and continue to simulate his system, adding one additional service channel each run, until the simulation terminated. The simulation will terminate either when the total cost of the system with  $N$  servers exceeds the total cost with  $N - 1$  servers or when the maximum number of allowable service channels has been reached.

For John's problem, the effect of adding additional servers in the shoppe is shown below. The cost figures in Figure 9-7 come directly from the computer printouts for the solution to John's problem. These figures like all simulation results, are a function of a random number generator which may be different for each computer. Hence, these figures may be slightly different on different computers.

Number of channels	Waiting cost (\$)	Idle time cost (\$)	Total cost of operations (\$)
1	16.55	0.19	16.74
2	7.14	0.49	7.63
3	0.26	2.61	2.87
4	0.96	3.71	4.67

Figure 9-7 The total cost of operations for one to four service channels.

Figure 9-7 shows that adding a second service channel dramatically reduces the cost of customer waiting from \$16.55 to \$7.14. Adding a third service channel (server) continues to decrease waiting time cost and is the number of servers which minimizes the total cost of operations. Thus the solution to John Entrepreneur's problem, as given by QUESIM, is for John to provide three servers in his shoppe operating under his expected steady state conditions. Keep in mind, however, that if we treat each simulation time unit as one minute, we have simulated only one hour of operations. Thus, John may want better data and/or a longer simulation run before coming to a definite conclusion about his problem.

### 9.3 JOHN'S ICE CREAM SHOPPE REVISITED

**John's New Data** Grand Opening!! John Entrepreneur's ice cream shoppe is now open. He is so excited about testing out his previous conclusions on the number of servers to have in his shoppe that after observing only the first fifteen arrivals

he rushes over to the local computer center to simulate QUESIM with his empirical data. In recording his data, John kept track of both the time that each arrival entered the shoppe and the time it took to serve each customer. To John's surprise, he found that all of the service times were a constant, three minutes. John now wants to use program QUESIM with the data that he has obtained. The required input and the resulting computer output for John's new data are described next.

Computer  
Input  
—John's  
Ice Cream  
Shoppe  
Revisited

The *user name card* is always the first card in the data deck.

The *arrival data card* is the second card in the data deck. For this problem it reads as follows:

```

4          0          .05         15.
XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49
    
```

Note that in column 1 of the *arrival data card* the code number is 4, which specifies that all arrival times are to be "read in" from additional data cards. The cost of waiting is punched in columns 21-25. The number of arrivals to be read-in is indicated by the value specified in columns 31-33. Although this value was not required in the previous problem, here it has a specified value of 15.

*Read-in arrivals* are keypunched twelve per card and immediately follow the arrival data card. Since John has fifteen data values he needs two read-in arrival data cards, with twelve data points on the first card and three on the second card. These two cards have a format of 12F5.0 and are shown below for Problem Two. Notice that it is the actual arrival times that are recorded, not the elapsed time between arrivals.

```

0    9.    13.    19.    34.    36.    37.    38.    39.    42.    62.    63.
XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49
    
```

```

65.    65.    69.
XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49
    
```

The *service data card* follows the arrival data cards. John noted that each service required exactly three minutes, i.e., a constant service time. Code 3 keypunched in column 1 specifies a constant service time. The service data card now reads as follows:

```

3          3.0          .03
XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49
    
```

This card requests a constant service time of 3.0 time units per arrival at a cost of \$0.03 for each unit of idle service time.

The *simulation control card* is again the last card in the data deck.



The complete input data deck, one card per typewritten line, now appears as shown in Figure 9-8.

Computer  
Output  
—John's Ice Cream  
Shoppé  
Revisited

Shown in Figure 9-9 is the computer output for the results of this problem for one channel. On the computer output, the identification information at the top of the page is changed to reflect the changes in the input data. The arrival type, service type, and simulation-run time are different from the previous situation. Furthermore, the simulation table is for only fifteen arrivals and services, as that is the total number of arrivals read in. Notice that on this output a warning message (\*\*WARNING\*\*OUT OF DATA BEFORE TIME LIMIT\*\*) has been printed out. This message is printed out by QUESIM because the last arrival occurred at time 69, which was before the simulation time limit of 100 units. Moreover, the service facility was idle from time 77 to time 100; thus, the actual idle time in the service facility is overstated in the summary statistics. When this message appears, the user of QUESIM must exercise some care in the interpretation of the results or go back and rerun with a lower, more realistic, time limit. The summary statistics and cost information printed out below the simulation table is the same for all computer printouts.

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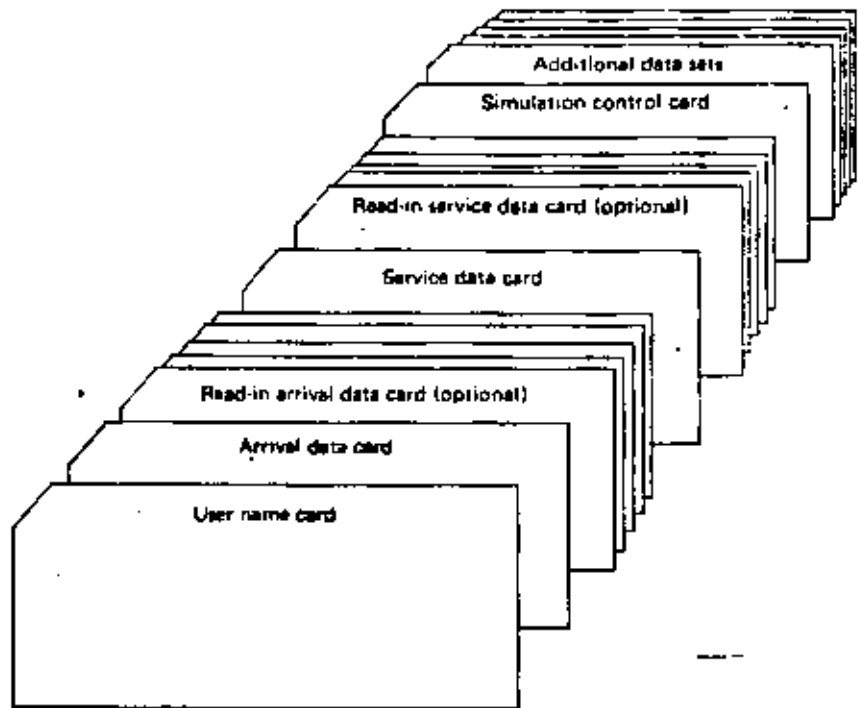
#### 9.4 QUESIM DATA DECK STRUCTURE

Arrival  
Cards

- 1. Arrival data card must always be included

Card No.	Format	Item
1	F1	code* for distribution
2-5	F5.0	mean arrival rate per unit time
6-10	F5.0	cost per unit of waiting time
11-15	F3.0	no. of arrivals to be read in

- 2. Read-in arrival data card is optional, depending upon the data. Its format is L2F5.0, so that arrival times are punched, 12 to a card, in columns 2-5, 6-10, 11-15, 16-20, etc.



3. Service data card must always be included.

<i>Card columns</i>	<i>Format</i>	<i>Item</i>
1	I1	code* for distribution
11-15	F5.0	mean service time
21-25	F5.0	cost per unit of idle time
31-33	F3.0	no. of service times to be read in

4. Read-in service data card is optional, depending upon the data. Its format is 12F5.0, so that service times are punched, 12 to a card, in columns 1-5, 6-10, 11-15, 16-20, etc.

5. Control card must always be included.

<i>Card columns</i>	<i>Format</i>	<i>Item</i>
1	I1	beginning no. of service channels
11	I1	maximum no. of service channels
21-25	F5.0	simulation run time

\*Code for distribution

- 1 the Poisson distribution
- 2 the negative-exponential distribution
- 3 a constant rate
- 4 historical input data, read-in

9.5 QUESIM PROGRAM LISTING

C	PROGRAM QUESIM	IBM	1
C	COPYRIGHT JUNE 1970 HOY O HARRIS	A	2
C	THIS VERSION FOR THE 16M/360	IBM	3
C	DICTIONARY OF VARIABLES	A	4
C	ATIME THE HOURS OF SYSTEM IDLE TIME - TOTAL	A	5
C	ANUM,SNUM NUMBER OF HEAD IN ARRIVALS AND SERVICE	A	6
C	AR(S00) AN ARRAY OF READ IN ARRIVAL TIMES	A	7
C	ARR RT,ARR TM THE ARRIVAL RATE AND MEAN TIME	A	8
C	CH AN ARRAY OF ARRIVAL AND SERVICE ON FIRST 20 CUSTOMERS	A	9
C	CIULE THE COST OF SYSTEM IDLE TIME - TOTAL	A	10
C	CUMQUE(100) AN ARRAY WHICH STORES IDLE CUSTOMER HOURS	A	11
C	COSTS THE COST PER TIME UNIT OF IDLE SERVICE	A	12
C	COSTA THE COST PER TIME UNIT OF IDLE CUSTOMERS	A	13
C	CUSERV,KCUS THE NUMBER OF THE CUSTOMER BEING SERVED	A	14
C	CWAIT THE COST OF CUSTOMERS HOURS IN QUEUE- TOTAL	A	15
C	DEP RT,DEP TM THE SERVICE RATE AND MEAN DURATION	A	16
C	HRSTG THE HOURS OF CUSTOMER TIME IN QUEUE- TOTAL	A	17
C	I+J THE CHANNEL NUMBER BEING PROCESSED	A	18
C	I2 NUMBER OF ARRIVALS WHICH HAVE OCCURED	A	19
C	KA,KS OPTION CODES FOR ARRIVALS AND SERVICE	A	20
C	N+MARS BEGINNING,MAXIMUM NUMBER CHANNELS	A	21
C	PLUTIL THE PERCENT UTILIZATION OF THE SERVICE FACILITY	A	22
C	QUEUE THE NUMBER OF CUSTOMERS IN QUEUE AT ANY POINT	A	23
C	SH(S00) AN ARRAY OF READ IN SERVICE TIMES	A	24
C	TCLUP THE TOTAL COST OF THE SYSTEM	A	25
C	TIME,TTIME CLOCK TIME,MAX SIMULATION TIME	A	26
C	TNARY THE LATEST ARRIVAL TIME	A	27
C	TNUPR THE DEPARTURE TIME OF THE LATEST DEPARTURE	A	28
C	MAY BE SET ARTIFICIALLY FOR PROGRAM EFFICIENCY	A	29
C	XMNTN,XMNTA MEAN WAIT TIME,MEAN NUMBER IN QUE	A	30
	COMMON ALPHA(1), ANUM, AR(S00), ARRRT, ARRTM, CH(20, 10), CUMQUE(	A	31
	100), CUMUTL, CUSERV, DEPRT, DEPTH, I, IUSERV, I2, KA, KCUS, KS, N	A	32
	2, NFLAG,QUEUE,SNUM, SH(S10), STATUS(9), T, TIME, TTIME, TNARY, TND	A	33
	3PH(9)	A	34
	NIN * 5	IBM	35
	NOUT * 6	IBM	36
C	HEAD AND PRINT STUDENT NAME CARD	A	37
1	HEAD (NIN,23) ALPHA	A	38
	WRITE (NOUT,24) ALPHA	A	39
C	HEAD AND PRINT ARRIVAL DATA CARD	A	40
	HEAD (NIN,25) KA, ARRRT, COSTA, ANUM	A	41
	WRITE (NOUT,26) KA, ARRRT, COSTA	A	42
C	HEAD ARRIVAL STATISTICS	A	43
	IF (ANUM .LE. 0.0) GO TO 2	A	44
	NUM = ANUM	A	45
	ARRRT = 1.236	A	46
	KA = 4	A	47
	HEAD (NIN,27) (AR(I), I = 1, NUM)	A	48
	WRITE (NOUT, 8) NUM	A	49
	WRITE (NOUT,29) (AR(I), I = 1, NUM)	A	50
C	SET ARRIVAL TIME AT INVERSE OF ARRIVAL RATE	A	51
2	ARRTM = 1.0/ARRRT	A	52
C	HEAD AND PRINT SERVICE DATA CARD	A	53
	HEAD (NIN,25) KS, DEPTH, COSTS, SNUM	A	54
	WRITE (NOUT,30) KS, DEPTH, COSTS	A	55
	IF (SNUM .LE. 0.0) GO TO 3	A	56
	NUM = SNUM	A	57
	DEPTH = 1.236	A	58
	KS = 4	A	59
	HEAD (NIN,27) (SR(I), I = 1, NUM)	A	60
	WRITE (NOUT,31) NUM	A	61

	WRITE (NOUT,29) (SR(I), I = 1, NUM)	A 64
C	SET SERVICE RATE AT INVERSE OF SERVICE TIME	A 65
3	DEPRT = 1.0/DEPTH	A 66
C	READ SIMULATION CONTROL CARD AND PRINT	A 67
	HEAD (ININ,32) N, MAXS, TTIME	A 68
	WRITE (NOUT,33) N, MAXS	A 69
	WRITE (NOUT,34) TTIME	A 70
C	CHECK SIMULATION RUN LIMITS	A 71
	IF TARRRT .LE. 0.0) GO TO 7	A 72
	IF IDEPTH .LE. 0.0) GO TO 7	A 73
	IF (TTIME .LE. 0.0) GO TO 7	A 74
	IF (N .EQ. 0) GO TO 7	A 75
	IF (MAXS .LT. N) GO TO 7	A 76
	IF (KA .EQ. ) GO TO 7	A 77
	IF (KA .GT. ) GO TO 7	A 78
	IF (KS .EQ. ) GO TO 7	A 79
	IF (KS .GT. ) GO TO 7	A 80
	IF (ANUM .EQ. 0.0) GO TO 5	A 81
	IF (ANUM .GT. 500.0) GO TO 7	A 82
	NUM = ANUM	A 83
	DO 4 I = 2, NUM	A 84
	J = I-1	A 85
	IF (AR(J) .GT. AR(I)) GO TO 7	A 86
4	CONTINUE	A 87
5	IF (SNUM .EQ. 0.0) GO TO 8	A 88
	IF (SNUM .GT. 500.0) GO TO 7	A 89
	NUM = SNUM	A 90
	DO 6 I = 1, NUM	A 91
	IF (SN(I) .LT. 0.0) GO TO 7	A 92
6	CONTINUE	A 93
	GO TO 4	A 94
C	PRINT OUT DATA ERROR MESSAGE	A 95
7	WRITE (NOUT,35)	A 96
	WRITE (NOUT,36)	A 97
	GO TO 1	A 98
C	END OF INPUT DATA CHECK	A 99
B	BCCOP = 999999.9	A 100
C	SIMULATION OF A GIVEN NUMBER OF CHANNELS (N) BEGINS HERE	A 101
C	INITIALIZE SYSTEM FOR NEXT SIMULATION RUN	A 102
V	TIME = 0.0	A 103
	TNARY = 0.0	A 104
	QUEUE = 0.0	A 105
	CUMUTL = 0.0	A 106
	CUSERV = 0.0	A 107
	I2 = 0	A 108
	KCUS = 0	A 109
	NFLAG = 0	A 110
	IUSERV = 0	A 111
	SET = RAND(1234567)	A 112
	DO 10 M = 1, 100	A 113
10	CUMQUE(M) = 0.0	A 114
	DO 11 L = 1, N	A 115
	TNDPH(L) = 999999.9	A 116
11	STATUS(L) = 0.0	A 117
	DO 12 I = 1, 20	A 118
	DO 12 J = 1, 10	A 119
12	CH(I, J) = 0.0	A 120
C	PRINT HEADINGS FOR RESULTS	A 121
	WRITE (NOUT,37)	A 122
	WRITE (NOUT,38) N	A 123
	WRITE (NOUT,39)	A 124
	WRITE (NOUT,40)	A 125

	SET FIRST ARRIVAL OCCURANCE AT TIME ZERO	A 124
	TNARV = 0.0	A 125
	CH(1, 1) = 0.0	A 126
	I2 = I2 + 1	A 127
C	MAIN SIMULATION BRANCH POINT	A 128
C	CHECK EACH CHANNEL IN TURN FOR POSSIBLE DEPARTURE	A 129
C	IF ALL CHANNELS ARE IDLE (TNOPR = 99999.9) THEN GO TO ARRIVE	A 130
C	IF ALL CHANNELS ARE BUSY (TNARV IS .GE. TNUPR) THEN GO TO ARRIVE	A 131
C	IF A DEPART IS NEXT (TNOPR IS .GE. TNARV) THEN GO TO DEPART	A 132
C	SET AND IVALUE KEEP MULTIPLE DEPARTURES IN CORRECT TIME SEQUENCE	A 133
13	SET = 888888.	A 134
	DO 14 I = 1, N	A 135
	IF (TNOPR(I) .GT. TNARV) GO TO 14	A 136
	IF (TNOPR(I) .GT. SET) GO TO 14	A 137
	SET = TNOPR(I)	A 138
	IVALUE = I	A 139
14	CONTINUE	A 140
	I = IVALUE	A 141
	IF (SET .LT. 888888.) GO TO 15	A 142
	CALL ARRIVE	A 143
	GO TO 13	A 144
15	CALL DEPART	A 145
C	ON RETURN FROM DEPART CHECK SIMULATION TIME LIMIT	A 146
	IF (TIME .GT. TIME) GO TO 13	A 147
C	END OF SIMULATION RUN---PRINT FIRST TWENTY TRIALS	A 148
	N1 = N + 1	A 149
	IF (CUSERV .GE. 20.0) GO TO 16	A 150
	NAX = CUSERV	A 151
	GO TO 17	A 152
16	NAX = 20	A 153
17	DO 18 I = 1, NAX	A 154
6	WRITE (NOUT, 41) (CH(I), J), J = 1, N1	A 155
	COMPUTE HOURS IN QUEUE FOR SUMMARY PRINTOUT	A 156
	HRSNQ = 0.0	A 157
	MAXQUE = 0	A 158
	DO 20 M = 2, 100	A 159
	IF (CUMQUE(M) .EQ. 0.0) GO TO 19	A 160
	MAXQUE = M - 1	A 161
19	XM = M - 1	A 162
20	HRSNQ = HRSNQ + (XM * CUMQUE(M))	A 163
	IF (MAXQUE .LT. 99) GO TO 21	A 164
	WRITE (NOUT, 42)	A 165
21	IF (NFLAG .NE. 76) GO TO 22	A 166
	WRITE (NOUT, 43)	A 167
22	XN = N	A 168
	XIZ = IZ	A 169
C	PRINT SUMMARY STATISTICS FOR THIS NUMBER (N) CHANNELS	A 170
	WRITE (NOUT, 44) IZ, CUSERV, TIME	A 171
	WRITE (NOUT, 5) MAXQUE	A 172
	AMNTX = HRSNQ / TIME	A 173
	WRITE (NOUT, 16) AMNTX	A 174
	AMNTM = HRSNQ / XIZ	A 175
	WRITE (NOUT, 7) AMNTM	A 176
	PCUTIL = ((CUMUTL / TIME) * 100.) / XN	A 177
	WRITE (NOUT, 48) PCUTIL	A 178
	CWAIT = HRSNQ * COSTA	A 179
	WRITE (NOUT, 49) HRSNQ, COSTA, CWAIT	A 180
	AITIME = (TIME * XN) - CUMUTL	A 181
	CIOLE = AITIME * COSTS	A 182
	WRITE (NOUT, 50) AITIME, COSTS, CIOLE	A 183
	TCOOP = CIOLE + CWAIT	A 184
	WRITE (NOUT, 5) TCOOP	A 185



```

C   STOP RUN IF TCOOP INCREASED FROM LAST RUN                A 180
   IF (TCOOP .GE. BCOOP) GO TO 1                               A 181
C   STOP RUN IF MAXIMUM NUMBER OF SERVERS REACHED             A 180
   IF (N .GE. MAXS) GO TO 1                                    A 187
C   UPDATE NUMBER OF CHANNELS AND CURRENT TOTAL COST          A 190
   N = N+1                                                     A 191
   TCOOP = TCOOP                                               A 192
C   RETURN FOR NEXT RUN WITH MORE CHANNELS (N)                 A 193
   GO TO 4                                                      A 194
C   A 195
23  FORMAT (10A4)                                              A 196
24  FORMAT (20H PROGRAM QUESTIM FOR *10A4)                    A 197
25  FORMAT (11.9X.F5.0.5X.F5.0.5X.F3.0)                       A 190
26  FORMAT (14H ARRIVAL TYPE *11.8M RATE = .F6.2.8M COST =.F8.2) A 194
27  FORMAT (12F5.0)                                           A 200
28  FORMAT (11H *1+28M ARRIVALS READ IN AS FOLLOWS)         A 201
29  FORMAT (11H *12F5.0)                                       A 202
30  FORMAT (14H SERVICE TYPE *11.8M TIME = .F6.2.8M COST =.F8.2) A 203
31  FORMAT (11H *1+28M SERVICES READ IN AS FOLLOWS)         A 204
32  FORMAT (11.9X.11.9X.F5.0)                                  A 205
33  FORMAT (20H NO. CHANNELS START *11.5H MAX *11)           A 200
34  FORMAT (10H MAX TIME *F6.0)                                A 207
35  FORMAT (35H ****ERROR IN QUESTIM DATA CARDS****)       A 200
36  FORMAT (35H ****CONNECT DATA AND TRY AGAIN****)        A 204
37  FORMAT (1H0)                                              A 210
38  FORMAT (31H FIRST TWENTY OCCURANCES FOR **11.18M**SERVICE CHANNE A 211
   ILS)                                                       A 212
39  FORMAT (6M ARRIVAL,*X,*4H-----DEPARTURE TIME AT CHANNEL NUMBER-- A 213
   I-----)                                                 A 214
40  FORMAT (6M TIME---,*X,*4H ONE TWO THREE FOUR FIVE SIX SEVEN EIGHT A 215
   I NINE)                                                    A 216
41  FORMAT (11H *F6.1.3X.9F5.1)                                A 217
42  FORMAT (50M *****WARNING*****QUE EXCEEDED PROGRAM LIMIT OF 99****) A 218
43  FORMAT (48H *****WARNING*****OUT OF DATA BEFORE TIME LIMIT****) A 214
44  FORMAT (6M0AFTER*16.8M ARRIVED*F6.0*7M SERVED*F6.0*11H TIME UNITS A 220
   I)                                                         A 221
45  FORMAT (23H QUEUE-MAXIMUM LENGTH =*I7)                    A 222
46  FORMAT (23H          -MEAN LENGTH      =*F7.1)            A 223
47  FORMAT (23H          -MEAN WAIT TIME   =*F7.1)            A 224
48  FORMAT (23H SERVICE UTILIZATION =*F7.1*8M PERCENT)       A 225
49  FORMAT (20H COSTS-WAIT IN QUEUE*F7.1*11M UNITS AT $.F6.2*4M = $. A 220
   I F9.2)                                                    A 227
50  FORMAT (7X*13M IDLE SERVICE *F7.1*11M UNITS AT $.F6.2*4M = $.F9.2) A 220
51  FORMAT (7X*24M TOTAL COST OF OPERATIONS*16X*1M*.F9.2)    A 224
   END                                                         A 230

```

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SUBROUTINE ARRIVE
COMMON ALPHA(10), ANUM, AQ(500), ARHRT, ARHTM, CH(20, 10), CUMQUE(
1100), CUMUTL, CUSERV, DEPRT, DEPTM, I, IUSERV, IZ, KA, KCUS, KS, N
2, NFLAG, QUEUE, SNUM, SR(500), STATUS(9), T, TIME, TTIME, TNARV, TNO
3PR(9)

```

```

C   THIS SUBROUTINE CALLED WHEN AN ARRIVAL IS THE NEXT OCCURANCE B 1
C   IT UPDATES THE TIME SPENT IN QUEUE B 2
C   IT UPDATES THE CLOCK TO THE TIME OF THE NEW ARRIVAL (PREVIOUSLY B 3
C   SELECTED) B 4
C   IT CHECKS EACH CHANNEL TO SEE IF THE NEW ARRIVAL CAN BEGIN SERVICE B 10
C   IF A CHANNEL IS AVAILABLE IT DOES THE FIRST PART OF THE B 11
C   DEPART PROCESSING OTHERWISE IT ADDS ONE TO THE QUEUE B 12
C   LASTLY, IT SELECTS THE TIME FOR THE NEXT ARRIVAL TO OCCUR B 13
C   N = QUEUE B 14
C   CHECK LENGTH OF QUEUE, IF OVER 99 HOLD AT 99 B 15
   IF (M .LE. 99) GO TO 1 B 16

```

	N = 49	H	17
C	UPDATE HOURS SPENT IN QUEUE	H	18
1	CUMQUE(M+1) = CUMQUE(M+1)+TNARV+TIME	H	19
C	UPDATE CLOCK TIME TO NEXT ARRIVAL	H	20
	TIME = TNARV	H	21
C	CHECK EACH CHANNEL, IF STATUS = 0 IT IS AVAILABLE	H	22
	DO 12 J = 1, N	H	23
	IF (STATUS(J) .GT. 0.0) GO TO 11	H	24
C	DO FIRST PART OF DEPART PROCESSING	H	25
	STATUS(J) = 1.	H	26
	GO TO (2+3+4+5), K5	H	27
C	POISSON SERVICE RATE	H	28
2	H = RAND(0)	H	29
	T = ABS(DEPRT*ALOG(R))	H	30
	GO TO 7	H	31
C	NEGATIVE EXPONENTIAL SERVICE TIME	H	32
3	R = RAND(0)	H	33
	T = ABS(DEPTM*ALOG(R))	H	34
	GO TO 7	H	35
C	CONSTANT SERVICE TIME	H	36
4	T = DEPTM	H	37
	GO TO 7	H	38
C	HEAD-IN SERVICE TIME	H	39
5	IUSERV = KCUS+1	H	40
	NUM = SNUM	H	41
	IF (IUSERV .LE. NUM) GO TO 6	H	42
	MFLAG = 76	H	43
	T = 666666.	H	44
	GO TO 7	H	45
6	T = SH(IUSERV)	H	46
	SET TIME OF NEXT DEPARTURE	H	47
7	TNDR(J) = TIME+T	H	48
C	STORE FIRST TWENTY DEPARTURE TIMES IN CH	H	49
	KCUS = KCUS+	H	50
	IF (KCUS .GT. 20) GO TO 8	H	51
	I1 = J+1	H	52
	CHKCUS(I1) = TNDR(J)	H	53
8	CONTINUE	H	54
C	CHECK IF OUT OF SIMULATION TIME	H	55
	IF (TTIME .LT. TNDR(J)) GO TO 9	H	56
C	ACCUMULATE PROCESSING TIME	H	57
	CUMUTL = CUMUTL+T	H	58
	CUSERV = CUSERV+1.0	H	59
	GO TO 14	H	60
C	END OF SIMULATION UPDATING	H	61
C	LAST DEPARTURE FORCED OUT AT TTIME	H	62
9	TR = T - (TNDR(J) - TTIME)	H	63
	IF (TR .GT. 0.0) GO TO 10	H	64
	TR = 0.	H	65
10	TNDR(J) = TTIME	H	66
	CUMUTL = CUMUTL+TR	H	67
	GO TO 14	H	68
11	IF (J .GE. N) GO TO 13	H	69
12	CONTINUE	H	70
C	ALL CHANNELS ARE BUSY, ADD ONE TO THE QUEUE	H	71
13	QUEUE = QUEUE + 1	H	72
C	SELECT ARRIVAL TIME (STORE FIRST TWENTY IN CH)	H	73
14	GO TO (15+16+17+18), K4	H	74
C	POISSON ARRIVAL TIME DISTRIBUTION	H	75
15	H = RAND(0)	H	76
	TNARV = ABS(ARRTM*ALOG(R))	H	77
	TNARV = TNARV+TIME	H	78

	12 = 12+1	R	79
	IF (12 .GT. 20) GO TO 20	R	80
	CH(12, 1) = TNARV	B	81
	GO TO 20	R	82
C	NEGATIVE EXPD ARRIVAL TIME DISTRIBUTION	B	83
16	R = RAND(0)	R	84
	TNARV = ANS(ARRRT)*ALOG(R)	B	85
	TNARV = TNARV+TIME	H	86
	12 = 12+1	H	87
	IF (12 .GT. 20) GO TO 20	R	88
	CH(12, 1) = TNARV	B	89
	GO TO 20	R	90
C	CONSTANT ARRIVAL TIMES	R	91
17	TNARV = TIME*ARRTM	B	92
	12 = 12+1	R	93
	IF (12 .GT. 20) GO TO 20	H	94
	CH(12, 1) = TNARV	B	95
	GO TO 20	R	96
C	HEAD IN ARRIVAL TIMES	R	97
18	12 = 12+1	B	98
	NUM = ANUM	B	99
	IF (12 .LE. NUM) GO TO 19	B	100
	AR(12) = 777777.	B	101
	NFLAG = 76	B	102
19	TNARV = AR(12)	H	103
	IF (12 .GT. 20) GO TO 20	R	104
	CH(12, 1) = TNARV	B	105
20	RETURN	B	106
	END	H	107
	 SUBROUTINE DEPART	C	1
	COMMON ALPHA(10), ANUM, AR(500), ARRRT, ARRTM, CH(20, 10), CUMQUE(	C	2
	1100), CUMUTL, CUSERV, DEPTH, I, IUSERV, 12, RA, KCUS, KS, N	C	3
	2, NFLAG, QUEUE, SNUM, SR(500), STATUS(9), T, TIME, TTIME, TNARV, TND	C	4
	3PH(9)	C	5
C	THIS SUBROUTINE PROCESSES THE DEPARTURE OF EVERY CUSTOMER	C	6
C	IT UPDATES THE HOURS SPENT IN THE QUEUE	C	7
C	IT UPDATES THE CLOCK TO THE NEXT DEPARTURE TIME (PREVIOUSLY	C	8
C	SELECTED)	C	9
C	IT CHECKS THE LENGTH OF THE QUEUE	C	10
C	IF NO ONE IN QUEUE IT SETS THE CHANNEL AT AN IDLE STATUS (THIS	C	11
C	DEPARTURE WAS PREVIOUSLY PARTIALLY PROCESSED EITHER AT	C	12
C	ARRIVE OR BY A PRIOR PASS THROUGH DEPART)	C	13
C	IF A QUEUE EXISTS THEN TAKE ONE FROM THE QUEUE, SET ITS DEPARTURE	C	14
C	TIME, SET THE CHANNEL AT A BUSY STATUS AND RETURN	C	15
	M = QUEUE	C	16
C	CHECK LENGTH OF QUEUE, IF OVER 99 HOLD AT 99	C	17
	IF (M .LE. 99) GO TO 1	C	18
	M = 99	C	19
C	UPDATE THE HOURS SPENT IN QUEUE	C	20
1	CUMQUE(M+1) = CUMQUE(M+1)+TNDPR(I)-TIME	C	21
C	UPDATE THE CLOCK TO NEXT DEPARTURE TIME	C	22
	TIME = TNDPR(I)	C	23
	IF (QUEUE-GE.1.0) GO TO 2	C	24
C	THIS SECTION COMPLETES THE PROCESSING OF A CUSTOMER	C	25
C	WHEN NO ONE IS WAITING IN THE QUEUE	C	26
	STATUS(I) = 0.0	C	27
	TNDPR(I) = 999999.9	C	28
	RETURN	C	29
C	THIS SECTION DOES THE DEPART PROCESSING	C	30
C	WHEN THE CHANNEL HAS BEEN BUSY	C	31
2	QUEUE = QUEUE - 1.0	C	32

```

C      GO TO (3,4,5,6), KS
C      SELECT NEXT DEPARTURE TIME
C      POISSON SERVICE RATE
3     H = RAND(0)
      T = ABS(DEPRT*ALOG(R))
      GO TO 6
C      NEGATIVE EXPONENTIAL SERVICE TIME
4     R = RAND(0)
      T = ABS(UDEPTN*ALOG(R))
      GO TO 6
C      CONSTANT SERVICE TIME
5     T = UDEPTN
      GO TO 6
C      HEAD-IN SERVICE TIME
6     IUSERV = KCUS+1
      NUM = SNUM
      IF (IUSERV .LE. NUM) GO TO 7
      NFLAG = 76
      T = 666666.
      GO TO 4
7     T = SH(IUSERV)
8     TNDPR(I) = TTIME+T
C     STORE FIRST TWENTY DEPARTURE TIMES IN CH
      KCUS = KCUS+1
      IF (KCUS .GT. 20) GO TO 9
      II = I+1
      CH(KCUS, II) = TNDPR(I)
9     CONTINUE
C     CHECK IF OUT OF SIMULATION TIME
      IF (TTIME .LT. TNDPR(I)) GO TO 10
C     RESET STATUS BACK TO BUSY AND RETURN
      CUMUTL = CUMUTL+T
      CUSERV = CUSERV+1.0
      STATUS(I) = 1.0
      RETURN
C     ADJUST T AND CUMUTL AT TERMINATION OF SIMULATION
C     LAST CUSTOMER FORCED TO DEPART AT TTIME
10    TK = T-(TNDPR(I)-TTIME)
      IF (T .GT. 0.0) GO TO 11
      TK = 0.
11    TNDPR(I) = TTIME
      CUMUTL = CUMUTL+TK
      STATUS(I) = 1.0
      RETURN
      END

      FUNCTION RAND (K)
C     MACHINE DEPENDENT RANDOM NUMBER GENERATOR (0 TO 1)
C     THIS VERSION IS FOR 32 BIT WORD (IBM 360)
C     K SET AT POSITIVE ODD INTEGER TO INITIALIZE
C     K SET AT ZERO TO CONTINUE STRING OF RANDOM NUMBERS
C     SEE NAYLON, COMPUTER SIMULATION TECHNIQUES, WILEY *SUNS, 1966
      IF (K) 2,2,1
1     N = K
2     N = N*16807
      IF (N) 3,4,4
3     N = N*2147483647+1
4     XN = N
      RAND = XN/2147483647.
      RETURN
      END

```

```

C 33
C 34
C 35
C 36
C 37
C 38
C 39
C 40
C 41
C 42
C 43
C 44
C 45
C 46
C 47
C 48
C 49
C 50
C 51
C 52
C 53
C 54
C 55
C 56
C 57
C 58
C 59
C 60
C 61
C 62
C 63
C 64
C 65
C 66
C 67
C 68
C 69
C 70
C 71
C 72
C 73
C 74
C 75
C 76
C 77-
D 1
D 2
IBM J
D 4
D 5
D 6
D 7
D 8
IBM 9
D 10
IBM 11
D 12
IBM 13
D 14
D 15-

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PROGRAMA DE QUEVEDO (CUIAS)

MARCELO VICENTE S. S.

PROGRAMA QUEUES ( COIAS )

24

```

YOUR NAME - A1 PREMIUM TRUCK
1 .05 .1667 2
2 15. 1000. .133
1 1. 6000.
YOUR NAME - A2 DELUX TRUCK
1 .05 .1667 2
2 12. 1400. .167
1 1. 6000.
YOUR NAME - A3 TWO PREMIUM TRUCKS
1 .05 .1667 2
2 15. 1000. .133
2 2. 6000.
YOUR NAME - B1 NEW PREMIUM TRACK
1 .05 .1667 2
2 15. 800. .10
1 1. 6000.
YOUR NAME - B2 ONE DELUX TRUCK
1 .05 .1667 2
2 12. 1400. .167
1 1. 6000.
YOUR NAME - B3 TWO NEW PREMIUM TRUCKS
1 .05 .1667 2
2 15. 800. .10
2 2. 6000.
YOUR NAME - C1 PREMIUM / 4 PER HOUR
1 .0007 .1667 2
2 15. 1000. .133
1 1. 6000.
YOUR NAME - C2 DELUX / 4 PER HOUR
1 .0007 .1667 2
2 12. 1400. .167
1 1. 6000.
YOUR NAME - C3 TWO PREMIUM / 4 PER HOUR
1 .0007 .1667 2
2 15. 1000. .133
2 2. 6000.
YOUR NAME - D1 50T
1 .05 .1667 3
2 12. 1400. .167
1 1. 6000.
YOUR NAME - D2 50T
1 .05 .1667 1
2 15. 1000. .133
2 2. 6000.
YOUR NAME - D3 50T
1 .05 .1667 3
2 15. 1000. .133
2 2. 6000.
YOUR NAME - D4 RANDOM
1 .05 .1667 1
2 15. 1000. .133
1 1. 6000.
YOUR NAME - D5 RANDOM
1 .05 .1667 3
2 15. 1000. .133
1 1. 6000.
YOUR NAME - D6 RANDOM
1 .05 .1667 1
2 12. 1400. .167
1 1. 6000.
STOP
    
```

23

PROGRAM QUEUES FOR YOUR MODEL - 20: SERVICE TO 20

ARRIVAL TYPE 1 RATE = 1.00 COST = 1.00 SCHEDULE WHILE 2 (FCFS)

SERVICE TYPE 2 TIME = 10.00  
 FIXED COST \$ 1000.00 VARIABLE COST \$ .13

NO. CHANNELS NEEDED 1 MAX 1 MAX TIME 4000

FIRST TWENTY OCCURRENCES FOR 1 SERVICE CHANNELS

ARRIVAL TIME	DEPARTING TIME AT CHANNEL NUMBER
0	2.0
26.0	45.0
26.2	45.0
40.6	56.0
124.2	193.0
135.6	194.0
148.0	208.0
148.0	208.0
164.8	236.0
270.1	247.0
271.3	263.0
273.0	265.0
243.3	287.0
244.4	281.0
246.7	282.0
249.7	285.0
202.2	324.0
376.8	335.0
310.9	338.0
374.1	421.0

AFTER 276 ARRIVED 277 SERVED 4000 TIME UNITS  
 QUEUE--MAXIMUM LENGTH 7  
 -MEAN LENGTH 1.0  
 -MEAN WAIT TIME 21.5  
 SERVICE UTILIZATION 74.0 PERCENT  
 AVERAGE ARRIVALS PER TIME UNIT 14.00  
 AVERAGE SERVICE TIME 16.7672  
 MEAN NO. IN THE SYSTEM 1.7396  
 MEAN TIME IN THE SYSTEM 17.6141

COST INFORMATION ON OPERATIONS  
 COSTS--WAIT IN QUEUE 4000.0 UNITS AT \$ .17 = \$ 680.00  
 SERVICE COST VARIABLE 277.0 UNITS AT \$ .13 = \$ 36.11  
 SERVICE COST FIXED 1000.00 WITH 1 CHANNELS \* \$ 1000.00  
 TOTAL COST OF OPERATIONS \$ 2023.20

PROGRAM QUEUES FOR YOUR NAME = H1 NEW PREMIUM TRACK

ARRIVAL TYPE 1 RATE = .15 COST = .17 SCHEDULE RULE 2  
(FCFS)

SERVICE TYPE 2 TIME = 15.00  
FIXED COST 5 400.00 VARIABLE COST 1 .17

NO. CHANNELS START 1 MAX 1 MAX TIME 6000

FIRST TWENTY OCCURRENCES FOR 1 SERVICE CHANNELS

25

ARRIVAL TIME	DEPARTURE TIME AT CHANNEL NUMBER
ONE	TWO THREE FOUR FIVE SIX SEVEN EIGHT NINE
0	2.4
26.0	45.4
26.2	45.6
40.6	56.4
128.2	143.4
135.6	149.4
148.0	208.7
148.0	208.7
184.8	236.4
200.1	247.4
221.3	263.7
223.0	265.0
243.3	280.7
244.4	281.1
246.7	282.4
249.7	285.0
292.2	324.0
306.8	335.0
310.9	338.1
374.1	421.7

AFTER 276 ARRIVED 272 SERVED 6000 TIME UNITS  
 QUEUE-MAXIMUM LENGTH 7  
 -MEAN LENGTH 1.0  
 -MEAN WAIT TIME 21.5  
 SERVICE UTILIZATION 74.2 PERCENT  
 AVERAGE ARRIVAL PER TIME UNIT 1.0400  
 AVERAGE SERVICE TIME 15.2633  
 MEAN NO. IN THE SYSTEM 1.7344  
 MEAN TIME IN THE SYSTEM 37.8141

COST INFORMATION OF OPERATIONS

COSTS-WAIT IN QUEUE 5421.5 UNITS AT \$ .17 = \$ 927.12  
 SERVICE COST VARIABLE 272.0 UNITS AT \$ .10 = \$ 27.20  
 SERVICE COST FIXED 400.00 WITH 1 CHANNELS = \$ 400.00  
 TOTAL COST OF OPERATIONS \$ 1814.32



PROGRAM QUEUES FOR YOUR NAME - CI DEPTUM / 4 PER HOUR

ARRIVAL TYPE 1 RATE = .17 COST = .17 SCHEDULE TIME 0 (PCHS)

SERVICE TYPE 2 RATE = .15  
FIXED COST \$ 1000.00 VARIABLE COST \$ .15

NO. CHANNELS START 1 MAX 1 MAX TIME 6000

26

FIRST TWENTY OCCURRENCES FOR 1 SERVICE CHANNELS

ARRIVAL TIME	DEPARTURE TIME AT CHANNEL NUMBER
ONE TWO THREE FOUR FIVE SIX SEVEN EIGHT NINE	
0	2.4
19.5	39.8
19.6	39.1
30.4	49.9
96.1	161.8
101.6	167.4
110.9	176.8
110.9	176.7
138.5	204.2
150.0	215.8
165.9	231.8
167.2	232.9
182.4	248.1
183.2	249.8
184.9	250.7
187.2	252.9
219.0	284.8
230.0	295.7
233.1	298.8
280.5	346.3

AFTER 388 ARRIVED 374 SERVED 6000 TIME UNITS  
 QUEUE-MAXIMUM LENGTH 17  
 -MEAN LENGTH 5.3  
 -MEAN WAIT TIME 31.8  
 SERVICE UTILIZATION 98.7 PERCENT  
 AVERAGE ARRIVALS PER TIME UNIT .1667  
 AVERAGE SERVICE TIME 15.7217  
 MEAN NO. IN THE SYSTEM 6.342  
 MEAN TIME IN THE SYSTEM 47.4871

COST INFORMATION OF OPERATIONS  
 COSTS-WAIT IN QUEUE 31729.0 UNITS AT \$ .17 = \$ 5288.55  
 SERVICE COST VARIABLE 374.0 UNITS AT \$ .15 = \$ 49.70  
 SERVICE COST FIXED 1000.00 WITH 1 CHANNELS \* \$ 1000.00  
 TOTAL COST OF OPERATIONS \$ 6338.30

PROGRAM QUEUES FOR YOUR NAME = DJ SOT

ARRIVAL TYPE 1 RATE \* .05 COST \* .17 SCHEDULE RULE 3 (SOT)

SERVICE TYPE 2 TIME \* 12.00  
FIXED COST \$ 1400.00 VARIABLE COST \$ .17

NO. CHANNELS START 1 MAY 1 MAY TIME 4000

FIRST TWENTY OCCURRENCES FOR 1 SERVICE CHANNELS

ARRIVAL TIME	ONE	TWO	THREE	FOUR	FIVE	SIX	SEVEN	EIGHT	NINE
0	2.0								
26.0	41.4								
26.2	41.7								
40.6	50.4								
128.2	180.7								
135.6	185.7								
148.0	185.7								
148.0	192.4								
184.8	201.4								
210.1	223.4								
221.3	236.4								
223.0	237.7								
243.3	255.4								
244.4	256.1								
246.7	257.4								
249.7	259.1								
292.2	317.4								
306.8	326.4								
308.9	328.4								
374.1	412.1								

AFTER 276 ARRIVED 277 SERVED 6000 TIME UNITS

QUEUE-MAXIMUM LENGTH 6

-MEAN LENGTH .5

-MEAN WAIT TIME 10.8

SERVICE UTILIZATION 59.4 PERCENT

AVERAGE ARRIVALS PER TIME UNIT .0460

AVERAGE SERVICE TIME 13.1084

MEAN NO. IN THE SYSTEM 1.0974

MEAN TIME IN THE SYSTEM 23.8664

COST INFORMATION OF OPERATIONS

COSTS-WAIT IN QUEUE 2944.8 UNITS AT \$ .17 = \$ 494.89

SERVICE COST VARIABLE 277.0 UNITS AT \$ .17 = \$ 45.42

SERVICE COST FIXED 1400.00 WITH 1 CHANNELS = \$ 1400.00

TOTAL COST OF OPERATIONS \$ 1940.32

PROGRAM QUEUES FOR YOUR NAME = 01 RANDOM

ARRIVAL TYPE 1 RATE = .17 COST = .17 SCHEDULE RULE 1  
RANDOM

SERVICE TYPE 1 TIME = 16.00 **28**  
FIXED COST \$ 1,000.00 VARIABLE COST \$ .13

NO. CHANNELS START 1 MAX 1 MAX TIME 6000

FIRST TWENTY OCCURRENCES FOR 1 SERVICE CHANNELS

ARRIVAL TIME	DEPARTURE TIME AT CHANNEL NUMBER
	ONE TWO THREE FOUR FIVE SIX SEVEN EIGHT NINE
0	2.4
26.0	45.5
26.2	45.6
40.6	56.4
128.2	193.4
135.6	199.4
148.0	208.7
148.0	220.3
184.8	247.4
200.1	247.4
221.3	263.7
223.0	278.4
243.3	281.1
244.4	313.0
246.7	314.7
249.7	317.4
292.2	318.6
306.8	324.6
310.9	330.4
374.1	421.5

AFTER 276 ARRIVED 276 SERVED 6000 TIME UNITS

QUEUE-MAXIMUM LENGTH	7
-MEAN LENGTH	1.6
-MEAN WAIT TIME	22.3
SERVICE UTILIZATION	74.8 PERCENT
AVERAGE ARRIVALS PER TIME UNIT	.0460
AVERAGE SERVICE TIME	16.3207
MEAN NO. IN THE SYSTEM	1.7773
MEAN TIME IN THE SYSTEM	38.6374

COST INFORMATION OF OPERATIONS

COSTS-WAIT IN QUEUE	6159.5 UNITS AT \$ .17 = \$	1026.85
SERVICE COST VARIABLE	276.0 UNITS AT \$ .13 = \$	36.57
SERVICE COST FIXED	1000.00 WITH 1 CHANNELS = \$	1000.00
TOTAL COST OF OPERATIONS		\$ 2063.37

ANALYSIS OF RESULTS

The three alternatives available to Rio Valley Electric Co-op (herein referred to as Rio) are:

Alt.	Mean service rate	Variable cost/unit	Fixed cost/simulation run	Description
A-1	15	\$.13	\$1000	one premium truck
A-2	12	.17	1400	one deluxe truck
A-3	15	.13	2000	two premium trucks

For all the alternatives the FCFS priority rule was used and the simulated runs were for 6000 minutes. The results for the runs are:

Alt.	Mean length Queue	Mean wait time	Service util.	Cost wait	Var. cost	Fix cost	Total cost
A-1	1.0	21.5	74.2%	\$987.12	\$36.18	\$1000	\$2023.29
A-2	.5	11.5	59.4	529.42	45.42	1400	1975.22
A-3	.1	1.1	37.2	51.25	36.44	2000	2087.69

From the runs Rio should choose alternative A-2 as it has the lowest total cost. However, if the Rio Company is planning to grow it might prefer to choose alternative A-3 since this alternative has the lowest service utilization and thus would allow for the most growth (note the very low waiting cost as compared to alternatives A-1 and A-2).

The lower cost of the premium truck definitely changes the optimal cost alternative of question 1. The alternatives now available are:

Alt.	Mean service rate	Variable cost/unit	Fixed cost/simulation run	Description
B-1	15	\$.10	\$ 800	new premium truck
B-2	same as alternative A-2			
B-3	15	.10	1600	two new premium trucks

The results from the computer runs are:

Alt.	Mean length Queue	Mean wait time	Service util.	Cost wait	Var. cost	Fix cost	Total cost
B-1	1.0	21.5	74.2%	\$987.12	\$27.12	\$ 800	\$1814.32
B-2	.5	11.5	59.4	529.42	45.42	1400	1973.22
B-3	.1	1.1	37.2	51.25	27.40	1600	1678.65

Clearly Rio should select B-3 as it has by far the lowest cost and because of the low service utilization will allow for the greatest expansion.

3. The alternatives C-1, C-2, and C-3 are the same as A-1, A-2, and A-3. In these runs the arrival rate was increased from 3 to 4 per hour (Poisson). The results of the runs are as follows:

Alt.	Mean length Queue	Mean wait time	Service util.	Cost Wait	Var. cost	Fix cost	Total cost
C-1	5.3	81.8	98.0%	\$5288.55	\$4974	\$1000	\$6338.30
C-2	1.3	19.8	79.8	1285.83	64.60	1400	2750.62
C-3	.1	2.1	49.9	137.50	51.60	2000	2189.10

Alternative C-3 is the best selection. This is due, as was mentioned in part 1, to the fact that the alternative C-3 had room for expansion while the others were already being highly utilized. There is still quite a difference between the waiting time cost.

4. In this part we are asked to compare the result of part 1 using the other two priority rules, SOT (D-1S, D-2S, and D-3S) and RANDOM (D-1R, D-2R, and D-3R). The results of the computer runs are shown below:

Alt.	Mean length Queue	Mean wait time	Service util.	Cost Wait	Var. cost	Fix cost	Total cost
A-1	1.0	21.5	74.2%	\$987.12	\$36.18	\$1000	\$2023.29
D-1S	.9	19.0	74.2	873.53	36.18	1000	1909.70
D-1R	1.0	22.3	74.2	1026.80	36.57	1000	2063.37
A-2	.5	11.5	59.4	\$529.42	\$45.42	\$1400	\$1975.22
D-2S	.5	10.8	59.4	494.89	45.42	1400	1940.32
D-2R	.5	10.7	59.4	493.38	45.42	1400	1938.81
A-3	.1	1.1	37.2	\$ 51.25	\$36.44	\$2000	\$2087.69
D-3S	.1	1.1	37.2	51.01	36.44	2000	2087.45
D-3R	.1	1.1	37.2	52.84	36.44	2000	2089.29

In the first set of alternatives, D-1S is the best selection. This is due primarily to the fact that the mean waiting time is less for the SOT rule since the shorter jobs are worked on first and gotten out of the system quickly.

The runs using the deluxe truck, D-2R gave the best result. Here the range was not nearly as wide as for the single premium truck.

In the case of the two premium trucks (A-3, D-3S, and D-3R) the run using the SOT rule gave the best results. The best explanation for this is that because of the large amount of slack in the system (35% utilization) it really doesn't make too much difference which rule is used.

D-2R has the lowest cost of all nine runs. This indicates that under present conditions the deluxe truck would be the best selection and that the RANDOM priority rule should be used. In actuality the company should probably select the deluxe truck and use a modified SOT rule (such SOT between 8am and 8pm, all jobs in QUEUE at 8pm on FCFS until 8am following morning).

#### CONCLUDING REMARKS

From the results of the run, the following would be recommended to Rio:

1. If Rio expects the arrival rate of calls to remain about 3/hr, they should buy the deluxe truck, provided the premium is not available at the reduced rate.
2. If arrival rate is expected to increase, buy the two premium trucks.

As is suggested, the two premium trucks are probably the best selection all around. One major reason for this would be that if one of the trucks broke down, the other would still be able to make service calls.

	PROGRAM QUEUES	A	1
C	MANCH 1472 M J MAGGARD	A	2
C	THIS VERSION FOR CUC 3100	A	2A
C	DICTIONARY OF VARIABLES	A	3
	ATTIME THE HOURS OF SYSTEM IDLE TIME - TOTAL	A	4
	ANUM*SNUM NUMBER OF READS IN ARRIVALS AND SERVICE	A	5
	ARR(S00) AN ARRAY OF READ IN ARRIVAL TIMES	A	6
C	ARR RT,ARR TM THE ARRIVAL RATE AND TIME	A	7
C	CH AN ARRAY OF ARRIVAL AND SERVICE ON FIRST 20 CUSTOMERS	A	8
C	CIDLE THE COST OF SYSTEM IDLE TIME - TOTAL	A	9
C	CUMQUE(100) AN ARRAY WHICH STORES IDLE CUSTOMER HOURS	A	10
C	COSTS THE COST PER TIME UNIT OF IDLE SERVICE	A	11
C	COSTA THE COST PER TIME UNIT OF IDLE CUSTOMERS	A	12
C	CUSERV,KCUS THE NUMBER OF CUSTOMERS BEING SERVED	A	13
C	CWAIT THE COST OF CUSTOMERS HOURS IN QUEUE - TOTAL	A	14
C	DEP RT,DEP TM THE SERVICE RATE AND MEAN DURATION	A	15
C	HRSNQ THE HOURS OF CUSTOMER TIME IN QUEUE - TOTAL	A	16
C	I,J THE CHANNEL NUMBER BEING PROCESSED	A	17
C	IZ NUMBER OF ARRIVALS WHICH HAVE OCCURED	A	18
C	KA,KS OPTION CODES FOR ARRIVALS AND SERVICE	A	19
C	N,MAXS BEGINNING,MAXIMUM NUMBER CHANNELS	A	20
C	PCUTIL THE PERCENT UTILIZATION OF THE SERVICE FACILITY	A	21
C	QUE THE NUMBER OF CUSTOMERS IN QUEUE AT ANY POINT	A	22
C	SR(S00) AN ARRAY OF READ IN SERVICE TIMES	A	23
C	TCCOP THE TOTAL COST OF THE SYSTEM	A	24
C	TIME,TTIME CLOCK TIME,MAX SIMULATION TIME	A	25
C	TINRV THE LATEST ARRIVAL TIME	A	26
C	TNDPR THE DEPARTURE TIME OF THE LATEST DEPARTURE	A	27
C	MAY BE SET ARTIFICIALLY FOR PROGRAM EFFICIENCY	A	28
C	XMNTN,AMNTX MEAN WAIT TIME,MEAN NUMBER IN QUE	A	29
C	AVARRA AVERAGE ARRIVALS PER TIME UNIT	A	30
C	AVSERV AVERAGE SERVICE TIME	A	31
C	AMNIS MEAN NO. IN THE SYSTEM	A	32
	AMTIS MEAN TIME IN THE SYSTEM	A	33
	VCOST TOTAL VARIABLE COST OF OPERATIONS	A	34
C	VCOSTS VARIABLE COST PER UNIT	A	35
C	FCOST TOTAL FIXED COST OF OPERATIONS	A	36
C	FCOSTS FIXED COST PER UNIT	A	37
C	USVCT AN ARRAY OF QUEUED SERVICE TIMES	A	38
C	KRULE SCHEDULE RULE CODE (1=RANDOM,2=FCFS,3=SUT)	A	39
	COMMON ALPHA(10),ANUM,ARRNT,ARRTM,CM(20,10),CUMULC,CUSERV,DEPRT,	A	40
1	DEPTM,I,IUSERV,IZ,KA,KCUS,KS,N,AFLAG,SNUM,STATUS(9),T,	A	41
2	TIME,TTIME,TINRV,TNDPR(9),AVARRA,AVSERV,AMNIS,AMTIS,	A	42
3	VCOST,VCOSTS,FCOST,FCOSTS,KRULE,IQUE,CUMQUE(1,1),	A	43
4	USVCT(101),AM(S00),SR(S00)	A	44
	COMMON /DATA/ IEND	A	45
	DATA (IEND=4MSTOP)	A	46
	ISTOP=IEND	A	47
	NIN=60	A	48
	NDUT=61	A	49
C	READ AND PRINT USER NAME CARD	A	50
11	CONTINUE	A	51
	READ (NIN,311) ALPHA	A	52
	WRITE (NDUT,321) ALPHA	A	53
	IF (ALPHA(1)).EQ.(5MSTOP) GO TO 301	A	54
C	READ AND PRINT ARRIVAL DATA CARD AND SCHEDULE RULE CODE	A	55
	READ (NIN,331) KA,ARRNT,COSTS,KRULE,ANUM	A	56
	WRITE (NDUT,341) KA,ARRNT,COSTS,KRULE	A	57
	IF (KA.LT.1) GO TO 241	A	58
	IF (KA.GT.4) GO TO 241	A	59
	IF (KA.LE.LT.1) GO TO 241	A	60
	IF (KA.LE.GT.4) GO TO 241	A	61
	GO TO (21,3) + (KA - LE)	A	62
21	CONTINUE	A	63
	WRITE (NDUT,351) ANUM	A	64

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      GO TO 51
3) CONTINUE
   WRITE (NOUT,36)
      GO TO 41
4) CONTINUE
   WRITE (NOUT,37)
C READ ARRIVAL STATISTICS
5) CONTINUE
   IF (ANUM.LE.0.0) GO TO 71
   NUM=ANUM
   ARRT=1.234
   KA*4
   WRITE (NOUT,39) NUM
   IF (ANUM.GT.500.0) GO TO 291
   READ (IN,36) (AR(I),I=1,NUM)
   WRITE (NOUT,40) (AR(I),I=1,NUM)
   DO 6) I=1,NUM
     J=1
     IF (AR(J).GT.ART(I)) GO TO 291
6) CONTINUE
C SET ARRIVAL TIME AT INVERSE OF ARRIVAL RATE
7) CONTINUE
   IF (ARRT.LE.0.0) GO TO 291
   ARRTM=1.0/ARRT
C READ AND PRINT SERVICE DATA CARD
   READ (IN,41) KS,DEPTH,FCOSTS,VCOSTS,SNUM
   WRITE (NOUT,42) KS,DEPTH
   WRITE (NOUT,43) FCOSTS,VCOSTS
   IF (KS.EQ.0) GO TO 291
   IF (KS.GT.4) GO TO 291
   IF (SNUM.LE.0.0) GO TO 91
   NUM=SNUM
   DEPTH=1.234
   KS*4
   WRITE (NOUT,44) NUM
   IF (SNUM.GT.500.0) GO TO 291
   READ (IN,38) (SM(I),I=1,NUM)
   WRITE (NOUT,40) (SR(I),I=1,NUM)
   DO 8) I=1,NUM
     IF (SM(I).LT.0.0) GO TO 291
8) CONTINUE
C SET SERVICE RATE AT INVERSE OF SERVICE TIME
9) CONTINUE
   IF (DEPTH.LE.0.0) GO TO 291
   DEPTH=1.0/DEPTH
C READ SIMULATION CONTROL CARD AND PRINT
   READ (IN,45) N,MAXS,TIME
   WRITE (NOUT,40) N,MAXS,TIME
C CHECK SIMULATION RUN LIMITS
   IF (N.GT.1) GO TO 291
   IF (MAXS.LT.N) GO TO 291
   IF (TIME.LE.0.0) GO TO 291
C END OF INPUT DATA CHECK
   BCOOP=999999.9
C SIMULATION OF A GIVEN NUMBER OF CHANNELS (N) BEGINS HERE
C INITIALIZE SYSTEM FOR NEXT SIMULATION RUN
In) CONTINUE
   TIME=0.0
   TNARV=0.0
   IQUE=1
   CUMUTL=0.0
   CUSERV=0.0
   IZ=0
   KCUS=0
   NFLAG=0
   IUSEMV=0

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A 129
A 130

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SET=RAND(1234567*U)
DO 111 M=1,100
USVCT(M)=0.0
CUMQUE(M)=0.0
11 CONTINUE
    DETERMINE SERVICE TIME FOR THE 1ST ARRIVAL
    GO TO (121,131,141,151), KS
C 121 POISSON SERVICE RATE
CONTINUE
R=RAND(U*9)
T=ABS(DEPTM*ALOG(W))
GO TO 161
C 131 NEGATIVE EXPONENTIAL SERVICE TIME
CONTINUE
R=RAND(U*9)
T=ABS(DEPTM*ALOG(W))
GO TO 161
C 141 CONSTANT SERVICE TIME
CONTINUE
T=DEPTM
GO TO 161
C 151 READ IN SERVICE TIME
CONTINUE
T=SR(1)
161 CONTINUE
OSVCT(1)=T
DO 171 L=1,N
INDPR(L)=999999.9
STATUS(L)=0.0
171 CONTINUE
DO 181 I=1,20
DO 181 J=1,10
CH(I,J)=0.0
81 CONTINUE
PRINT HEADING FOR RESULTS
WRITE (NUNIT,471) N
WRITE (NUNIT,481)
WRITE (NUNIT,491)
C SET FIRST ARRIVAL OCCURANCE AT TIME ZERO
TNARV=0.0
CH(1,1)=0.0
IZ=IZ+1
C MAIN SIMULATION BRANCH POINT
C CHECK EACH CHANNEL IN TURN FOR POSSIBLE DEPARTURE
C IF ALL CHANNELS ARE IDLE (INDPR = 999999.9) THEN GO TO ARRIVE
C IF ALL CHANNELS ARE BUSY (TNARV IS .GE. INDPR) THEN GO TO ARRIVE
C IF A DEPART IS NEXT (INDPR IS .GE. TNARV) THEN GO TO DEPART
C SET AND IVALUE KEEP MULTIPLE DEPARTURES IN CORRECT TIME SEQUENCE
191 CONTINUE
SET=888888.
DO 201 I=1,N
IF (INDPR(I).GT.TNARV) GO TO 201
IF (INDPR(I).GT.SET) GO TO 201
SET=INDPR(I)
IVALUE=I
201 CONTINUE
I=IVALUE
IF (SET.LT.888888.) GO TO 211
CALL ARRIVE
GO TO 191
211 CONTINUE
CALL DEPART
ON RETURN FROM DEPART CHECK SIMULATION TIME LIMIT
IF (TIME.GT.TIME) GO TO 191
C END OF SIMULATION RUN---PRINT FIRST TWENTY TRIALS
NI=N+1

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A 131
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A 196

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      IF (CUSERV.GE.20.0) GO TO 221
      NXX=CUSERV
      GO TO 231
221  CONTINUE
      NXX=20.
231  CONTINUE
      DO 241 I=1,NXX
      WRITE (NOUT,501) (CHI,I,J),J=1,N1)
241  CONTINUE
C    COMPUTE HOURS IN QUEUE FOR SUMMARY PRINTOUT
      HRSNQ=0.0
      MAXQUE=0
      DO 261 M=1,100
      IF (CUMQUE(M).EQ.0.0) GO TO 251
      MAXQUE=M-1
251  CONTINUE
      XM=M-1
      HRSNQ=HRSNQ+(XM*CUMQUE(M))
261  CONTINUE
      IF (MAXQUE.LT.99) GO TO 271
      WRITE (NOUT,511)
271  CONTINUE
      IF (MPLAG.NE.76) GO TO 281
      WRITE (NOUT,521)
281  CONTINUE
      XN=N
      IZ=IZ-1
      XIZ=IZ
C    PRINT SUMMARY STATISTICS FOR THIS NUMBER (N) CHANNELS
      WRITE (NOUT,531) IZ,CUSERV,TIME
      WRITE (NOUT,541) MAXQUE
      XMNTX=HRSNQ/TIME
      WRITE (NOUT,551) XMNTX
      XMNTM=HRSNQ/XIZ
      WRITE (NOUT,561) XMNTM
      PCUTIL=((CUMUTL/TIME)*100.)/XN
      WRITE (NOUT,571) PCUTIL
      CWAIT=HRSNQ*COSTA
      AITIME=(TIME*XN)-CUMUTL
C    COMPUTE AVERAGE ARRIVALS PER TIME UNIT
      TZ=IZ
      AVARRA=(TZ/TIME)
      WRITE (NOUT,581) AVARRA
C    COMPUTE AVERAGE SERVICE TIME
      AVSERV=CUMUTL/CUSERV
      WRITE (NOUT,591) AVSERV
C    COMPUTE MEAN NO. IN THE SYSTEM
      AMNIS=XMNTX+(AVARRA/(1.0/AVSERV))
      WRITE (NOUT,601) AMNIS
C    COMPUTE MEAN TIME IN THE SYSTEM
      AMTIS=XMNTM+AVSERV
      WRITE (NOUT,611) AMTIS
      WRITE (NOUT,621)
      WRITE (NOUT,631) HRSNQ,COSTA,CWAIT
C    COMPUTE TOTAL VARIABLE COST
      VCOST = CUSERV*VCOSTS
C    COMPUTE TOTAL FIXED COST
      FCOST=XN*FCOSTS
C    PRINT SUMMARY COST INFORMATION
      WRITE (NOUT,641) CUSERV,VCOSTS,VCOST
      WRITE (NOUT,651) FCOSTS,N,FCOST
      TCOOP=FCOST+VCOST+CWAIT
      WRITE (NOUT,661) TCOOP
C    STOP RUN IF TCOOP INCREASED FROM LAST RUN
      IF (TCOOP.GE.8CUOP) GO TO 11
C    STOP RUN IF MAXIMUM NUMBER OF SERVERS REACHED

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A 197
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A 262

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IF (N.GE.MAXS) GO TO 11
UPDATE NUMBER OF CHANNELS AND CURRENT TOTAL COST
N=N+1
BCOUP=TCOUP
RETURN FOR NEXT RUN WITH MORE CHANNELS (N)
GO TO 101
PRINT OUT DATA ERROR MESSAGE
291 CONTINUE
WRITE (NOU1,671)
WRITE (NOU1,681)
301 CONTINUE
WRITE (NOU1,691)
C
C
311 FORMAT (10A4)
321 FORMAT (20H1PROGRAM QUEUES FOR ,10A4)
331 FORMAT (11,9X,F5.0,5X,F5.0,5X,11,9X,F3.0)
341 FORMAT (14M0ARRIVAL TYPE ,11,8M RATE = ,F8.2,8M COST = ,F8.2,16M
1 SCHEDULE RULE ,11)
351 FORMAT (54X,8M(RANDOM))
361 FORMAT (55X,6M(FC+S))
371 FORMAT (55X,5M(SO))
381 FORMAT (12F5.0)
391 FORMAT (1M ,14,28M ARRIVALS READ IN AS FOLLOWS)
401 FORMAT (1M ,12F5.0)
411 FORMAT (11,9X,F5.0,5X,F10.0,F10.0,F3.0)
421 FORMAT (14M0SERVICE TYPE ,11,8M TIME = ,F8.2)
431 FORMAT (2X,13M FIXED COST $,F8.2,8X,14M VARIABLE COST $,F8.2)
441 FORMAT (1M ,14,27M SERVICE READ IN AS FOLLOWS)
451 FORMAT (11,9X,11,9X,F5.0)
461 FORMAT (20M0NO. CHANNELS START ,11,5M MAX ,11,8X,16M MAX TIME ,F6
1.0)
471 FORMAT (31M0FIRST TWENTY OCCURRENCES FOR 11,18M SERVICE CHANNE
1LS)
481 FORMAT (4M ARRIVAL,4X,44M-----DEPARTURE TIME AT CHANNEL NUMBER--
1----)
491 FORMAT (4M TIME---,4X,44MONE TWO THREE FOUR FIVE SIX SEVEN EIGHT
1NINE)
501 FORMAT (1M ,F6.1,3X,9F5.1)
511 FORMAT (60M0***WARNING***QUE EXCEEDED PROGRAM LIMIT OF 99***)
521 FORMAT (68M0***WARNING***OUT OF DATA BEFORE TIME LIMIT***)
531 FORMAT (6M0AFTER ,16,8M ARRIVED ,F6.0,7M SERVED ,F6.0,11M TIME UNITS
1)
541 FORMAT (22M QUEUE-MAXIMUM LENGTH ,8X,17)
551 FORMAT (22M -MEAN LENGTH ,8X,F9.1)
561 FORMAT (22M -MEAN WAIT TIME ,8X,F9.1)
571 FORMAT (22M SERVICE UTILIZATION ,8X,F9.1,8M PERCENT)
581 FORMAT (32M AVERAGE ARRIVALS PER TIME UNIT ,F10.4)
591 FORMAT (32M AVERAGE SERVICE TIME ,F10.4)
601 FORMAT (32M MEAN NO. IN THE SYSTEM ,F10.4)
611 FORMAT (32M MEAN TIME IN THE SYSTEM ,F10.4)
621 FORMAT (31M0COST INFORMATION OF OPERATIONS)
631 FORMAT (20M COSTS-WAIT IN QUEUE ,F9.1,11M UNITS AT $,F6.2,4M = $
1,F9.2)
641 FORMAT (22M SERVICE COST VARIABLE ,F7.1,11M UNITS AT $,F6.2,4M = $
1,F9.2)
651 FORMAT (22M SERVICE COST FIXED ,F7.2,6M WITH ,11,14M CHANNELS
1= $,F9.2)
661 FORMAT (60M0TOTAL COST OF OPERATIONS $,F9. A 321
12)
671 FORMAT (35M0***ERROR IN GUESIM DATA CAUSD*** A 322
681 FORMAT (35M ***CORRECT DATA AND TRY AGAIN*** A 323
691 FORMAT (22M0QUEUES RUN TERMINATED) A 324
END A 325
SUBROUTINE ARRIVE B 1

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33

	COMMON ALPHA(10),ANUM,ARRRT,ARRTM,CM(20,10),CUMUTL,CUSERV,DEPRT,	B	2
1	DEPTM=I+IUSEMV+JZ+KA+KCUS+KS+N+FLAG,SNUM,STATUS(9),T,	B	3
2	TIME,TTIME,TNARV,TNDPR(9),AVAKHA,AVSERV,AMNIS,AMIS,	B	4
3	VCOST,VCOSTS,FCOST,FCOSTS,KNOLE,IQUE,CUMQUE(101),	B	5
4	QSVCT(101)*K(500)*SR(500)	B	6
C	THIS SUBROUTINE CALLED WHEN AN ARRIVAL IS THE NEXT OCCURANCE	B	7
C	IT UPDATES THE TIME SPENT IN QUEUE	B	8
C	IT UPDATES THE CLOCK TO THE TIME OF THE NEW ARRIVAL (PREVIOUSLY	B	9
C	SELECTED)	B	10
C	IT CHECKS EACH CHANNEL TO SEE IF THE NEW ARRIVAL CAN BEGIN SERVICE	B	11
C	IF A CHANNEL IS AVAILABLE IT DOES THE FIRST PART OF THE	B	12
C	DEPART PROCESSING OTHERWISE IT ADDS ONE TO THE QUEUE	B	13
C	LASTLY, IT SELECTS THE TIME FOR THE NEXT ARRIVAL TO OCCUR	B	14
	IF (IQUE.LT.100) GO TO 11	B	15
C	CHECK LENGTH OF QUEUE, IF OVER 99 HOLD AT 99	B	16
	IQUE=100	B	17
C	UPDATE HOURS SPENT IN QUEUE	B	18
11	CONTINUE	B	19
	CUMQUE(IQUE)=CUMQUE(IQUE)+TNARV-TIME	B	20
C	UPDATE CLOCK TIME TO NEXT ARRIVAL	B	21
	TIME=TNARV	B	22
C	CHECK EACH CHANNEL, IF STATUS = 0 IT IS AVAILABLE	B	23
	DO 61 J=1,N	B	24
	IF (STATUS(J).GT.0.0) GO TO 51	B	25
C	DO FIRST PART OF THE DEPART PROCESSING	B	26
	STATUS(J)=1.0	B	27
C	SET TIME OF NEXT DEPARTURE	B	28
	TNDPR(J)=TIME+QSVCT(J)	B	29
C	STORE FIRST TWENTY DEPARTURE TIMES IN CM	B	30
	KCUS=KCUS+1	B	31
	IF (KCUS.GT.20) GO TO 21	B	32
	II=J+1	B	33
	CH(KCUS+II)=TNDPR(J)	B	34
21	CONTINUE	B	35
C	CHECK IF OUT OF SIMULATION TIME	B	36
	IF (TIME.LT.TNDPR(J)) GO TO 31	B	37
C	ACCUMULATE PROCESSING TIME	B	38
	CUMUTL=CUMUTL+QSVCT(J)	B	39
	CUSERV=CUSERV+1.0	B	40
	GO TO 41	B	41
C	END OF SIMULATION UPDATING	B	42
C	LAST DEPARTURE FORCED OUT AT TTIME	B	43
31	CONTINUE	B	44
	TK=QSVCT(J)-(TNDPR(J)-TTIME)	B	45
	IF (KA.GT.0.0) GO TO 41	B	46
	TK=0.	B	47
41	CONTINUE	B	48
	TNDPR(J)=TTIME	B	49
	CUMUTL=CUMUTL+TK	B	50
	GO TO 41	B	51
51	CONTINUE	B	52
	IF (J.GE.N) GO TO 71	B	53
61	CONTINUE	B	54
C	ALL CHANNELS ARE BUSY, ADD ONE TO THE QUEUE	B	55
71	CONTINUE	B	56
	IQUE=IQUE+1	B	57
C	SELECT ARRIVAL TIME (STORE FIRST TWENTY IN CH)	B	58
81	CONTINUE	B	59
	GO TO (91+101+111+121)*KA	B	60
C	POISSON ARRIVAL TIME DISTRIBUTION	B	61
91	CONTINUE	B	62
	R=HAND(0.0)	B	63
	TNARV=ABS(ARRTM*ALOG(R))	B	64
	TNARV=TNARV+TIME	B	65
	GO TO 141	B	66
C	NEGATIVE EXPD ARRIVAL TIME DISTRIBUTION	B	67

101	CONTINUE	P 68
	R=RAND(0+0)	P 69
	TNARV=ABS(ARRRT*ALOG(R))	P 70
	TNARV=TNARV+TIME	P 71
	GO TO 141	P 72
	CONSTANT ARRIVAL TIME	P 73
114	CONTINUE	P 74
	TNARV=TIME+ARRTM	P 75
	GO TO 141	P 76
C	READ IN ARRIVAL TIMES	P 77
121	CONTINUE	P 78
	NUM=ANUM	P 79
	IZQQ=IZ+1	P 80
	IF (IZQQ.LE.NUM) GO TO 131	P 81
	AR(IZQQ)=777777.	P 82
	NFLAG=70	P 83
131	CONTINUE	P 84
	TNARV=AR(IZQQ)	P 85
141	CONTINUE	P 86
	IZ=IZ+1	P 87
	IF (IZ.GT.20) GO TO 151	P 88
	CH(IZ)=TNARV	P 89
C	BEGIN LOGIC TO STORE ARRIVAL AND SERVICE TIMES IN QUEUE ARRAYS	P 90
C	FOR EACH WAITING CUSTOMER/PRODUCT	P 91
C	DETERMINE SERVICE TIME FOR THE NEW ARRIVAL	P 92
151	CONTINUE	P 93
	GO TO (161+171+181+191)*KS	P 94
C	POISSON SERVICE RATE	P 95
161	CONTINUE	P 96
	R=RAND(0+0)	P 97
	T=ABS(DEPRT*ALOG(R))	P 98
	GO TO 211	P 99
C	NEGATIVE EXPONENTIAL SERVICE TIME	P 100
171	CONTINUE	P 101
	R=RAND(0+0)	P 102
	T=ABS(DEPTM*ALOG(R))	P 103
	GO TO 211	P 104
C	CONSTANT SERVICE TIME	P 105
181	CONTINUE	P 106
	T=DEPTM	P 107
	GO TO 211	P 108
C	READ-IN SERVICE TIME	P 109
191	CONTINUE	P 110
	NUM=SNUM	P 111
	IF (14.LE.NUM) GO TO 201	P 112
	NFLAG=70	P 113
	T=666666.	P 114
	GO TO 211	P 115
201	CONTINUE	P 116
	T=SR(12)	P 117
211	CONTINUE	P 118
	QSVCT(IQUE)*T	P 119
C	IF ONLY ONE IN QUE - NO SCHEDULING NECESSARY	P 120
	IF (IQUE.LE.2) GO TO 241	P 121
	IQUE=IQUE	P 122
C	USE SCHEDULE RULE TO REORDER THE QUEUE FOR PROCESSING	P 123
C	KRULE = 1 FOR RANDOM	P 124
C	KRULE = 2 FOR FCFS	P 125
C	KRULE = 3 FOR SUT	P 126
	GO TO (231+241+221)*KRULE	P 127
C	NOT SCHEDULE RULE	P 128
221	CONTINUE	P 129
	IF (IQUE.LE.2) GO TO 241	P 130
	IF (QSVCT(IQUE).GE.QSVCT(IQUE-1)) GO TO 241	P 131
	QTS=QSVCT(IQUE-1)	P 132
	QSVCT(IQUE-1)=QSVCT(IQUE)	P 133

38

```

USVCT(IQU)=QTS
IQU=IQU-1
GO TO 21
C   RANDOM SCHEDULE RULE
231 CONTINUE
QT=IQU
IQU=(RAND(0,99)*Q1)
IQU=IQU+1
IF (IQU.LE.1) GO TO 241
QTS=USVCT(IQUE)
QSVCT(IQU)=USVCT(IQU)
QSVCT(IQU)=QTS
C   QUEUE IS SCHEDULED - RETURN
241 CONTINUE
RETURN
END

SUBROUTINE DEPART
COMMON ALPHA(10),ANUM,ARRT,ARRTM,CH(20,10),CUMUL,CUSERV,DEPT,
1   DEPTM,I,USERV,I2,KA,KCUS,KS,N,AFLAG,SNUM,STATUS(9),T,
2   TIME,TIME,INARV,TNDPR(9),AVARRA,AVSERV,AMNIS,AMTIS,
3   VCUST,VCOSTS,FCOST,FCOSTS,KRULE,IQUE,CUMQUE(10),
4   USVCT(10),AM(500),SR(500)
C   THIS SUBROUTINE PROCESSES THE DEPARTURE OF EVERY CUSTOMER
C   IT UPDATES THE HOURS SPENT IN THE QUEUE
C   IT UPDATES THE CLOCK TO THE NEXT DEPARTURE TIME (PREVIOUSLY
C   SELECTED)
C   IT CHECKS THE LENGTH OF THE QUEUE
C   IF NO ONE IN THE QUEUE IT SETS THE CHANNEL AT AN IDLE STATUS (THIS
C   DEPARTURE WAS PREVIOUSLY PARTIALLY PROCESSED EITHER AT
C   ARRIVE OR BY A PRIOR PASS THROUGH DEPART)
C   IF A QUEUE EXISTS THEN TAKE ONE FROM QUEUE, ITS DEPARTURE TIME,
C   SET THE CHANNEL AT A BUSY STATUS AND RETURN
C   CHECK LENGTH OF QUEUE, IF OVER 99 HOLD AT 99
C   IF (IQUE.LT.100) GO TO 11
IQUE=IQU
C   UPDATE THE HOURS SPENT IN QUEUE
11 CONTINUE
CUMQUE(IQUE)=CUMQUE(IQUE)+TNDPR(I)-TIME
C   UPDATE THE CLOCK TO NEXT DEPARTURE TIME
TIME=TNDPR(I)
IF (IQUE.GT.1) GO TO 21
C   THIS SECTION COMPLETES THE PROCESSING OF A CUSTOMER
C   WHEN NO ONE IS WAITING IN THE QUEUE
STATUS(I)=0.0
TNDPR(I)=999999.9
RETURN
C   THIS SECTION DOES THE DEPART PROCESSING
C   WHEN THE CHANNEL HAS BEEN BUSY
C   SET NEXT DEPARTURE TIME
21 CONTINUE
TNDPR(I)=TIME+QSVCT(I)
C   STORE FIRST TWENTY DEPARTURE TIMES IN CH
KCUS=KCUS+1
IF (KCUS.GT.20) GO TO 31
II=I+1
CH(KCUS,II)=TNDPR(I)
31 CONTINUE
C   CHECK IF OUT OF SIMULATION TIME
IF (TIME.LT.TNDPR(I)) GO TO 51
C   RESET STATUS BACK TO BUSY AND RETURN
CUMUL=CUMUL+QSVCT(I)
CUSERV=CUSERV+1.0
STATUS(I)=1.0
C   SHIFT SERVICE QUEUE UP ONE POSITION
DO 41 II=1,IQUE

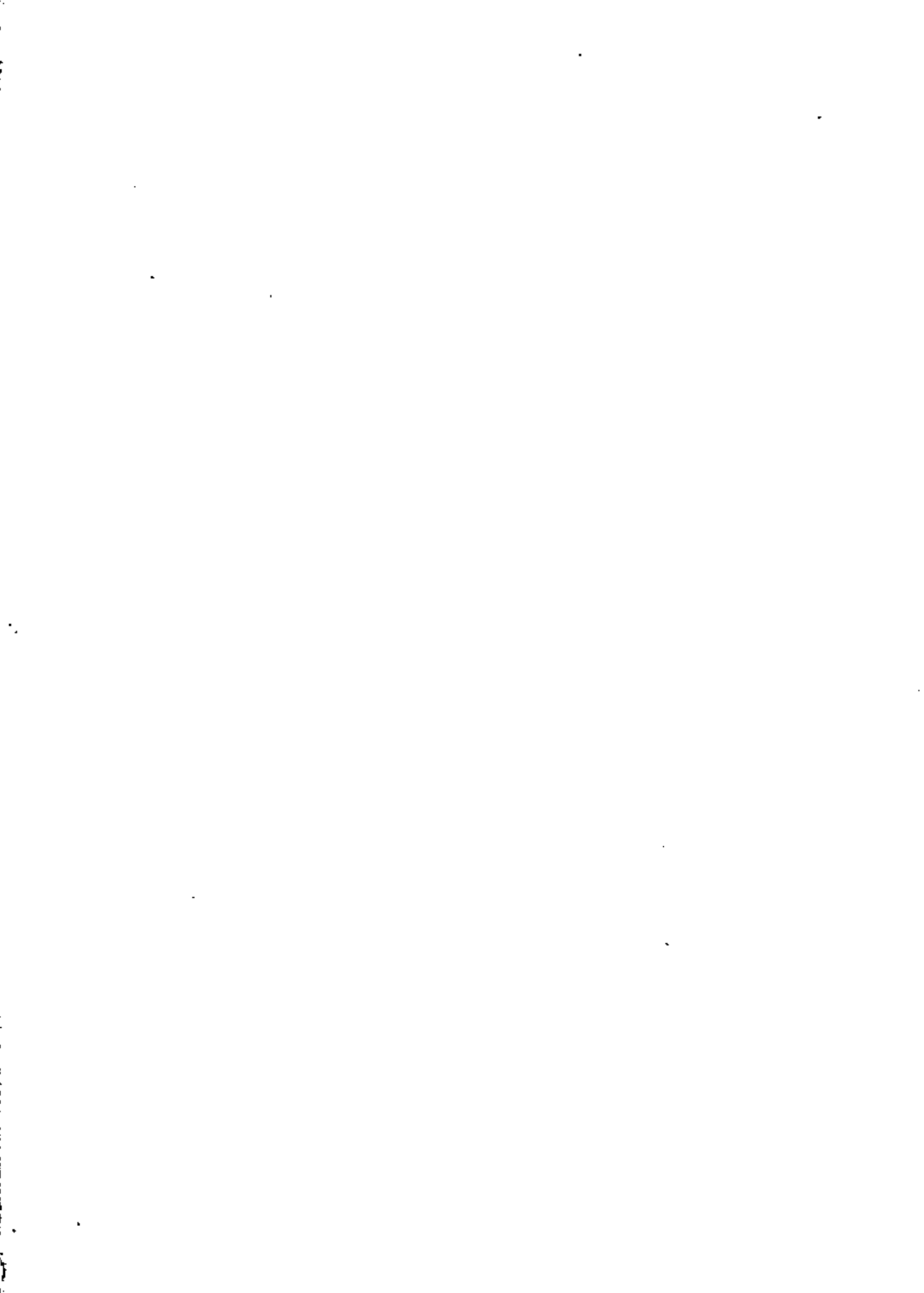
```

41

E 134  
B 135  
B 136  
B 137  
B 138  
B 139  
B 140  
B 141  
B 142  
B 143  
B 144  
B 145  
B 146  
B 147  
B 148  
B 149

C 1  
C 2  
C 3  
C 4  
C 5  
C 6  
C 7  
C 8  
C 9  
C 10  
C 11  
C 12  
C 13  
C 14  
C 15  
C 16  
C 17  
C 18  
C 19  
C 20  
C 21  
C 22  
C 23  
C 24  
C 25  
C 26  
C 27  
C 28  
C 29  
C 30  
C 31  
C 32  
C 33  
C 34  
C 35  
C 36  
C 37  
C 38  
C 39  
C 40  
C 41  
C 42  
C 43  
C 44  
C 45  
C 46  
C 47  
C 48  
C 49

	III=II+1	C	50	
	QSVCT(III)=QSVCT(III)	C	51	42
41	CONTINUE	C	52	
	QSVCT(IQUE)=0.0	C	53	
	SUBTRACT ONE FROM IQUE	C	54	
	IQUE=IQUE-1	C	55	
	RETURN	C	56	
C	ADJUST I AND CUMUL AT TERMINATION OF SIMULATION	C	57	
C	LAST CUSTOMER FORCED TO DEPART AT TTIME	C	58	
51	CONTINUE	C	59	
	TK=QSVCT(III)-(TNDPR(III)-TTIME)	C	60	
	IF (TK.GT.0.0) GO TO 61	C	61	
	TK=0.	C	62	
61	CONTINUE	C	63	
	TNDPR(III)=TTIME	C	64	
	CUMUL=CUMUL+TK	C	65	
	STATUS(III)=1.0	C	66	
	RETURN	C	67	
	END	C	68	
	FUNCTION RAND (K, KK)	D	1	
C	MACHINE DEPENDENT RANDOM NUMBER GENERATOR (0 TO 1)	D	2	
C	THIS VERSION FOR CDC 3100	D	3	
C	K SET AT POSITIVE ODD INTEGER TO INITIALIZE	D	4	
C	K SET AT ZERO TO CONTINUE STRING OF RANDOM NUMBERS	D	5	
C	SEE NAYLOR, COMPUTER SIMULATION TECHNIQUES, WILEY SONS, 1966	D	6	
	IF (K) 21, 21, 11	D	7	
11	CONTINUE	D	8	
	N=K	D	9	
	NN=K	D	10	
	NNN=K	D	11	
21	CONTINUE	D	12	
	IF (KK) 31, 31, 01	D	13	
31	CONTINUE	D	14	
	N=N+2051	D	15	
	IF (N) 41, 51, 51	D	16	
41	CONTINUE	D	17	
	N=N+8388607+1	D	18	
51	CONTINUE	D	19	
	XN=N	D	20	
	RAND=XN/8388607.	D	21	
	RETURN	D	22	
C	POSITIVE KK RUNS SECOND STRING OF RANDOM NUMBERS	D	23	
61	CONTINUE	D	24	
	IF (KK-50) 71, 71, 101	D	25	
71	CONTINUE	D	26	
	NN=NN+2051	D	27	
	IF (NN) 81, 91, 91	D	28	
81	CONTINUE	D	29	
	NN=NN+8388607+1	D	30	
91	CONTINUE	D	31	
	XNN=NN	D	32	
	RAND=XNN/8388607.	D	33	
	RETURN	D	34	
C	KK OVER 5 RUNS THIRD STRING OF RANDOM NUMBERS	D	35	
101	CONTINUE	D	36	
	NNN=NNN+2051	D	37	
	IF (NNN) 111, 121, 121	D	38	
111	CONTINUE	D	39	
	NNN=NNN+8388607+1	D	40	
121	CONTINUE	D	41	
	XNNN=NNN	D	42	
	RAND=XNNN/8388607.	D	43	
	RETURN	D	44	
	END	D	45	



## TARJETAS PARA USAR EL PROGRAMA GRANM

	Columna 1
Tarjeta 1	// JØB T
Tarjeta 2	// XEQ GRANM 1
Tarjeta 3	*LØCALINIT, PIVØT, TABNU, RMØVE, CLEAN, TABPR
	-
	- Tarjetas de datos (Ver página 3)
	-
Tarjeta final	/*

### NOTAS:

- Este programa está listo para usarse en la computadora IBM 1130 de CECAFI.
- La tarjeta 1 es la tarjeta anaranjada obtenida del CECAFI.
- El número 1 que aparece en la 2a. tarjeta se perfora en la columna 17.
- El programa en la IBM, tiene una capacidad de 10 restricciones y 15 variables incluyendo de holgura y artificiales.
- Este programa también se encuentra disponible en la Burroughs del CIMASS, bajo el nombre de II/SIMPLEX. Las instrucciones para correrlo en el CIMASS aparecen en la siguiente hoja. Este admite una capacidad mayor sobre el número de restricciones y variables como se indica en la segunda hoja.
- Este programa utilizó el método de la gran M.

## TARJETAS PARA USAR EL PROGRAMA II/SIMPLEX

	Columna 1
Tarjeta 1	# USER <u>clave</u> / _____
Tarjeta 2	# RUN (JRB2) II/SIMPLEX
Tarjeta 3	# DATA FILE 5
	-
	- Tarjetas de datos (Ver página 3)
	-
Tarjeta final	# END

### NOTAS:

- Este programa está listo para usarse en la computadora 8 6700 de CIMAS/CSC.
- La tarjeta 1 es la tarjeta roja obtenida del CIMASS.
- El símbolo "#" significa un carácter inválido. Este se obtiene presionando las teclas MULTIPUNCH Y NUMERIC simultáneamente y perforando los números 1, 2, 3, 4.
- Este programa tiene una capacidad de 30 restricciones y 40 variables incluyendo de holgura y artificiales.



## TARJETAS DE DATOS PARA EL PROGRAMA GRANM O II/SIMPLEX

La siguiente información deberá proporcionarse en la que se indica como tarjetas de datos en las hojas anteriores.

### TARJETA DE IDENTIFICACION DEL PROBLEMA.

En esta tarjeta pueda usar desde la columna 1 a la 70 para poder dar cualquier identificación que desee dar a su problema.

### TARJETA DE DIMENSION Y ETIQUETACION DEL PROBLEMA Y CONTROL PARA CORRER MAS DE UN PROBLEMA.

El usuario debe dar cuatro números enteros con formato (4110) en la siguiente forma:

- Columnas 1-10: Número de renglones del problema.
- Columnas 11-20: Número de columnas del problema.
- Columna 30 : Escriba el número 1 si desea poner etiquetas a los renglones y a las columnas.  
Escriba el número 0 en caso contrario.
- Columna 40 : Escriba un 1 si desea correr un problema adicional.  
Escriba un 0 en caso contrario.

### NOTAS:

El número de renglones no incluye la función objetivo.

Si escribo un 1 en la columna 30, el usuario, después de la tarjeta deberá dar el grupo de tarjetas para etiquetas de renglones y el grupo de tarjetas para etiquetas de columnas. Si en lugar de un 1 escribe cero deberá omitir este grupo de tarjetas y pasar a las tarjetas de coeficientes de las variables artificiales en la función objetivo.

Si escribo un 1 en la tarjeta 40 vea las notas generales.

### TARJETAS PARA ETIQUETAS DE RENGLONES.

Las etiquetas para identificar a los renglones de las restricciones, pueden tener como máximo 6 caracteres de cualquier tipo.

En una tarjeta puede escribir hasta 7 etiquetas. Estas etiquetas deben ir en las columnas 1-6, 11-16, 21-26, 31-36, 41-46, 51-56, 61-66.

### TARJETAS PARA ETIQUETAS DE COLUMNAS (VARIABLES)

Los tarjetas para identificar a las columnas o sea a las variables involucradas en el problema (incluyendo de holgura y artificiales) deberán escribirse de acuerdo a las reglas anteriores para etiquetar renglones.

### TARJETAS DE COEFICIENTES DE LAS VARIABLES ARTIFICIALES EN LA FUNCION OBJETIVO.

A cada variable artificial asigne un 1 y a las variables no artificiales asigne un 2. Estos números escribalos en las columnas 10, 20, 30, 40, 50, 60, 70, de acuerdo al orden en que etiquetó a sus variables (columnas)

IMPORTANTE. Esta tarjeta es requerida aún si el problema no tiene variables artificiales.

### TARJETAS DE COEFICIENTES DE LAS VARIABLES NO ARTIFICIALES EN LA FUNCION OBJETIVO.

Escriba los coeficientes de la función objetivo con el formato (7 F 10.0). Estos coeficientes debe escribirlos de acuerdo al orden en que etiquetó sus variables (columnas). Los coeficientes de las variables de holgura y artificiales deberá ser cero.

IMPORTANTE: Los coeficientes de la función objetivo deben corresponder al problema a minimizar. Por lo tanto, si su problema es de maximizar multiplique por -1 y considere los coeficientes que resultan como los datos de entrada en este programa.

### TARJETAS DE LOS COEFICIENTES DE LA MATRIZ DE RESTRICCIONES.

Cada renglón de restricciones va en una o varias tarjetas, escribiendo los elementos sucesivamente en una tarjeta con un formato (7 F 10.0). Cada vez que proporcione un nuevo renglón debe empezar en otra tarjeta.

### TARJETAS DE LOS LADOS DERECHOS DE LAS RESTRICCIONES.

Los coeficientes del lado derecho de restricciones se proporcionan sucesivamente en una tarjeta o en caso de ser insuficiente uso otra tarjeta. El formato es (7 F 10.0)

### TARJETAS PARA INDICAR EL CONJUNTO INICIAL DE VARIABLES BASICAS.

En una tarjeta programe sucesivamente los números de las columnas que van a ser usadas como columnas (variables) básicas iniciales. Use formato (7 I 10).

NOTAS GENERALES:

- 1. El orden de las tarjetas debe ser como el indicado.
- 2. Si en la TARJETA DE DIMENSION Y ETIQUETACION escribiste un 1 en la columna 40 entonces tu nuevo problema debe ir después de la TARJETA PARA INDICAR EL CONJUNTO INICIAL DE VARIABLES ARTIFICIALES. Es importante que en el nuevo problema empiece con la TARJETA DE IDENTIFICACION DEL PROBLEMA.

EJEMPLO 1. Considere el problema lineal

$$\begin{aligned} \max z &= x_4 - x_5 \\ \text{s.o.} \\ 2x_2 - x_3 - x_4 + x_5 &\geq 0 \\ -2x_1 + 2x_3 - x_4 + x_5 &\geq 0 \\ x_1 - 2x_2 - x_4 + x_5 &\geq 0 \\ x_1 + x_2 + x_3 &= 1 \\ x_i &\geq 0 \end{aligned}$$

Deberemos multiplicar la función objetivo por -1 para que el problema sea de minimización y también agregar variables de holgura a las primeras tres restricciones para que lleguen a ser igualdades. Con estas observaciones el programa lineal estará en forma estándar, lo cual es una condición para aplicar el programa GRAN M. Si definimos  $z' = -z$ , nuestro problema en forma estándar es

$$\begin{aligned} \min z' &= -x_4 + x_5 \\ -2x_2 + x_3 + x_4 - x_5 + s_1 &= 0 \\ 2x_1 - 2x_3 + x_4 - x_5 + s_2 &= 0 \\ -x_1 + 2x_2 + x_4 - x_5 + s_3 &= 0 \\ x_1 + x_2 + x_3 &= 1 \\ x_i &\geq 0; \quad i = 1, 2, \dots, 5 \\ s_j &\geq 0; \quad j = 1, 2, 3 \end{aligned}$$

Obsérvese que aunque el programa lineal ya está en forma estándar, todavía no está listo para empezar el algoritmo de la Gran M porque en la última restricción no existe una variable que aparezca en esta restricción pero no se encuentre en las otras restricciones. (i.e., no tiene una solución básica factible inmediata). Por lo tanto, deberemos agregar una variable artificial que llamaremos  $t_1$ , a la cuarta restricción para así completar nuestra solución básica factible en la cual se inicia el algoritmo. Sin embargo, al introducir esta variable artificial en la restricción deberemos agregarla en la función objetivo multiplicada por una cantidad positiva  $M$  muy grande. Así nuestro problema resulta ser:

$$\begin{aligned} \min z' &= -x_4 + x_5 + Mt_1 \\ -2x_2 + x_3 + x_4 - x_5 + s_1 &= 0 \\ 2x_1 - 2x_3 + x_4 - x_5 + s_2 &= 0 \\ -x_1 + 2x_2 + x_4 - x_5 + s_3 &= 0 \\ x_1 + x_2 + x_3 + t_1 &= 1 \\ x_i &\geq 0; \quad i = 1, 2, \dots, 5 \\ s_j &\geq 0; \quad j = 1, 2, 3 \\ t_1 &\geq 0 \end{aligned}$$

Es conveniente representar el programa lineal en un tablero (o tableau), para poder entender más fácilmente la información que deberemos proporcionar al programa de computadora GRAN M ó II/SIMPLEX. Esta representación aparece abajo

	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$s_1$	$s_2$	$s_3$	$t_1$	
Función Obj. (F.O.)	0	0	0	-1	1	0	0	0	M	$z'$
Renglón 1 (R. 1)	0	-2	1	1	-1	1	0	0	0	0
Renglón 2 (R. 2)	2	0	-2	1	-1	0	1	0	0	0
Renglón 3 (R. 3)	-1	2	0	1	-1	0	0	1	0	0
Renglón 4 (R. 4)	1	1	1	0	0	0	0	0	1	1

$\underbrace{\quad \quad \quad}_{\text{Var. Holgu-}} \quad \underbrace{\quad \quad \quad}_{\text{ra}} \quad \underbrace{\quad \quad \quad}_{\text{Var.}} \quad \underbrace{\quad \quad \quad}_{\text{Art.}}$   
 Solución inicial  
 básica factible

Este tablero contiene toda la información necesaria y la notación apropiada para correr el programa GRAN M ó el II/SIMPLEX. A continuación se presenta su codificación para el GRAN M. Para correr el II/SIMPLEX la codificación es idéntico excepto por las tarjetas de control como se mencionó en la explicación de estos programas.



EJEMPLO 2

$$\begin{aligned} \max z &= x_1 + x_2 \\ \text{s.o.} \\ x_1 + x_2 &\geq 1 \\ x_1 + x_2 &\leq 1 \\ -x_1 + x_2 &\leq 1 \\ x_1 &\geq 0 \end{aligned}$$

Expresando la función objetivo en términos de minimización e introduciendo variables de holgura, artificiales; el problema es equivalente a :

$$\begin{aligned} \min (-z) &= -x_1 - x_2 + Mt_1 \\ x_1 + x_2 - s_1 &+ t_1 = 1 \\ x_1 - x_2 + s_2 &= 1 \\ -x_1 + x_2 + s_3 &= 1 \end{aligned}$$

En forma de tableau:

	$x_1$	$x_2$	$s_1$	$t_1$	$s_2$	$s_3$	
Func. Obj. (F.O.)	-1	-1	0	M	0	0	-z
Renglón 1 (R.1)	1	1	-1	1	0	0	1
Renglón 2 (R.2)	1	-1	0	0	1	0	1
Renglón 3 (R.3)	-1	+1	0	0	0	1	1

\* \* \*  
Solución básica factible inicial.

U N A M

HOJA DE CODIFICACION Y/O DATOS FORTRAN

FACULTAD DE INGENIERIA

NUMERO DE PROPOSICION	PROGRAMA		HOJA DE		IDENTIFICACION Y SECUENCIA
	PROGRAMADOR		FORMA		
1	2	3	4	5	6
7	8	9	10	11	12
13	14	15	16	17	18
19	20	21	22	23	24
25	26	27	28	29	30
31	32	33	34	35	36
37	38	39	40	41	42
43	44	45	46	47	48
49	50	51	52	53	54
55	56	57	58	59	60
61	62	63	64	65	66
67	68	69	70	71	72
73	74	75	76	77	78
79	80	81	82	83	84
85	86	87	88	89	90
91	92	93	94	95	96
97	98	99	100	101	102
103	104	105	106	107	108
109	110	111	112	113	114
115	116	117	118	119	120
121	122	123	124	125	126
127	128	129	130	131	132
133	134	135	136	137	138
139	140	141	142	143	144
145	146	147	148	149	150
151	152	153	154	155	156
157	158	159	160	161	162
163	164	165	166	167	168
169	170	171	172	173	174
175	176	177	178	179	180
181	182	183	184	185	186
187	188	189	190	191	192
193	194	195	196	197	198
199	200	201	202	203	204
205	206	207	208	209	210
211	212	213	214	215	216
217	218	219	220	221	222
223	224	225	226	227	228
229	230	231	232	233	234
235	236	237	238	239	240
241	242	243	244	245	246
247	248	249	250	251	252
253	254	255	256	257	258
259	260	261	262	263	264
265	266	267	268	269	270
271	272	273	274	275	276
277	278	279	280	281	282
283	284	285	286	287	288
289	290	291	292	293	294
295	296	297	298	299	300

PROGRAMA: XEQ GRANM 1  
 LOCALINI I PIVOT, TABNU, RMØVE, CLEAN, TABP R  
 PROBLEMA: NO ACOTADO DE INVESTIGACION DE OPERACIONES 1

R.1 3 6 1 0  
 X.1 X.2 S.1 T.1 S.2 S.3  
 0 0 0 1 0 0  
 1.0 1.0 -1.0 1.0 0.0 0.0  
 1.0 1.0 -1.0 0.0 0.0 1.0  
 1.0 1.0 1.0 0.0 0.0 1.0  
 4 5 6

EJEMPLO 3 Resolver el dual del siguiente par de problemas primal - dual.

Primal

$$\begin{aligned} \min z &= 2x_1 - 3x_2 \\ 2x_1 - x_2 - x_3 &\geq 3 \\ x_1 - x_2 + x_3 &\geq 2 \\ x_i &\geq 0 \end{aligned}$$

Dual

$$\begin{aligned} \max w &= 3 \lambda_1 + 2 \lambda_2 \\ 2\lambda_1 + \lambda_2 &\leq 2 \\ -\lambda_1 - \lambda_2 &\leq -3 + \lambda_1 + \lambda_2 \geq 3 \\ -\lambda_1 - \lambda_2 &\leq 0 \\ \lambda_i &\geq 0 \end{aligned}$$

Este dual es equivalente a

$$\begin{aligned} \min (-w) &= -3 \lambda_1 - 2 \lambda_2 + M t_1 \\ 2\lambda_1 + \lambda_2 + s_1 &= 2 \\ \lambda_1 + \lambda_2 - s_2 + t_1 &= 3 \\ -\lambda_1 + \lambda_2 + s_3 &= 0 \end{aligned}$$

En forma de tableau; el dual está dado por

	$\lambda_1$	$\lambda_2$	$s_2$	$s_1$	$t_1$	$s_3$	
F.O.	-3	-2	0	0	M	0	-w
R1	2	1	0	1	0	0	2
R2	1	1	-1	0	1	0	3
R3	-1	1	0	0	0	1	0

\* \* \*





EJEMPLO 4

$$\max z = x_1 - x_2 + x_3 - 3x_4 + x_5 - x_6 - 3x_7$$

s.o.

$$3x_3 + x_5 + x_6 = 6$$

$$x_2 + 2x_3 - x_4 = 10$$

$$-x_1 + x_6 = 0$$

$$x_3 + x_6 + x_7 = 6$$

$$x_i \geq 0$$

$$\min (-z) = -x_1 + x_2 - x_3 + 3x_4 - x_5 + x_6 + 3x_7$$

s.o.

$$3x_3 + x_5 + x_6 = 6$$

$$x_2 + 2x_3 - x_4 = 10$$

$$x_1 - x_6 = 0$$

$$x_3 + x_6 + x_7 = 6$$

En forma de Tableau:

	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$x_6$	$x_7$	
F.O.	-1	1	-1	3	-1	1	3	-z
R1	0	0	3	0	1	1	0	6
R2	0	1	2	-1	0	0	0	10
R3	1	0	0	0	0	-1	0	0
R4	0	0	1	0	0	1	1	6

UNAM

HOJA DE CODIFICACION Y/O DATOS FORTRAN

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	PROGRAMADOR																														FECHA																																																
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80
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